

# Worksheet 14 (March 5)

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## 1 Review

### METHODS AND IDEAS

**Theorem 1.** (rank-nullity)

Let  $T : V \rightarrow W$  be a linear transformation, we will always have

$$\dim \ker(T) + \dim \operatorname{Im}(T) = \dim V.$$

**Theorem 2.** (coordinates under base change)

Let  $\mathcal{B}$  and  $\mathcal{C}$  be two bases of vector space  $V$ , then the coordinates of the same vector  $\mathbf{x} \in V$  under  $\mathcal{B}$  and  $\mathcal{C}$  are related by

$$[\mathbf{x}]_{\mathcal{C}} = P_{\mathcal{C} \leftarrow \mathcal{B}} [\mathbf{x}]_{\mathcal{B}},$$

where the base change matrix is given by

$$P_{\mathcal{C} \leftarrow \mathcal{B}} = ([\mathbf{b}_1]_{\mathcal{C}} \ \cdots \ [\mathbf{b}_n]_{\mathcal{C}}).$$

**Theorem 3.** (linear transformation under base change)

Let  $\mathcal{A}$  and  $\mathcal{B}$  be two bases of vector space  $V$ ,  $\mathcal{C}$  and  $\mathcal{D}$  be two bases of vector space  $W$ , and  $T : V \rightarrow W$  a linear transformation. Then the matrices of the same linear transformation  $T$  under different bases are related by

$${}_{\mathcal{D}}[T]_{\mathcal{B}} = P_{\mathcal{D} \leftarrow \mathcal{C}} {}_{\mathcal{C}}[T]_{\mathcal{A}} \cdot P_{\mathcal{A} \leftarrow \mathcal{B}}.$$

In particular, if  $V = W$  and  $\mathcal{A}$  and  $\mathcal{B}$  are two bases of  $V$ ,

$${}_{\mathcal{B}}[T]_{\mathcal{B}} = P_{\mathcal{B} \leftarrow \mathcal{A}} {}_{\mathcal{A}}[T]_{\mathcal{A}} \cdot P_{\mathcal{A} \leftarrow \mathcal{B}}.$$

## 2 Problems

**Example 1.** True or false.

- ( ) Base change matrices  $P_{\mathcal{C} \leftarrow \mathcal{B}}$  are always invertible.
- ( ) If  $\mathcal{A}$ ,  $\mathcal{B}$  and  $\mathcal{C}$  be three bases of the vector space  $V$ , then

$$P_{\mathcal{C} \leftarrow \mathcal{A}} = P_{\mathcal{C} \leftarrow \mathcal{B}} \cdot P_{\mathcal{B} \leftarrow \mathcal{A}}.$$

- ( ) If  $M$  and  $N$  are two matrices of a linear transformation  $T : V \rightarrow W$  (relative to different bases), then  $\text{rank } M = \text{rank } N$ .

**Example 2.** *Example 3 from the previous worksheet.* Let  $\mathcal{A} = \{\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3\}$  and  $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3\}$  be two different bases of  $\mathbb{R}^3$ , where

$$\mathbf{a}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \mathbf{a}_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \mathbf{a}_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \mathbf{b}_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \mathbf{b}_2 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \mathbf{b}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}.$$

- (a) Find  $[\mathbf{a}_i]_{\mathcal{B}}$  for  $i = 1, 2, 3$ .  
 (b) If  $[\mathbf{x}]_{\mathcal{A}} = (1, 1, 1)^T$ , find  $[\mathbf{x}]_{\mathcal{B}}$ .  
 (c) If  $[\mathbf{y}]_{\mathcal{A}} = [\mathbf{y}]_{\mathcal{B}}$ , find  $\mathbf{y}$ .

**Example 3.** *Example 4 from the previous worksheet.* Consider the linear transformation  $T : \mathbb{P}_2 \rightarrow M_{2 \times 2}(\mathbb{R})$  defined as

$$T(a + bx + cx^2) = \begin{pmatrix} 3a + b & b + c \\ -2b & a + b + c \end{pmatrix}.$$

- (a) Consider the basis  $\mathcal{B} = \{1+x, x, x^2-x\}$  of  $\mathbb{P}_2$  and the basis  $\mathcal{E} = \{E_{11}, E_{12}, E_{21}, E_{22}\}$  of  $M_{2 \times 2}(\mathbb{R})$ . Compute  $_{\mathcal{B}}[T]_{\mathcal{E}}$ .  
 (b) Consider instead the basis  $\mathcal{C} = \{C_1, C_2, C_3, C_4\}$  of  $M_{2 \times 2}(\mathbb{R})$ , where

$$C_1 = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}, C_2 = \begin{pmatrix} 4 & 1 \\ -2 & 2 \end{pmatrix}, C_3 = \begin{pmatrix} 1 & 1 \\ -2 & 1 \end{pmatrix}, C_4 = \begin{pmatrix} -1 & 0 \\ 2 & 0 \end{pmatrix}.$$

Compute  $_{\mathcal{B}}[T]_{\mathcal{C}}$ .

- (c) Is  $T$  one-to-one? Onto?