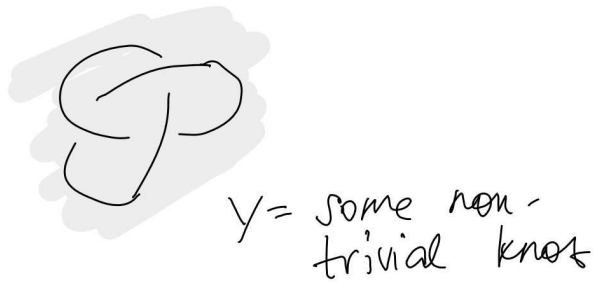


Lec 09 Another example to diffeomorphisms.  
 This is an example when  $X \subset \mathbb{R}^3$ ,  $Y \subset \mathbb{R}^3$   
 are diffeomorphic, but there exists no  
 global diffeomorphism  $F: \mathbb{R}^3 \rightarrow \mathbb{R}^3$   
 such that  $F(X) = Y$ .



### Definition of a manifold

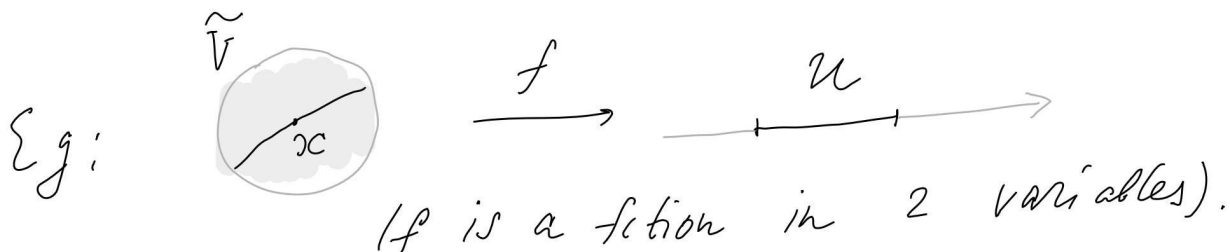
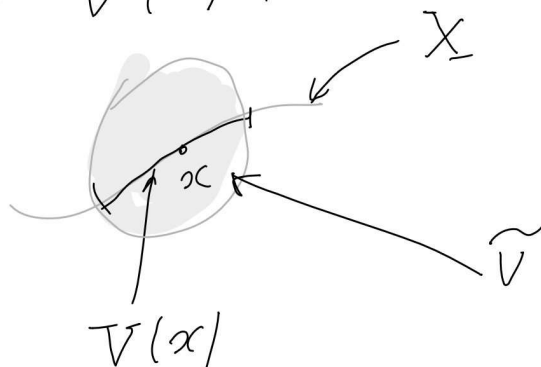
Def A subset  $X \subset \mathbb{R}^k$  is an  
 $n$ -dimensional mfd if

$\forall x \in X$ ,  $\exists$  nbhd  $V(x) \subset X$

such that there is a diffeomorphism

$f: V(x) \rightarrow$  an open subset  $U \subset \mathbb{R}^n$ .

- Recall that this means in particular  
 that  $f$  is defined on an open set  $\tilde{V} \subset \mathbb{R}^k$   
 containing  $V(x)$ :



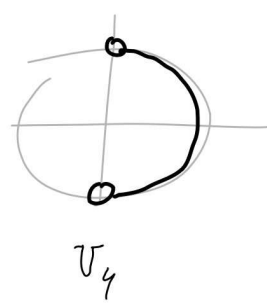
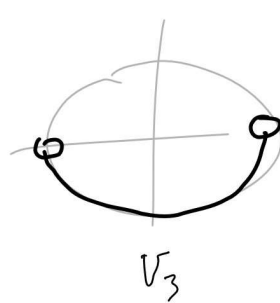
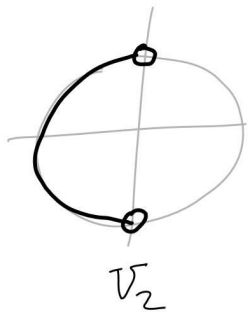
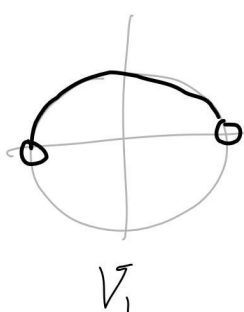
- Observe that  $f$  has to be bijective only when restricted to  $V(x) \subset X$ .
- Remember that  $f^{-1} : U \rightarrow V(x)$  must also be a smooth map, which by definition means that  $f^{-1}$  is a smooth map  $U \rightarrow \mathbb{R}^k$  whose image lands in  $V(x)$ .

### Some terminology

- A set  $V(x)$  from above is called a chart.
- The map  $\varphi = f^{-1} : U \rightarrow V(x)$  is called a parametrisation of the chart  $V(x)$ , or local coordinates on  $V(x)$ . We usually assume  $\varphi(0) = x$ .

Example  $X = \{x^2 + y^2 = 1\} \subset \mathbb{R}^2$  (circle)  
is a 1-dim'l mfd.

Proof We cover  $X$  by 4 charts:  
 $X = \bigcup_{i=1}^4 V_i$  where  $V_i$  are as shown:



For each  $V_i$ ,  $\exists$  diffeomorphism

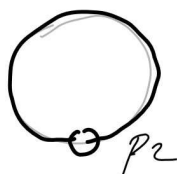
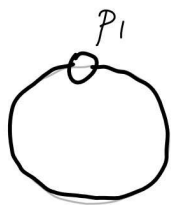
$$V_i \rightarrow U = (-1, 1) \subset \mathbb{R}$$

as we have previously seen.

This proves  $X$  is a manifold: indeed,  $\forall$  point  $x \in X$ , take a  $V_i \ni x$  and use it as a chart  $\mathcal{V}(x)$ .  $\square$

Note One can cover  $X$  by two charts, but never by one chart (as proved in the earlier examples).

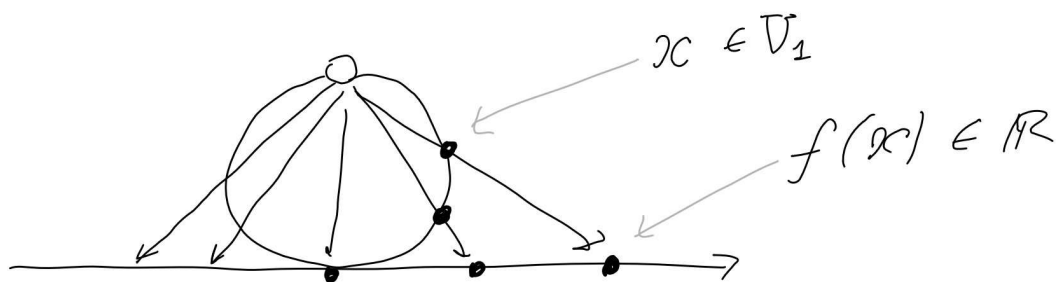
To cover  $X$  by two charts, consider



$$V_1 = X \setminus \{p_1\}$$

$$V_2 = X \setminus \{p_2\}$$

& take diffeomorphism  $f: V_1 \rightarrow \mathbb{R}$  which is the stereographic projection:



One must write  $f$  by a formula to verify it's a diffeomorphism.

Example Similarly,

$$S^n = \left\{ \sum_{i=1}^{n+1} x_i^2 = 1 \right\} \subset \mathbb{R}^{n+1} (x_1, \dots, x_{n+1})$$

is an  $n$ -dim'l mfd, and can be covered by 2 charts

Example (Product)

$$\begin{array}{l} X \subset \mathbb{R}^{k_1} \\ Y \subset \mathbb{R}^{k_2} \end{array} \supset \text{mfd's}$$

then  $X \times Y \subset \mathbb{R}^{k_1} \times \mathbb{R}^{k_2}$  is also a mfd,  
and  $\dim(X \times Y) = \dim X + \dim Y$ .

Proof let  $x \in X$ ,  $y \in Y$ , and find

charts  $V(x) \subset X$ ,  $W(y) \subset Y$

& diffeomorphisms

$$f_1 : V(x) \rightarrow U_1 \subset \mathbb{R}^{\dim X}$$

$$f_2 : W(y) \rightarrow U_2 \subset \mathbb{R}^{\dim Y}$$

then  $V(x) \times W(y) \subset X \times Y$  is a  
chart for  $X \times Y$ , with a diffeo.

$$f_1 \times f_2 : V(x) \times W(y) \rightarrow U_1 \times U_2$$

defined by  $(f_1 \times f_2)(v, w) = (f_1(v), f_2(w))$

$$\begin{array}{l} v \in V(x) \\ w \in W(y). \end{array}$$

- $U_1 \times U_2$  is open in  $\mathbb{R}^{\dim X + \dim Y}$
- $f_1 \times f_2$  extends smoothly on a product open neighborhood of  $V(x) \times W(y)$ , is bijective, and has smooth inverse  $\square$

## Derivatives & tangents

Let  $U \subset \mathbb{R}^n$  be open,  
and  $f: U \rightarrow \mathbb{R}^k$  be a smooth map.  
One can write it in coordinates:

$$f = \begin{pmatrix} f_1(x_1, \dots, x_n) \\ \vdots \\ f_k(x_1, \dots, x_n) \end{pmatrix}$$

where  $f_i: U \rightarrow \mathbb{R}$  and  $x_1, \dots, x_n$  are the coords. on  $\mathbb{R}^n$  (and on  $U$ ).

Recall: for  $h \in \mathbb{R}^n$  and  $x \in U$ ,

$$df_x^0(h) = \lim_{t \rightarrow 0} \frac{f(x+th) - f(x)}{t} \in \mathbb{R}^k.$$

Fix  $x$  & let  $h$  vary, then we get

$$dP_x : \mathbb{R}^n \longrightarrow \mathbb{R}^k.$$

a linear map.

Note this linear map is given by the

matrix 
$$\begin{pmatrix} \frac{\partial f_1}{\partial x_1}(x) & \dots & \frac{\partial f_1}{\partial x_n}(x) \\ \vdots & & \vdots \\ \frac{\partial f_k}{\partial x_1}(x) & \dots & \frac{\partial f_k}{\partial x_n}(x) \end{pmatrix}$$

$n \times k$  matrix.

Recall Let  $U \subset \mathbb{R}^n$ ,  $V \subset \mathbb{R}^m$  open,  
and let  $f, g$  be smooth maps between

$$x \in U \xrightarrow{f} V \xrightarrow{g} \mathbb{R}^k$$

-----  
 $g \circ f$

then the chain rule says:

$$d(g \circ f)_x = (dg)_{f(x)} \circ df(x)$$

$\forall x \in U$

Here: 
$$\mathbb{R}^n \xrightarrow{df_x} \mathbb{R}^m \xrightarrow{(dg)_{f(x)}} \mathbb{R}^k$$

-----  
 $d(g \circ f)_x$

Recall  $df_x$  is the best linear approximation of  $f$  at  $x \in \mathbb{R}^n$ :

$$f(x+h) = f(x) + df_x(h) + o(\|h\|)$$

Def (Tangent space to a mfd)

Let  $X \subset \mathbb{R}^n$  be a  $k$ -dim'l mfd and  $x \in X$  a point.

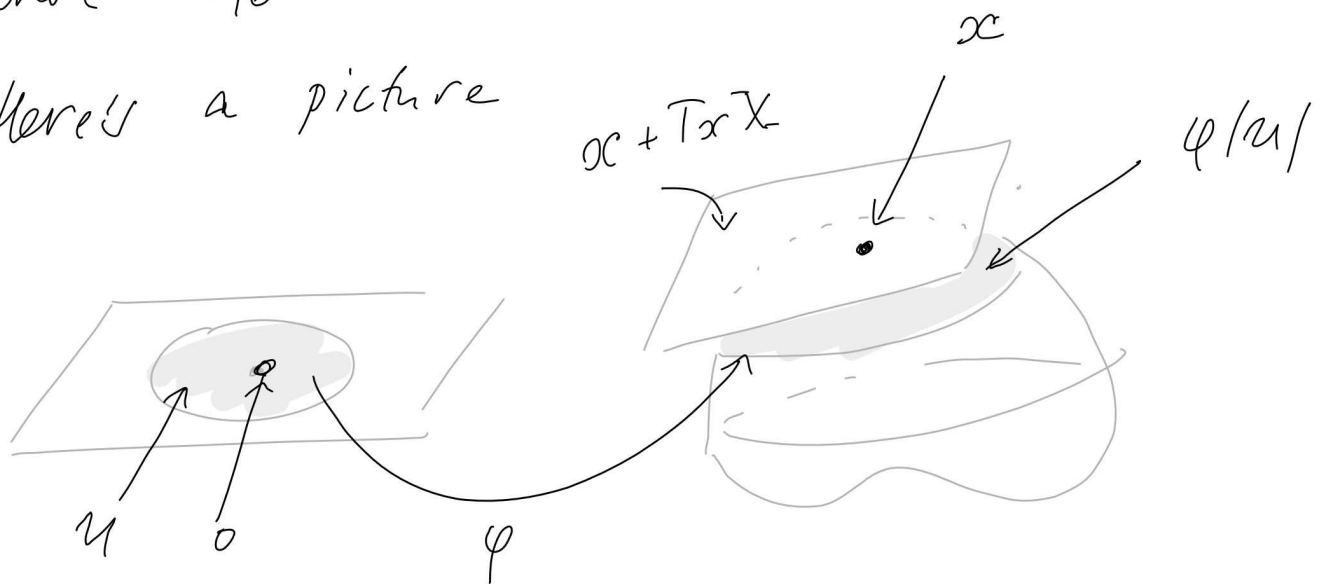
The tangent space  $T_x X \subset \mathbb{R}^n$  is a  $k$ -dim'l subspace defined as follows.

Let  $\varphi: U \rightarrow X$  be a local parametrisation near  $x$ ,  $\varphi(0) = x$ ,

$$T_x X = \text{image of } d\varphi_0$$

where  $d\varphi_0: \mathbb{R}^k \rightarrow \mathbb{R}^n$ .

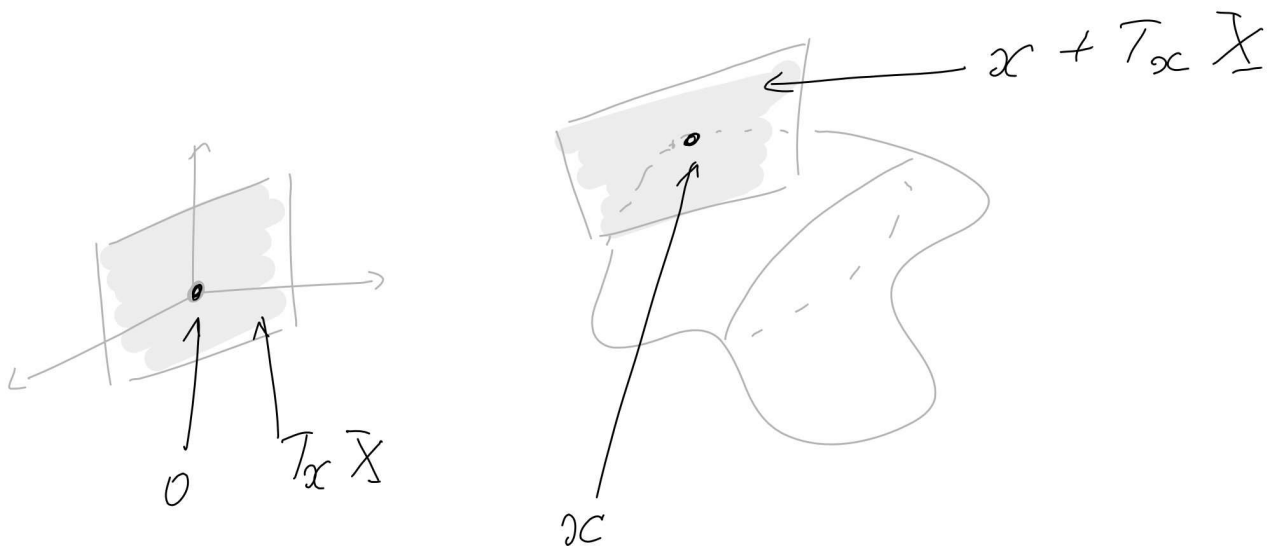
Here's a picture



A small caveat / annoying detail: according to our def'n,  $T_x X$  is always a plane passing through the origin.

The actual tangent plane we think of geometrically is the translate of  $T_x X$ :

$$x + T_x X$$



Lemma  $T_x X \subset \mathbb{R}^n$  does not depend on a choice of local parametrisation  $\varphi: U \rightarrow X$ .

Suppose  $\varphi: U \rightarrow X$  and  $\psi: V \rightarrow X$  are two pairs.

We have  $\varphi(0) = \psi(0) = x$  & can assume

$$\varphi(U) = \psi(V).$$

(otherwise redefine  $U = \varphi^{-1}(\varphi(U) \cap \psi(V))$   
 $V = \psi^{-1}(\varphi(U) \cap \psi(V))$ )

Then  $h = \psi^{-1} \circ \varphi: U \rightarrow V$  is a diffeo,

because it's a composition of diffeos

(Exercise:  $f, g$  diffeos  $\Rightarrow f \circ g$  diffeo,  $f^{-1}$  diffeo)



Write  $\varphi = \varphi \circ h$ , then:

$$d\varphi_0 = d\varphi_0 \circ dh_0$$

$$\Rightarrow \text{Image}(d\varphi_0) \subseteq \text{Image}(d\varphi_0)$$

The converse is analogous.  $\square$

Lemma  $\dim T_x X = \dim X (=k)$ ,  
and  $d\varphi_0: \mathbb{R}^k \rightarrow T_x X$  is an isomorphism,  
for any loc. param.  $\varphi$ .

Proof Let  $\varphi: U \rightarrow X$  be a param. at  $x$   
 $U$  open  
 $\mathbb{R}^k$

and  $\varphi^{-1}: X \rightarrow U$  the inverse.

$\varphi^{-1}$  is smooth meaning:

$$\exists W \subset \mathbb{R}^n, \exists F: W \rightarrow \mathbb{R}^k \text{ st}$$

$W$  open  
 $x \in W$

$$F \circ \varphi = \text{Id}$$

Derivate this:

$$\begin{array}{ccc} \mathbb{R}^k & \xrightarrow{d\varphi_0} & T_x(X) & \xrightarrow{dF_x} & \mathbb{R}^k \\ & & \text{Id} & \nearrow & \end{array}$$

The composition is Id, and  $d\varphi_0$  is  
surjective (by def. of  $T_x X$ )

$\Rightarrow$  both arrows are isomorphisms  $\square$

Def (Derivative of a smooth map)  
(sometimes called differential)

Let  $X \subset \mathbb{R}^n$ ,  $Y \subset \mathbb{R}^m$  be manifolds;

$f: X \rightarrow Y$  smooth map (not nec. diffeom)

$x \in X$ ,  $y \in Y$ ,  $f(x) = y$ .

The derivative is a linear map

$$df_x: T_x X \rightarrow T_y Y$$

defined as follows.

Take any smooth map

$$F: W \rightarrow \mathbb{R}^m,$$

$x \in W \subset \mathbb{R}^n$  open,

extending  $f$  in neighborhood  $W \cap X$  of  $x$

For  $v \in T_x X \subset \mathbb{R}^n$

$$df_x(v) \stackrel{\text{def}}{=} dF_x(v),$$

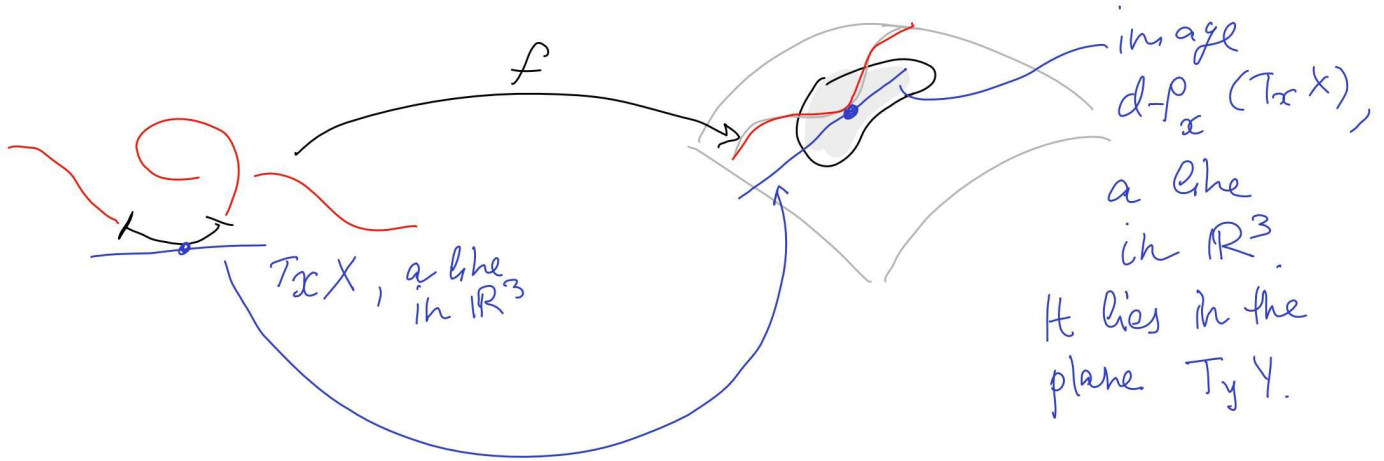
where  $dF_x: \mathbb{R}^n \rightarrow \mathbb{R}^m$  is the

derivative in the classical analysis sense:

it's given by partial derivatives

$$\left( \frac{\partial F^i(x)}{\partial x^j} \right)_{\substack{i=1 \dots m \\ j=1 \dots n}}$$

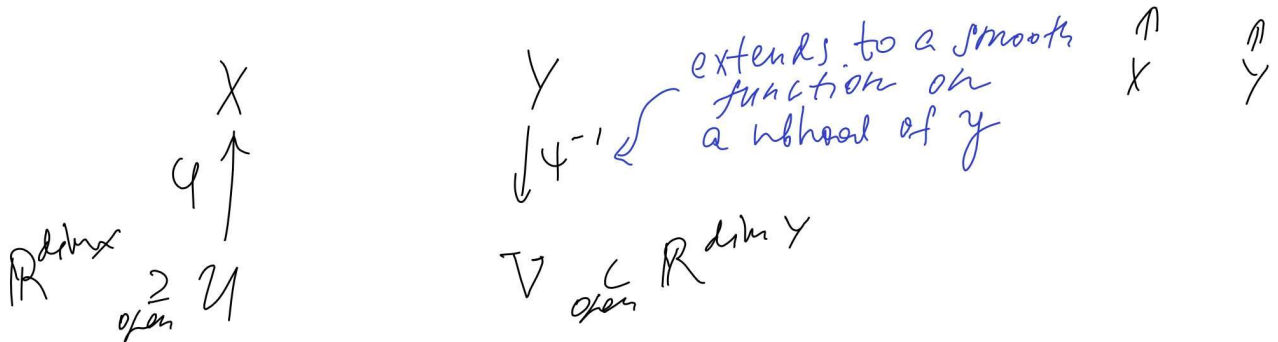
Here's a picture:



$df_x$ ,  
linear map between the lines  $\subset \mathbb{R}^3$

Lemma  $df_x$  does not depend on the choice of extension  $F$ .

Proof. Consider local parametrizations at  $x, y$



Take  $x \in W \subset \mathbb{R}^n$  open as in the above def'n; assume  $U$  is small enough so that  $\psi(U)$  lands in  $W$ , and that  $F(W)$  lands an open nbhd  $Z$  of  $y$  on which  $\psi^{-1}$  extends smoothly.

Rewrite the above maps  $\varphi, \psi$ , adding  $F$  defined on  $W$ :

$$\begin{array}{ccc}
 \mathbb{R}^k \supseteq W & \xrightarrow{F} & Z \subseteq \mathbb{R}^m \\
 \varphi \uparrow & & \downarrow \psi^{-1} \text{ smooth} \\
 U & \xrightarrow{h} & V \\
 \text{open} & & \text{open}
 \end{array}$$

Denote  $h = \psi^{-1} \circ F \circ \varphi$ , note it is smooth

Next, we actually have

$$h = \psi^{-1} \circ f \circ \varphi$$

because  $\text{Im } \varphi \subset X$  and  $F|_{W \cap X} \equiv f$ .

Consider derivatives of functions between open sets:

$$\begin{array}{ccc}
 \mathbb{R}^k & \xrightarrow{dF_x} & \mathbb{R}^m \\
 d\varphi_0 \uparrow & & \uparrow d\psi_0 \\
 \mathbb{R}^{d\dim X} & \xrightarrow{dh_0} & \mathbb{R}^{d\dim Y}
 \end{array}$$

The diagram commutes, so

$$\begin{array}{ccc}
 dF_x \text{ takes } \text{Image } (d\varphi_0) & \text{inside } & \text{Image } (d\psi_0) \\
 \parallel \text{ def } & & \parallel \\
 T_x X & & \text{def } T_y Y
 \end{array}$$

So  $dF_x|_{T_x X}$  is a map  $T_x X \rightarrow T_y Y$ .

Also, we can write  $dF_x|_{T_x X}$  as:

$$(*) \quad d\psi_0 \circ d\phi_0 \circ (d\phi_0)^{-1}$$

using that  $d\phi_0 : \mathbb{R}^{\dim X} \rightarrow \mathbb{R}^k$  is  
an isomorphism onto  $T_x X$  (see above),  
therefore has an inverse

$$(d\phi_0)^{-1} : T_x X \rightarrow \mathbb{R}^{\dim X}$$

Finally,  $(*)$  does not depend on  $F$ ,  
since  $h$  does not depend on  $F$  (only on  $f$ ). □

Note It may seem at the end of proof  
that  $dF_x$  depends on the parametrisation,  
but we know that it doesn't, by the  
original definition!

Lemma Image  $(dF_x) \subset T_y Y$

Proof Shown above □

Lemma We have chain rule. If

$$\begin{array}{ccccc} X & \xrightarrow{f} & Y & \xrightarrow{g} & Z \\ \psi & & \varphi & & \chi \\ X & \xrightarrow{\quad} & Y & \xrightarrow{\quad} & Z \end{array}$$

are smooth maps then

the diagram commutes:

$$\begin{array}{ccccc} T_x X & \xrightarrow{df_x} & T_y Y & \xrightarrow{dg_y} & T_z Z \\ & & & & \nearrow \\ & & & & d(g \circ f)_x \end{array}$$