# Math 185 Final Topics 

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## 1 New material

### 1.1 Conformal functions and mappings: complex analysis in a more general geometric context

Useful source: https://math.mit.edu/~jorloff/18.04/notes/topic10.pdf

- A conformal function is a function which preserves angles. A conformal mapping is a bijective conformal function.
- Two surfaces $X, Y$ are said to be conformally equivalent if a conformal mapping $f: X \rightarrow Y$ exists.
- A conformal mapping $f: \Omega \rightarrow \Omega^{\prime}$ has an inverse, which is also conformal.
- Statements: For two complex domains $\Omega$ and $\Omega^{\prime}$, a function $f: \Omega \rightarrow \Omega^{\prime}$ is conformal if and only if $f$ is holomorphic and for all $z \in \Omega$, we have $f^{\prime}(z) \neq 0$.
- A conformal mapping $f: \Omega \rightarrow S^{2}$ (for $S^{2}$ the Riemann sphere) is equivalent to the data of a meromorphic function (function with isolated singularities which are poles) $F: \Omega-\rightarrow \mathbb{C}$ such that $F$ has at worst simple poles and $F^{\prime}(z) \neq 0$ when $z \in \Omega$ is not a pole. The correspondence is via $f(z):=P_{N}^{-1}(F(z))$, with $f(z):=N$ (the north pole, corresponding to the point at "infinity") for $z$ a pole.
- A conformal function $f: S^{2} \rightarrow X$ (for $X$ any domain in the plane, the sphere, or any other surface) is a continuous function $f: S^{2} \rightarrow X$ for which both $f \circ P_{N}$ and $f \circ \bar{P}_{S}$ are conformal functions from $\mathbb{C}$ to $X$.
- Any conformal function $f: S^{2} \rightarrow S^{2}$ is the extension of a fractional linear transformation.
- For $\mathbb{D} \subset \mathbb{C}$ the unit disk Any conformal function $f: \mathbb{D} \rightarrow \mathbb{D}$ is also a fractional linear transformation, of a particular kind (specifically: $z \mapsto$ $\frac{z-\alpha}{1-\bar{\alpha} \cdot z}$ for some complex number $\alpha$ ). There exists a conformal function (indeed, many) that take any point of the disk to any other point.
- Riemann mapping theorem. The interior of any simple closed curve in $\mathbb{C}$ (and more generally, any proper simply-connected open domain in $\mathbb{C}$ ) is conformally equivalent to the disk.
- Uniformization theorem (for the disk): any surface $X \subset \mathbb{R}^{3}$ (or more generally in $\mathbb{R}^{n}$ ) which is smoothly topologically equivalent to the open disk (i.e., parametrized by a disk with injective Jacobian at every point) is conformally equivalent either to the disk $\mathbb{D}$ or the plane $\mathbb{C}$.


### 1.2 The argument principle

- A good source with more details: https://math.mit.edu/~jorloff/18. 04/notes/topic11.pdf.
- For a function $f: \Omega \rightarrow \mathbb{C}$, its logarithmic derivative is defined as $\frac{\operatorname{dlog} f}{d z}:=$ $\frac{f^{\prime}}{f}$. It satisfies $\operatorname{dlog}(f g) d z=\frac{\mathrm{d} \log f}{d z}+\frac{\mathrm{d} \log g}{d z}$.
- Main result: if $f: \Omega-\rightarrow \mathbb{C}$ is a meromorphic function (function with isolated singularities which are poles) and $\gamma$ is a simple closed curve in $\Omega$, then $\oint_{\gamma} \frac{\operatorname{dlog} f}{d z}=2 \pi i(Z-P)$, where $Z$ is the number of zeroes and $P$ the number of poles in the interior of $\gamma$, counted with multiplicity.


## 2 Old material

### 2.1 Complex numbers and functions (I.1, Chap. 1 of Gamelin)

Basic question: how to do algebra and calculus with complex numbers?

- Question: How to multiply two complex numbers in polar form,

$$
r_{1} \exp \left(i \theta_{1}\right) \cdot r_{2} \exp \left(i \theta_{2}\right)=r_{1} r_{2} \exp \left(i\left(\theta_{1}+\theta_{2} \bmod 2 \pi\right)\right)
$$

- Question: How to define exp, $\sin$, cos for complex numbers. Properties of exp.
- Question: How to take the $\operatorname{limit} \lim _{z \rightarrow z_{0}} f(z)$ of a complex function.
- What is the complex logarithm $\ln (z)$ ? Where is it defined? Why is it not the only solution to the equation $\exp (a+b i)=z$ and what are all the solutions in terms of polar coordinates $(r, \theta)$ for $z$ ?


### 2.2 Complex derivatives and holomorphicity basics (I.2)

Basic question: what are holomorphic functions? What are some examples?

- Question: What is a complex derivative? When does it exist?
- Cauchy-Riemann Theorem: holomorphicity implies existence of (continuous) partial derivatives. Conversely, existence of (continuous) partial derivatives does not imply holomorphicity. We need to impose the CauchyRiemann relation, $\partial_{y} f=i \partial_{x} f$. Think: "rate of change in the $i$ direction is $i$ times the rate of change in the 1 direction".
- Analytic functions are holomorphic. Intuition of proof: the complex derivative of any partial sum $\sum_{k=0}^{N} a_{k}\left(z-z_{0}\right)^{k}$ is equal to $\sum_{k=1}^{N} k a_{k} z^{k-1}$. In particular, $\sum_{k=0}^{N} a_{k}\left(z-z_{0}\right)^{k}$ are holomorphic functions and their derivatives converge to $\sum_{k=1}^{\infty} j a_{k} z^{k-1}$ within the radius of convergence. To prove the the theorem, we need to be a little more careful with convergence (specifically: control the error terms that show up in the computation of the derivative), but you don't need to remember how to do this.


### 2.3 Path integrals and antiderivatives (I.3, II.1, II.2)

## Questions.

- What is the definition of $\int_{\gamma} f(z) d z$ for $\gamma$ a path from $a \in \mathbb{C}$ to $b \in \mathbb{C}$ ?
- What is $\int_{\gamma} f(z) d z$ when $f$ has a holomorphic antiderivative $F$ ? (Answer: it is $F(b)-F(a)$, this is the complex chain rule applied to the composition $F \circ \gamma$.)
- Does this hold if we don't assume $f$ has an antiderivative in $\Omega$ ? (Answer: not necessarily.)


## Statements.

- The functions $z^{n}$ for any integer $n \neq-1$ have antiderivatives, so they are easy to integrate along a path. In particular, their integral along a loop equal to zero. (Why?)
- The fact $\oint_{C_{1}} \frac{1}{z}=2 \pi i$ implies that $\frac{1}{z}$ cannot have an antiderivative on any domain that contains the circle $C_{1}$. (Why?)
- Key theorem: Cauchy's Theorem: if $\gamma$ is a simple closed loop and $f$ is holomorphic on (a domain containing) $\gamma$ and its interior, then $\oint_{\gamma} f(z) d z=$ 0 . Derived from the (extremely similar) Goursat's Theorem, which is Cauchy's theorem for a simple polygon (rectangle in class; triangle in book. You can use any version.)
- Corollaries of Cauchy:

1. Antiderivative theorem: a function which is holomorphic on the interior of a simple closed loop has a holomorphic antiderivative in the interior of this loop.
2. If $f$ is holomorphic on a simple closed loop $\gamma$ but $\oint_{\gamma} f(z) d z \neq 0$ then $f$ must not be holomorphic (e.g. have a pole) somewhere in the interior of $\gamma$.

### 2.4 Cauchy integral formula and Analyticity (II.4, Morera from II.5)

## Questions.

- How can we turn the seeming bug in complex analysis, that the change of variables formula fails for loops, into a feature?
- How can we express a value or a derivative of $f\left(z_{0}\right)$ in terms of values of $f$ "far away" from $z_{0}$ ?
- When does the converse of "holomorphic $\Longrightarrow$ analytic" hold? (Answer: always, because of Cauchy integral magic.)


## Statements.

- Cauchy Integral formula If $f$ is holomorphic on (a domain containing) $\gamma$ and the interior of $\gamma$ then

$$
f\left(z_{0}\right)=\frac{1}{2 \pi i} \oint_{\gamma} \frac{f(z)}{z-z_{0}} d z
$$

for $z_{0}$ is in the interior of $\gamma$ (but not on $\gamma$ itself or else the path integral is undefined!).

- Generalization More generally, we can compute any derivative $f^{(n)}\left(z_{0}\right)$ in terms of a path integral using the following formula:

$$
\frac{f^{(n)}\left(z_{0}\right)}{n!}=\frac{1}{2 \pi i} \oint_{\gamma} \frac{f(z)}{\left(z-z_{0}\right)^{n+1}} d z .
$$

- Liouville: A consequence of Cauchy for first derivatives: a function which is bounded and entire (everywhere holomorphic) must be constant. Corollary: fundamental theorem of arithmetic (every polynomial with coefficients in $\mathbb{C}$ has a root in $\mathbb{C}$ ).
- Holomorphic functions are analytic. Notice that $\frac{f^{(n)}\left(z_{0}\right)}{n!}$ is the $n$th Taylor coefficient of $f$ around $z_{0}$. A real infinitely differentiable function has a Taylor series, but might not be equal to the analytic function defined by this series. A holomorphic function, however, satisfies $f(z)=\sum a_{n}(z-$ $\left.z_{0}\right)^{n}$ for $a_{n}=\frac{f^{(n)}\left(z_{0}\right)}{n!}$ within a nonzero radius of convergence. We show this by expanding the term $\frac{1}{\left(z-z_{0}\right)^{n+1}}$ in the Cauchy theorem as a geometric series. This is one of the important ways in which complex analysis is "magic".
- Morera A consequence of analyticity is Morera's theorem: a continuous function (on a domain $\Omega$ ) whose integral over any simple closed loop is 0 must be holomorphic. Note that the converse is not necessarily true, since $\Omega$ might not be simply connected (it might have a "hole"). But if $\Omega$ is, for example, the interior of a simple closed curve, then the converse is true by Cauchy's theorem.


### 2.5 Poles and residues (III.1, III.2)

If $f$ is defined on a domain $\Omega$ that contains all the points in some disk around $z_{0}$ except for $z_{0}$ itself (sometimes called a punctured neighborhood of $z_{0}$ ), then we say $f$ has an (at worst) isolated singularity at $z_{0}$. The singularity removable if $f$ can be extended to $z_{0}$ holomorphically (in which case we say $f$ is not singular at $z_{0}$ ). It is a pole if $f$ is singular at $z_{0}$ but $f^{-1}$ (here understood as $\frac{1}{f(z)}$ ) is not (in which case $f^{-1}$ must have a zero at $z_{0}$ ). An isolated singularity which is neither removable nor a pole is called an essential singularity.

## Statements.

- A function $f$ which is holomorphic at $z_{0}$ has a zero of order $n$ if $f(z)=$ $\left(z-z_{0}\right)^{n} \tilde{f}(z)$ for $\tilde{f}$ a function which is holomorphic and nonzero (a.k.a. invertible) at $z_{0}$. (If $f\left(z_{0}\right) \neq 0$ we say $f$ has a "zero of order zero" at $z_{0}$.)
- A function $f$ with a singularity at $z_{0}$ has a pole of order $n$ if $f^{-1}$ has a zero of order $n$.
- If $f$ has a zero of order $n$ it has a Taylor series $f(z)=a_{n}\left(z-z_{0}\right)^{n}+$ $O\left(z-z_{0}\right)^{n+1}$. If $f$ has a pole of order $n$ then $f(z)$ has a Laurent series, $f(z)=a_{-n}\left(z-z_{0}\right)^{-n}+O\left(z-z_{0}\right)^{-(n-1)}$. The finite sum $\sum_{k=-n}^{-1} a_{k} z^{k}$ is called the singular part, also known as the principal part. And the (holomorphic at $z_{0}$ ) infinite sum $\sum_{k=0}^{\infty} a_{k} z^{k}$ is called the holomorphic part.
- The most important term in the principal part is the residue, $\operatorname{Res}_{z_{0}}(f)=$ $a_{-1}\left(\right.$ for $f=\sum a_{k}\left(z-z_{0}\right)^{k}$ the Laurent expansion).
- A key formula: if $f$ has a simple pole, i.e. a pole of order 1 , at $z_{0}$ then $f(z)=a_{-1}\left(z-z_{0}\right)^{-1}+O(1)$ and $f^{-1}=a_{1}^{-1}\left(z-z_{0}\right)^{1}+O\left(z-z_{0}\right)^{2}$. Therefore if we write $g(z)=f^{-1}(z)$ and it has a power series expansion $g(z)=$ $\sum b_{k}\left(z-z_{0}\right)^{k}$, then $a_{-1}=b_{1}^{-1}$ (in particular, it is never 0 ). Alternatively: If $f$ has a simple pole at $z_{0}$, then

$$
\operatorname{Res}_{z_{0}} f=\left(\frac{1}{f}\right)^{\prime}\left(z_{0}\right)
$$

- The residue formula Assume $f$ is defined on (a domain $\Omega$ that contains) $\gamma$ and also on the interior of $\gamma$ except for at finitely many points $z_{1}, \ldots, z_{n}$, all of which are poles of $f$. Then $\oint_{\gamma} f(z) d z=2 \pi i \cdot\left(\sum_{k=1}^{n} \operatorname{Res}_{z_{k}} f(z)\right)$. This formula is obvious from the Laurent series expression if there is one pole $z_{1}$, and if there are multiple poles can be obtained either as a keyhole contour argument or by observing that the sum of the singular parts of $f$ at the $z_{k}$ exactly cancels the singularities of $f$.


### 2.6 Toy contours, keyholes and proving an $R \rightarrow \infty$ integral goes to 0 (II. 3 and other places).

- It is sometimes useful to "split" a contour into smaller contours, using cancellation of the path integral over a segment and the same segment going in the opposite direction. We used this, for example, in our proof of Goursat's theorem. Sometimes it is useful instead to take a pair of segments $\epsilon$ apart which almost cancel, and to observe that they cancel in the limit (this is the keyhole argument).
- More generally, many integrals can be reduced to a path integral by taking a limit of contours depending on a parameter $R$, taking this parameter to $\infty$, and noticing that certain contour integrals go to zero. Useful facts:

1. For $n \geq 2$, the contour integral of a function of the form $\frac{1}{z^{n}}$ (and more generally, the inverse to a polynomial of degree $n$ ) will go to 0 over any arc of a circle of radius $R \rightarrow \infty$.
2. As $y \rightarrow \infty$, the function $e^{-x+i y_{0}}$ goes to 0 exponentially while $\left|e^{x+i y_{0}}\right|$ goes to $\infty$ exponentially in the $x \rightarrow \infty$ limit.
3. Both $\left|\sin \left(e^{x_{0}+i y}\right)\right|$ and $\left|\cos \left(e^{x_{0}+i y}\right)\right|$ go to $\infty$ exponentially in the $y \rightarrow \pm \infty$ limit (since they have both a $e^{-y+i x_{0}}$ and an $e^{y-i x_{0}}$ term).
