

Worksheet 29 (April 23)

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1 Review

DEFINITIONS

- fundamental solution set, fundamental solution matrix.

METHODS AND IDEAS

Theorem 1. Consider the 1st-order linear ODE system

$$\mathbf{x}' = A\mathbf{x},$$

with A being a diagonalizable $n \times n$ matrix. Assume $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ is an eigenbasis of A , and denote by $\{\lambda_1, \dots, \lambda_n\}$ the corresponding eigenvalues. Then

$$\{e^{\lambda_1 t} \mathbf{v}_1, \dots, e^{\lambda_n t} \mathbf{v}_n\}$$

is a fundamental solution set. In other words, the general solution is

$$\mathbf{x}(t) = c_1 \cdot e^{\lambda_1 t} \mathbf{v}_1 + \dots + c_n \cdot e^{\lambda_n t} \mathbf{v}_n.$$

Remark 1. When A is diagonalizable over \mathbb{C} , we have a similar theorem. More precisely, let's assume $\lambda_1 = \alpha + i\beta$ and $\lambda_2 = \alpha - i\beta$ are the two complex eigenvalues, and $\mathbf{v}_1 = \mathbf{a} + i\mathbf{b}$ and $\mathbf{v}_2 = \mathbf{a} - i\mathbf{b}$ be the complex eigenvectors (complex eigenvalues and eigenvectors come in pairs). Then,

$$\{e^{\alpha t} \cos \beta t \mathbf{a} - e^{\alpha t} \sin \beta t \mathbf{b}, e^{\alpha t} \cos \beta t \mathbf{b} + e^{\alpha t} \sin \beta t \mathbf{a}, e^{\lambda_3 t} \mathbf{v}_3, \dots, e^{\lambda_n t} \mathbf{v}_n\}$$

is a fundamental solution set. Note that for the first two terms, we are simply taking the real and imaginary parts of $e^{\lambda_1 t} \mathbf{v}_1$:

$$e^{\alpha t} \cos \beta t \mathbf{a} - e^{\alpha t} \sin \beta t \mathbf{b} = \operatorname{Re}(e^{\lambda_1 t} \mathbf{v}_1) = \operatorname{Re}(e^{(\alpha+i\beta)t} (\mathbf{a} + i\mathbf{b})),$$

$$e^{\alpha t} \cos \beta t \mathbf{b} + e^{\alpha t} \sin \beta t \mathbf{a} = \operatorname{Im}(e^{\lambda_1 t} \mathbf{v}_1) = \operatorname{Im}(e^{(\alpha+i\beta)t} (\mathbf{a} + i\mathbf{b})).$$

2 Problems

Example 1. Consider the 1st order homogeneous linear system of ODE

$$\mathbf{x}'(t) = \begin{pmatrix} 1 & 1 \\ -2 & 4 \end{pmatrix} \mathbf{x}(t).$$

- (a) Find a fundamental solution matrix of the system.
- (b) Solve the initial value problem $\mathbf{x}(0) = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$.
- (c) Sketch the trajectory of $\mathbf{x}(t)$ in (b).

Example 2. Find the general solution of the linear ODE

$$y'''(t) + y(t) = 0.$$