

## Explicit formulas for some DEs

A linear ODE is of the form

$$a_n(x)f^{(n)}(x) + \dots + a_1(x)f'(x) + a_0(x)f(x) = g(x)$$

$a_i, g$  are given. We may also demand  $f$  and its derivatives satisfy initial conditions (e.g.  $f(0)=0, f'(1)=2$ ).

Named linear since

$$f \mapsto a_n(x)f^{(n)} + \dots + a_1(x)f' + a_0(x)f$$

is a linear map. If  $g=0$  the ODE is called homogeneous.

Since the kernel is a subspace, homogeneous equations have the superposition property i.e. if  $f_1$  and  $f_2$  are solutions

then so is

$$c_1 f_1 + c_2 f_2 \quad \text{for all } c_1, c_2 \in \mathbb{R}$$

A solution to an inhomogeneous equation (i.e.  $g \neq 0$ ) is called a particular solution. If  $f_1$  and  $f_2$  are particular solutions, then  $f_1 - f_2$  is a solution to the homogenous equation. Thus to solve:

i) Find all homogeneous solutions  $f_h$   
(usually a superposition of finitely many)

ii) Find one particular solution  $f_p$

iii) The general solution is then

$$f_p + f_h$$

iv) Plug in initial conditions to general soln.

Spring 2008 4A First solve the homogeneous equation

$$y'' - 2y' - y = 0$$

$r^2 - 2r - 1$  has roots  $1 \pm \sqrt{2}$ , thus

$$C_1 e^{(1+\sqrt{2})x} + C_2 e^{(1-\sqrt{2})x}$$

are homogeneous solutions. For a particular soln,

guess  $Ae^{-x}$ . Then

$$Ae^{-x} + 2Ae^{-x} - Ae^{-x} = e^{-x}$$

$\Rightarrow$  need  $A = \frac{1}{2}$ , so  $\frac{1}{2}e^{-x}$  is a particular soln,

so general soln is

$$\frac{1}{2}e^{-x} + C_1 e^{(1+\sqrt{2})x} + C_2 e^{(1-\sqrt{2})x}$$

The initial condition gives

$$\frac{1}{2} + C_1 + C_2 = 0$$

$$-\frac{1}{2} + (1+\sqrt{2})C_1 + (1-\sqrt{2})C_2 = 0$$

which has a unique solution. ✓

A linear system of m ODEs is an equation of the form

$$x'(t) = A(t)x(t) + b(t)$$

where  $A(t)$  is  $m \times n$  matrix valued,  $b$  is  $\mathbb{R}^n$ -valued, and  $x(t)$  is an unknown  $\mathbb{R}^n$ -valued function. If  $b \equiv 0$ , it is homogeneous. Steps i) - iv) for solving linear ODEs still apply. E.g. If  $A$  is a constant, diagonalizable matrix, the homogeneous solutions are

$$C_1 e^{\lambda_1 t} v_1 + \dots + C_n e^{\lambda_n t} v_n$$

where  $v_i$  is a  $\lambda_i$ -eigenvector.

Fall 2021 6A This is a symmetric matrix,  
making it easy to diagonalize, we will discuss later.

For now,

$\begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix}$  basis of the kernel

$\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$  basis of the  $\text{I}_4$  eigen space.

General soln is then

$$y(t) = C_1 \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix} + C_2 \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix} + C_3 e^{14t} \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

Initial condition gives

$$-2C_1 - 3C_2 + C_3 = 1$$

$$C_1 + 2C_3 = 0$$

$$C_2 + 3C_3 = 0$$

So  $C_1 = -2C_3$ ,  $C_2 = -3C_3$ , so first eqn becomes

$$14C_3 = 1 \Rightarrow C_3 = \frac{1}{14}$$

✓

A couple more techniques. Consider a diff eq of the form

$$f'(x) = g(x) h(f(x))$$

if we sub  $y = f(x)$ , then

$$\frac{dy}{dx} = g(x) h(y)$$

$$\Rightarrow \frac{1}{h(y)} dy = g(x) dx$$

Then integrate both sides. This is called "separation of variables".

Ex.

$$\frac{dy}{dx} = xy \Rightarrow \frac{1}{y} dy = x dx$$

$$\Rightarrow \ln|y| = \frac{x^2}{2} + C$$

$$\Rightarrow y = k e^{\frac{x^2}{2}}$$

Another technique is integrating factors. For an eqn of the form

$$f' + p(x)f = q(x)$$

Can take  $r(x) = \int p$  so then

$$\begin{aligned}(e^r f)' &= e^r (f' + pf) \\ &= e^r q\end{aligned}$$

Integrating both sides gives

$$f = C e^{-r} + e^{-r} \int e^r q$$

### Fall 2021 1A

a)  $y_1(t) = t$  works

b) If  $y(t)$  is another solution, then

$u(t) = y(t) - y_1(t)$  is s.t. :

$$\begin{aligned}u' &= y' - 1 \\ &= y^2 - t y \\ &= (y-t)^2 + t(y-t) \\ &= u^2 + t u\end{aligned}$$

So  $u$  solves  $u' = u^2 + t u \Leftrightarrow \frac{u'}{u^2} - \frac{t}{u} = 1$

Change variables to  $z = \frac{1}{u}$ , so  $z' = \frac{u'}{u^2}$  and

$$z' + t z = 1$$

Now apply the integrating factor  $e^{\delta t} = e^{t^2/2}$

$$\Rightarrow z(t) = \left( e^{-t^2/2} + e^{-t^2/2} \int e^{t^2/2} \right)$$

$$\Rightarrow u(t) = \frac{1}{\left( e^{-t^2/2} - e^{-t^2/2} \int e^{t^2/2} \right)} \quad \checkmark$$

### Establishing Existence & Uniqueness

The following guarantees local existence & uniqueness under mild assumption.

Thm (Picard-Lindelöf) Suppose  $f(t, y)$  is uniformly Lipschitz in  $y$  and continuous in  $t$ . Then for some  $\varepsilon > 0$  the initial value problem

$$\frac{dy}{dt} = f(t, y(t)), \quad y(0) = y_0$$

has a unique solution on  $(-\varepsilon, \varepsilon)$ .

3.1.3 Fall 1993 14 This is a question of existence for the IVP

$$\frac{dy}{dx} = y^n$$

First separate variables:  $\frac{1}{y^n} dy = dx$

$$\Rightarrow \frac{1}{(1-n)y^{n-1}} = x + C$$

$$\Rightarrow \frac{1}{y^{n-1}} = (1-n)x + C$$

$$C = \frac{1}{y(0)^{n-1}} > 0$$

So  $y = \frac{1}{((-(n-1)x)^{\frac{1}{n-1}})} \text{ solves the equation}$

in  $[0, \frac{C}{n-1})$ , it blows up as  $x \mapsto \frac{C}{n-1}$   
 but is unique by Picard-Lindelöf, thus none defined  
 on  $[0, \infty)$  exist. ✓

Another tool is the implicit and inverse function theorems. Note that the derivative of an inverse function is given by  $(f^{-1}(y))' = \frac{1}{f'(f^{-1}(y))}$ .

3.I.O-Fall 1982

If  $f$  is not necessarily Lipschitz so can't apply P-L.  
 Instead, since  $f$  is nonvanishing we can invert  $y$  and  $x$  so instead consider

$$\frac{dx}{dy} = \frac{1}{f(y)}, \quad x(C) = 0$$

which is continuous in  $y$ , Lipschitz in  $x$  (no  $x$  dependence).  
 Now apply P-L, then invert back to  $y$ .

2. We need the solution to

$$\frac{dx}{dy} = \frac{1}{f(y)}, \quad x(c) = 0$$

to go to  $\pm\infty$  to the right,  $\mp\infty$  to the left.

So need

$$x(\infty) = \int_c^\infty dx = \int_c^\infty \frac{1}{f(y)} dy \quad \text{diverge}$$

$$x(-\infty) = \int_{-\infty}^c dx = \int_{-\infty}^c \frac{1}{f(y)} dy$$



### Gronwall's Inequality

This about extracting information about a function from a differential inequality.

Summer 1982 6 (Also on 2021 exam)

Consider  $(e^{-x} f)' = e^{-x} f' - e^{-x} f = e^{-x} (f' - f) > 0$

$\Rightarrow e^{-x_0 f}$  strictly increasing.  $e^{-x_0 f}$  is zero at  $x_0$ ,  
 so  $e^{-x f} > 0$  for all  $x > x_0 \Rightarrow f > 0$  for all  $x > x_0$

✓

By generalizing this argument, one gets

Thm If  $\gamma: [0, T] \rightarrow \mathbb{R}$  differentiable,  $\phi$  integrable  
 s.t.

$$\gamma'(t) \leq \phi(t) \gamma(t)$$

Then

$$\gamma(t) \leq e^{\int_0^t \phi(s) ds} \gamma(0)$$

if differentiate  $(\gamma(t) e^{-\int_0^t \phi(s) ds})$  and apply

assumptions

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