

Problem 1 - 2 Points

Compute AB and BA for the following matrices. If the product is not defined explain why not.

$$A = \begin{bmatrix} 2 & 4 \\ 1 & -1 \\ -2 & 1 \end{bmatrix}, B = \begin{bmatrix} 2 & 1 \\ 3 & -2 \end{bmatrix}$$

3×2 2×2

$$\underline{AB} = \begin{pmatrix} 2 & 4 \\ 1 & -1 \\ -2 & 1 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 3 & -2 \end{pmatrix} = \begin{pmatrix} 16 & -6 \\ -1 & 3 \\ -1 & -4 \end{pmatrix}$$

\underline{BA} not defined as $\# \text{ cols } B \neq \# \text{ rows } A$

$\uparrow \quad \uparrow$
 $2 \times 2 \quad 3 \times 2$

Problem 2 - 4 Points

Consider the following transformation $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$

$$T\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}\right) = \begin{bmatrix} x_1 \\ x_2 - x_3 \end{bmatrix}$$

Show whether this transformation is linear or not. If it is, find the standard matrix A of the transformation T .

$$\begin{aligned} T\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}\right) &= T\left(\begin{bmatrix} x_1 + y_1 \\ x_2 + y_2 \\ x_3 + y_3 \end{bmatrix}\right) = \begin{pmatrix} x_1 + y_1 \\ x_2 + y_2 - x_3 - y_3 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 - x_3 \end{pmatrix} + \begin{pmatrix} y_1 \\ y_2 - y_3 \end{pmatrix} \\ &= T\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}\right) + T\left(\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}\right) \end{aligned}$$

$$T\left(c \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}\right) = T\left(\begin{bmatrix} cx_1 \\ cx_2 \\ cx_3 \end{bmatrix}\right) = \begin{pmatrix} cx_1 \\ cx_2 - cx_3 \end{pmatrix} = c \begin{pmatrix} x_1 \\ x_2 - x_3 \end{pmatrix} = c T\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}\right)$$

So T is linear.

$$T(e_1) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad T(e_2) = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \quad T(e_3) = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix}$$

$$\Rightarrow \underline{\underline{A}} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & -1 \end{pmatrix}$$

Problem 3 - 4 Points

Suppose a linear transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ is defined by

$$T\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ -1 \\ -1 \end{bmatrix}, \quad T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \quad T\left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

1. Write the standard matrix A of the transformation T . Find A^{-1} .

2. Compute $A^{-1} \begin{bmatrix} 1 \\ -1 \\ -1 \end{bmatrix}$. What do you get?

$$1) \underline{\underline{A}} = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -1 & 1 & 0 \end{pmatrix}, \quad \text{for } \underline{\underline{A}}^{-1},$$

$$\left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 0 \\ -1 & 1 & 1 & 0 & 1 & 0 \\ -1 & 1 & 0 & 0 & 0 & 1 \end{array} \right) \sim \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \end{array} \right)$$

$$\sim \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & 1 & 1 & 1 & 0 \end{array} \right) \sim \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & -1 \end{array} \right) \quad \underbrace{\hspace{10em}}_{\underline{\underline{A}}^{-1}}$$

$$2) \underline{\underline{A}}^{-1} \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad \text{as expected}$$