

Worksheet 24 (April 9)

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1 Review

DEFINITIONS

- symmetric matrices, orthogonally diagonalizable;
 - singular value (of non-square matrices).
- $A = A^T$ \exists orthogonal P and diagonal D s.t. $A = PDP^T = P \cdot D \cdot P^T$
- are square roots of the nonzero eigenvalues of $A^T A$.*
non symmetric
all e-values are non-negative.

Symmetric matrix
 ↓ generalization
 any matrix $A = P \cdot D \cdot Q^T$
 diagonal matrix of singular values

METHODS AND IDEAS

Theorem 1. (Properties of Symmetric Matrices)

Let A be a symmetric $n \times n$ matrix, then:

- all eigenvalues of A are real;
- eigenspaces of different eigenvalues of A are orthogonal;
- there is a basis of \mathbb{R}^n consisting of orthonormal eigenvectors of A (which means A is orthogonally diagonalizable).

In fact the converse of (c) is also true: if a square matrix is orthogonally diagonalizable, it must be symmetric, too.

Method 1. (Algorithm of Singular Value Decomposition)

Assume that we are given an $m \times n$ matrix A with $m > n$.

- Find eigenvalues of the symmetric matrix $A^T A$, which are all real and non-negative. Denote them by $\lambda_1, \dots, \lambda_n$. Assume that the first r of them are strictly positive and the rest are zero.
- Find orthonormal eigenvectors of $A^T A$ corresponding to the strictly positive eigenvalues $\lambda_1, \dots, \lambda_r$. Denote them by $\mathbf{v}_1, \dots, \mathbf{v}_r$.
- Let $\sigma_i = \sqrt{\lambda_i}$ for $i = 1, \dots, r$. These are the **singular values** of A .
- Let $\mathbf{u}_i = \frac{1}{\sigma_i} A \mathbf{v}_i$ for $i = 1, \dots, r$. Then,

$$A = \sigma_1 \mathbf{u}_1 \mathbf{v}_1^T + \dots + \sigma_r \mathbf{u}_r \mathbf{v}_r^T.$$

This is the **singular value decomposition (SVD)** of A .

Note that in this case $\text{rank } A = r$. Moreover, $\{\mathbf{v}_1, \dots, \mathbf{v}_r\}$ is an orthonormal basis of $\text{Row}(A)$, while $\{\mathbf{u}_1, \dots, \mathbf{u}_r\}$ is an orthonormal basis of $\text{Col}(A)$.

A $m \times n$ $A^T A$ $n \times n$
 $D = \begin{pmatrix} \sigma_1 & & & \\ & \sigma_2 & & \\ & & \dots & \\ & & & \sigma_r \end{pmatrix}$
 $Q = \begin{pmatrix} \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_n \end{pmatrix}$
 $P = \begin{pmatrix} \vec{u}_1 & \dots & \vec{u}_n \end{pmatrix}$
 $A = P_{m \times n} \cdot D_{r \times r} \cdot Q_{n \times n}^T$

2 Problems

Example 1. Diagonalize the matrix below with orthogonal matrices.

$$S = \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix}$$

e-value λ . $\det(S-\lambda I)=0$.
Want λ s.t. $S-\lambda I$ is not invertible.

$\lambda=1$ $S-I = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$

$\dim E_1 = 2$
 $\lambda=4$ $S-4I = \begin{pmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix}$

Step 1 Find eigenvalues.

$$\chi_S(\lambda) = \dots$$

$$\lambda_1=1 \quad \lambda_2=4$$

Step 2. Find basis for each eigenspace

For $\lambda_1=1$, basis of $E_1 = \text{Mul}(S-I)$

$$\left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \right\}$$

For $\lambda_2=4$, basis of $E_2 = \text{Mul}(S-4I)$

$$\left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\}$$

Step 3 Apply G-S to make the eigenvectors orthonormal.

Note It is sufficient to do G-S within each eigenspace.

$$\vec{w}_1 = \vec{u}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \xrightarrow{\text{unit}} \begin{pmatrix} \frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} \\ 0 \end{pmatrix}$$

$$\vec{w}_2 = \vec{u}_2 - \frac{\vec{u}_2 \cdot \vec{w}_1}{\|\vec{w}_1\|} \cdot \vec{w}_1 = \begin{pmatrix} -1/2 \\ -1/2 \\ 1 \end{pmatrix} \xrightarrow{\text{unit}} \begin{pmatrix} -\sqrt{2}/6 \\ -\sqrt{2}/6 \\ \sqrt{2}/3 \end{pmatrix}$$

$$\vec{w}_3 = \vec{u}_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \xrightarrow{\text{unit}} \begin{pmatrix} \sqrt{3}/3 \\ \sqrt{3}/3 \\ \sqrt{3}/3 \end{pmatrix}$$

Example 2. Let us still consider the matrix S from the previous example. Is there a vector $\vec{x} \in \mathbb{R}^3$ such that $\vec{x}^T S \vec{x} < 0$?

Idea.

$$\vec{x} = c_1 \vec{w}_1 + c_2 \vec{w}_2 + c_3 \vec{w}_3$$

$$S \vec{x} = c_1 S \vec{w}_1 + c_2 S \vec{w}_2 + c_3 S \vec{w}_3$$

$$= c_1 \vec{w}_1 + c_2 \vec{w}_2 + 4c_3 \vec{w}_3$$

$$\vec{x}^T S \vec{x} = \vec{x}^T (S \vec{x}) = (c_1 \vec{w}_1 + c_2 \vec{w}_2 + c_3 \vec{w}_3)^T (c_1 \vec{w}_1 + c_2 \vec{w}_2 + 4c_3 \vec{w}_3)$$

Example 3. Find SVD of the matrix

$$A = \begin{pmatrix} 1 & 3 \\ 2 & 2 \\ 3 & 1 \end{pmatrix}$$

Conclusion. $S = P \cdot D \cdot P^{-1} = P \cdot D \cdot P^T$
where $P = \begin{pmatrix} -\sqrt{2}/2 & \sqrt{2}/6 & \sqrt{3}/3 \\ \sqrt{2}/2 & -\sqrt{2}/6 & \sqrt{3}/3 \\ 0 & \sqrt{6}/3 & \sqrt{2}/2 \end{pmatrix}$
and $D = \begin{pmatrix} 1 & & \\ & 1 & \\ & & 4 \end{pmatrix}$.

$$\geq 1 \cdot c_1^2 + 1 \cdot c_2^2 + 4 \cdot c_3^2 \geq 0$$

Reason All e-values of S are positive.