

```
In [1]: using PyPlot
        using LinearAlgebra
```

Problem 1 - Computational geometry

Given a function $f(x)$ defined on $[0, 1]$, and its derivatives $f'(x)$, $f''(x)$ draw the osculating circle of at a point $x_0 \in (0, 1)$.

An osculating circle at x_0 is the circle that passes through the point and has the same tangent and curvature of the curve at $f(x_0)$.

Reminder that curvature can be written as $\frac{f''(x)}{(1+f'(x))^{\frac{3}{2}}}$

Solution:

```
In [2]: function osculatingCircle( f, df, d2f, x0 )

        #Calculate function and derivatives
        fx0 = f(x0);
        dfx0 = df(x0);
        d2fx0 = d2f(x0);

        #Calculate circle quantities
        kappa = d2fx0 / abs( 1.0+dfx0 )^(3.2);
        radius = 1/kappa;
        vec = [-dfx0,1];
        vec /= norm(vec)
        centre = [x0, fx0] + vec*radius;

        #Draw function
        xpts = LinRange(0,1,40);
        ypts = [f(x) for x in xpts];
        plot(xpts, ypts, "b-")

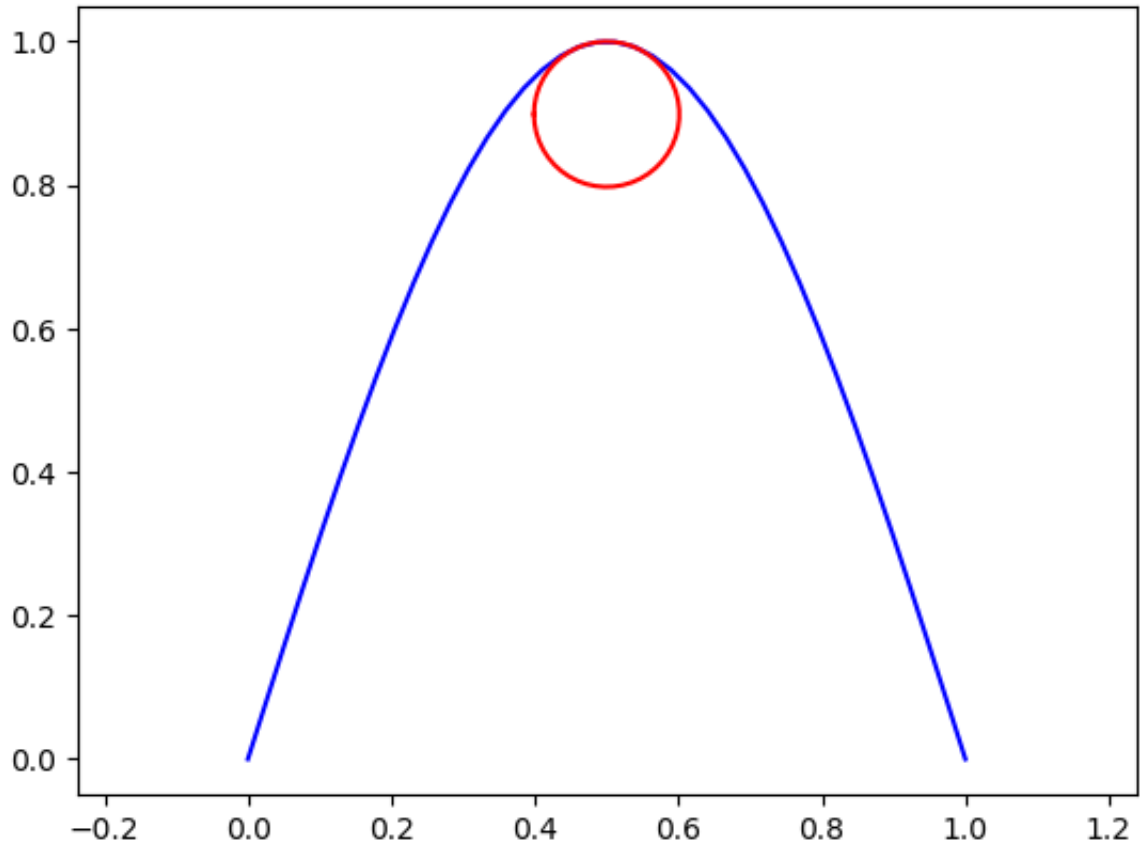
        #Draw circle
        theta = LinRange( 0, 2*pi, 50 )
        xpts = [ radius*cos(t)+centre[1] for t in theta ]
        ypts = [ radius*sin(t)+centre[2] for t in theta ]
        plot(xpts, ypts, "r-")

    end
```

Out [2]: osculatingCircle (generic function with 1 method)

```
In [3]: g(x) = sin(x*pi)
dg(x) = cos(x*pi)*pi
d2g(x) = -sin(x*pi)*(pi)^2
x0 = 0.5

osculatingCircle( g, dg, d2g, x0 );
axis("equal");
```



Problem 2 - Optimisation

Part 1: Write out the Taylor Series approximation for $f(x_0 + h)$ centred at the point x_0 up to second order terms.

Part 2: Write out the Taylor Series approximation for $f(x_0 - h)$ centred at the point x_0 up to second order terms.

Part 3: Combine these two to get an approximation for the first derivative $f'(x_0)$.

Part 4: Use this approximate derivative to implement gradient descent to minimise some function $f(x)$ (100 maximum iterations, $h = 1e-4$, $\alpha=0.1$).

Solution

$$1) f(x_0 + h) = f(x_0) + hf(x_0) + \frac{h^2}{2} f''(x_0)$$

$$2) f(x_0 - h) = f(x_0) - hf(x_0) + \frac{h^2}{2} f''(x_0)$$

$$3) \frac{f(x_0+h)-f(x_0-h)}{2h} \approx f'(x_0)$$

Code for part 4:

```
In [4]: function approxGradientDescent( f, x0 )

    maxiters = 100;
    prevx = 0.0;
    currx = x0;
    h = 1e-4;
    alpha = 0.1;

    for iter = 1:maxiters

        dfx = ( f( currx+h ) - f( currx-h ) ) / ( 2*h );
        prevx = currx + 0.0;
        currx -= alpha * dfx;
        if abs( prevx-currx ) < 1e-8
            return currx
        end

    end

    return currx

end
```

Out [4]: approxGradientDescent (generic function with 1 method)

```
In [5]: f1(x) = cos(x)^2

        approxGradientDescent( f1,0.1 )
```

Out [5]: 1.5707962946425253

Problem 3 - Graphs

A bipartite graph is one where you can separate nodes into two groups A , B such that each edge of the graph connects a vertex of A to one of B .

Edit BFS to determine whether a graph is bipartite.

```
In [6]: struct Vertex
        neighbors::Vector{Int}      # Indices of neighbors of this Vertex
        coordinates::Vector{Float64} # 2D coordinates of this Vertex - only
        Vertex(neighbors; coordinates=[0,0]) = new(neighbors, coordinates)
    end

    function Base.show(io::IO, v::Vertex)
        print(io, "Neighbors = ", v.neighbors)
    end
```

```
In [7]: struct Graph
        vertices::Vector{Vertex}
    end

    function Base.show(io::IO, g::Graph)
        for i = 1:length(g.vertices)
            println(io, "Vertex $i, ", g.vertices[i])
        end
    end
```

```

In [8]: function PyPlot.plot(g::Graph; scale=1.0)
        fig, ax = subplots()
        ax.set_aspect("equal")

        xmin = minimum(v.coordinates[1] for v in g.vertices)
        xmax = maximum(v.coordinates[1] for v in g.vertices)
        ymin = minimum(v.coordinates[2] for v in g.vertices)
        ymax = maximum(v.coordinates[2] for v in g.vertices)
        sz = max(xmax-xmin, ymax-ymin)
        cr = scale*0.05sz
        hw = cr/2
        axis([xmin-2cr,xmax+2cr,ymin-2cr,ymax+2cr])
        axis("off")

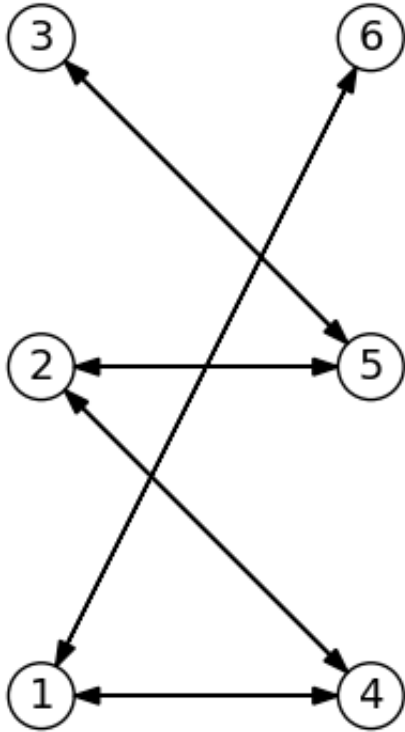
        for i in 1:length(g.vertices)
            c = g.vertices[i].coordinates
            ax.add_artist(matplotlib.patches.Circle(c, cr, facecolor="none")
            ax.text(c[1], c[2], string(i),
                    horizontalalignment="center", verticalalignment="center")
            for nb in g.vertices[i].neighbors
                cnb = g.vertices[nb].coordinates
                dc = cnb .- c
                L = sqrt(sum(dc.^2))
                c1 = c .+ cr/L * dc
                c2 = cnb .- cr/L * dc
                arrow(c1[1], c1[2], c2[1]-c1[1], c2[2]-c1[2],
                    head_width=hw, length_includes_head=true, facecolor="none")
            end
        end
    end
end

```

Here is an example of a bipartite graph:

```
In [9]: v1 = Vertex([4,6], coordinates=[0,-1])
v2 = Vertex([5,4], coordinates=[0,0])
v3 = Vertex([5], coordinates=[0,1])
v4 = Vertex([1,2], coordinates=[1,-1])
v5 = Vertex([2,3], coordinates=[1,0])
v6 = Vertex([1], coordinates=[1,1])
g1 = Graph([v1,v2,v3,v4,v5,v6]);

plot(g1)
```



Here is BFS:

```
In [10]: function bfs(g::Graph, start)
          visited = falses(length(g.vertices))
          S = [start]
          visited[start] = true
          while !isempty(S)
              ivertex = popfirst!(S)
              println("Visiting vertex #${ivertex}")
              for nb in g.vertices[ivertex].neighbors
                  if !visited[nb]
                      visited[nb] = true
                      push!(S, nb)
                  end
              end
          end
      end
```

Out[10]: bfs (generic function with 1 method)

Solution:

```
In [11]: function isBipartite(g::Graph, start)
          isAB = -ones{Int, length(g.vertices)}
          isAB[start] = 0

          visited = falses{length(g.vertices)}
          S = [start]
          visited[start] = true
          while !isempty(S)
              ivertex = popfirst!(S)
              println("Visiting vertex #\$ivertex")

              for nb in g.vertices[ivertex].neighbors
                  if !visited[nb]
                      visited[nb] = true
                      isAB[nb] = 1-isAB[ivertex];
                      push!(S, nb)
                  else
                      if isAB[nb] == isAB[ivertex]
                          return false
                      end
                  end
              end
          end

          return true
      end
```

Out[11]: isBipartite (generic function with 1 method)

```
In [12]: isBipartite(g1,1)
```

```
Visiting vertex #1
Visiting vertex #4
Visiting vertex #6
Visiting vertex #2
Visiting vertex #5
Visiting vertex #3
```

Out[12]: true

```
In [ ]:
```