

THE METAMATHEMATICS OF STABLE RAMSEY'S THEOREM FOR PAIRS

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ABSTRACT. We show that, over the base theory RCA_0 , Stable Ramsey's Theorem for Pairs implies neither Ramsey's Theorem for Pairs nor Σ_2^0 -induction.

1. INTRODUCTION

This paper resolves two questions in reverse mathematics about the strength of Stable Ramsey's Theorem for Pairs. Ramsey's Theorem for Pairs states that if f is a coloring of the set of pairs of natural numbers by two colors, then there is an infinite set H all of whose pairs of elements have the same color under f . H is said to be f -homogeneous. Closely related to Ramsey's Theorem for Pairs, and intuitively a more controlled coloring scheme, is Stable Ramsey's Theorem for Pairs, which asserts the existence of an infinite f -homogeneous set for stable colorings: i.e. those f 's such that for every x , all but finitely many y 's are assigned the same color by f . Our purpose here is to investigate the logical aspects of these two theorems, considered as principles onto themselves.

We will be working with models of second order arithmetic,

$$\mathfrak{M} = \langle M, \mathcal{S}, +, \times, 0, 1, \epsilon \rangle.$$

These structures consist of two parts: $\langle M, +, \times, 0, 1 \rangle$ is a version of the natural numbers with addition and multiplication; \mathcal{S} is a version of the power set of the natural numbers, whose elements are subsets of M . When the arithmetic structure is understood, we will abbreviate our notation to $\langle \mathfrak{M}, \mathcal{S} \rangle$. Our base theory, RCA_0 as is standard in this context, is the mathematical system that incorporates the basic rules of the arithmetical operations, closure of sets under Turing reducibility and join, and mathematical induction for existential formulas, $I\Sigma_1^0$, (see Simpson (2009)). There are two canonical ways to obtain models of RCA_0 . We can take the arithmetic part of our model to be the natural numbers \mathbb{N} with its standard structure of arithmetic, and let \mathcal{S} either be the set of recursive subsets of \mathbb{N} or be the set of all subsets of \mathbb{N} . Ultimately, we are attempting to understand what is true of the natural numbers and of the relationships between one closure property of $2^{\mathbb{N}}$ and another, so models of second order arithmetic of the form $\langle \mathbb{N}, \mathcal{S} \rangle$, so-called ω -models, are particularly important.

2010 *Mathematics Subject Classification*. Primary 03B30, 03F35, 03D80; Secondary 05D10.

Key words and phrases. Reverse mathematics, RCA_0 , Σ_2^0 -bounding, Ramsey's Theorem for Pairs, Stable Ramsey's Theorem for Pairs.

Chong was partially supported by NUS grant WBS C146-000-025-00 for this research. Slaman's research was partially supported by NSF award DMS-1001551 and by the John Templeton Foundation. Yang's research was partially supported by NUS research grant WBS 146-000-159-112 and NSFC (No. 11171031).

We let RT_2^2 be the formal assertion of Ramsey's Theorem for Pairs and let SRT_2^2 be the assertion restricted to stable colorings. Both can be expressed in the language of second order arithmetic. An early recursion theoretic theorem of Jockusch (1972) states that there is a recursive coloring of pairs with no infinite homogeneous set recursive in the halting set \emptyset' , or equivalently with no infinite homogeneous set that is Δ_2^0 -definable. In particular, this coloring has no infinite recursive homogeneous set, so in weak form Jockusch's Theorem implies $RCA_0 \not\vdash RT_2^2$. Though stable colorings do have Δ_2^0 infinite homogeneous sets, another recursion theoretic argument shows that there is a recursive stable coloring with no infinite recursive homogeneous set, so the stronger $RCA_0 \not\vdash SRT_2^2$ also holds.

The strength of these two combinatorial principles, RT_2^2 and SRT_2^2 , has been a subject of considerable interest in reverse mathematics. Strengthening Hirst (1987) for RT_2^2 , Cholak, Jockusch, and Slaman (2001) showed that SRT_2^2 implies the Σ_2^0 -bounding principle, $B\Sigma_2^0$, an induction scheme equivalent to Δ_2^0 -induction (see Slaman (2004)) and whose strength is known to lie strictly between Σ_1^0 and Σ_2^0 -induction (see Paris and Kirby (1978)). It is also shown in Cholak et al. (2001) that RT_2^2 is Π_1^1 -conservative over RCA_0 + the Σ_2^0 -induction scheme $I\Sigma_2^0$, i.e. any Π_1^1 -statement that is provable in $RT_2^2 + RCA_0 + I\Sigma_2^0$ is already provable in the system $RCA_0 + I\Sigma_2^0$. It follows immediately that any subsystem of $RT_2^2 + RCA_0 + I\Sigma_2^0$ (such as replacing RT_2^2 by SRT_2^2) is Π_1^1 -conservative over $RCA_0 + I\Sigma_2^0$.

Investigations of aspects of Ramsey's Theorem in the context of subsystems of second order arithmetic over the past two decades have shed much light on the strength of the theorem. Three problems relating to RT_2^2 and SRT_2^2 are of particular interest: (1) whether over RCA_0 , RT_2^2 is strictly stronger than SRT_2^2 ; (2) whether RT_2^2 or even SRT_2^2 proves $I\Sigma_2^0$, given that they already imply $B\Sigma_2^0$; and (3) whether RT_2^2 , or even SRT_2^2 , is Π_1^1 -conservative over $RCA_0 + B\Sigma_2^0$. Of course, a positive answer to (3) would provide a negative answer to (2).

It has been generally believed that RT_2^2 is stronger than SRT_2^2 , and the approach to establishing this as fact has been to look for a collection of subsets of \mathbb{N} satisfying Ramsey's Theorem for Pairs for stable colorings and not for general ones. Historically, using ω -models to study Ramsey type problems has been successful, as witnessed by further work of Jockusch (1972) which, when cast in the language of subsystems of second-order arithmetic, shows that Ramsey's Theorem for triples implies arithmetic comprehension, the results presented in Cholak et al. (2001), Seetapun's theorem (see Seetapun and Slaman (1995)) separating RT_2^2 from Ramsey's Theorem for triples, and recent work of Liu (2012) showing Weak König's Lemma to be independent of RT_2^2 . However, the search for an ω -model separating RT_2^2 from SRT_2^2 has been unsuccessful.

The most direct approach to separating SRT_2^2 was that suggested by Cholak et al. (2001). SRT_2^2 is equivalent to the condition that for every Δ_2^0 -predicate P on the numbers, there is an infinite set G such that either all of the elements of G satisfy P or none of the elements of G satisfy P .¹ The suggestion was that if for every Δ_2^0 -predicate there were such a set G which is also low (i.e. $G' = \emptyset'$), then by an iterative argument one could produce an ω -model of SRT_2^2 in which every set was low, and hence Δ_2^0 . By the result of Jockusch (1972) mentioned above, this

¹The equivalence requires $B\Sigma_2^0$ in the proof. However it is known that each of the statements implies $B\Sigma_2^0$. Hence such a condition does not impose additional assumption to the base theory. See Chong, Lempp, and Yang (2010).

model would not satisfy RT_2^2 . However, this approach was ruled out by Downey, Hirschfeldt, Lempp, and Solomon (2001), who exhibited a Δ_2^0 predicate for which there is no such G that is low.

Here, we exhibit a model $\mathfrak{M} = \langle M_0, \mathcal{S} \rangle$ of $RCA_0 + B\Sigma_2^0 + \neg I\Sigma_2$, hence not an ω -model, that is a model of SRT_2^2 but not RT_2^2 . Thus, we have a positive answer to the first question and partial negative answer to the second. While Downey et al. (2001) demonstrated an insurmountable obstruction to the low-set proposal in the context of ω -models, quite the contrary is true in the realm of nonstandard models, where we are able to make use of the customized features of \mathfrak{M}_0 . In \mathfrak{M} , we do manage to bring the original proposal to fruition and all of the sets in \mathcal{S} are low in the sense of \mathfrak{M} . The existence of \mathfrak{M} is a prima facie demonstration that Stable Ramsey's Theorem for Pairs does not imply Σ_2^0 -induction over the base theory RCA_0 . Finally, by observing that Jockusch's theorem is provable in $RCA_0 + B\Sigma_2^0$, we conclude that \mathfrak{M} is not a model of RT_2^2 .

The paper is organized as follows. In Section 2, we review the basic facts about subsystems of first and second order arithmetic, and state the main results. In Section 3, we construct the first order model \mathfrak{M}_0 . In Section 4, we show how to solve the one-step problem, given a Δ_2^0 -predicate P there is a low set G either contained in or disjoint from P . In Section 5, we construct the collection of subsets of M_0 used to satisfy SRT_2^2 . This is where we establish the results already mentioned. We also extend the method to show that $SRT_2^2 + WKL_0 \not\vdash RT_2^2$, so the assertion that $2^{\mathbb{N}}$ is compact does not strengthen SRT_2^2 sufficiently to prove RT_2^2 . We draw some conclusions in Section 6.

2. SUBSYSTEMS OF ARITHMETIC

We recall some basic notions and notations. We will focus on subsystems of first order arithmetic in the first part of this section and on subsystems of second order arithmetic in the second part. We will use the recursion theoretic notation Σ_n^0 to describe formulas in which all of the quantifiers range only over numbers and Σ_n^1 to describe formulas with quantifiers over sets of numbers. Unless indicated otherwise, all formulas are allowed to mention parameters.

2.1. First Order Arithmetic. Let P^- denote the standard Peano axioms without mathematical induction. For $n \geq 0$, let $I\Sigma_n^0$ denote the induction scheme for Σ_n^0 -formulas. Suppose $\mathfrak{M} = \langle M, +, \times, 0, 1 \rangle$ is a model of $P^- + I\Sigma_1^0$. A bounded set S in \mathfrak{M} is \mathfrak{M} -finite if it is coded in \mathfrak{M} , i.e., there is an $a \in M$ which \mathfrak{M} interprets as a Gödel number for a set with exactly the elements of S . It is known (Paris and Kirby (1978)) that $I\Sigma_n^0$ is equivalent to the assertion that every Σ_n^0 -definable set has a least element. We will use this fact implicitly throughout the paper.

$B\Sigma_n^0$ denotes the scheme given by the universal closures of

$$(\forall x < a)(\exists y)\varphi(x, y) \rightarrow (\exists b)(\forall x < a)(\exists y < b)\varphi(x, y),$$

in which $\varphi(x, y)$ is a Σ_n^0 -formula, possibly with other free variables. Intuitively, $B\Sigma_n^0$ asserts that every Σ_n^0 -definable function with \mathfrak{M} -finite domain has \mathfrak{M} -finite range. In Paris and Kirby (1978), it was also shown that for all $n \geq 1$,

$$\dots \rightarrow I\Sigma_{n+1}^0 \rightarrow B\Sigma_{n+1}^0 \rightarrow I\Sigma_n^0 \rightarrow B\Sigma_n^0 \rightarrow \dots,$$

and that the implications are strict. Our interest here concerns the hierarchy up to level $n = 2$.

A *cut* $I \subset M$ is a set that is closed downwards as well as under the successor function. I is a Σ_n^0 -cut if it is Σ_n^0 -definable over \mathfrak{M} . The next proposition is well-known and we state it without proof.

Proposition 2.1. *If $\mathfrak{M} \models P^- + I\Sigma_1^0$, then $\mathfrak{M} \models I\Sigma_n^0$ if and only if every bounded Σ_n^0 -set is \mathfrak{M} -finite. If $I\Sigma_n^0$ fails, then in \mathfrak{M} there is a Σ_n^0 -cut I and a Σ_n^0 -definable function that maps I cofinally into \mathfrak{M} .*

We next turn our attention to sequences and trees. By a *sequence*, we will mean an element of $M^{<M}$, as defined in \mathfrak{M} by way of a standard Gödel numbering. We use $\sigma \prec \tau$ to mean σ is an initial segment of τ and use $\tau_0 * \tau_1$ to denote the concatenation of the two sequences in the indicated order. We will refer to a subset of the numbers which appear in the range of τ simply as a subset of τ . A *tree* T is a subset of the \mathfrak{M} -finite sequences from \mathfrak{M} , such that T is closed under \mathfrak{M} -finite initial segments. T is *binary* or *increasing* if each sequence in T is binary or increasing, respectively. T is *recursively bounded* if there is a function f which is recursive in the sense of \mathfrak{M} such that for all $s \in M$, there are at most $f(s)$ many elements in T of length s . These trees will be important later, when we use them in the context of compactness arguments.

Sequences in \mathfrak{M} can also be used to define subsets of ω . We say that $X \subseteq \omega$ is *coded in \mathfrak{M}* if there is a binary sequence $\sigma \in \mathfrak{M}$ such that for every $i \in \omega$, $i \in X$ if and only if $\sigma(i) = 1$. In this case, we say that σ is a code for X on ω . The existence of codes in nonstandard models of PA is a feature of the model-theoretic saturation of those models and will be important later.

Finally, a set $X \subseteq M$ is *amenable* if its intersection with any \mathfrak{M} -finite set is \mathfrak{M} -finite. If $\mathfrak{M} \models B\Sigma_n^0$, then every X that is provably Δ_n^0 in \mathfrak{M} is amenable.

2.2. Second Order Arithmetic. RCA_0 is the system consisting of P^- , $I\Sigma_1^0$ and the second-order recursive comprehension scheme

$$(\forall x)[\varphi(x) \leftrightarrow \neg\psi(x)] \rightarrow (\exists X)(\forall x)[x \in X \leftrightarrow \varphi(x)],$$

where φ and ψ are Σ_1^0 -formulas with parameters (we will refer to such formulas as Δ_1^0 -formulas). Let $\mathfrak{M} = \langle M, \mathcal{S}, +, \times, 0, 1 \rangle$ be a model of RCA_0 .

There is a well-developed theory of computation for structures \mathfrak{M} that satisfy RCA_0 plus $B\Sigma_n^0$ or $I\Sigma_n^0$, albeit with restricted inductive power. In particular, one may define notions of computability and Turing reducibility over \mathfrak{M} . Thus, a set is recursively (computably) enumerable (r.e.) if and only if it is Σ_1^0 -definable. It is recursive (computable) if both the set and its complement are recursively enumerable. If X and Y are subsets of M , then $X \leq_T Y$ (" X is Turing reducible to Y ") if there is an e such that for any \mathfrak{M} -finite o , there exist \mathfrak{M} -finite sets $P \subset Y$ and $N \subset \overline{Y}$ satisfying

$$o \subseteq X \leftrightarrow \langle o, 1, P, N \rangle \in \Phi_e$$

and

$$o \subseteq \overline{X} \leftrightarrow \langle o, 0, P, N \rangle \in \Phi_e,$$

where Φ_e is the e th r.e. set of quadruples. Two subsets of M (note that it is not required that they belong to \mathcal{S}) have the same Turing degree if each is reducible to the other. If $n \geq 1$ and $\mathfrak{M} \models B\Sigma_n^0$, then as in classical recursion theory there is a complete Σ_i^0 -set $\emptyset^{(i)}$ for $1 \leq i < n$, and Post's Theorem holds: $X \subset M$ is Δ_{i+1}^0 if and only if $X \leq_T \emptyset^{(i)}$. A set in \mathfrak{M} is *low* if its Σ_1^0 -theory (otherwise called its jump) is recursive in \emptyset' . From the point of view of recursion theory, a structure \mathfrak{M}

is a model of RCA_0 if \mathcal{S} is closed under Turing reducibility and join and \mathfrak{M} satisfies $P^- + I\Sigma_1^0$.

We include set variables \check{G} and \check{G}_i , where $i < \omega$, in the language of second-order arithmetic which will be used to denote the generic homogeneous sets to be constructed. We let $\psi(\check{G})$ denote a Σ_1^0 -formula of the form $\exists s \varphi(s, \check{G})$ where φ is a bounded formula possibly with first and second order parameters. The relationship between ψ and φ will always be as shown above and will be assumed without further mention. We will often not distinguish between a set and its characteristic function unless there is possibility of confusion. If $\psi(\check{G})$ is a Σ_1^0 -formula, and o is an \mathfrak{M} -finite set, then we adopt the convention that $\mathfrak{M} \models \psi(o)$ (or “ $\psi(o)$ holds”) means $(\exists s \leq \max o) \varphi(s, o)$ is true in \mathfrak{M} . If $G \subset M$, then $\mathfrak{M}[G]$ is the structure containing G but having the same first-order universe M , and in addition all the sets recursive in G generated over \mathfrak{M} .

Let $\mathfrak{M} \models RCA_0$. We list two combinatorial principles which are central to the subject matter of this paper. The first is D_2^2 (the second, WKL_0 , will be introduced subsequently):

- D_2^2 : Every Δ_2^0 -set contains an infinite subset in it or its complement.

As mentioned earlier, D_2^2 is equivalent to SRT_2^2 over RCA_0 . The main technical theorem we will establish is the following:

Theorem 2.2 (Main Theorem). *There is a model $\mathfrak{M} = \langle M, \mathcal{S}, +, \times, 0, 1, \epsilon \rangle$ of $RCA_0 + B\Sigma_2^0$ but not $I\Sigma_2^0$ such that every $G \in \mathcal{S}$ is low and $\mathfrak{M} \models D_2^2$.*

Corollary 2.3. *The statement “There is a Δ_2^0 -set with no infinite low subset in it or its complement” is not provable in $P^- + B\Sigma_2^0$.*

The following result of Jockusch (1972), appropriately adapted to the setting of second order arithmetic, yields Corollary 2.5 from Theorem 2.2:

Proposition 2.4. *Let $\mathfrak{M} = \langle M, \mathcal{S} \rangle \models RCA_0 + B\Sigma_2^0$ and $X \in \mathcal{S}$. There is an X -recursive two coloring of pairs with no X' -recursive infinite homogeneous set in \mathfrak{M} .*

Proof. We repeat here the argument for Theorem 3.1 of Jockusch (1972). Define an X -recursive two-coloring r and b (for *red* and *blue* respectively) of pairs of numbers in M for which no $\Delta_2^0(X)$ -set is homogeneous.

Since $\mathfrak{M} \models B\Sigma_2^0$, every $\Delta_2^0(X)$ -set is amenable. Furthermore, A is $\Delta_2^0(X)$ if and only if $A \leq_T X'$. Now there is a uniformly recursive collection of X -recursive functions f_e such that $\lim_s f_e(s, x) = A_e(x)$ for all x if and only if A_e is $\Delta_2^0(X)$. Furthermore, if A_e is such a set, then by $B\Sigma_2^0$ again, for each a , the “ $\Delta_2^0(X)$ convergence of f_e to A_e ” is tame, i.e. there is an s_a such that for all $s \geq s_a$, $f_e(s, x) = A_e(x)$ whenever $x \leq a$. For each e and s , let $D_e[s]$ be the set with $2e + 2$ numbers that appear to be the first $2e + 2$ members of A_e at stage s . There are two possible reasons for the guess to be wrong: The correct stage s has not yet been reached, or A_e has less than $2e + 2$ elements. If A_e has at least $2e + 2$ elements, then by tameness of $\Delta_2^0(X)$ -sets, a correct s_e exists such that $D_e[s] = D_e[s]$ for all $s \geq s_e$. Define the coloring C as follows: (i) At stage s , in increasing order of $e \leq s$, if $D_e[s]$ is not defined, skip to the next e . Otherwise, there must be at least two (least) numbers x and y in $D_e[s]$ such that no colors have been assigned to (x, s) and (y, s) . Color one r and the other b ; (ii) For all (x, s) , $x \leq s$, not colored

following the above scheme, let $C(x, s) = r$. This diagonalization procedure ensures that no $\Delta_2^0(X)$ -set is homogeneous for C .

We note that no priority argument is involved and the coloring C requires only $B\Sigma_2^0$ for the desired conclusion to hold. \square

Corollary 2.5. *SRT_2^2 does not imply RT_2^2 .*

Corollary 2.6. *SRT_2^2 does not imply $I\Sigma_2^0$.*

Let T be a tree in \mathfrak{M} . A *path* on T is a maximal compatible set of strings in T . A Π_1^0 -class is the collection of paths on a recursively bounded recursive tree T . Note that not all paths on T have to be in \mathfrak{M} . The next combinatorial principle is known to be independent of RT_2^2 (Liu (2012)).

- WKL_0 (Weak Kőnig's Lemma): If T is an infinite subtree of the full binary tree, then T contains an infinite path.

Theorem 2.7. *There is a model \mathfrak{M} of $RCA_0 + SRT_2^2 + WKL_0 + B\Sigma_2^0$ in which RT_2^2 fails.*

Corollary 2.8. *$SRT_2^2 + WKL_0$ does not prove RT_2^2 over $RCA_0 + B\Sigma_2^0$.*

Definition 2.9. Given two models $\mathfrak{M}_0 = \langle M_0, \mathcal{S}_0 \rangle$ and $\mathfrak{M} = \langle M, \mathcal{S} \rangle$ of RCA_0 , we say that \mathfrak{M} is an M_0 -*extension* of \mathfrak{M}_0 if $M_0 = M$ and $\mathcal{S}_0 \subseteq \mathcal{S}$, i.e. only subsets of M_0 are added to form \mathfrak{M} .

In the next section, we exhibit a model $\mathfrak{M}_0 \models RCA_0 + B\Sigma_2^0$ that satisfies a bounding principle called *BME*. The models for Theorems 2.2 and 2.7 will be M_0 -extensions of \mathfrak{M}_0 .

3. THE FIRST ORDER PART OF A MODEL OF SRT_2^2

3.1. A Σ_1 -Reflecting Model. We will now describe \mathfrak{M}_0 , the first order part of our model of SRT_2^2 . As indicated in Proposition 3.1, \mathfrak{M}_0 has three features which will be important in what follows. The first feature is that \mathfrak{M}_0 is a union of Σ_1 -reflecting initial segments $(\mathcal{J}_k : k \in \omega)$, such that each \mathcal{J}_k is a model of PA . The use of Σ_1 -reflection has a long tradition in higher recursion theory to bound the scope of existential quantifiers for which there are no a priori bounds (see Sacks (1990), the use of α -stable ordinals in α -recursion theory), and we will see another such application here. The second feature is that \mathfrak{M}_0 has an explicit failure of $I\Sigma_2^0$ and that ω is a Σ_2^0 -cut in \mathfrak{M}_0 . This gives not only the obvious conclusion that SRT_2^2 does not imply $I\Sigma_2$, but also that \mathfrak{M}_0 has definable cofinality ω . The third feature of \mathfrak{M}_0 is that it is highly saturated, which we exploit to exhibit parameters that capture the behavior of our constructions as they appear at the various points along \mathfrak{M}_0 's cofinal sequence.

Proposition 3.1. *There is a countable model $\mathfrak{M}_0 = \langle M_0, +, \times, 0, 1 \rangle$ of $P^- + B\Sigma_2^0$ within which there is a Σ_2^0 -function g behaving as follows.*

- (1) \mathfrak{M}_0 is the union of a sequence of Σ_1 -elementary end-extensions of models of PA :

$$\mathcal{J}_0 \prec_{\Sigma_1, e} \mathcal{J}_1 \prec_{\Sigma_1, e} \mathcal{J}_2 \prec_{\Sigma_1, e} \cdots \prec_{\Sigma_1, e} \mathfrak{M}_0$$

- (2) For each $i \in \omega$, $g(i) \in \mathcal{J}_i$, and for $i > 0$, $g(i) \notin \mathcal{J}_{i-1}$, hence $\mathfrak{M}_0 \not\models I\Sigma_2^0$.
- (3) Every \mathfrak{M}_0 -arithmetical subset of ω is coded on ω .

Proof. We will give a direct, though metamathematically inefficient, proof of the existence of the desired model.

We begin with an uncountable model \mathcal{V} of set theory such that $\mathbb{N}^{\mathcal{V}}$, the natural numbers of \mathcal{V} , is nonstandard and such that every subset of ω is coded in \mathcal{V} on ω . For example, \mathcal{V} could be any ω_1 -saturated model of a large fragment of *ZFC*. Fix b to be a nonstandard element of $\mathbb{N}^{\mathcal{V}}$.

Working in \mathcal{V} , our second step is to define a sequence of theories T_i . We will use $S_{\Pi_1^0}$ to indicate the set of Π_1^0 sentences with parameters defined within a model of *PA* using that model's definition of Π_1^0 -satisfaction. For a definable theory T , $CON(T)$ is the assertion that T is consistent, expressed in the usual way using Gödel numbering. Let

$$\begin{aligned} T_0 &= PA + S_{\Pi_1^0}, \\ T_{i+1} &= T_i + CON(T_i). \end{aligned}$$

Our third step is to define a sequence of Σ_1 -elementary end-extensions of length b :

$$\mathbb{N}^{\mathcal{V}} = J_0 \prec_{\Sigma_1, e} J_1 \prec_{\Sigma_1, e} J_2 \prec_{\Sigma_1, e} J_3 \prec_{\Sigma_1, e} \cdots \prec_{\Sigma_1, e} J_b.$$

In \mathcal{V} , we will appear to be constructing a finite Σ_1 -elementary sequence of models by injecting inconsistencies while unfolding the iterated consistency statements used to define the theories T_i , for $i < b$. We begin by setting $J_0 = \mathbb{N}^{\mathcal{V}}$ and noting that J_0 satisfies $PA + CON(T_{b-1})$, since it is the standard model of arithmetic in \mathcal{V} . Thus, from J_0 's perspective, T_{b-1} is consistent. However, by the Gödel second incompleteness theorem, which is provable in *PA* and thereby holds in J_0 , J_0 satisfies that T_{b-1} cannot prove $CON(T_{b-1})$. Finally, by the arithmetical completeness theorem, there is an J_1 such that $J_0 \prec_e J_1$,

$$J_1 \models T_{b-1} + \neg CON(T_{b-1}),$$

and J_1 is definable in J_0 . (See McAloon (1978) for more details on applications of the arithmetical completeness theorem.) We could even take J_1 to be defined in J_0 as a low predicate relative to $0'$. Note, by the definition of T_{b-1} , $J_1 \models PA + CON(T_{b-2})$.

Working in \mathcal{V} , we can iterate this step b many times. For $0 < i < b$, we define J_{i+1} to be an end-extension of J_i such that J_{i+1} is a definable low model in J_i and

$$J_{i+1} \models T_{b-(i+1)} + \neg CON(T_{b-(i+1)}).$$

The only difference between the initial and the general inductive step is that we are required to find an end-extension of J_i , which \mathcal{V} sees to be a nonstandard. It is for this reason that we invoke the fact that $J_i \models PA + CON(T_{b-(i+1)})$ and then apply the Gödel second incompleteness theorem (as a consequence of *PA*) and the arithmetical completeness theorem in J_i to obtain an J_i -definable model of $T_{b-(i+1)} + \neg CON(T_{b-(i+1)})$.

Now, we prove the proposition. For each $n \in \omega$, define $I_n^{\mathcal{V}}$ to be the universe of J_n and define $M_0^{\mathcal{V}} = \cup_{n \in \omega} I_n^{\mathcal{V}}$. Define $g(0) = 0$. For $n > 0$, define $g(n)$ to be the shortest proof in $\mathfrak{M}_0^{\mathcal{V}}$ of $\neg CON(T_{b-n})$. Whether a formula belongs to T_n is a Π_1^0 -property of that formula and Π_1^0 -properties are absolute between all the models being discussed, so the function g is Σ_2^0 in $\mathfrak{M}_0^{\mathcal{V}}$. Finally, since $\mathfrak{M}_0^{\mathcal{V}} \prec_{\Sigma_1, e} J_b$, $\mathfrak{M}_0^{\mathcal{V}}$ is a model of $B\Sigma_2^0$ (see Kaye (1991) chapter 10). Thus, $\mathfrak{M}_0^{\mathcal{V}}$, g , and the initial segments $J_n^{\mathcal{V}}$ satisfy the first two conditions of the proposition.

To finish, let \mathfrak{M}_0 be a countable substructure of \mathfrak{M}_0^\forall such that the following conditions hold.

- (1) $b \in \mathfrak{M}_0$.
- (2) \mathfrak{M}_0 with predicates for the $I_n \cap \mathfrak{M}_0$ is an elementary substructure of \mathfrak{M}_0^\forall with predicates for the I_n .
- (3) Every \mathfrak{M}_0 -arithmetical subset of ω is coded on ω .

We can obtain \mathfrak{M}_0 by closing under the usual Skolem functions for first-order elementarity and also under the additional Skolem function that for each definable predicate adds a parameter coding the restriction of that predicate to ω . We let $I_n = I_n^\forall \cap \mathfrak{M}_0$ and let g be defined in \mathfrak{M}_0 as in \mathfrak{M}_0^\forall .

\mathfrak{M}_0 , g , and the I_n satisfy the first two conditions of the proposition by elementarity. They satisfy the third condition of the proposition by construction. \square

Notation 3.2. We fix the notation \mathfrak{M}_0 , $\{J_n : n < \omega\}$ and g to refer to the model, cuts and function constructed in Lemma 3.1.

3.2. Monotone Enumerations. We will have two notational conventions in this subsection, to be interpreted in the models that we just constructed.

- (1) When written with no argument, V will denote a procedure to compute a recursively-bounded tree. Then, $V(X)$ will denote the procedure applied relative to X to compute an X -recursively-bounded X -recursive tree. In the context of relativizing V , we will use τ to denote a finite string. Then, $V(\tau)$ will be the finite tree that can be computed from τ according to V . We follow the usual convention that if m is the maximum of the length of τ and its greatest element, then $V(\tau)$ is defined only for arguments less than m such that the evaluation of V relative to τ takes less than m steps and τ is queried only at arguments for which it is defined.
- (2) When written with no argument, E will denote a procedure to recursively enumerate a finitely-branching enumerable tree. We will use σ to denote a finite string in the context of relativizing E , with $E(X)$ and $E(\sigma)$ interpreted as above.
- (3) When clear from context, we will also use V or E to refer to the recursive or recursively enumerable trees defined by them.

Definition 3.3. We say that E is a *monotone enumeration* if and only if the following conditions apply to its stage-by-stage behavior.

- (1) The empty sequence is enumerated by E during stage 0.
- (2) Only \mathfrak{M} -finitely many sequences are enumerated by E during any stage.
- (3) Suppose that τ is enumerated by E during stage s and let τ_0 be the longest initial segment of τ that had been enumerated by E at a stage earlier than s . Then,
 - (i) τ_0 had no extensions enumerated by E prior to stage s and
 - (ii) all the sequences enumerated by E during stage s are extensions of τ_0 .

Let $E[s]$ denote the set of sequences that have been enumerated by E by the end of stage s . Condition (3) above asserts that if $E[s+1] \setminus E[s]$ is not empty, then there is a maximal path τ_0 in $E[s]$ such that for every element τ of $E[s+1] \setminus E[s]$, $\tau_0 \prec \tau$, i.e. $\tau = \tau_0 * \tau_1$, for some nontrivial sequence τ_1 . Here, \prec and $*$ indicate initial segment and concatenation according to the conventions of Section 2.1. We

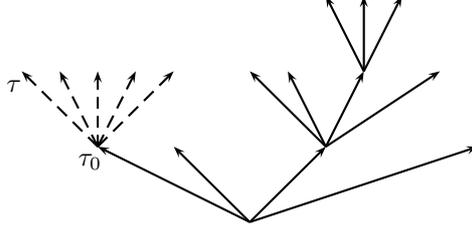


FIGURE 1. Monotone Enumeration

display this situation in Figure 1, where the nodes enumerated by E during that stage are indicated by dashed lines.

Similarly, we can define E 's being a monotone enumeration relative to a predicate X , or even relative to all strings σ in a recursive tree V .

Definition 3.4. Suppose that E is a monotone enumeration.

- (1) For an element τ enumerated by E , let k be the number of stages in the enumeration by E during which τ or an initial segment of τ is enumerated. Let $(\tau_i : i < k)$ be the stage-by-stage sequence of the maximal initial segments of τ associated with those stages.
- (2) We say that E 's enumeration is bounded by b if for each τ in E , its stage-by-stage sequence has length less than or equal to b .

Proposition 3.5. *Suppose that $\mathfrak{M} \models P^- + I\Sigma_2^0$ and that E is a monotone enumeration procedure in \mathfrak{M} which is bounded by b . Then $\mathfrak{M} \models \text{“}E \text{ is finite”}$.*

Proof. Work in \mathfrak{M} to show by induction on ℓ that there are only \mathfrak{M} -finitely many τ such that the stage-by-stage sequence associated with E 's enumeration of τ has length ℓ . \square

By Proposition 3.5, $I\Sigma_2^0$ is sufficient to show that bounded monotone enumerations are \mathfrak{M} -finite. However, that is not the case for $B\Sigma_2^0$.

Proposition 3.6. *There is a model $\mathfrak{M} \models P^- + B\Sigma_2^0$ such that in \mathfrak{M} there is a monotone enumeration E which is bounded by b , but yet the enumeration of E is not finite in \mathfrak{M} .*

Proof. Let \mathfrak{N} be a nonstandard model of PA and let b be a nonstandard element of \mathfrak{N} . To fix some notation, let \emptyset' denote the universal Σ_1^0 -predicate in \mathfrak{N} and let $\emptyset'[s]$ denote the recursive approximation to it given by bounding the existential quantifier in its definition by s .

Define the function $t : \mathfrak{N} \rightarrow \mathfrak{N}$ by recursion: Let $t(0) = 0$, let $t(1) = b$ and let $t(x+1)$ be the least s such that $\emptyset'[s] \upharpoonright t(x) = \emptyset' \upharpoonright t(x)$. Define \mathfrak{M} to be the substructure of \mathfrak{N} with elements given by

$$x \in \mathfrak{M} \iff (\exists n \in \omega) \mathfrak{N} \models x < t(n).$$

Then, \mathfrak{M} is a Σ_1 -substructure of \mathfrak{N} . Further, since \mathfrak{N} is an end-extension of \mathfrak{M} , \mathfrak{M} satisfies $B\Sigma_2^0$, an implication that we also noted in the construction of \mathfrak{M}_0 .

Now, we give a monotone enumeration in \mathfrak{M} of a tree whose height is bounded by b but which is not \mathfrak{M} finite. Again, we let $E[s]$ denote the set of sequences that have been enumerated by E by the end of stage s . At stage 0, E enumerates the empty sequence. So, $E[0]$ is the singleton set consisting of the empty sequence. At stage 1, E enumerates all the sequences $\langle x \rangle$ of length one such that $x \leq b$. At stage $s+1$, we let m be the largest number that appears in any sequence in $E[s]$. If there is an $x \leq m$ such that $x \in \emptyset'[s+1] \setminus \emptyset'[s]$, then for each such x , for each sequence $\tau \in E[s]$ such that x is the last element of τ , τ is maximal in $E[s]$ and τ has length less than b (if any), and for each $y \leq s+1$, E enumerates $\tau * \langle y \rangle$. That concludes stage $s+1$.

By construction, our enumeration of E is monotone. It remains to show that the enumeration by E is not finite in \mathfrak{M} . For this, note that for each $n \in \omega$, if n is greater than 0, then $t(n)$ appears on the n th level of E . We prove this by induction on n . It is true for $t(1)$, since $t(1)$ is b and the first level enumerated by E consists of all numbers less than or equal to b . Assume that E enumerates $t(n)$ on level n . When E enumerates the sequence $\tau_0 * \langle t(n) \rangle$ of length n , for each x less than $t(n)$ E also enumerates the sequence $\tau_0 * \langle x \rangle$. Now, $\mathfrak{M} \prec_{\Sigma_1^0} \mathfrak{M}$ and so the enumeration of $\emptyset' \upharpoonright t(n)$ viewed within \mathfrak{M} is completed exactly at stage $t(n+1)$. Let x be an element less than $t(n)$ that is enumerated into \emptyset' at stage $t(n+1)$ and not before. The sequence $\tau_0 * \langle x \rangle$ will be a maximal element of $E[t(n+1)-1]$, since $x \notin E[t(n+1)-1]$, and of length n , which is less than b . By construction, E will enumerate $\tau_0 * \langle x \rangle * \langle t(n+1) \rangle$ at stage $t(n+1)$. \square

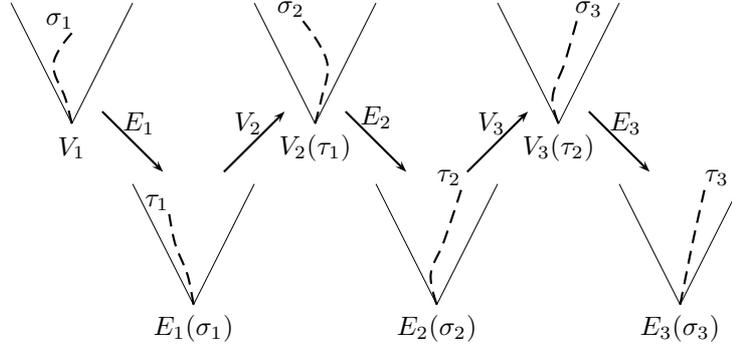
Definition 3.7. Suppose that V is the index for a recursively bounded recursive tree and suppose that E is a monotone enumeration procedure. For σ in the tree computed by V , say that σ is *E-expansive* if in the enumeration of $E(\sigma)$ some new element is enumerated at stage $|\sigma|$. We say that a level ℓ in the tree computed by V is *E-expansive* if there is an n such that ℓ is the least level in the tree computed by V at which every σ in that tree with $|\sigma| = \ell$ has at least n many *E-expansive* initial segments.

Definition 3.8. A *k-iterated monotone enumeration* is a sequence $(V_i, E_i)_{1 \leq i \leq k}$ with the following properties.

- (1) Each V_i is an index for a relativized recursive recursively-bounded tree.
- (2) Each E_i is an index for a monotone enumeration procedure.
- (3) For each $1 \leq j \leq k$, if $\sigma \in V_j$ is E_j -expansive, then for every new element τ enumerated in $E_j(\sigma)$, $V_{j+1}(\tau)$ is a proper E_{j+1} -expansive extension of $V_{j+1}(\tau_0)$, where τ_0 is the longest initial segment of τ that had previously been enumerated in $E_j(\sigma)$, that is by a stage less than the length of σ .

Definition 3.9. A *k-path* of the *k-iterated monotone enumeration* $(V_i, E_i)_{1 \leq i \leq k}$ is a sequence $(\sigma_i, \tau_i)_{1 \leq i \leq k}$ such that $\sigma_1 \in V_1$ and τ_1 is a maximal sequence in $E_1(\sigma_1)$, and for each j with $1 < j \leq k$, σ_j is a maximal sequence in $V_j(\tau_{j-1})$ and τ_j is a maximal sequence in $E_j(\sigma_j)$.

Figure 2 shows a 3-iterated monotone enumeration as realized by a particular 3-path.

FIGURE 2. An example of k -path when $k = 3$

- Definition 3.10.** (1) A k -iterated monotone enumeration is b -bounded if and only if for every sequence enumerated in $E_k(\sigma_k)$ by some k -path of the k -iterated enumeration, its stage-by-stage enumeration has length less than or equal to b .
- (2) We say that \mathfrak{M} satisfies *bounding for iterated monotone enumerations (BME)* if and only if for every $k \in \omega$, every b in \mathfrak{M} and every b -bounded k -iterated monotone enumeration, there are only boundedly many E_1 -expansory levels in V_1 .
- (3) If we restrict our attention to k -iterated monotone enumerations, we say that \mathfrak{M} satisfies BME_k .

Proposition 3.11. \mathfrak{M}_0 satisfies BME.

Proof. Suppose that $(V_i, E_i)_{i \leq k}$ is a k -iterated monotone enumeration and that in \mathfrak{M}_0 there are unboundedly many E_1 -expansory levels in V_1 . We must show that there is no b which bounds the lengths of the stage-by-stage enumerations of elements of E_k on all k -paths of $(V_i, E_i)_{i \leq k}$.

Fix n so that b and the other parameters defining $(V_i, E_i)_{i \leq k}$ belong to \mathcal{J}_n . Since $\mathcal{J}_n \prec_{e, \Sigma_1} \mathfrak{M}_0$ and there are unboundedly many E_1 -expansory levels in V_1 ,

$$\mathcal{J}_n \models \text{There are unboundedly many } E_1\text{-expansory levels in } V_1.$$

In particular, since \mathcal{J}_n is a model of PA ,

$$\mathcal{J}_n \models V_1 \text{ is a recursively bounded infinite tree.}$$

Again, since $\mathcal{J}_n \models PA$, let X_1 be an \mathcal{J}_n -definable infinite path in V_1 . Note that $\mathcal{J}_n[X_1]$, obtained by adding X_1 as an additional predicate to \mathcal{J}_n , still satisfies PA relativized to X_1 . Since E_1 is a monotone enumeration and there are unboundedly many E_1 -expansory levels in V_1 ,

$$\mathcal{J}_n[X_1] \models E_1(X_1) \text{ is a finitely branching unbounded tree.}$$

Now, we can let Y_1 be an $\mathcal{J}_n[X_1]$ -definable infinite path in $E_1(X_1)$, and note that $\mathcal{J}_n[X_1, Y_1]$ satisfies *PA* relative to (X_1, Y_1) . Further, because each sequence τ enumerated in E_1 exhibits a new E_2 -expansionary level in $V_2(\tau)$,

$$\mathcal{J}_n[X_1, Y_1] \models (V_i, E_i)_{1 \leq i \leq k} \text{ is a } (k-1)\text{-iterated monotone enumeration.}$$

By a k -length recursion, there is an \mathcal{J}_n -definable sequence $(X_1, Y_1, \dots, X_k, Y_k)$ extending (X_1, Y_1) such that for each i , X_i is an infinite path in $V_{i-1}(Y_{i-1})$ and Y_i is an infinite path in $E_i(X_i)$. Consequently, the stage-by-stage enumeration of the initial segments of Y_k in $\mathcal{J}_n[X_1, Y_1, \dots, X_k]$ is infinite, and there is no b which bounds the lengths of the stage-by-stage enumerations of elements of E_k on all k -paths of $(V_i, E_i)_{1 \leq i \leq k}$, as required. \square

4. LOW HOMOGENEOUS SETS

4.1. A Generic Instance of SRT_2^2 . Let \mathfrak{M}_0 be the model constructed in Proposition 3.1. This section is devoted to a proof of the following theorem.

Theorem 4.1. *Suppose that A is Δ_2^0 . There is a pair of sets (G_r, G_b) with the following properties.*

- (i) $G_r \subseteq A$ and $G_b \subseteq \bar{A}$.
- (ii) At least one of G_r or G_b has unboundedly many elements in \mathfrak{M}_0 . Call that set G .
- (iii) G is low in \mathfrak{M}_0 . Consequently, $\mathfrak{M}_0[G]$ satisfies $B\Sigma_2^0$.

Given a set A , we refer to the numbers in A and in \bar{A} as *red* and *blue*, respectively. We first describe a way to select a homogeneous set which decides one Σ_1^0 -formula ψ (meaning to make either ψ or $\neg\psi$ true in the structure $\mathfrak{M}_0[G]$). The approach derives its inspiration from Seetapun and Slaman (1995) and is central to the techniques developed in this paper. Two key notions—that of *Seetapun disjunction* (to force a Σ_1^0 -formula) and that of *U-tree* (to force the negation of a Σ_1^0 -formula)—will be introduced for this purpose. After analyzing the situation for a single Σ_1^0 -formula, we will move to handling an \mathfrak{M}_0 -finite set of formulas, leading to the definition of the notion of forcing in Definition 4.7, and then construct the desired low homogeneous set stated in Theorem 4.1.

We will generalize from the notion of a Seetapun disjunction to that of an exit tree, which is defined by a stage-by-stage enumeration. The enumeration of an exit tree is the origin of the abstract notion of a k -iterated monotone enumeration introduced in §3.2, and is key to our proof. On the other hand, the notion of a *U-tree* used extensively in §4 and §5 is a concrete realization of the recursively bounded recursive tree V in §3.2. Note also that the construction in this section only requires the simplest version of the bounded monotone enumeration principle, namely BME_1 . The k -iterated version is required in §5, where we will implement a scheme to perform iterations of a more complex construction in order to preserve additionally BME in the generic extension.

4.2. Seetapun Disjunction for a Single Σ_1^0 -formula. We begin with some terminology. We will refer to a recursive sequence of \mathfrak{M}_0 -finite sets \vec{o} as a sequence of *blobs* if for each s less than the length of the sequence, $\max o_s < \min o_{s+1}$. Let \vec{o} be an \mathfrak{M}_0 -finite sequence of blobs, say of length h . Consider the set of all choice functions σ with domain h such that $\sigma(s) \in o_s$, together with their initial segments $\sigma \upharpoonright h'$ for $h' < h$. By regarding them as strings and adding the empty string as root,

the collection may be viewed naturally as a tree, called the *Seetapun tree* associated with \vec{o} .

Definition 4.2. Given a Σ_1^0 -formula $\psi(\check{G})$, a *Seetapun disjunction* δ (or *S-disjunction* for short) for ψ is a pair (\vec{o}, S) , where \vec{o} is a sequence of blobs of length $h > 0$ and S is the Seetapun tree associated with \vec{o} , such that:

- (i) For each $s < h$, $\mathfrak{M}_0 \models \psi(o_s)$ in the sense of §2.2.
- (ii) For each maximal branch τ of S , there exists an \mathfrak{M}_0 -finite subset $\iota \subseteq \tau$ such that $\mathfrak{M}_0 \models \psi(\iota)$ (here again we identify a string with its range and $\mathfrak{M}_0 \models \psi(\iota)$ is interpreted in the sense of §2.2. This convention will be followed throughout the paper). We refer to the set ι as a *thread* (in τ).

Figure 3 is an illustration of a Seetapun disjunction:

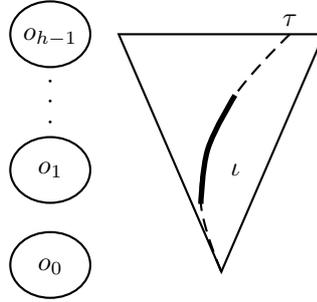


FIGURE 3. A Seetapun disjunction

Notice that an \mathfrak{M}_0 -finite tree's being a Seetapun disjunction for a fixed Σ_1^0 -formula ψ is a recursive property of that tree. The main feature of an S-disjunction is that it anticipates all possible amenable sets. Namely, if an S-disjunction for ψ is found, then for any amenable set A , ψ can be “forced” in a Σ_1^0 -way by either a subset of A or a subset of \overline{A} . We isolate this fact in the following lemma, which also informally explains the meaning of a “disjunction” and the meaning of “forcing ψ ”:

Lemma 4.3. *Let $\psi(\check{G})$ be a Σ_1^0 -formula and δ be an S-disjunction for ψ . Then for any amenable set A , one of the following applies:*

- (i) *There is an \mathfrak{M}_0 -finite set $o \subseteq A$ such that $\psi(o)$ holds in \mathfrak{M}_0 .*
- (ii) *There is an \mathfrak{M}_0 -finite set $\iota \subseteq \overline{A}$ such that $\psi(\iota)$ holds in \mathfrak{M}_0 .*

Proof. Assume that the S-disjunction δ is (\vec{o}, S) with code c . For any amenable set A , let D and \overline{D} be the \mathfrak{M}_0 -finite sets $A \upharpoonright (c+1)$ and $\overline{A} \upharpoonright (c+1)$ respectively. If $D \supseteq o$ for some o in the sequence \vec{o} , then (i) holds. Otherwise, every o in \vec{o} contains at least one element in \overline{D} . By induction for bounded formulas and the definition of δ , there exists a thread ι in some τ which is contained entirely in \overline{D} such that $\psi(\iota)$ holds, which establishes (ii). \square

Definition 4.4. We define the *exit taken by A from δ* to be the (canonically) least o or ι that satisfies Lemma 4.3.

4.3. Forcing a Π_1^0 -Formula. Now assume that no S-disjunction for ψ exists. Then it is possible to “force $\neg\psi$ ” as follows. Begin with enumerating a sequence of blobs \vec{o} by stages. (The sequence \vec{o} of blobs may be either \mathfrak{M}_0 -finite or \mathfrak{M}_0 -infinite.)

At stage 0, the blob sequence $\vec{o}[0]$ is empty.

At stage $s + 1$, suppose $\vec{o}[s]$ has been defined. Check if there exists an \mathfrak{M}_0 -finite set o such that the code of o is less than $s + 1$, $\min o >$ any number appearing in any blob in the sequence $\vec{o}[s]$ and $(\exists t < s + 1)\varphi(t, o)$. If no such o exists, then let $\vec{o}[s + 1] = \vec{o}[s]$; otherwise, take o^* to be the least (in a canonical order) such o . Define $\vec{o}[s + 1] = \vec{o}[s] * o^*$ and proceed to the next stage.

The Seetapun tree associated with this blob sequence \vec{o} which we defined previously may now be given a precise description as follows. Let $S[0] = \emptyset$. $S[s + 1] = S[s] \cup \{\tau * x : \tau \in S[s] \wedge x \in o[s + 1]\}$. Then $S = \bigcup_s S[s]$ is the Seetapun tree. Moreover S is \mathfrak{M}_0 -finite if and only if \vec{o} is \mathfrak{M}_0 -finite. There are two possibilities to consider (corresponding to two possible ways of “forcing $\neg\psi$ ”):

Case 1. The Seetapun tree S is \mathfrak{M}_0 -infinite. Then the U -tree for $\neg\psi$ defined as

$$U = \{\tau \in S : (\forall s < |\tau|)(\forall \iota \subseteq \tau)\neg\varphi(s, \iota)\}$$

is a recursively bounded increasing recursive tree due to the absence of a Seetapun disjunction. Then as long as one stays within U (meaning the numbers to be used at any stage in the rest of the construction are taken from one of its branches), $\neg\psi$ will always hold. We refer to this as *forcing $\neg\psi$ by thinning*.

Case 2. The Seetapun tree S is \mathfrak{M}_0 -finite. Then by working with sets consisting only of numbers larger than (the code of) S , ψ will never be satisfied. Hence $\neg\psi$ is forced instead. We refer to this action as *forcing $\neg\psi$ by skipping*.

Notice that exactly how $\neg\psi$ is forced depends on whether the Seetapun tree S is \mathfrak{M}_0 -finite or infinite, which is a two-quantifier question. In general, \emptyset' is unable to answer this question. This is the reason that Seetapun’s original argument could not produce low homogeneous sets. However, in \mathfrak{M}_0 we will exploit the presence of codes to reduce the complexity of the Π_2^0 -question above by one quantifier. First though, we apply the *blocking method*, which is next discussed, to handle simultaneously an \mathfrak{M}_0 -finite block of Σ_1^0 -formulas.

4.4. A Block of Requirements and Exit Trees.

4.4.1. Requirement Blocks. Fix an enumeration $\{\psi_e(\check{G}) : e \in M_0\}$ of all Σ_1^0 -formulas. Given an \mathfrak{M}_0 -finite set B , we call the set of Σ_1^0 -formulas $\{\psi_e : e \in B\}$ a *block* of formulas. We will identify a formula ψ_e with its index e and loosely say that ψ_e is in B when e is in B .

Given an \mathfrak{M}_0 -finite set B of Σ_1^0 -formulas, we first force in Σ_1^0 -fashion as many formulas in B as possible using S-disjunctions. Each S-disjunction brings with it exits o and ι each of which forces at least one formula in B . Lemma 4.3 says that if A is amenable, then either there is an $o \subseteq A$ or an $\iota \subseteq \overline{A}$. Since different Δ_2^0 -sets may take different exits, a situation which we cannot recursively decide, one assumes that each exit is a possible subset of A or \overline{A} , and use each exit as a *precondition* to search for a new S-disjunction that will force another formula in B .

This brings up the two main issues in this subsection. One is the organization of the exits as a tree, which we will call an *exit tree*; the other is the enumeration of Seetapun disjunctions using previously enumerated exits as preconditions. After clarifying these points, we will note that B ’s being \mathfrak{M}_0 -finite implies that our enumeration is bounded, and we invoke *BME* to argue that our enumeration

process eventually stops. When that happens, we will have completed the portion of forcing those formulas in B which can be decided in a Σ_1^0 -way. The formulas in B not yet forced to be true by this stage will be forced negatively in a Π_1^0 -fashion via a suitable recursively bounded recursive increasing tree.

We begin by introducing a modified version of the notion of a Seetapun disjunction.

Definition 4.5. Given two blocks B_r and B_b of Σ_1^0 -formulas, and a pair of disjoint \mathfrak{M}_0 -finite sets ρ and β , a *Seetapun disjunction* δ for (B_r, B_b) with preconditions (ρ, β) is a pair (\vec{o}, S) as in Definition 4.2, such that:

- (i) For each $s < h$, $\mathfrak{M}_0 \models \psi_e(\rho * o_s)$ for some $e \in B_r$.
- (ii) For each maximal branch τ of S , there exists an \mathfrak{M}_0 -finite subset $\iota \subseteq \tau$ such that $\mathfrak{M}_0 \models \psi_d(\beta * \iota)$ for some $d \in B_b$.

We use the letters ρ and β to suggest red and blue, respectively. Given $\varepsilon = (\rho, \beta)$, define two blocks $B_r(\varepsilon)$ and $B_b(\varepsilon)$ to be the set of formulas in B yet to be forced by ρ and β , respectively. In other words, $B_r(\varepsilon) = B \setminus \{e : \mathfrak{M}_0 \models \psi_e(\rho)\}$ and $B_b(\varepsilon) = B \setminus \{d : \mathfrak{M}_0 \models \psi_d(\beta)\}$. Lemma 4.6 is the generalization of Lemma 4.3 to S-disjunctions with preconditions. The proof is similar and is omitted.

Lemma 4.6. Let $\varepsilon = (\rho, \beta)$ be a pair of disjoint \mathfrak{M}_0 -finite sets. Let $\delta = (\vec{o}, S)$ be an S-disjunction for $(B_r(\varepsilon), B_b(\varepsilon))$ with preconditions (ρ, β) . Let A be amenable such that $\rho \subseteq A$ and $\beta \subseteq \overline{A}$. Then one of the following applies:

- (i) There is an $o \in \vec{o}$ such that $\rho * o \subseteq A$;
- (ii) There is a $\tau \in S$ and a thread $\iota \subseteq \tau$ such that $\beta * \iota \subseteq \overline{A}$.

4.4.2. *Exit Trees.* We now enumerate the *exit tree* E for B as follows.

At stage 0, set $E[0]$ to be the code of the empty set (as root of the exit tree). Begin the search for a Seetapun disjunction δ for (B, B) with preconditions (\emptyset, \emptyset) .

We pause to explain the intuitive idea behind this enumeration procedure and introduce some terminology. First we describe how the exit tree will look once the first S-disjunction δ is enumerated. Assume that the exits in δ consist of blobs $o_0, o_1, \dots, o_{s_0-1}$ and threads $\iota_0, \iota_1, \dots, \iota_{t_0-1}$ (in the case of an ι appearing in multiple τ 's, we simply ignore the repetitions). The sets o_s ($0 \leq s < s_0$) and ι_t ($0 \leq t < t_0$) are represented by their codes denoted by ρ_s and β_t . Let a node ε (on the first level of the exit tree) be a pair of codes (ρ, β) , where ρ or β (but not both) is the code of the empty set. As in the case of an S-disjunction for a single ψ , given an amenable set A , either A is a superset of some o_s or \overline{A} is a superset of some ι_t . Thus A must exit from some $\varepsilon = (\rho, \beta)$. The first level of the exit tree E may be visualized as the diagram below,

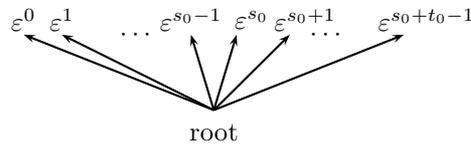


FIGURE 4. First level of an exit tree

where $\varepsilon^s = (\rho^s, \beta^s)$, ρ^s is the code of o_s for $s < s_0$ and the code of the empty set \emptyset for $s \geq s_0$, and β^s is the code of \emptyset for $s < s_0$ and the code of ι_{s-s_0} when $s \geq s_0$. The

enumeration of future S-disjunction will have their own versions “over” each exit. In other words, future S-disjunctions will use (ρ, β) as preconditions. Therefore over certain preconditions, we may enumerate further S-disjunctions, and over others, we may enumerate no more. In general, we obtain a stack of Seetapun disjunctions which generates the exit tree. A typical node ε in an exit tree is of the form

$$(\langle \rho_1 * \rho_2 * \cdots * \rho_h \rangle, \langle \beta_1 * \beta_2 * \cdots * \beta_h \rangle),$$

where (ρ_1, β_1) is an exit taken from the first S-disjunction δ_1 , followed by (ρ_2, β_2) which is an exit taken from the next S-disjunction δ_2 which uses (ρ_1, β_1) as precondition, and so on. Also for each i , one of ρ_i, β_i , but not both, may code the empty set \emptyset .

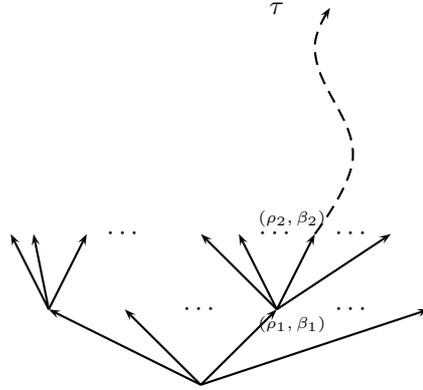


FIGURE 5. An example of an exit tree

For an exit ε of the above form, after discarding those that code \emptyset , we may assume that each ρ_s or β_t is the code of a blob o_s or a thread ι_t respectively. We let the sets specified by ε be $o_1 \cup o_2 \cup \cdots \cup o_h$ and $\iota_1 \cup \iota_2 \cup \cdots \cup \iota_h$, and denote them by ρ and β respectively, here we have abused the notations for the sake of simplicity.

We now return to the description of the enumeration of the exit tree E .

At stage $s + 1$, suppose that the exit tree $E[s]$ is given. Following the canonical order of exits on the tree $E[s]$, check each maximal branch ε (with specified sets ρ and β) on $E[s]$ to see if there exists an S-disjunction δ for $(B_r(\varepsilon), B_b(\varepsilon))$ with preconditions (ρ, β) , whose code is less than $s + 1$. If no such δ is found, do nothing. Otherwise, without loss of generality, we may assume that only one S-disjunction is enumerated, say over ε . Concatenate with ε all of (the codes of) the exits of δ , and also concatenate with ε pairs of the form (ρ, \emptyset) and (\emptyset, β) where ρ and β are exits in δ . Let the resulting tree be $E[s + 1]$. This ends the description of enumerating E .

The enumeration of E is clearly monotone. Since the height of the tree E is no more than $2|B|$ (each formula can be forced at most twice, once by red and the other by blue), BME_1 implies that the enumeration process will stop at some stage s^* . In other words, after stage s^* , no new S-disjunctions for B on any ε of $E[s^*]$ will be enumerated.

Given an amenable set A , by Lemma 4.6 there is an exit $\varepsilon^* = (\rho^*, \beta^*)$ that A may take from this maximal stack of S-disjunctions. Then the formulas forced by ε^* are exactly those that may be forced in a Σ_1^0 -way using ε^* through the enumeration of E .

For the remaining formulas in B not yet forced by ε^* , we now show that their negations can be forced in a similar way as in §4.2.

First continue to enumerate the sequence of blobs *over* ε^* , i.e., those \mathfrak{M}_0 -finite sets o with $\min o > \max \varepsilon^*$ such that $\mathfrak{M}_0 \models \psi_e(\rho^* * o)$ for some $e \in B_r(\varepsilon^*)$. Form the Seetapun tree S associated with this blob sequence \vec{o} . Then either by skipping the Seetapun tree S over ε^* (if it is \mathfrak{M}_0 -finite) or by thinning through the U -tree U_b for $B_b(\varepsilon^*)$,

$$U_b = \{\tau \in S : (\forall s < |\tau|)(\forall \iota \subseteq \tau)(\forall d \in B_b(\varepsilon^*)) \neg \varphi_d(s, \beta^* * \iota)\},$$

we force the remaining formulas in a Π_1^0 -way. This leads us to the formal definition of a notion of forcing which we next introduce.

4.5. Forcing Formalized.

Definition 4.7. The partial order $P = \langle p, \leq \rangle$ of forcing conditions p satisfies:

- (1) $p = (\varepsilon, U)$ where $\varepsilon = (\rho, \beta)$ is a pair of \mathfrak{M}_0 -finite increasing strings of the same length and U is an \mathfrak{M}_0 -infinite recursively bounded recursive increasing tree such that the maximum number appearing in either ρ or β is less than the minimum number appearing in U .
- (2) We say that $q = (\varepsilon_q, U_q)$ is *stronger* than $p = (\varepsilon_p, U_p)$ (written $p \geq q$) if and only if
 - (i) If $\varepsilon_p = (\rho_p, \beta_p)$ and $\varepsilon_q = (\rho_q, \beta_q)$, then $\rho_p \preceq \rho_q$ and $\beta_p \preceq \beta_q$;
 - (ii) There is a recursive extension-preserving map F from U_q to the set of \mathfrak{M}_0 -finite subtrees of U_p such that for all $\sigma_q \in U_q$, for all η which is a maximal branch of $F(\sigma_q)$, either η has no extensions in U_p or $\text{range}(\sigma_q) \subseteq \text{range}(\eta)$.

Similarly, we could work in $\mathfrak{M}_0[X]$ and relativize Definition 4.7 to X .

Given a Σ_1^0 -formula ψ with a free set variable \check{G} of the form $\exists s \varphi(s, \check{G})$, we say that p *red forces* ψ (written $p \Vdash_r \psi$) if

$$\mathfrak{M}_0 \models \exists s \leq \max(\rho_p) \varphi(s, \rho_p).$$

Define *blue forcing* similarly, except that ρ_p is replaced by β_p and \Vdash_r by \Vdash_b . Also we say that p *red forces* $\neg \psi$ (written $p \Vdash_r \neg \psi$) if p does not red force ψ and for all $\tau \in U_p$, for all $o \subseteq \tau$,

$$(*) \quad \mathfrak{M}_0 \models \forall s \leq \max(\tau) \neg \varphi(s, \rho_p * o).$$

Define $p \Vdash_b \neg \psi$ similarly, replacing ρ_p by β_p and “ p does not red force ψ ” by “ p does not blue force ψ ”. [For consistency of notations with S-disjunctions, we use ι in place of o in (*) above for $p \Vdash_b \neg \psi$.]

Let the Δ_2^0 -set A be fixed and let $B_n = \{\psi_e(\check{G}) : e \leq g(n)\}$. The generic set G will be obtained from an ω -sequence of conditions $\langle p_n : n \in \omega \rangle$ which we now construct. The sequence will have the property that $p_{n+1} \leq p_n$, $p_n = \langle \varepsilon_n, U_n \rangle$, $\varepsilon_n = (\rho_n, \beta_n)$ with $\rho_n \subseteq A$ and $\beta_n \subseteq \bar{A}$. Furthermore, for each n , either (a) for each $\psi_e \in B_n$, p_n red forces ψ_e or its negation, or (b) for each $\psi_e \in B_n$, p_n blue forces ψ_e or its negation. The construction is carried out in ω -many steps and recursively in \emptyset' modulo some parameters.

4.6. Construction of a Generic Set. We enumerate Σ_1^0 -formulas in blocks $B_n = \{\psi_e : e < g(n)\}$ where $n \in \omega$. Let $B_{-1} = \emptyset$. The enumeration of the sets B_n relies on \emptyset' which is able to compute the sequence $\langle g(n) : n \in \omega \rangle$.

Let the initial recursively bounded recursive increasing tree U_{-1} be the tree version of the identity function, i.e., for any $\sigma \in U_{-1}$, $\sigma(i) = i$ for all $i < |\sigma|$. In particular, the (only) branch of U_{-1} has range M_0 . Also let ε_{-1} be the pair of (codes of) empty strings and let the condition p_{-1} be $\langle \varepsilon_{-1}, U_{-1} \rangle$.

At stage $n+1$ ($n \geq -1$), suppose that we have defined conditions $p_i = \langle \varepsilon_i, U_i \rangle$ such that $\varepsilon_i = (\rho_i, \beta_i)$ with $\rho_i \subseteq A$ and $\beta_i \subseteq \overline{A}$, $p_{-1} \geq p_0 \geq \dots \geq p_i \geq \dots \geq p_n$ and either for each $\psi_e \in B_i$, $p_i \Vdash_r \psi_e$ or $p_i \Vdash_r \neg\psi_e$; or for each $\psi_e \in B_i$, $p_i \Vdash_b \psi_e$ or $p_i \Vdash_b \neg\psi_e$. Also, assume we have defined the sequence $\langle z(0), z(1), \dots, z(n) \rangle$ where $z(i) = 0$ (for thinning) or > 0 (for skipping). We now consider the block B_{n+1} .

First apply the enumeration procedure E described in §4.4 along each \mathfrak{M}_0 -finite branch of the tree U_n . Thus, instead of forming blobs by taking arbitrary numbers, we require the numbers to be drawn from (the range of) a node $\sigma \in U_n$. The procedure E will guarantee that $E(\sigma)$ will be an \mathfrak{M}_0 -finite tree. If λ were an \mathfrak{M}_0 -infinite path of U_n , then $E(\lambda)$ would be a tree which may or may not be \mathfrak{M}_0 -finite. In this sense, what we did in §4.4 was to enumerate $E(M_0)$.

Now we are poised to apply BME_1 . By construction, E specifies a monotone enumeration procedure. Since the height of any exit tree is uniformly bounded by $2|B_{n+1}| = 2g(n+1)$, there are only \mathfrak{M}_0 -finitely many expansionary levels on U_n .

For $\sigma \in U_n$, let $\#\sigma$ be the number of S-disjunctions enumerated using σ as a pool of numbers, which is also equal to the number of interior nodes in $E(\sigma)$. For each $a \in M_0$, let T_a be the subtree of U_n every node of which computes at most a many S-disjunctions. More precisely:

$$T_a = \{\sigma \in U_n : \#\sigma \leq a\}.$$

Then T_a is a recursive subtree of U_n . Since there are only \mathfrak{M}_0 -finitely many expansionary levels, it cannot be the case that for all $a \in M_0$, T_a is \mathfrak{M}_0 -finite. In other words, for some $a \in M_0$, T_a is \mathfrak{M}_0 -infinite.

Consider the set $\{a' : T_{a'} \text{ is } \mathfrak{M}_0\text{-finite}\}$, which is Σ_1^0 . By assumption, it is bounded. Let a_0 be the largest such a' which can be found using \emptyset' . In the case when the set is empty, let $a_0 = -1$. Then $a_0 + 1$ is the least number a such that T_a is \mathfrak{M}_0 -infinite.

Claim. There is a $\sigma_0 \in T_{a_0+1}$ such that $\#\sigma_0 = a_0 + 1$ and σ_0 has \mathfrak{M}_0 -infinitely many extensions in T_{a_0+1} .

Proof of Claim. Assume otherwise. Since T_{a_0} is \mathfrak{M}_0 -finite, there is an s where every σ of length s had computed at least $(a_0 + 1)$ -many S-disjunctions along σ . If every $\sigma \in T_{a_0+1}$ has only \mathfrak{M}_0 -finitely many extensions with $(a_0 + 1)$ -many S-disjunctions, let $s(\sigma)$ be the least bound for σ on the number of such extensions. Then $\sigma \mapsto s(\sigma)$ is recursive. By $B\Sigma_1^0$ there is a uniform bound on the set $\{s(\sigma) : \sigma \in T_{a_0+1}\}$. But this implies that T_{a_0+1} is \mathfrak{M}_0 -finite as well, a contradiction, proving this Claim.

Note that \emptyset' is able to compute this σ_0 . Once σ_0 is fixed, we may select an \mathfrak{M}_0 -infinite recursively bounded recursive increasing tree $\hat{U}_n \subseteq T_{a_0+1}$ such that every node in \hat{U}_n enumerates the same $(a_0 + 1)$ -many S-disjunctions over ε_n . The collection of these S-disjunctions will be maximal if at any future stages in the construction, the numbers involved in any computation of blobs or S-disjunctions

always form a subset of some nodes in \hat{U}_n . Let E_{n+1} be the exit tree corresponding to this maximal collection of S-disjunctions and let $\varepsilon_{n+1} = (\rho_{n+1}, \beta_{n+1})$ be the exit in E_{n+1} taken by A . In particular, $\rho_{n+1} \subseteq A$ and $\beta_{n+1} \subseteq \bar{A}$. This completes the construction for the “ Σ_1^0 -part” of forcing for the block B_{n+1} . [Note: ε_{n+1} and \hat{U}_n together handle the “ Σ_1^0 -part” of the block B_{n+1} .]

We now take up the matter of forcing the negation of ψ_e for $B_{n+1,r(\varepsilon_{n+1})}$ and $B_{n+1,b(\varepsilon_{n+1})}$, i.e. formulas not yet “positively forced”. This is resolved by a similar yet more delicate “ T_a analysis” than the one given above.

First, given a $\sigma \in \hat{U}_n$, define a sequence of σ -blobs to be blobs $o \subseteq \sigma$. For each σ in \hat{U}_n , let the $(n+1)$ -blobs enumerated by σ be the sequence of σ -blobs \vec{o} such that for each $o \in \vec{o}$, $\mathfrak{M}_0 \models \psi_e(\rho_{n+1} * o)$ for some $e \in B_{n+1,r(\varepsilon_{n+1})}$. This enumeration can be carried out uniformly for any node σ in the recursive tree \hat{U}_n in a coherent way, i.e., if $\sigma \preceq \sigma'$, then the sequence of $(n+1)$ -blobs enumerated by σ' end-extends the one by σ . Let $\#\sigma$ denote the number of $(n+1)$ -blobs enumerated by σ under such an enumeration.

Let $T_a = \{\sigma \in \hat{U}_n : \#\sigma \leq a\}$. We consider two cases. The case that we are in will be recorded by the $(n+1)$ -st bit $z(n+1)$.

Case 1 (Skipping for $(n+1)$ -blobs). There is an $a \in M_0$ for which T_a is \mathfrak{M}_0 -infinite. Fix the least such a . Set $z(n+1) =$ the least l such that $g(l) \geq a$ and $l > \max\{z(i) : i \leq n\}$.

Applying a similar argument as in the case of S-disjunctions, we use \emptyset' to find the number a_0 and a node $\sigma_0 \in \hat{U}_n$ such that $\#\sigma_0 = a_0 + 1$ and the tree

$$\tilde{U}_n = \{\sigma \in \hat{U}_n : \sigma_0 \preceq \sigma \text{ and } \#\sigma = a_0 + 1\}$$

is \mathfrak{M}_0 -infinite. Since every node $\sigma \in \tilde{U}_n$ is of the form $\sigma_0 * \tau$ for some τ , we may “discard the initial segment σ_0 ” thus form the new tree $U_{n+1} = \{\tau : \sigma_0 * \tau \in \tilde{U}_n\}$. It is clear that U_{n+1} is a recursively bounded recursive increasing tree since \tilde{U}_n is. Let $p_{n+1} = \langle \varepsilon_{n+1}, U_{n+1} \rangle$. By taking the recursive function $F : \tau \mapsto \{\sigma_0 * \tau\}$, we see that p_{n+1} extends p_n as forcing conditions. Moreover p_{n+1} red forces $\neg\psi_e$ for all $e \in B_{n+1,r(\varepsilon_{n+1})}$ in the sense that for any $\tau \in U_{n+1}$ no $o \subset \tau$ satisfies $\psi_e(\rho_{n+1} * o)$, and red forces ψ_e for all other $\psi_e \in B_{n+1}(\varepsilon_{n+1})$ through ρ_{n+1} . Notice that this form of skipping also involves some thinning of the tree \tilde{U}_n .

Case 2 (Thinning for $(n+1)$ -blobs). For all $a \in M_0$, T_a is \mathfrak{M}_0 -finite. We set $z(n+1) = 0$ to record this fact.

In this case, along any \mathfrak{M}_0 -infinite path λ on \hat{U}_n there will be \mathfrak{M}_0 -infinitely many $(n+1)$ -blobs enumerated, and any such λ would offer sufficient number of λ -blobs for building an \mathfrak{M}_0 -infinite Seetapun tree, thereby a new U -tree. However this would only be a recursive in λ tree, and λ need not be a recursive path. To overcome this difficulty, we make use of the \mathfrak{M}_0 -finiteness of the T_a 's to enumerate a recursively bounded recursive increasing tree S which will play the role of a Seetapun tree (indeed S is *almost* a Seetapun tree). We also define in parallel a recursive extension preserving function F from S to the set of \mathfrak{M}_0 -finite subtrees of \hat{U}_n satisfying Clause (ii) of Definition 4.7.

The recursive enumeration of S and F is as follows.

Stage -1 . Let $S[-1]$ be \emptyset (the root) and $F[-1](\emptyset)$ be the \mathfrak{M}_0 -finite subtree of \hat{U} which only contains its root.

Stage $v+1$. Suppose that we have enumerated $S[v]$ and $F[v]$ satisfying the following conditions:

- (1) For every maximal branch τ in $S[v]$, $F(\tau)$ is a subtree of T_v . Moreover, for any maximal branch $\sigma \in F(\tau)$, if σ is not a dead end in \hat{U}_n , then the range of τ is a subset of the range of σ .
- (2) Any maximal branch σ in T_v by definition enumerates v many σ -blobs, say $\vec{\sigma}$, provided it is not a dead end of \hat{U}_n . Then for any \mathfrak{M}_0 -finite choice function f for $\vec{\sigma}$, there is some maximal branch $\tau \in S[v]$ such that the range of τ equals the range of f . [Note that a Seetapun tree is essentially a tree built from collecting all \mathfrak{M}_0 -finite choice functions at every stage.]

First enumerate all maximal branches in T_{v+1} : say $\sigma_1, \sigma_2, \dots, \sigma_k$. By discarding the dead ends in \hat{U}_n if necessary, assume none of them is terminal. For each $\tau \in S[v]$, for each $\sigma \in F(\tau)$, if none of σ_i extends σ , then go to the next τ ; otherwise, for each σ_i extending σ , σ_i necessarily enumerates exactly one more $(n+1)$ -blob than σ , say o . For each number $x \in o$, concatenate it with τ (if it has not been concatenated by a σ_j where $j < i$) and enumerate σ_i into $F(\tau * x)$. Once this is done for each τ , $\sigma_i \in F(\tau)$ and $x \in \sigma_i$, let the resulting tree be $S[v+1]$ and for any $\sigma \in T_{v+1}$ if it is not enumerated into $F(\tau)$ for some τ , then it will never be so enumerated after stage $v+1$.

By construction, it is easy to see that for all v , $S[v+1]$ properly end-extends $S[v]$, F is a recursive extension preserving map, and condition (1) holds. We use induction on v to verify that $S[v+1]$ satisfies Condition (2). Let σ_i be a maximal branch in T_{v+1} as specified in the enumeration above. Since T_v is an initial segment of T_{v+1} , σ_i must end extend some σ in T_v . Thus the σ_i -blob sequence $\vec{\sigma}(\sigma_i)$ end-extends that of σ -blobs $\vec{\sigma}(\sigma)$, and every choice function for $\vec{\sigma}(\sigma_i)$ end-extends some choice function f for $\vec{\sigma}(\sigma)$. By induction hypothesis (2) on v , there is a maximal branch $\tau^- \in S_v$ such that the range of τ^- equals the range of f . By the construction, when we consider the node τ^- and σ , we will make $\tau^- * x \in S[v+1]$ for all x in the unique extra blob enumerated by σ_i . Hence (2) holds for $v+1$. Thus S and F satisfy Condition (2).

Define the subtree U_{n+1} of S by

$$U_{n+1} = \{\sigma \in S : (\forall t < \max(\sigma))(\forall \iota \subseteq \sigma)(\forall e \in B_{n+1,b}(\varepsilon_{n+1})) \neg \varphi_e(t, \beta_{n+1} * \iota)\}.$$

Clearly U_{n+1} is a recursively bounded recursive increasing tree because S is. We show that U_{n+1} is \mathfrak{M}_0 -infinite: Suppose that U_{n+1} is \mathfrak{M}_0 -finite. Then on the tree S , there is a level h such that every node σ of length h has a thread ι such that for some $e \in B_{n+1,b}(\varepsilon)$ $\mathfrak{M}_0 \models \psi_e(\beta_{n+1} * \iota)$. Choose v large enough such that $F(U_{n+1}) \subset T_v$. Let $\sigma \in T_v$ be a maximal branch, and consider the sequence of σ -blobs $\vec{\sigma}$. By Condition (2), the range of any choice function of $\vec{\sigma}$ also contains a thread, which means that $\sigma \in T_v$ enumerates an S-disjunction for the sets $B_{n+1,r}(\varepsilon)$ and $B_{n+1,b}(\varepsilon)$ with the preconditions $(\rho_{n+1}, \beta_{n+1})$. But this is a contradiction since \hat{U}_n does not enumerate any S-disjunctions. Moreover, since U_{n+1} is a subtree of S , $F \upharpoonright U_{n+1}$ also works for U_{n+1} , and therefore U_n, U_{n+1} , and $F \upharpoonright U_{n+1}$ satisfy Definition 4.7, condition 2 (ii). Let p_{n+1} be the forcing condition $\langle \varepsilon_{n+1}, U_{n+1} \rangle$. Then $p_n \geq p_{n+1}$ and p_{n+1} blue forces $\neg \psi_e$ for every $\psi_e \in B_{n+1,b}(\varepsilon_{n+1})$ and blue forces every other $\psi_e \in B_{n+1}$ through β_{n+1} .

This completes the construction at stage $n+1$. We summarize the discussion as a lemma for future reference.

Lemma 4.8. *At the end of stage $n+1$, we have one of the following two possibilities:*

- (a) *If skipping occurs, then for all $\psi_e(\check{G}) \in B_{n+1}$, either $p_{n+1} \Vdash_r \psi_e(\check{G})$ or $p_{n+1} \Vdash_r \neg\psi_e(\check{G})$. Furthermore, for any amenable set G , if $\rho_{n+1} \preceq G$ and every \mathfrak{M}_0 -finite initial segment of $G \setminus \rho_{n+1}$ is a subset of (the range of) some node in U_{n+1} , then forcing by p_{n+1} is equal to truth for G in the following sense: If $p_{n+1} \Vdash_r \psi_e(\check{G})$ then $\mathfrak{M}_0 \models \psi_e(G)$; and if $p_{n+1} \Vdash_r \neg\psi_e(\check{G})$ then $\mathfrak{M}_0 \models \neg\psi_e(G)$.*
- (b) *If thinning occurs, then the corresponding statement holds upon replacing r by b and ρ by β .*

Observe that save for the reference to the sequence $\langle z(n) : n \in \omega \rangle$, the entire construction may be carried out using \emptyset' as oracle. Now, since the sequence $\langle z(n) : n \in \omega \rangle$ is definable, it is coded on ω by an \mathfrak{M}_0 -finite set \hat{z} . Using \hat{z} as parameter, \emptyset' is able to retrace the steps in the construction and compute the sequence of conditions $\langle p_n : n \in \omega \rangle$.

4.7. Verification. We now extract from the “generic sequence” $\langle p_n \rangle$ a homogenous set G that is a low set contained in either A or \bar{A} . There are two cases to consider: Case 1. The set $\{n : z(n) = 0\}$ is unbounded in ω .

Let $G = \bigcup_{n \in \omega} \beta_n$. Then $G \subseteq \bar{A}$ and recursive in \emptyset' . Fix a Σ_1^0 -formula $\psi_e(\check{G})$. Let $n \in \omega$ be large enough such that $g(n+1) > e$ and $z(n+1) = 0$. By Lemma 4.8 (b), either $\psi_e(\check{G})$ or its negation is blue forced by p_{n+1} at the end of stage $n+1$. Furthermore, the construction guarantees that G end-extends β_{n+1} , and for all $m > n+1$, β_m is a subset of some node τ of U_{m-1} , thus a subset of $F_{m-n-1} \circ \cdots \circ F_{m-1}(\tau)$, where each F_i is the extension-preserving function of $p_{i+1} \leq p_i$. Thus by Lemma 4.8 (b) again, $\mathfrak{M}_0 \models \psi_e(G)$ or $\mathfrak{M}_0 \models \neg\psi_e(G)$ was determined by the time p_{n+1} is selected, which may be computed by \emptyset' with the help of \hat{z} . In other words, the Σ_1^0 -theory of G can be computed from \emptyset' , thus G is low.

To see that G is \mathfrak{M}_0 -infinite, we argue that the range of β_n is not empty for $z(n) = 0$, assuming that there are “new trivial formulas” such as $\exists x(a < x \wedge x \in \check{G})$ in every block that do not belong to any smaller block, where a is some appropriate parameter. If the range of β_n is empty, then $B_{n,b}(\varepsilon_{n-1}) = B_n$ throughout the construction with no need for update. Since n -blobs are \mathfrak{M}_0 -infinite (as $z(n) = 0$), there must be a moment when the blue side forces the trivial formulas to form an S-disjunction over ε_{n-1} , which would then add at least one point to the range of β_n .

Case 2. The set $\{n : z(n) = 0\}$ is bounded in ω .

Then from some n_0 onwards, the act of skipping for blobs always occurs. Let $G = \bigcup_{n \in \omega} \rho_n$. Then $G \subseteq A$ and is again recursive in \emptyset' . G is low by a similar argument by quoting Lemma 4.8 (a). It remains to show that G is \mathfrak{M}_0 -infinite. We show that the range of ρ_n for $n > n_0$ is not empty under the same assumption on trivial formulas. For any $n > n_0$, if the range of ρ_n is empty, then $B_{n,r}(\varepsilon_{n-1}) = B_n$ throughout the construction with no need for update. However, there must be blobs enumerated for the sake of trivial formulas, which means that the Seetapun tree over ε_{n-1} is \mathfrak{M}_0 -infinite. This implies that there is no skipping at step n of the construction, which is a contradiction.

5. COMPARING SRT_2^2 AND RT_2^2

5.1. Preserving Bounding for Iterated Monotone Enumerations.

Theorem 5.1. *Assume that X is a predicate on \mathfrak{M}_0 with the following properties.*

(H-i) $\mathfrak{M}_0[X]$ satisfies $B\Sigma_2$ and BME .

(H-ii) Every predicate on ω defined in $\mathfrak{M}_0[X]$ is coded on ω .

Suppose that A is $\Delta_2^0(X)$. There is an $\mathfrak{M}_0[X]$ -infinite G with the following properties.

- (i) $G \subseteq A$ or $G \subseteq \bar{A}$.
- (ii) G has unboundedly many elements in \mathfrak{M}_0 .
- (iii) In $\mathfrak{M}_0[X]$, G is low relative to X . Consequently, $\mathfrak{M}_0[X, G]$ satisfies $B\Sigma_2^0$.
- (iv) $\mathfrak{M}_0[X, G]$ satisfies BME .

Proof. Intuitively we want to apply a relativization to X of the construction in Theorem 4.1. However, preserving BME in the generic extension as specified in (iv) is essential to allowing iterations of the construction. The construction here parallels closely that in §4. We focus the discussion on preserving BME in $\mathfrak{M}_0[X, G]$.

Define a notion of forcing P as in Definition 4.7, but relative to X so that the U in a condition $p = \langle \varepsilon, U \rangle$ is now an X -recursively bounded increasing X -recursive tree. Construct an X' -definable sequence of forcing conditions $\{p_n : n < \omega\}$ such that $p_n = \langle \varepsilon_n, U_n \rangle$ and $p_n \geq p_{n+1}$. Suppose p_n is defined satisfying

- (1) $\varepsilon_n = (\rho_n, \beta_n)$ and $\rho_n \subseteq A, \beta_n \subseteq \bar{A}$;
- (2) There is a $c \in \{r, b\}$ such that all $\Sigma_1^0(X)$ -formulas ψ with parameters below $g(n)$, either $p_n \Vdash_c \psi$ or $p_n \Vdash_c \neg\psi$;
- (3) For $k \leq n$, let $BME_{k,n}$ denote BME_k relative to the predicate (X, \check{G}) restricted to the $g(n)$ -bounded, k -iterated monotone enumerations with parameters below $g(n)$. Then $BME_{k,n}$ holds in the following strong sense: For any instance $(V_i, E_i)_{1 \leq i \leq k}$ of $BME_{k,n}$, for any \mathfrak{M}_0 -finite subset Y of a string in U_n such that $\min Y > \max\{\rho_n, \beta_n\}$, no E_1 -expansionary level in V_1 relative to $(X, \rho_n * Y)$ (or $(X, \beta_n * Y)$, depending on whether U_n was obtained through skipping or thinning) is enumerated unless it was already enumerated relative to (X, ρ_n) (respectively, (X, β_n)).

The condition p_{n+1} has to satisfy the three requirements (1)–(3) with n replaced by $n + 1$. We achieve these in two steps. The first is to enumerate an exit tree E for U_n , following the construction in Theorem 4.1, for $\Sigma_1^0(X)$ -formulas with free set variable \check{G} and parameters below $g(n + 1)$. Apply BME_1 relative to X to conclude that there is a greatest ℓ where ℓ is an E -expansionary level in U_n . Select an exit $(\rho'_{n+1}, \beta'_{n+1})$ from the tree, with $\rho_n \preceq \rho'_{n+1} \subseteq A, \beta_n \preceq \beta'_{n+1} \subseteq \bar{A}$, and an X -recursively bounded increasing X -recursive tree U'_n such that $p = \langle \varepsilon', U'_n \rangle$ is a forcing condition stronger than $p_n = \langle \varepsilon_n, U_n \rangle$, where $\varepsilon' = (\rho'_{n+1}, \beta'_{n+1})$. The tree U'_n is obtained through skipping or thinning of U_n , and there is a $c \in \{r, b\}$ such that for any $\Sigma_1^0(X)$ -formula with parameters below $g(n + 1)$, either $p \Vdash_c \psi$ or $p \Vdash_c \neg\psi$. The second step in the construction is to define p_{n+1} so that it is stronger than p and satisfies (3) (with n replaced by $n + 1$). This ensures that p_{n+1} also satisfies (1) and (2). For this, we work within U'_n and address the problem of establishing every instance of the \mathfrak{M}_0 -finite collection $BME_{k,n+1}$ relative to the predicate (X, G) for $k \leq n + 1$.

Let $C = \{(V_{e,i}, E_{e,i})_{1 \leq i \leq k(e)} : e \leq e_0\}$ be the collection of all $g(n + 1)$ -bounded, k -iterated monotone enumerations relative to (X, G) with parameters below $g(n + 1)$ and $k \leq n + 1$. The idea is to associate C with a $g(n + 1)$ -bounded, $n + 2$ -iterated monotone enumeration relative to X and apply BME_{n+2} to conclude that requirement (3) is satisfied. We first make the following claim.

Claim. . There exists a $g(n+1)$ -bounded, $n+1$ -iterated monotone enumeration $(\hat{V}_i, \hat{E}_i)_{1 \leq i \leq n+1}$ such that

- For each $e \leq e_0$, i , σ and τ , $0 * e * \sigma \in \hat{V}_i(\tau)$ if and only if $\sigma \in V_{e,i}(\tau)$, and $\tau \in \hat{E}_i(0 * e * \sigma)$ if $\tau \in E_{e,i}(\sigma)$.

Proof of Claim. We “amalgamate” the enumeration of elements in C into a $(\hat{V}_i, \hat{E}_i)_{1 \leq i \leq n+1}$ as follows: \hat{V}_1 has 0 as root and has e_0 -many branches at level 1. A copy of $V_{e,1}$ “sits on top of the e branch” beginning at level 2. Thus $0 * e * \sigma \in \hat{V}_1$ if and only if $\sigma \in V_{e,1}$. For $1 < i \leq n+1$, \hat{V}_i will again have root 0 and e_0 -many branches at level 1. For each $e \leq e_0$, if $i > k(e)$ then \hat{V}_i has no extension above the string $0 * e$. Otherwise, a copy of $V_{e,i}$ sits on top of the string, so that $0 * e * \sigma \in \hat{V}_i$ if and only if $\sigma \in V_{e,i}$.

Define \hat{E}_i as given in the statement of the Claim. The enumeration of \hat{E}_i from \hat{V}_i , and that of \hat{V}_{i+1} from \hat{E}_i is carried out “componentwise” by following the algorithm for $(V_{e,i}, E_{e,i})_{1 \leq i \leq k(e)}$ for each component e . Then $(\hat{V}_i, \hat{E}_i)_{1 \leq i \leq n+1}$ is a $g(n+1)$ -bounded, $n+1$ -iterated monotone enumeration, proving the Claim.

Let $\psi(\ell, X, \check{G})$ be the $\Sigma_1^0(X)$ -formula saying that there is a stage s and a $(V_{e,i}, E_{e,i}) \in C$ such that $(V_{e,i}, E_{e,i})$ has ℓ -many $E_{e,1}$ -expansionary levels in $V_{e,1}$ relative to (X, \check{G}) . Since the enumeration of an $E_{e,1}$ -expansionary level in $V_{e,1}$ using blobs $\rho' * o$ for the set variable \check{G} is a $\Sigma_1^0(X)$ -process, we may subject the formula $\psi(\ell, X, \check{G})$ to an “S-disjunction analysis”. Begin by setting $\ell = 1$ and enumerate along each string σ in U'_n an S-disjunction $\delta_1(\sigma)$ and accompanying exit tree $E_1(\sigma)[s]$ using ε' as precondition. Thus every exit ρ or β in $E_1(\sigma)[s]$ generates an $E_{e,1}$ -expansionary level in $V_{e,1}$ for some $e \leq e_0$, relative to $(X, \rho'_{n+1} * \rho)$ or $(X, \beta'_{n+1} * \beta)$ respectively.

In general, suppose $\sigma \in U'_n$ and at the end of s steps of computation there are ℓ , but not $\ell+1$ -many, $E_1(\sigma)$ -expansionary levels in U'_n along σ arising from the enumeration of S-disjunctions $\delta_1(\sigma), \dots, \delta_\ell(\sigma)$, as in §4. If $s < |\sigma|$, compute $|\sigma|$ -steps to search for the next S-disjunction $\delta_{\ell+1}(\sigma)$ for ψ along σ using exits in $E_1(\sigma)[|\sigma|]$. Taking $(\hat{V}_i, \hat{E}_i)_{1 \leq i \leq n+1}$ as in the Claim, this implies that

$$\langle (U'_n, E_1), (\hat{V}_i, \hat{E}_i)_{1 \leq i \leq n+1} \rangle$$

is a $g(n+1)$ -bounded, $n+2$ -iterated monotone enumeration relative to X . By BME_{n+2} relative to X , there is a maximum ℓ , denoted ℓ^* , of E_1 -expansionary levels in U'_n . For each $\sigma \in U'_n$, let $\#\sigma$ be the largest number ℓ such that $\delta_\ell(\sigma)$ is defined in $|\sigma|$ -steps of computation. Let

$$T_\ell = \{\sigma \in U'_n : \#\sigma \leq \ell\}.$$

Then T_{ℓ^*} is unbounded. By an argument similar to that for the Claim in §4.6, there is a $\sigma^* \in T_{\ell^*}$ such that the subtree of T_{ℓ^*} extending σ^* is unbounded and there are ℓ^* -many S-disjunctions enumerated along σ^* and no new S-disjunctions along any string in T_{ℓ^*+1} extending σ^* . Let ε_{n+1} be the pair $(\rho_{n+1}, \beta_{n+1})$ of maximal exits in $E_1(\sigma^*)$ with $\rho_{n+1} \subseteq A$ and $\beta_{n+1} \subseteq \bar{A}$.

Let U^* be the part of T_{ℓ^*} above σ^* , so that all the numbers appearing in U^* are greater than $\max \sigma^*$. On U^* enumerate an increasing sequence of blobs o such that $\min o > \max \rho_{n+1}$ and $\psi(\ell^* + 1, X, \rho_{n+1} * o)$ holds. We conduct a further T_a analysis. For $\tau \in U^*$, let $\#\tau$ be the number of such blobs enumerated along τ after

$|\tau|$ steps of computation. Let

$$T_a = \{\tau \in U^* : \#\tau \leq a\}.$$

There are two cases to consider.

Case 1. (Skipping). There is an a such that T_a is unbounded.

Then as in the proof of the Claim in §4.6, there is a τ^* in U^* such that it has unboundedly many extensions in U^* and no blobs are enumerated along any such extension that are not already enumerated along τ^* . Call this subtree $U_{\tau^*}^*$.

We do skipping over τ^* and define U_{n+1} to be the part of $U_{\tau^*}^*$ above τ^* , meaning the least number appearing in U_{n+1} is greater than $\max \tau^*$. Then $p_{n+1} = (\varepsilon_{n+1}, U_{n+1})$ satisfies (1) and (2). We show that (3) holds when n is replaced by $n+1$. Let Y be \mathfrak{M}_0 -finite and a subset of a string in U_{n+1} . Each instance of $BME_{k,n+1}$ is $(V_{e,i}, E_{e,i})_{1 \leq i \leq k(e)}$ for some $e \leq e_0$. The choice of the condition p_{n+1} ensures that any $E_{e,1}$ -expansionary level in $V_{e,1}$ relative to $(X, \rho_{n+1} * Y)$ is enumerated relative to (X, ρ_{n+1}) . Thus (3) is satisfied.

Case 2. (Thinning). T_a is \mathfrak{M}_0 -finite for each a .

We do thinning of U^* by following the construction in §4.6 (conditions (1) and (2) before Lemma 4.8) to use the blobs o in U^* to form the (*almost* Seetapun) X -recursively bounded increasing X -recursive) tree S , and then define

$$U_{n+1} = \{\tau \in S : (\forall \iota \subseteq \tau) \neg \psi(\ell + 1, X, \beta_{n+1} * \iota)\}.$$

Then $(\varepsilon_{n+1}, U_{n+1})$ is the condition p_{n+1} . Furthermore, p_{n+1} satisfies (1), (2). The proof of (3) is by the same argument as in Case 1 above, except that we replace $\rho_{n+1} * Y$ by $\beta_{n+1} * Y$.

Finally, note that the data on skipping (and “how far”) or thinning for U_n , $n < \omega$, is X -definable and coded on ω by the same method used in Theorem 4.1. Hence the entire construction may be carried out recursively in X' .

Define $G = \bigcup_n \rho_n$ or $\bigcup_n \beta_n$ as appropriate. We wish to argue that $\mathfrak{M}_0[X, G] \models B\Sigma_2^0$, G is low relative to X and (i)–(iv) are satisfied. We verify (iv) for the case when $G = \bigcup_n \beta_n$. Let $(V_i, E_i)_{1 \leq i \leq k}$ be an instance of $BME_{k,n}$ relative to (X, G) . We claim that all the E_1 -expansionary levels in V_1 are enumerated relative to (X, β_n) and therefore there are only \mathfrak{M}_0 -finitely many such levels. Now by construction, any initial segment of the set $\{x \in G : x > \max \beta_n\}$ is contain as a subset of some string in U_n . Since (3) is satisfied, the claim follows. A similar argument holds for the case when $G = \bigcup_n \rho_n$. Note that (i) is immediate and that (ii) and (iii) may be verified as in the proof of Theorem 4.1. \square

5.2. A Model of SRT_2^2 . We are now ready to prove Theorem 2.2. Begin with \mathfrak{M}_0 as the ground model and let $A_1, A_2, \dots, A_i, \dots$ be a countable list of all Δ_2^0 -sets. Begin by setting $G_0 = \emptyset$. For $i \geq 1$, repeatedly apply Theorem 5.1 by letting $X = (G_0, \dots, G_{i-1})$ to obtain an unbounded G_i such that

- (1) G_1 is low;
- (2) $G_i \subseteq A_i$ or $G_i \subseteq \overline{A_i}$;
- (3) G_{i+1} is low relative to (G_1, \dots, G_i) ;
- (4) $\mathfrak{M}_0[G_1, \dots, G_i] \models BME$.

For $i = 1$, (1)–(4) hold for G_1 by Theorem 5.1 with $X = \emptyset$. Suppose G_1, \dots, G_i satisfy (1)–(4). Then BME_k relative to (G_1, \dots, G_{i+1}) is reducible to BME_{k+1} for (G_1, \dots, G_i) which is true by induction. Thus (G_1, \dots, G_{i+1}) satisfies BME_k for all k .

Let \mathcal{S} be the closure under the join operation and Turing reducibility of the set $\{G_i : i \in \mathbb{N}\}$. Then $\mathfrak{M} = \langle M_0, \mathcal{S} \rangle$ is an M_0 -extension of \mathfrak{M}_0 and is a model of $RCA_0 + B\Sigma_2^0$ that satisfies $SRT_2^2 + \neg I\Sigma_2^0$. Furthermore, since every member of \mathcal{S} is low, by Proposition 2.4, \mathfrak{M} is not a model of RT_2^2 .

5.3. SRT_2^2 and WKL_0 . We now strengthen Theorem 2.2 and prove Theorem 2.7: There is a model of $RCA_0 + B\Sigma_2^0 + SRT_2^2 + WKL_0$ that is not a model of RT_2^2 . We begin with a lemma.

Lemma 5.2. *For any low set X such that $\mathfrak{M}_0[X] \models BME$, any unbounded X -recursive subtree W of the full binary tree has an unbounded path G that is low relative to X such that $\mathfrak{M}_0[X, G] \models BME$.*

Proof. Let W be such a tree. We build an unbounded path G through W that satisfies the requirements. This is carried out in ω -many steps.

Step 0: Let $W_0 = W$ and $\nu_0 = \emptyset$.

Step $n + 1$: Suppose $W_n \subseteq W$ is unbounded, X -recursive and every string in W_n extends the string ν_n defined at end of stage n . On W_n first follow the Low Basis Theorem construction of Jockusch and Soare (1972) (see also Hájek (1993) on constructing a path that preserves $B\Sigma_2^0$) to obtain a string ν'_{n+1} in W_n extending ν_n , such that the subtree W'_{n+1} of W_n consisting of strings extending ν'_{n+1} is unbounded, and for any $\Sigma_1^0(X)$ -formula ψ with a free set variable \check{G} and parameters below $g(n + 1)$, either $\psi(\nu'_{n+1})$ holds or no string ν on W'_{n+1} satisfies $\psi(\nu)$.

Now we define an unbounded X -recursive subtree W_{n+1} contained in W'_{n+1} to guarantee $\mathfrak{M}_0 \models BME_{k,n+1}$ for $k \leq n + 1$. By the Claim in Theorem 5.1, it is sufficient to consider the $g(n + 1)$ -bounded, $n + 1$ -iterated monotone enumeration $(\hat{V}_i, \hat{E}_i)_{1 \leq i \leq n+1}$. Given a string $\nu \in W'_{n+1}$ and $t < |\nu|$, we say that \hat{V}_1 relative to $(X \upharpoonright |\nu|, \nu)$ is conservative over \hat{V}_1 relative to $(X \upharpoonright t, \nu \upharpoonright t)$ if they enumerate the same $\hat{E}_{1,s}$ -expansory levels after $|\nu|$ steps of computation. Let

$$\hat{W}_{n+1,t} = \{\nu \in W'_{n+1} : |\nu| > t \wedge [\hat{V}_1 \text{ relative to } (X \upharpoonright |\nu|, \nu) \text{ is conservative over } \hat{V}_1 \text{ relative to } (X \upharpoonright t, \nu \upharpoonright t)]\}.$$

Now $W_{n+1,t}$ is not \mathfrak{M}_0 -finite for every t , since this would contradict the assumption of BME_{n+1} for $(\hat{V}_i, \hat{E}_i)_{1 \leq i \leq n+1}$. Thus choose the least t , denoted t_{n+1} , such that $W_{n+1,t}$ is unbounded. Define $\nu_{n+1} \succeq \nu'_{n+1}$ to be the least string in $W_{n+1,t_{n+1}}$ such that the subtree of W'_{n+1} all of whose strings extend ν_{n+1} is unbounded. Let W_{n+1} be the subtree.

Let $G = \bigcup_n \nu_n$. Then G is a path on W . Furthermore, the map $n \mapsto t_n$ is recursive in X' . Thus X' is able to compute G correctly, implying that G is low relative to X . Finally, for each n , t_n pinpoints where the bound of any $g(n)$ -bounded, k -iterated monotone enumeration with $k \leq n$ and parameters in $g(n)$ is located. Thus BME holds relative to (X, G) . \square

Proof of Theorem 2.7. Let $A_1, W_1, A_2, W_2, \dots, A_i, W_i, \dots$ be a list in order type ω of all the Δ_2^0 -sets and unbounded recursively bounded increasing recursive trees relative to a low set. Let $G_0 = \emptyset$. Define low sets G_i , $1 \leq i < \omega$, such that

- (1) For $i \geq 0$, G_{2i+1} is contained in either A_i or $\overline{A_i}$;
- (2) For $i \geq 1$, G_{2i} is a path on W_i ;

- (3) G_1 is low and G_{i+1} is low relative to (G_1, \dots, G_i) ;
- (4) For $i \geq 1$, $\mathfrak{M}_0[G_1, \dots, G_i] \models BME$.

Let \mathcal{S} be the closure of $\{G_i : 1 \leq i < \omega\}$ under join and Turing reducibility. Then $\langle M_0, \mathcal{S} \rangle \models RCA_0 + SRT_2^2 + WKL_0 + B\Sigma_2^0$, and both $I\Sigma_2^0$ as well as RT_2^2 (by Proposition 2.4) fail in the model.

6. CONCLUSION

We end with three questions for further investigation and some comments about them.

Question 6.1. *Is every ω -model of SRT_2^2 also a model of RT_2^2 ?*

Rephrased, Question 6.1 asks whether there is a nonempty subset \mathcal{S} of $2^{\mathbb{N}}$ such that (1) \mathcal{S} is closed under join and relative computation, (2) for every X in \mathcal{S} and every $\Delta_2^0(X)$ predicate P , there is an infinite set G in \mathcal{S} all or none of whose elements satisfy P , and (3) there is an X in \mathcal{S} and an X -recursive f coloring the pairs of natural numbers with two colors such that there is no infinite f -homogeneous set in \mathcal{S} . The rephrasing of Question 6.1 makes it clear that it is a recursion theoretic question about subsets of \mathbb{N} .

If it had been the case that RT_2^2 were provable in $RCA_0 + SRT_2^2$, then the casting of Question 6.1 in the language of subsystems of second order arithmetic would have increased our understanding of the implication from SRT_2^2 to RT_2^2 . Namely, the proof of the implication would have worked over a weak base theory. By Theorem 2.2, there is no such formal implication, but our interest in the question is not decreased. In fact, the opposite is true. The truth of the relationship between the two principles lies in the recursion theoretic formulation. What we know now from the formalized problem should inform us as to what means may be needed to penetrate the matter fully.

Question 6.2. *Are there natural axiomatizations within first order arithmetic for the first order consequences of the second order principles SRT_2^2 and RT_2^2 ?*

We do not have a recursion theoretic rephrasing of Question 6.2. By its nature, recursion theory takes \mathbb{N} as the basis on which to erect the hierarchy of definability and does not allow for the variation of arithmetic truth. So, we are led naturally to formal systems and decisions as to which parts of the theory of \mathbb{N} should be preserved as base theory and which should be counted as non-trivial consequences of stronger principles. In the present setting, $I\Sigma_1^0$ was taken as given and the rest remained to be proven.

Let $FO(SRT_2^2)$ and $FO(RT_2^2)$ denote the consequences of these theories within first order arithmetic. Working over RCA_0 , our current state of knowledge is as follows.

$$\begin{aligned} B\Sigma_2^0 &\subseteq FO(SRT_2^2) \subsetneq I\Sigma_2^0 \\ B\Sigma_2^0 &\subseteq FO(RT_2^2) \subseteq I\Sigma_2^0 \end{aligned}$$

It is possible that the appearance of BME in our construction of \mathfrak{M}_0 was a necessary precondition to expanding \mathfrak{M}_0 by sets to a model of SRT_2^2 . It is worth explicitly raising the simplest instance of that issue.

Question 6.3. *Does either of $RCA_0 + SRT_2^2$ or $RCA_0 + RT_2^2$ prove that if E has a bounded monotone enumeration then the enumeration of E is finite?*

By Proposition 3.5, an affirmative answer is consistent with the known upper bound on $FO(RT_2^2)$. By Proposition 3.6, an affirmative answer for either SRT_2^2 or RT_2^2 would separate the first order consequences of that theory from $B\Sigma_2^0$.

When we approach questions concerning subsystems of second order arithmetic like 6.1, we have a well-developed set of tools, including forcing and priority methods. In comparison, there are remarkably few methods in place to investigate questions like 6.2 or 6.3. It seems strange that this area should be so little developed, since quantifying the implications from familiar and fruitful properties of the infinite to properties of the finite is a natural application of mathematical logic, especially of recursion theory.

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