

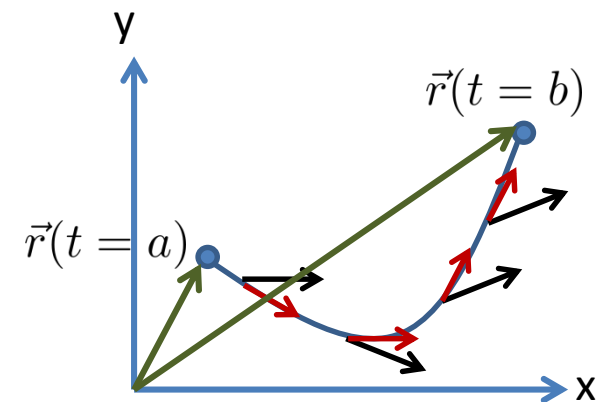
Section 16:4 Green's theorem

For 1D calculus, we had that $\int_a^b \frac{df}{dx} dx = f(b) - f(a)$

[The integral of the derivative of a function is just the difference between its values at the two endpoints]

Theorem: In more dimensions, we have that

$$\int_C \nabla f \cdot d\vec{r} = f[\vec{r}(t=b)] - f[\vec{r}(t=a)]$$



Conservative: There exists a scalar $f(x,y)$ such that $\nabla f = \vec{F}(x,y)$

The vector field $\vec{F} = (P, Q)$ is path-independent

So now we've got:
Given a vector field (P,Q)

$$\int_C \vec{F} \cdot d\vec{r} = 0 \quad \text{Over any closed curve } C$$

$$\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$$

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So now we've got:
Given a vector field (P,Q)

$\int_C \vec{F} \cdot d\vec{r} = 0$ Over any closed curve C



$$\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$$

Example: show that the vector field $\vec{F} = (xy^2, yx^2)$ is path-independent

$$P_y = 2xy \quad Q_x = 2xy \quad \text{so yes!!!}$$

Example: Suppose $(P,Q) = (3+2xy, x^2-3y^2)$.

(1) Is there a function $f(x,y)$ such that $\vec{F} = (P, Q) = \nabla f$

(2) Find that function $f(x,y)$

(3) Evaluate $\int_C \vec{F} \cdot d\vec{r}$ over the curve $C = \vec{r}(t) = e^t \sin t \vec{i} + e^t \cos t \vec{j}$, $0 \leq t \leq \pi$

Answer to #1

We check to see if $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$ $\frac{\partial P}{\partial y} = 2x$ and $\frac{\partial Q}{\partial x} = 2x$ ✓

Answer to #2

We try to build $f(x,y)$ through integration. We require that $f_x = P$ and $f_y = Q$

$$f_x = P \implies \int f_x dx = \int P(x, y) dx \implies f(x, y) = \int (3 + 2xy) dx = 3x + x^2 y + g(y)$$

So $f_y = x^2 + \frac{dg(y)}{dy}$ which must satisfy $f_y = Q$ which $= x^2 - 3y^2$ so $dg(y)/dy = -3y^2$ so $g(y) = -y^3$ so $f(x,y) = 3x + x^2 y - y^3 + C$

Since the vector field comes from a gradient, then we need only evaluate at endpoints

$$\begin{aligned} \int_C \nabla f \cdot d\vec{r} &= f[\vec{r}(t = b)] - f[\vec{r}(t = a)] = f(0, -e^\pi) - f(0, 1) \\ &= (3x + x^2 y - y^3) \Big|_{(0, -e^\pi)} - (3x + x^2 y - y^3) \Big|_{(0, 1)} = e^{3\pi} - (-1) \end{aligned}$$

So, let's think about these things in terms of the “dimensions in which they live”

1D input space:
 $f(x): \mathbb{R}^1 \rightarrow \mathbb{R}^1$
Blue axis

Integrate over 1D object
(purple line segment —)

Boundary ● is a 0D object

Fundamental theorem
 $\int_a^b \frac{df}{dx} dx = f(b) - f(a)$
Integral of **derivative** over **object**
= **function** over **object boundary**

2D input space:
 $f(x,y): \mathbb{R}^2 \rightarrow \mathbb{R}^1$
Blue axes

Integrate over 1D domain
(purple curve —)

Boundary ● is a 0D object

Fundamental theorem
 $\int_{t_1}^{t_2} \nabla f \cdot d\vec{r} = f[\vec{r}(t_2)] - f[\vec{r}(t_1)]$
Integral of **derivative** over **object**
equals **function** over **boundary**

Can we go higher?

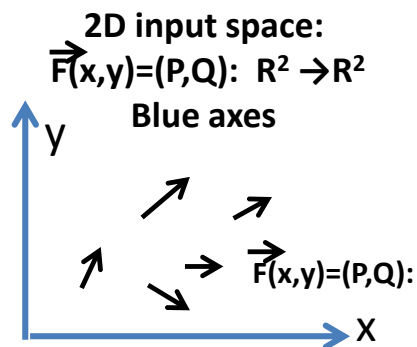
2D input space:
 $\vec{F}(x,y)=(P,Q): \mathbb{R}^2 \rightarrow \mathbb{R}^2$
Blue axes

Integrate over 2D domain
(purple region)

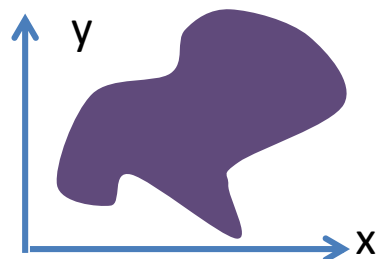
Boundary — is a 1D domain

A fundamental theorem?
 $\iint [\text{derivative of } \vec{F}] dx dy = \oint \text{vector field } \vec{F} \cdot d\vec{C}$
Integral of “derivative” over object
equals function over boundary
YES!!! Green's Theorem

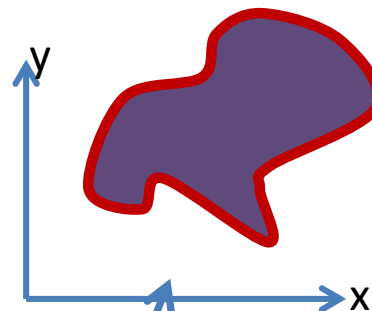
Can we go higher?



Integrate over 2D domain
 (purple region)



Boundary is a 1D domain



A fundamental theorem?

$$\iint [\text{derivative of } \vec{F}] \, dx dy = \int \text{vector field } \vec{F} \cdot d\vec{C}$$

Integral of "derivative" over object equals function over boundary

YES!!! Green's Theorem

Time for Green's theorem

Claim: Suppose $\vec{F} = (P, Q) = P\vec{i} + Q\vec{j}$

Let C be closed curve surrounding a region A

Then:

$$\int_C \vec{F} \cdot d\vec{r} = \int_C P dx + Q dy = \iint_A \left[\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right] dx dy$$

Wow!

The line integral of $\vec{F} \cdot d\vec{r}$ over the boundary equals the double integral of

$$\left[\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right] \quad \text{over the interior}$$

Green's Theorem

$$\int_C \vec{F} \cdot d\vec{r} = \int_C Pdx + Qdy = \int \int_A \left[\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right] dxdy$$

Conservative: There exists a scalar $f(x,y,z)$ such that $\nabla f = \vec{F}(x,y,z)$



The vector $\vec{F} = (P, Q)$ path-independent



Recall the loop of equalities:

$$\int_C \vec{F} \cdot d\vec{r} = 0 \quad \text{Over any closed curve } C$$



$$\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$$

I hope you see why this is so satisfying:

(1) If $\int_C \vec{F} \cdot d\vec{r} = 0$ then the above loop says $\left[\frac{\partial Q}{\partial x} = \frac{\partial P}{\partial y} \right]$ which works with Green's

(2) If $\left[\frac{\partial Q}{\partial x} = \frac{\partial P}{\partial y} \right]$ then the area integral integrates to zero, so that means $\int_C \vec{F} \cdot d\vec{r} = 0$

**Green's
Theorem**

$$\int_C \vec{F} \cdot d\vec{r} = \int_C P dx + Q dy = \int \int_A \left[\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right] dx dy$$

Before proving it, let's use it:

Example 1: Let C be the unit circle. Let $\vec{F} = \frac{-y}{2}\vec{i} + \frac{x}{2}\vec{j}$ Find $\int_C \vec{F} \cdot d\vec{r}$

(the hard way:) let's do the path integral $\int_C \vec{F} \cdot d\vec{r}$

(1) Parameterize the unit circle: $C(t) = (\cos t, \sin t)$, $0 \leq t \leq 2\pi$

(2) We have that $\vec{r}(t) = (\cos t, \sin t)$, so $\vec{r}'(t) = (-\sin t, \cos t)$

$$\begin{aligned} \text{(3) So } \int_C \vec{F} \cdot d\vec{r} &= \int_0^{2\pi} \left(\frac{-y}{2}, \frac{x}{2} \right) \cdot \vec{r}'(t) dt \\ &= \int_0^{2\pi} \left(\frac{-\sin t}{2}, \frac{\cos t}{2} \right) \cdot (-\sin t, \cos t) dt = \frac{1}{2} \int_0^{2\pi} (\sin^2 t + \cos^2 t) dt \\ &= \frac{1}{2} \int_0^{2\pi} dt = \pi \end{aligned}$$

(the easy way:) let's do the area integral $\int \int_A \left[\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right] dx dy$

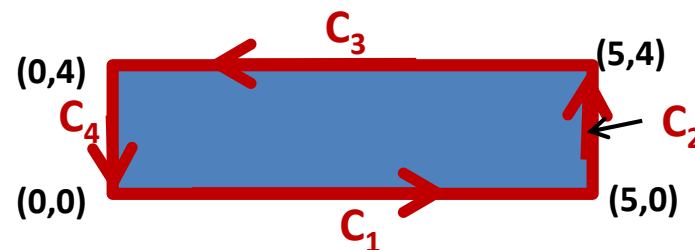
$$\int \int_A \left[\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right] dx dy = \int \int_A \left[\frac{1}{2} - \frac{-1}{2} \right] dx dy = \int \int_{unitdisk} 1 dx dy = \pi(1)^2$$

Green's Theorem

$$\int_C \vec{F} \cdot d\vec{r} = \int_C Pdx + Qdy = \iint_A \left[\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right] dxdy$$

Example 2: Another one: Let C bound the rectangle:

$$\vec{F} = y^2 \vec{i} + x^2 y \vec{j} \quad \text{Find } \int_C \vec{F} \cdot d\vec{r}$$



(the Green's theorem way:) let's do the area integral $\left[\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right] = 2xy - 2y$

$$\begin{aligned} \iint_A \left[\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right] dxdy &= 2 \int_0^5 \int_0^4 (xy - y) dy dx = 2 \int_0^5 \left[\frac{xy^2}{2} - \frac{y^2}{2} \right]_0^4 dx = 2 \int_0^5 (8x - 8) dx \\ &= 16 \int_0^5 (x - 1) dx = 16 \left[\frac{x^2}{2} - x \right]_0^5 = 16 \left(\frac{25}{2} - 5 \right) = (200 - 80) = 120 \end{aligned}$$

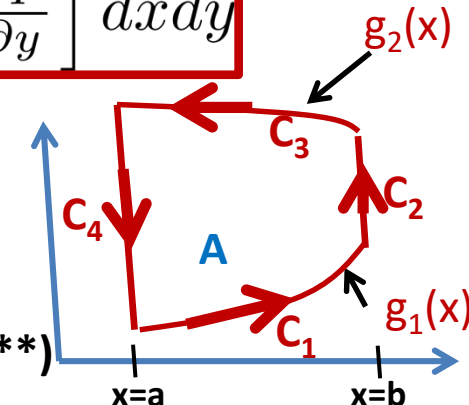
(the path integral way)

$$\begin{aligned} \int_C \vec{F} \cdot d\vec{r} &= \int_C [Pdx + Qdy] = \int_{C_1} Pdx + \int_{C_2} Qdy + \int_{C_3} Pdx + \int_{C_4} Qdy \\ &= \int_{C_1} y^2 dx + \int_{C_2} x^2 y dy + \int_{C_3} y^2 dx + \int_{C_4} x^2 y dy \\ &= \text{[0 because } y=0\text{]} + \int_0^4 25y dy + \int_5^0 16dx + \text{[0 because } x=0\text{]} \\ &= \left[\frac{25y^2}{2} \right]_0^4 + \left[16x \right]_5^0 = 25 * 16/2 + (-80) = 120 \end{aligned}$$

Green's Theorem

$$\int_C \vec{F} \cdot d\vec{r} = \int_C Pdx + Qdy = \iint_A \left[\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right] dxdy$$

Hard to prove in general: let's do it for region with $g_1(x)$ bottom curve and $g_2(x)$ top curve



(1) If we can show that

$\int_C Pdx = \iint_A -\frac{\partial P}{\partial y} dxdy$ (Eqn.*) and $\int_C Qdy = \iint_A \frac{\partial Q}{\partial x} dxdy$ (Eqn.**)
then we are done (hint: add them together and you get Green's theorem)

(2) First we do the area integral in Eqn. *:

$$\iint_A -\frac{\partial P}{\partial y} dxdy = \int_{x=a}^{x=b} \left[\int_{g_1(x)}^{g_2(x)} -\frac{\partial P}{\partial y} dy \right] dx = - \int_a^b [P(x, g_2(x)) - P(x, g_1(x))] dx$$

(3) Now we do the path integral in Eqn. *:

$$\int_C Pdx = \int_{C_1} Pdx + \int_{C_2} Pdx + \int_{C_3} Pdx + \int_{C_4} Pdx$$

$$\int_a^b P(x, g_1(x))dx + \int_b^a P(x, g_2(x))dx = \int_a^b [P(x, g_1(x)) - P(x, g_2(x))] dx$$

Second and fourth integrals are zero, since $dx = 0$ on those sides

Equal!

(4) Similar proof for Eqn. ** shows the other one. So proved!

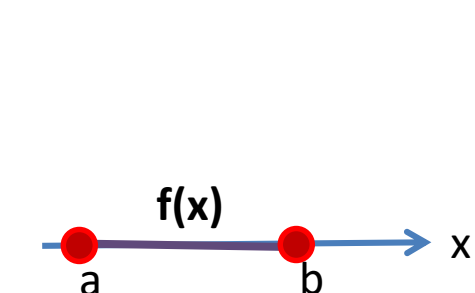
16.5: Curl and Divergence

So far, we have established three theorems that relate the integral of the derivative of a function over a region to the values of the function on the boundary:

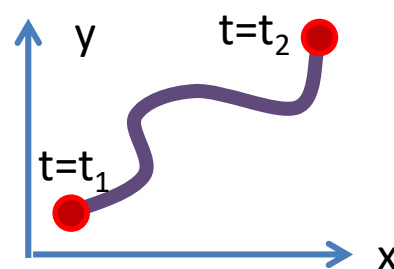
Boundary ● is a 0D object

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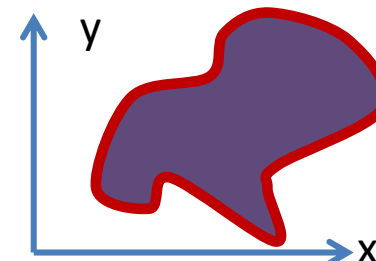
Boundary ∪ is a 1D domain



$$\int_a^b \frac{df}{dx} dx = f(b) - f(a)$$



$$\int_{t_1}^{t_2} \nabla f \cdot d\vec{r} = f[\vec{r}(t_2)] - f[\vec{r}(t_1)]$$



$$\int_C \vec{F} \cdot d\vec{r} = \int \int_A \left[\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right] dx dy$$

Amazingly, we can do more –but we need a few more definitions of “operators”

Curl and Divergence

Suppose \vec{F} is a vector field in \mathbb{R}^3 $\vec{F}(x, y, z) = P(x, y, z)\vec{i} + Q(x, y, z)\vec{j} + R(x, y, z)\vec{k}$

(at every point (x, y, z) in input space, it assigns a three dimensional vector)

We define the **curl of \vec{F} to be the vector** $\left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z}, \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x}, \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right)$

How is anyone supposed to remember this? **Note: THIS IS A VECTOR!**

Here's how:

(1) Recall that $\nabla f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right) = \left(\frac{\partial f}{\partial x} \vec{i} + \frac{\partial f}{\partial y} \vec{j} + \frac{\partial f}{\partial z} \vec{k} \right)$

(2) We can then think of ∇ as a vector operator with components

$$\nabla = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) = \left(\vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z} \right)$$

(3) So now we can **define the curl** as the cross product between ∇ and \vec{F}

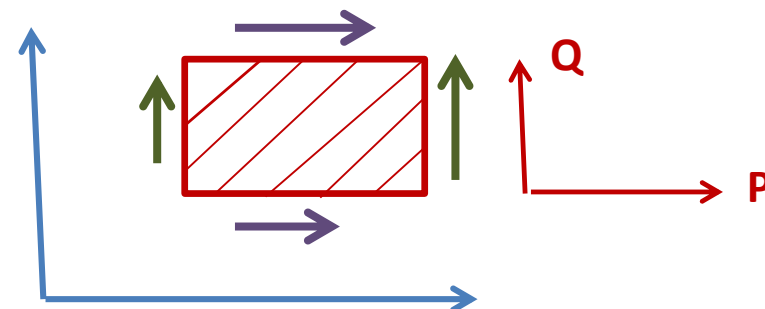
$$\begin{aligned} \nabla \times \vec{F} &\equiv \begin{bmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P(x, y, z) & Q(x, y, z) & R(x, y, z) \end{bmatrix} \\ &= \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \vec{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \vec{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \vec{k} \end{aligned}$$

So what is curl geometrically? Here goes.....

Let's look at a simpler vector field: $\vec{F} = (P, Q, R) = (P(x, y), Q(x, y), 0)$ (the z component is zero)

Then: $\nabla \times \vec{F} = \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \vec{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \vec{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \vec{k} = \left(0, 0, \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \right)$

Let's draw a box in the xy plane



$\frac{\partial P}{\partial y} =$ the twisting of the box due to P

If P is bigger on top than the bottom,
then it twists clockwise



If P is smaller on top than the bottom, then it twists counter clockwise



$\frac{\partial Q}{\partial x} =$ the twisting of the box due to Q

If Q is bigger on left than the right,
then it twists clockwise



If Q is smaller on left than the right, then it twists counter clockwise



So $\text{curl} = \nabla \times \vec{F}$ measures how much the vector field twists things

Lagrange Multipliers

Want to maximize $f(x,y) = -[x^2 + y^2]$

Let's plot the level curves:

Seems clear that the maximum occurs at $(0,0)$.
And the maximum $f(0,0)$ is 0

Constraint $g(x,y) = 2$

Level set $k=-9$: $f(x,y)=-9$

Level set $k=-4$: $f(x,y)=-4$

Level set $k=-1$: $f(x,y)=-1$

Level set $k=0$: $f(x,y)=0$

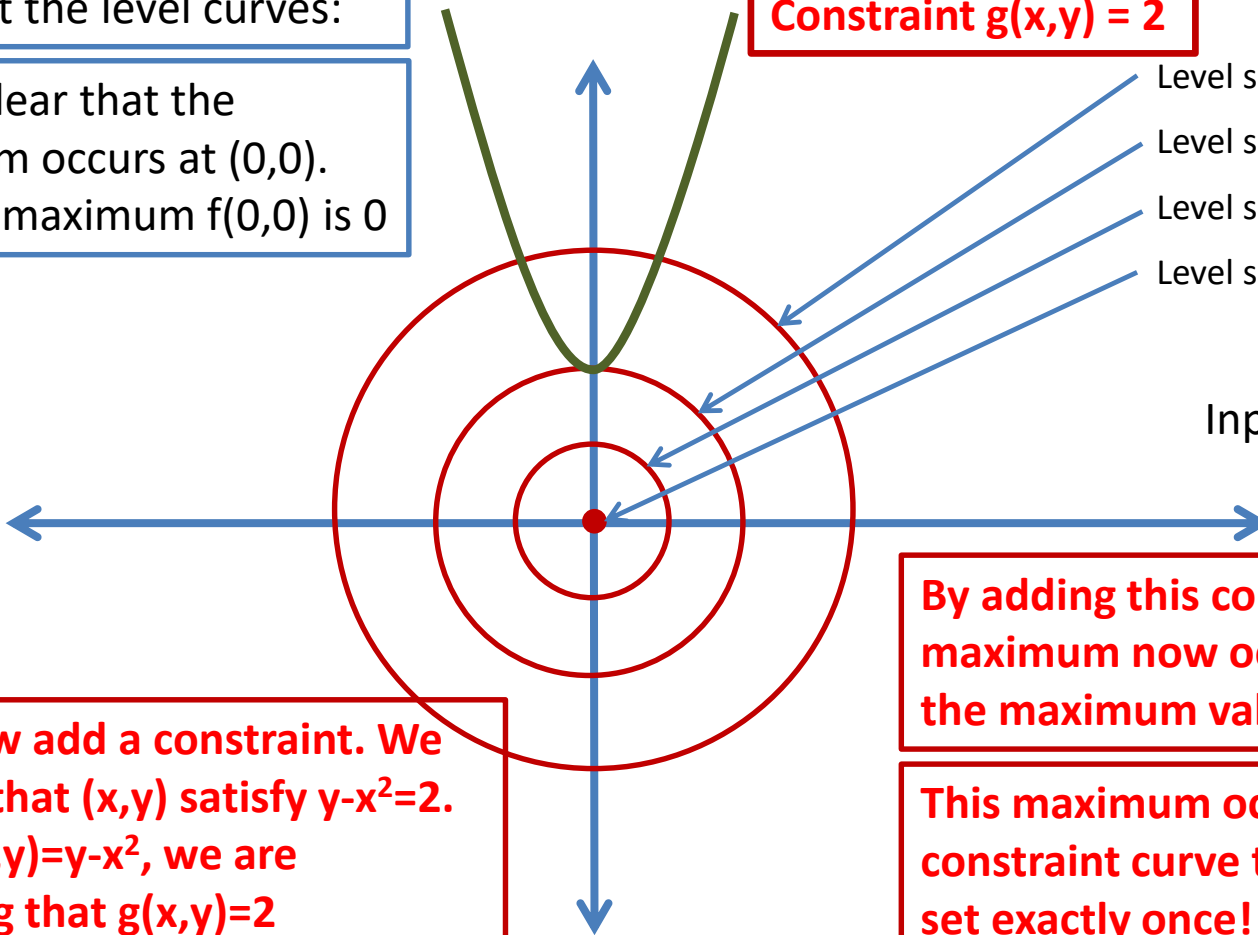
Input space

Let's now add a constraint. We require that (x,y) satisfy $y-x^2=2$. So if $g(x,y)=y-x^2$, we are requiring that $g(x,y)=2$

By adding this constraint, the maximum now occurs at $(0,2)$, and the maximum value $f(x,y)=-4$

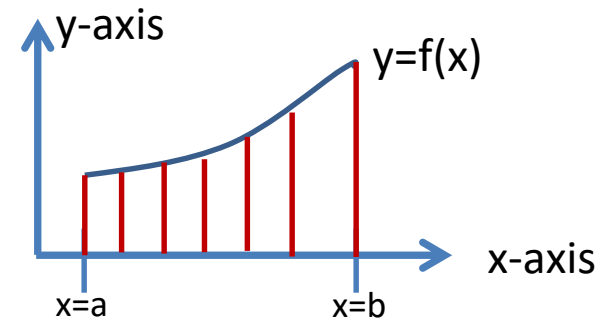
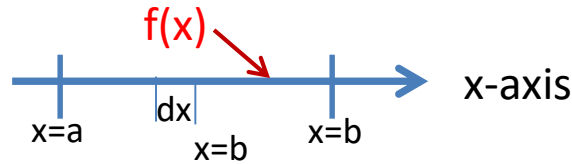
This maximum occurs where the constraint curve touches a level set exactly once!

Extreme value occurs where normal to the constraint curve points in the direction as the normal to the level set



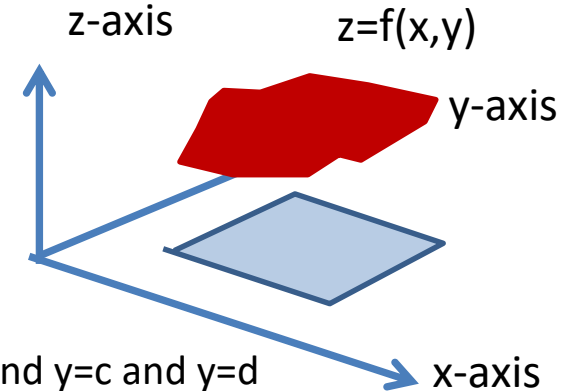
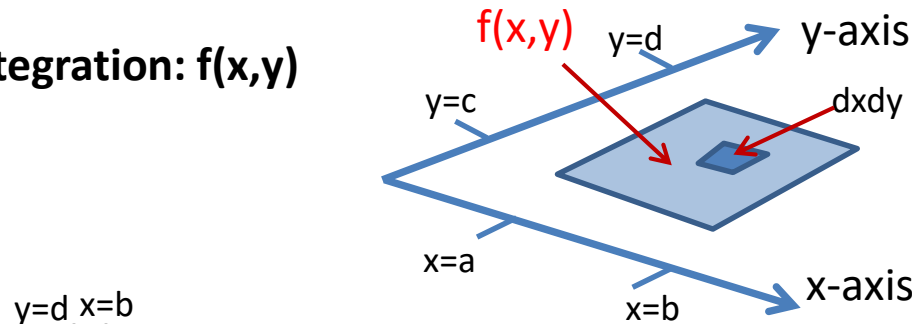
Chapter 15: Integration

1D Integration: $f(x)$



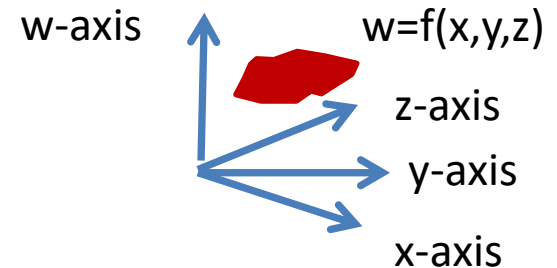
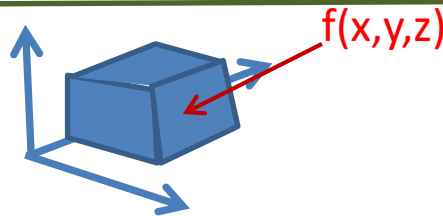
$\int_{x=a}^x f(x) dx$ = amount of $f(x)$ between $x=a$ and $x=b$
 = area under curve $y=f(x)$ between $x=a$ and $x=b$

2D Integration: $f(x,y)$



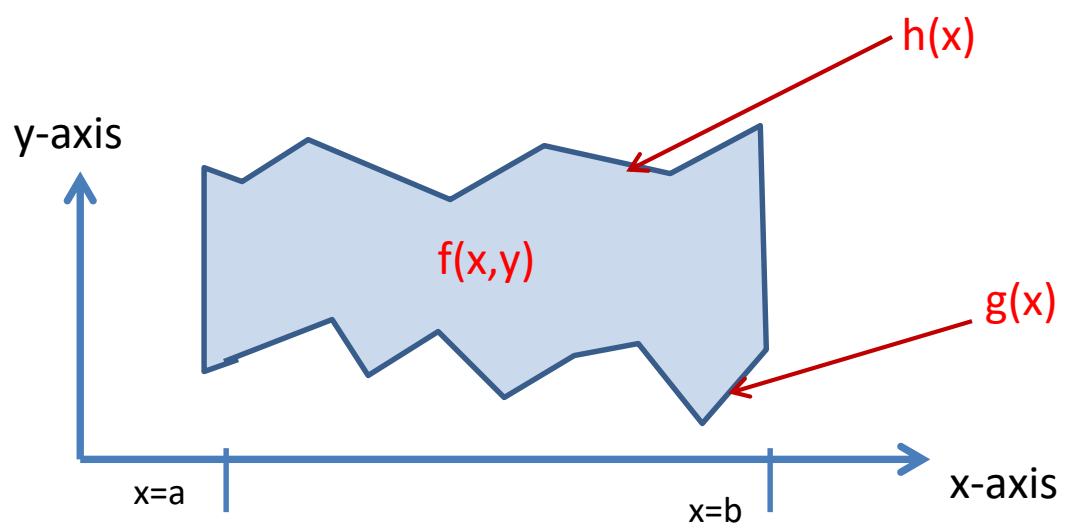
$\int_{y=c}^y \int_{x=a}^x f(x,y) dxdy$ = amount of $f(x,y)$ between $x=a$ and $x=b$ and $y=c$ and $y=d$
 = volume under surface $z=f(x,y)$ between $x=a$ and $x=b$ and $y=c$ and $y=d$

3D Integration: $f(x,y,z)$



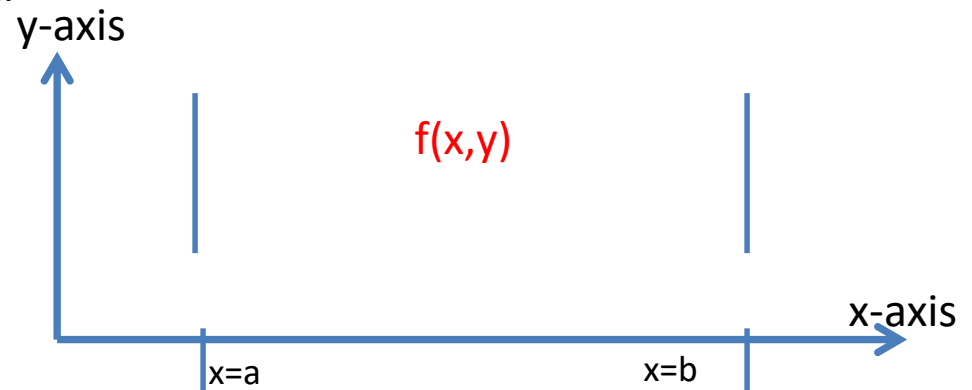
$\int_{z=e}^z \int_{y=c}^y \int_{x=a}^x f(x,y,z) dxdydz$ = amount of $f(x,y,z)$ between $x=a$ and $x=b$ and $y=c$ and $y=d$ and $z=e$ and $z=f$
 = volume under graph $z=f(x,y,z)$ between $x=a$ and $x=b$ and $y=c$ and $y=d$ and $z=e$ and $z=f$

Integration over weird regions



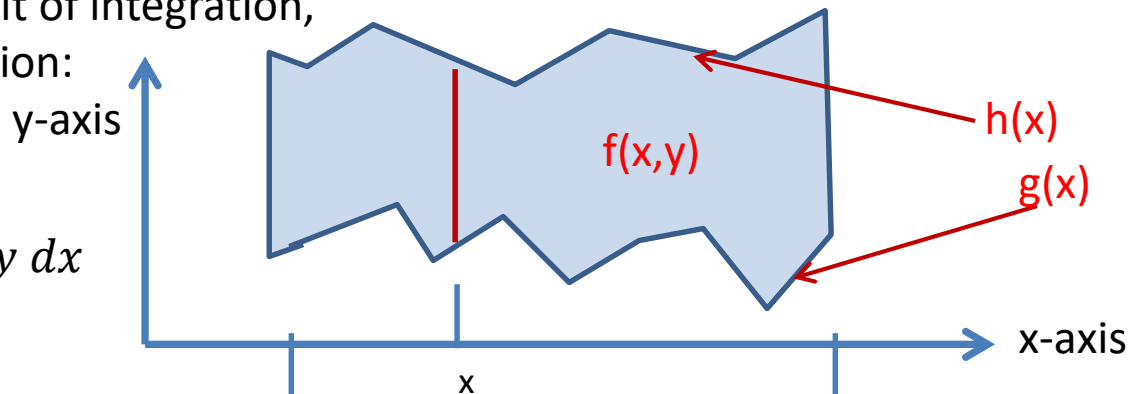
Choose outer limits of integration first:

$$\int_{x=a}^{x=b} \int_{?}^{?} dx$$



For each value of the outer limit of integration, find the inner limits of integration:

$$\int_{x=a}^{x=b} \int_{g(x)}^{h(x)} f(x,y) dy dx$$

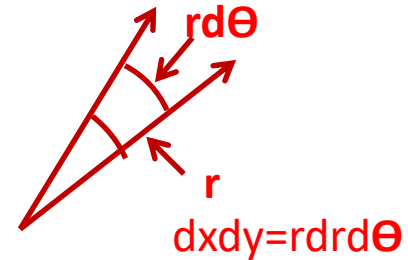
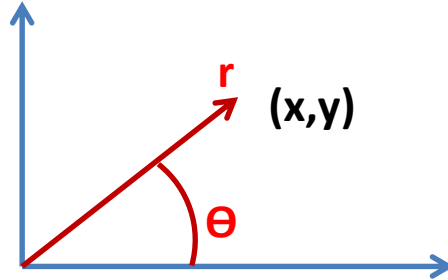


Other coordinate systems:

Polar coordinates:

$$x = r \cos(\theta)$$

$$y = r \sin(\theta)$$

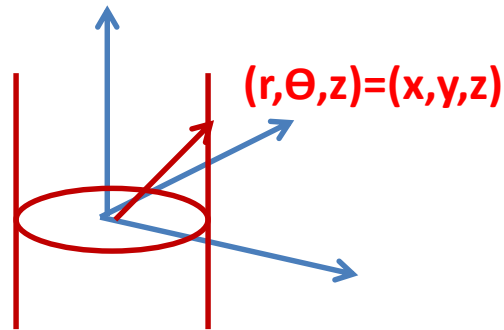


Cylindrical coordinates:

$$x = r \cos(\theta)$$

$$y = r \sin(\theta)$$

$$z = z$$



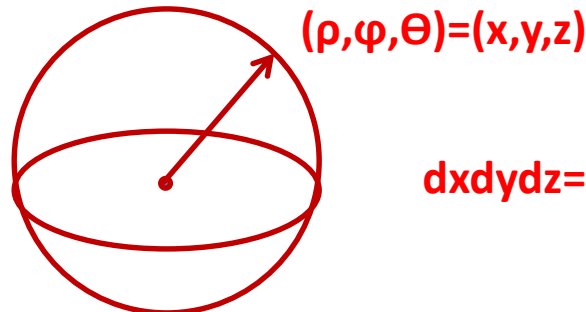
$$dx dy dz = r dr d\theta dz$$

Spherical coordinates:

$$x = \rho \sin(\phi) \cos(\theta)$$

$$y = \rho \sin(\phi) \sin(\theta)$$

$$z = \rho \cos(\phi)$$

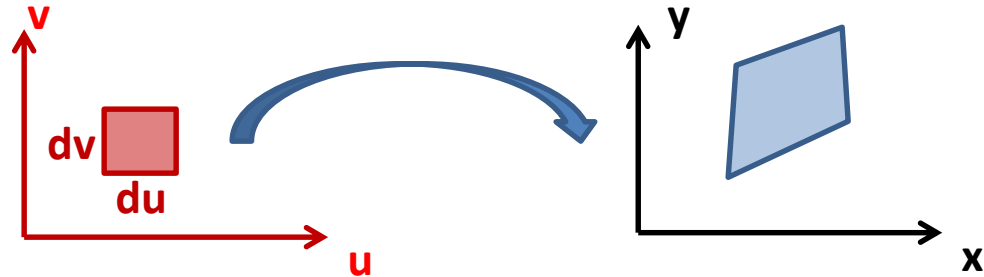


$$dx dy dz = \rho^2 \sin(\phi) d\rho d\phi d\theta$$

Change of Variable:

$$x = x(u, v)$$

$$y = y(u, v)$$



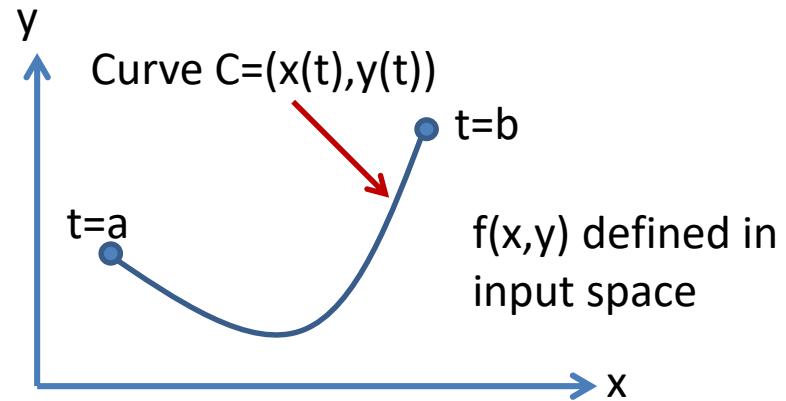
What is $dx dy$? (What is the magic factor?)

$$dx dy = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} du dv = J(u, v) du dv$$

$$\iint_{x1.y1}^{x2.y2} f(x, y) dx dy = \iint_{u1.v1}^{u2.v2} f(x(u, v), y(u, v)) J(u, v) du dv$$

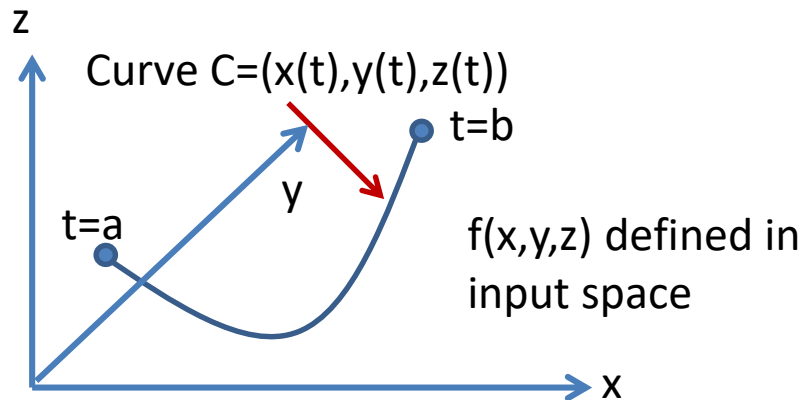
Chapter 16: Integration and the fundamental theorem of calculus

Line integrals of a scalar function $f: \mathbb{R}^2$ to \mathbb{R}



$$\int_C f(x, y) ds = \int f(x, y) \left[\left(\frac{\partial x}{\partial t} \right)^2 + \left(\frac{\partial y}{\partial t} \right)^2 \right]^{(1/2)} dt$$

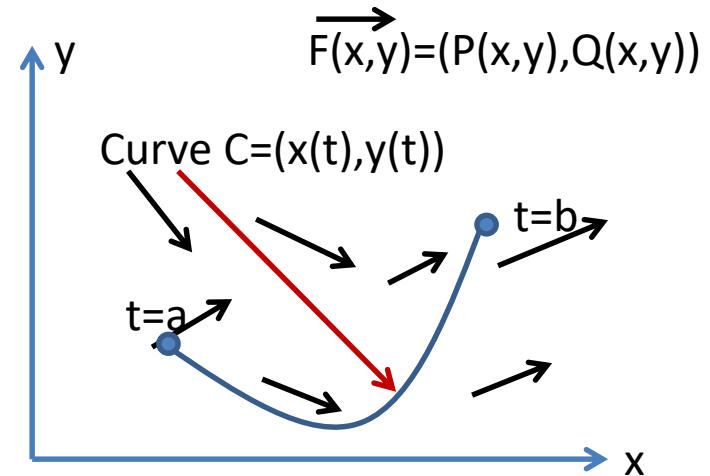
Line integrals of a scalar function $f: \mathbb{R}^3$ to \mathbb{R}



$$\int_C f(x, y, z) ds = \int f(x, y, z) \left[\left(\frac{\partial x}{\partial t} \right)^2 + \left(\frac{\partial y}{\partial t} \right)^2 + \left(\frac{\partial z}{\partial t} \right)^2 \right]^{(1/2)} dt$$

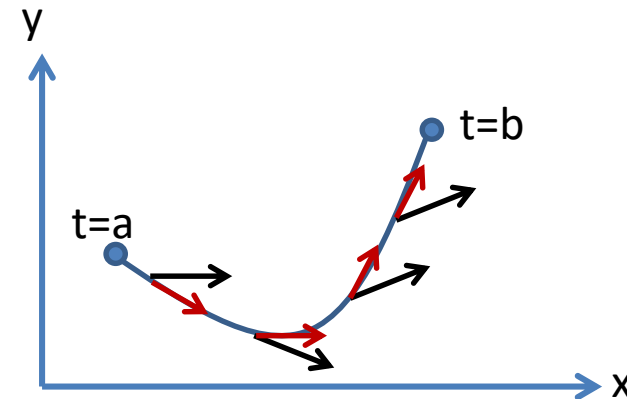
Chapter 16: Integration and the fundamental theorem of calculus

Line integrals over a vector field from \mathbb{R}^2 to \mathbb{R}^2



Collect all the **tangential components τ** of \vec{F} along C

$$\int_C \vec{F} \cdot d\vec{\tau} = \int_C P dx + Q dy$$



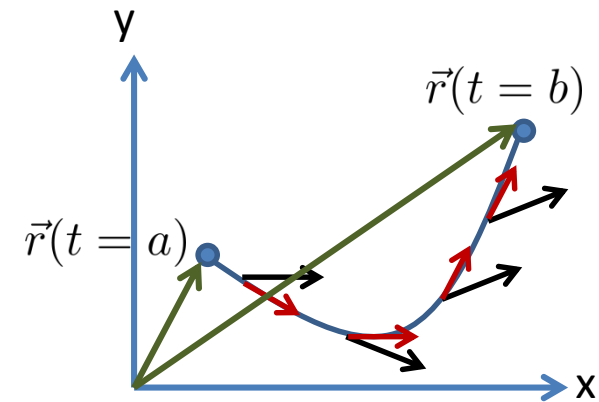
3D: Collect all the **tangential components τ** of \vec{F} along C

$$\int_C \vec{F} \cdot d\vec{\tau} = \int_C P dx + Q dy + R dz$$

And finally

Theorem: In more dimensions, we have that

$$\int_C \nabla f \cdot d\vec{r} = f[\vec{r}(t=b)] - f[\vec{r}(t=a)]$$



Conservative: There exists a scalar $f(x,y,z)$ such that $\nabla f = \vec{F}(x,y,z)$

The vector field $\vec{F} = (P, Q)$ is path-independent

So now we've got:
Given a vector field (P,Q)

$$\int_C \vec{F} \cdot d\vec{r} = 0 \quad \text{Over any closed curve } C$$

$$\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$$