

Worksheet 23 (April 2)

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1 Review

METHODS AND IDEAS

Theorem 1. The $\overset{\text{dim Row}(A)}{\text{row rank}}$ is equal to the $\overset{\text{dim Col}(A)}{\text{column rank}}$ for any matrix. In fact we have

$$\dim \text{Row}(A) + \dim \text{Nul}(A) = n \text{ and } \overset{\text{pivot}}{\dim \text{Col}(A)} + \overset{\text{free var.}}{\dim \text{Nul}(A)} = n,$$

where the former comes from the orthogonality, and the latter comes from the Rank-Nullity theorem.

Remark 1.

$$\text{Row}(A) = \text{Nul}(A)^\perp, \text{Col}(A) = \text{Nul}(A^T)^\perp. \quad \begin{array}{l} \text{Consider } A^T. \\ \text{Row}(A^T) = \text{Nul}(A)^\perp \\ \text{Col}(A) \end{array} \text{ for } A \text{ m} \times \text{n}.$$

Another idea of proof

Remark 2. Another way to see the theorem is by row reduction. In fact, both the row rank and the column rank are preserved by row reductions. (Why?) So we may reduce the theorem to the case of RREF. But in RREF both ranks are equal to the number of pivots.

Theorem 2. Orthogonal matrices preserve the inner product. \rightarrow norms, angles. In other words, given an orthogonal matrix U , we have

$$Ux \cdot Uy = x \cdot y, \forall x, y \in \mathbb{R}^n. \quad \begin{array}{l} \text{im} \quad \text{n} \times 1 \\ Ux \cdot Uy = (Ux)^T Uy \\ = x^T U^T Uy \\ = x^T y = x \cdot y \end{array}$$

Remark 3. In particular, this gives $\|Ux\| = \|x\|$ if we take $x = y$.

2 Problems

Example 1. True or false.

$$\det(U)^2 = \det(U^T U) = \det(I_n) = 1 \quad \rightsquigarrow \det(U) = \pm 1.$$

Example $U = \begin{pmatrix} 1 & \\ & 1 \end{pmatrix}, \det(U) = 1$
 $U = \begin{pmatrix} 1 & \\ & -1 \end{pmatrix}, \det(U) = -1$

(F) Let U be an orthogonal matrix, then $\det(U) = 1$.

Eigenvalues of orthogonal matrix can only be 1 or -1.

(T) Let U be an orthogonal matrix and x a vector such that Ux and x are linearly dependent, then $Ux = \pm x$.

(F) If U is diagonal and orthogonal, then U must be an identity matrix.

Counterexample $U = \begin{pmatrix} 1 & \\ & -1 \end{pmatrix}$

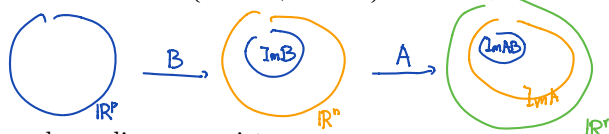
① $x = \vec{0}$ then $Ux = \vec{0}$, so $Ux = x$
 ② $x \neq \vec{0}$ Ux is a multiple of x
 (x is an e-vector of U)
 $\|Ux\| = \|x\| \quad Ux = \pm x$

(T) The Gram-Schmidt process produces from a linearly independent set $\{\mathbf{u}_1, \dots, \mathbf{u}_k\}$ an orthogonal set $\{\mathbf{w}_1, \dots, \mathbf{w}_k\}$ with the property that for each k ,

$$\text{span}\{\mathbf{w}_1, \dots, \mathbf{w}_i\} = \text{span}\{\mathbf{u}_1, \dots, \mathbf{u}_i\}, \forall i = 1, 2, \dots, k.$$

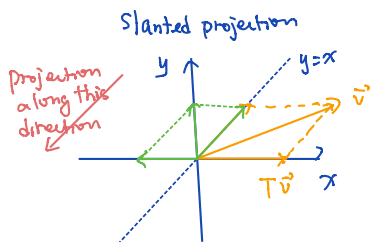
(T) For any two matrices A and B such that AB is well-defined,

$$\text{rank } AB \leq \max\{\text{rank } A, \text{rank } B\}.$$



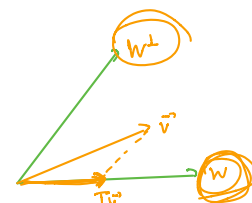
$$\begin{aligned} \text{rank } AB &= \dim \text{Im}(AB) \\ &\leq \dim \text{Im}(B) \\ &= \text{rank } B \end{aligned}$$

Example 2. Find an example or disprove existence: a linear transformation $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ that satisfies $T^2 = T$ but is not an orthogonal projection.



Take basis $B = \{ \vec{b}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \vec{b}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \}$ arbitrary
 Then $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \xrightarrow{P} \mathbb{R}^2$
 $\vec{v} \mapsto [\vec{v}]_B \mapsto \text{Proj}_{x\text{-axis}} [\vec{v}]_B$
 $\begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} x \\ 0 \end{pmatrix}$

Standard matrix of T is $\begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix}$. $T^2 = T$.



$$\begin{aligned} T^2 &= T \\ \Rightarrow T^2 \vec{v} &= T \vec{v} \\ T(T \vec{v}) &= T \vec{v} \\ \Rightarrow \text{Im } T &\subseteq E \\ E_1 \oplus E_0 &= \mathbb{R}^n \end{aligned}$$

Example 3. Find the best fitting model in the form $y = ax^2 + bx + c$ of the data points

$$\begin{aligned} x &= -1, y = 1 \\ (-1, 1), (0, 0), (1, 1), (2, 1). \end{aligned}$$

Find the least square solution of

$$\begin{cases} 1 = a - b + c \\ 0 = + c \\ 1 = a + b + c \\ 1 = 4a + 2b + c \end{cases}$$

$$A^T A \vec{x} = A^T \vec{b}$$

Rmk This method works even though the model is not "a linear model". It works as long as the model depends linearly on the coefficients.

Example 4. Find the values of a, b, c, d, e, f, g such that U is an orthogonal matrix:

$$\begin{pmatrix} 1 & c & e \\ a & \frac{\sqrt{2}}{2} & f \\ b & d & g \end{pmatrix}.$$