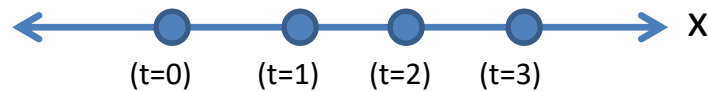


# Review of First Third of the Course

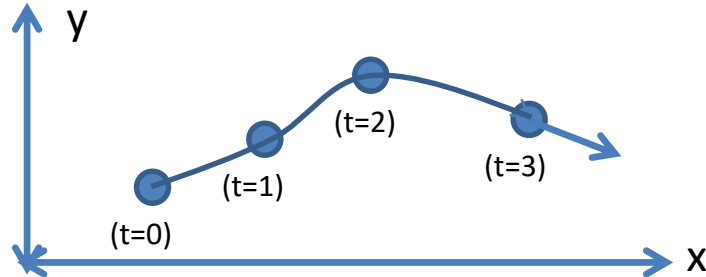
## Parameterized curves



$x = f(t)$  1D parameterized function

Mapping from 1D to 1D

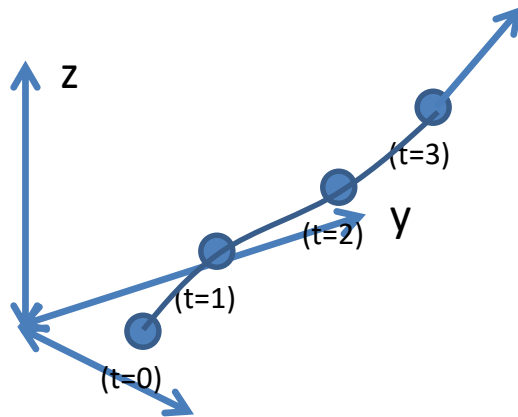
Gives  $x$  coordinate of object moving in 1D at time  $t$ .



$x = f(t), y = g(t)$  1D parameterized function

Mapping from 1D to 2D

Gives  $(x, y)$  coordinate of object moving in 2D at time  $t$ .



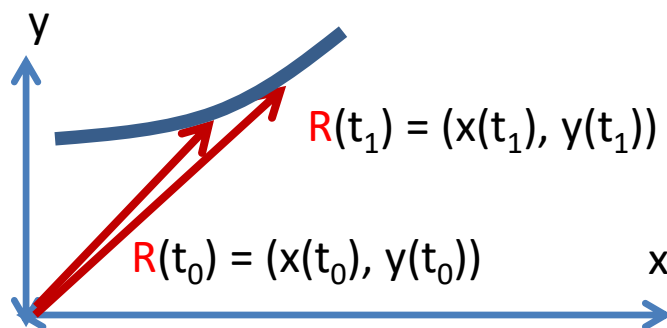
$x = f(t), y = g(t), z = h(t)$  1D parameterized function

Mapping from 1D to 3D

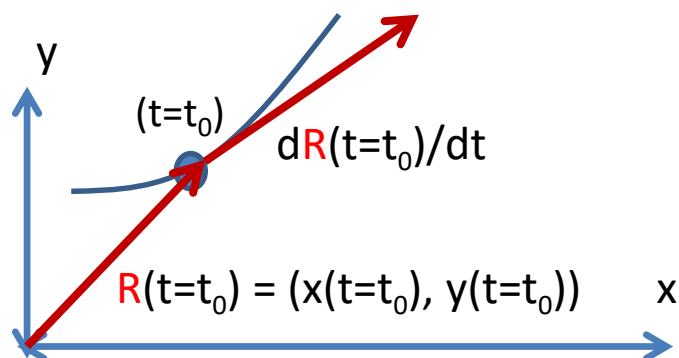
Gives  $(x, y, z)$  coordinate of object moving in 3D at time  $t$ .

## Review of First Third of the Course

## Derivatives of parameterized curves



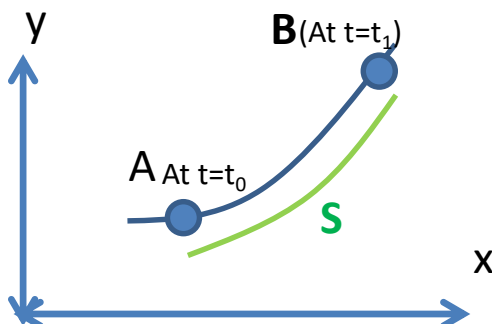
$\mathbf{R}(t) = (x(t), y(t))$  is vector description of curve in 2D.



$d\mathbf{R}(t)/dt = (dx(t)/dt, dy(t)/dt)$  is vector derivative of particle trajectory  
It is tangent to the curve at the point  $x(t=t_0), y(t=t_0)$

## Review of First Third of the Course

## Arc-length of parameterized curves



$(x(t), y(t))$  describes curve in 2D.

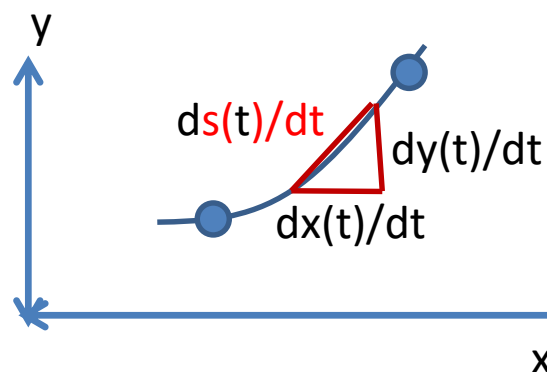
What is the total arc-length **S** from A to B?

$dS(t)/dt = [ (dx(t)/dt)^2 + (dy(t)/dt)^2 ]^{(1/2)}$  using “bob’s” theorem.

Add them all up to get total arc-length

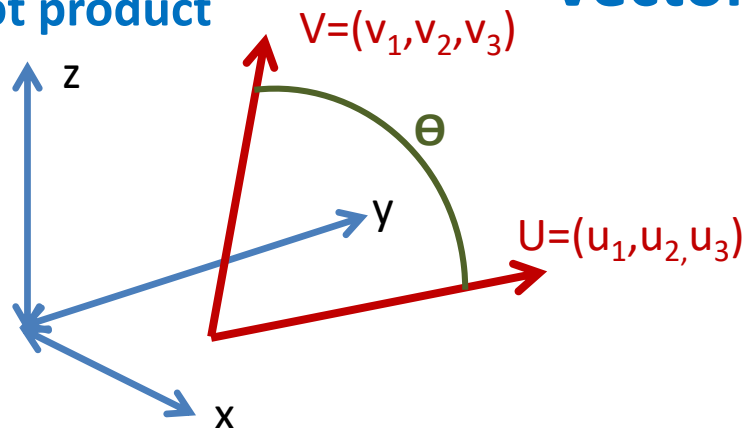
$$S = \int_{t_0}^{t_1} [ds(t)/dt] dt$$

$$S = \int_{t_0}^{t_1} [ (dx(t)/dt)^2 + (dy(t)/dt)^2 ]^{(1/2)} dt$$



# Dot product

## Vectors



Two vectors in 3D: angle between is  $\theta$

**Definition** of dot product:

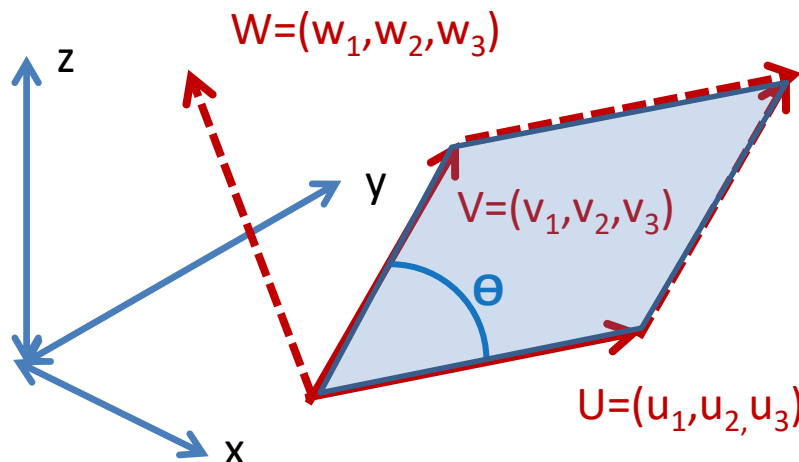
$$\mathbf{U} \cdot \mathbf{V} = (u_1 * v_1 + u_2 * v_2 + u_3 * v_3)$$

**Proved:**  $\mathbf{U} \cdot \mathbf{V} = |\mathbf{U}| |\mathbf{V}| \cos \theta$

**Proved:**

**Two vectors are orthogonal**  $\iff \mathbf{U} \cdot \mathbf{V} = 0$

## Cross product



Given two vectors in 3 dimensions

Can define their cross product as  $\mathbf{U} \times \mathbf{V} =$

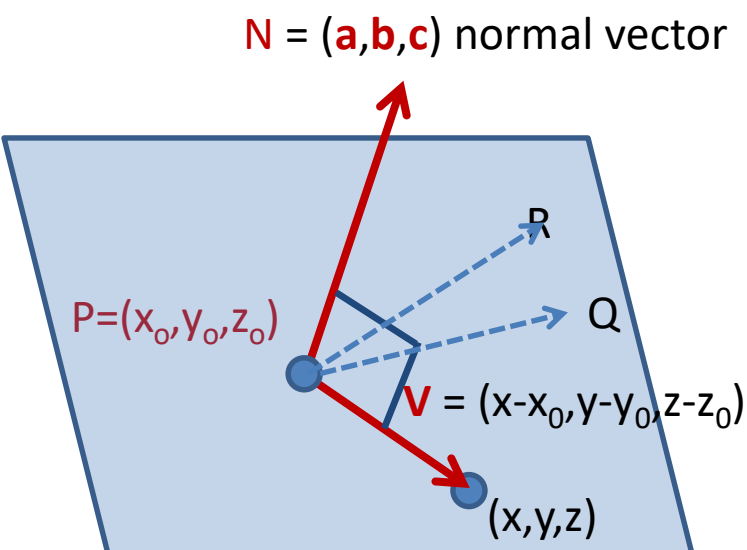
$$\mathbf{W} = (u_2 * v_3 - u_3 * v_2, u_3 * v_1 - u_1 * v_3, u_1 * v_2 - u_2 * v_1)$$

**Proved:**  $\mathbf{W} = \mathbf{U} \times \mathbf{V}$  is orthogonal to  $\mathbf{U}$  and to  $\mathbf{V}$

**Proved:**  $|\mathbf{U} \times \mathbf{V}| = |\mathbf{U}| |\mathbf{V}| \sin \theta$

**Proved:**  $|\mathbf{U} \times \mathbf{V}| = \text{area of parallelogram}$

# Defining planes using vectors



A plane is completely described if you are given a point  $P = (x_0, y_0, z_0)$  and normal vector  $N$

For any point  $(x, y, z)$  in the plane, the vector that connects  $(x, y, z)$  to  $P$  is given by  $V = (x - x_0, y - y_0, z - z_0)$

We can write an equation for any point  $(x, y, z)$  in the plane by realizing that any such vector  $V$  in the plane must be orthogonal to  $N$ : that is,  $N \cdot V = 0$

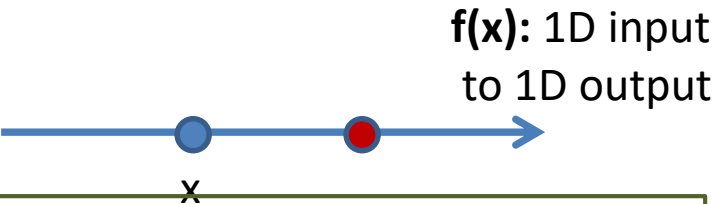
So any point  $(x, y, z)$  in the plane must satisfy  $N \cdot V = 0$ : which is the same as  $(a, b, c) \cdot (x - x_0, y - y_0, z - z_0) = 0$  which becomes  $a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$

If we are not given a normal vector  $N$ , but instead have three points  $P$ ,  $Q$ , and  $R$  in the plane, we can find a normal vector  $N$  by taking the cross product  $N = (Q - P) \times (R - P)$

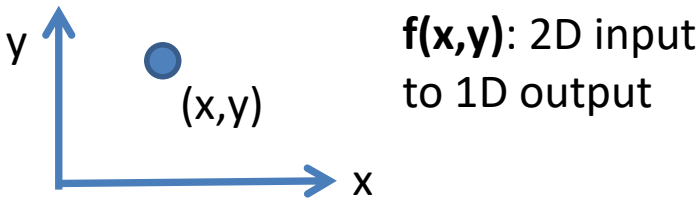
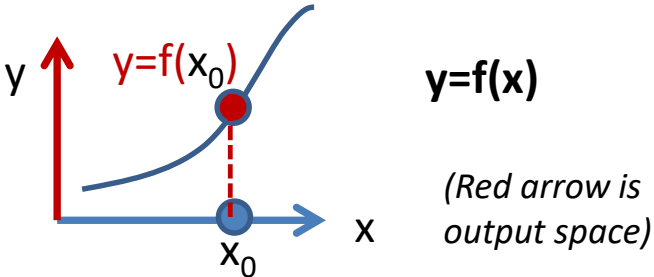
# Functions of more than one variable

Input space

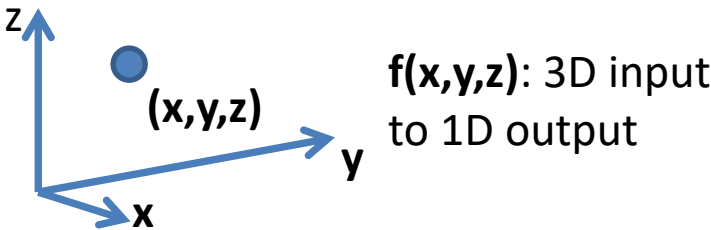
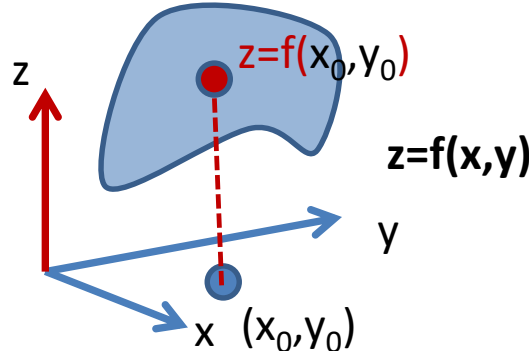
Need an extra dimension to graph it



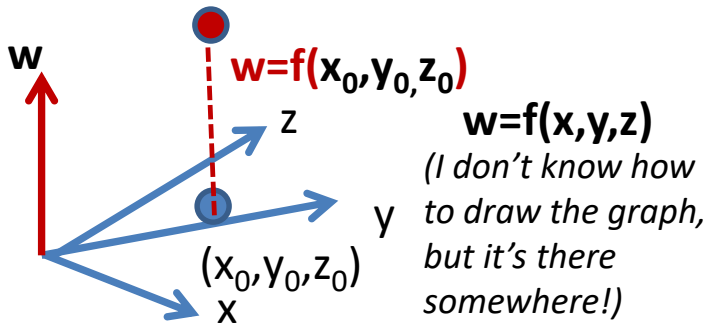
Function of one variable



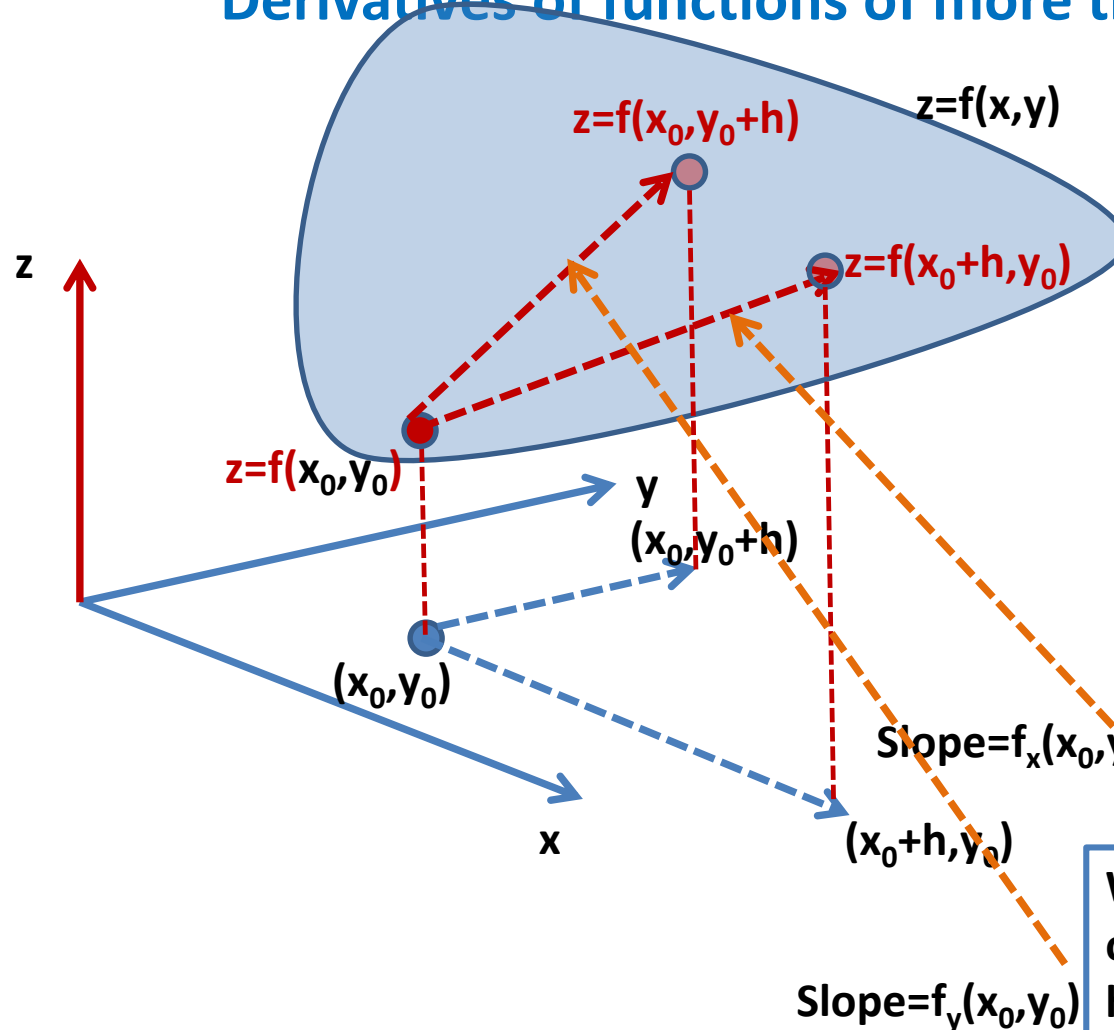
Function of two variables



Function of three variables



# Derivatives of functions of more than one variable



Start with a function  $f(x, y)$   
 The graph is 2D surface in  $\mathbb{R}^3$

At an input point  $(x_0, y_0)$  the  
 function has an output  $f(x_0, y_0)$

We can ask “how does the  
 output change as  $x$  increases,  
 holding  $y$  fixed?”

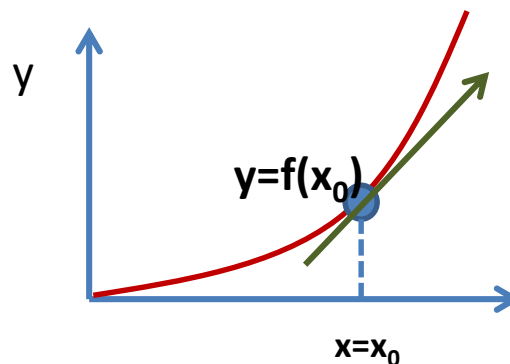
The slope of the line connecting  
 these changes is  $f_x(x_0, y_0)$

We can also ask “how does the  
 output change as  $y$  increases,  
 holding  $x$  fixed?” Answer =  $f_y(x_0, y_0)$

# Section 14.4: Tangent Planes: **WHEN YOU ARE GRAPHING OUTPUT AGAINST INPUT!!!!**

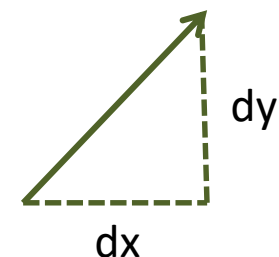
Let's recall 1D Calculus:  $y=f(x)$

Tangent line at  $(x_0, f(x_0))$  touches the graph  $y=f(x)$  at only one point near  $(x_0, f(x_0))$



Tangent line with slope  $f'(x_0)$  going through the point  $(x_0, f(x_0))$

The tangent line is given by  $y - f(x_0) = \text{slope}(x - x_0) = \left. \frac{df}{dx} \right|_{x_0} (x - x_0)$

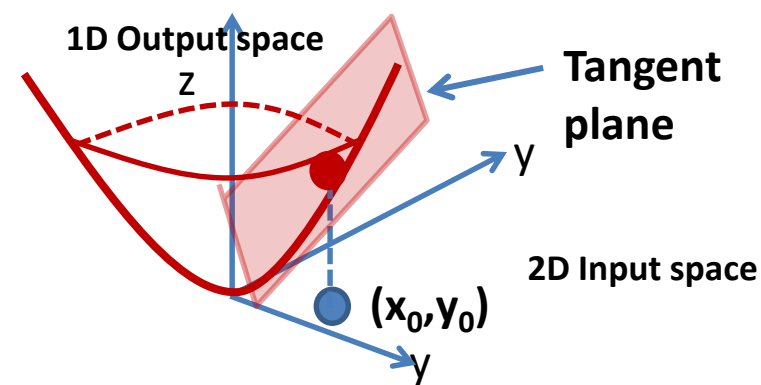


Tangent vector =  $(dx, dy) = (1, dy/dx) = (1, f'(a))$

We want to construct a similar idea for functions of two (or more variables):

## The Tangent Plane

Tangent plane at  $(x_0, y_0, f(x_0, y_0))$  touches the graph  $z=f(x, y)$  at only one point near  $(x_0, y_0, f(x_0, y_0))$



**Section 14.4: Tangent Planes: WHEN YOU ARE GRAPHING OUTPUT AGAINST INPUT!!!!****1d: Slope of a tangent line**

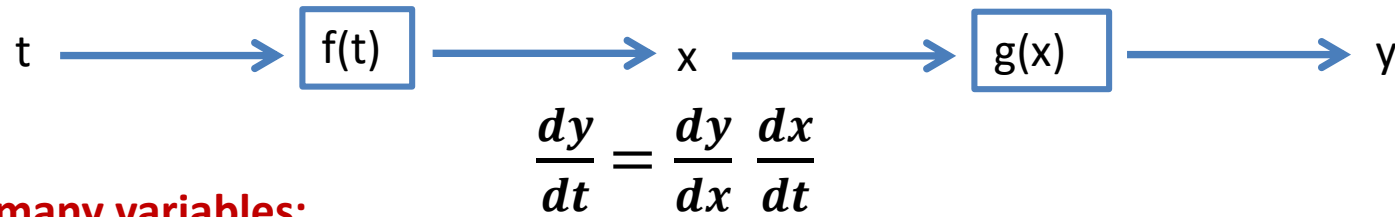
$$f(x) = f(a) + \left. \frac{df}{dx} \right|_a (x - a) \leftarrow \text{Equation for Line tangent to } a, f(a)$$

**2d: Formula for the tangent plane**

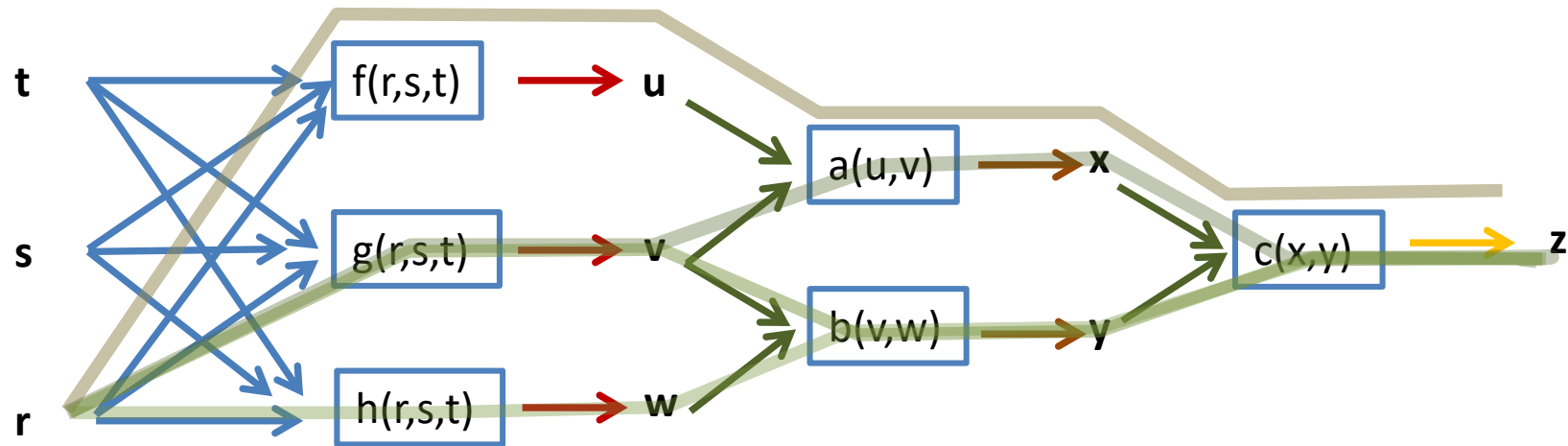
$$f(x, y) = f(a, b) + \left. \frac{\partial f}{\partial x} \right|_{a,b} (x - a) + \left. \frac{\partial f}{\partial y} \right|_{a,b} (y - b) \leftarrow \text{Equation for plane tangent to } a, b, (a, b)$$

# The Multi-Dimensional Chain Rule

Of one variable:



Of many variables:



To find  $\frac{\partial z}{\partial r}$  follow all pathways through the graph:

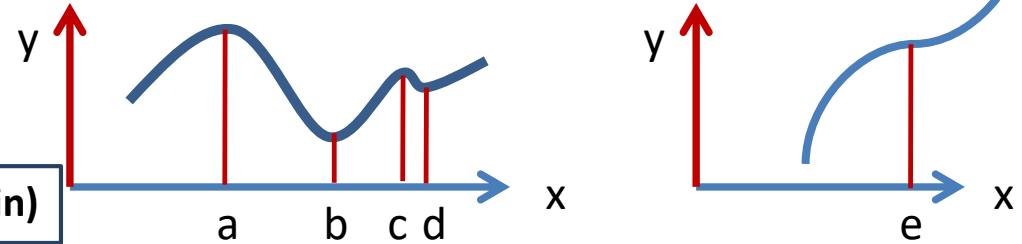
$$\frac{\partial z}{\partial r} =$$

# Critical Values of Multivariable functions

## One dimension $y=f(x)$

Critical points: Places where  $df/dx = 0$

If, in addition,  $d^2f/dx^2 < 0$  ( $> 0$ ) then max (min)



$x=a$ : global max ||  $x=b$ : global min ||  $x=a,c$ : local maximum ||  $x=b,d$ : local min ||  $x=e$ : (inflection)

## Two dimensions $z=f(x,y)$

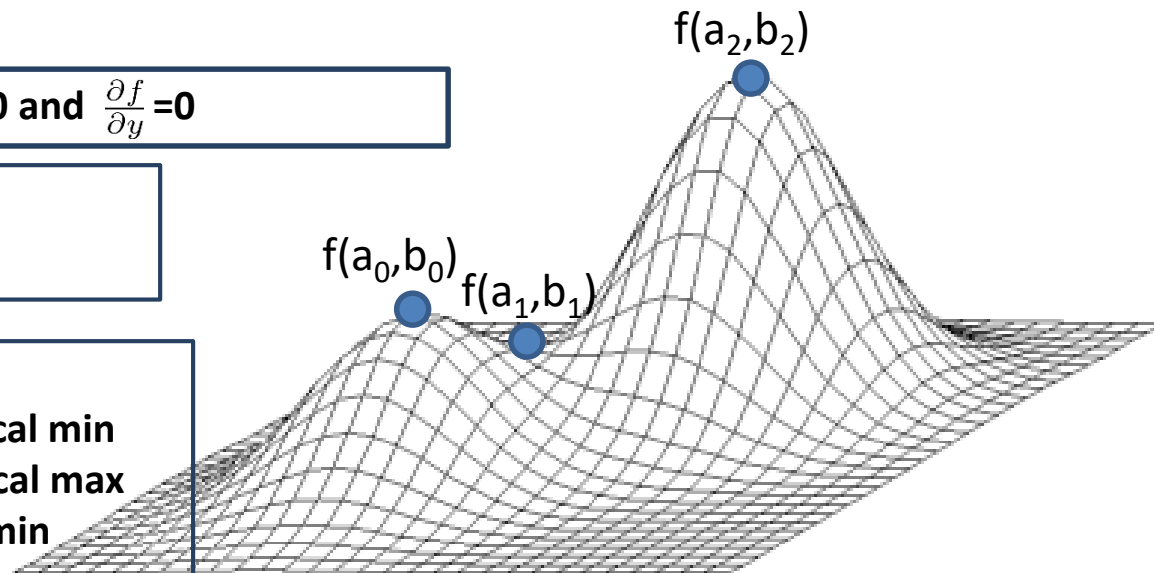
Critical points: Places where both  $\frac{\partial f}{\partial x} = 0$  and  $\frac{\partial f}{\partial y} = 0$

At the input point  $(a,b)$  define D as

$$D(a,b) = f_{xx}(a,b) f_{yy}(a,b) - [f_{xy}(a,b)]^2$$

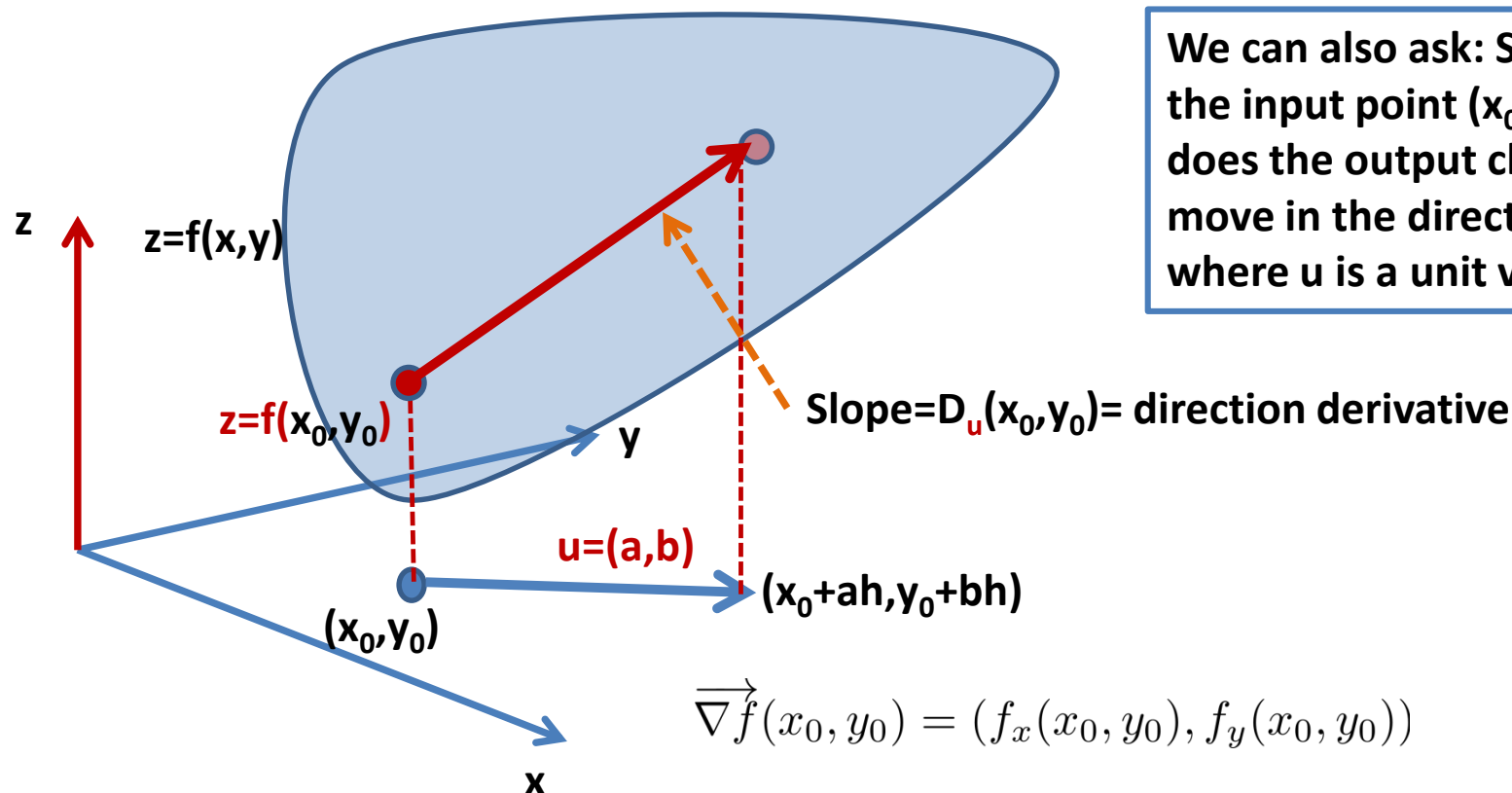
Suppose  $(a,b)$  is a critical point, then

- (a) if  $D(a,b) > 0$  and  $f_{xx}(a,b) > 0$ , then local min
- (b) if  $D(a,b) > 0$  and  $f_{xx}(a,b) < 0$ , then local max
- (c) if  $D(a,b) < 0$ , then neither max nor min



$(a_0, b_0)$  = local max.  $(a_1, b_1)$  = neither (saddle)  $(a_2, b_2)$  = global max

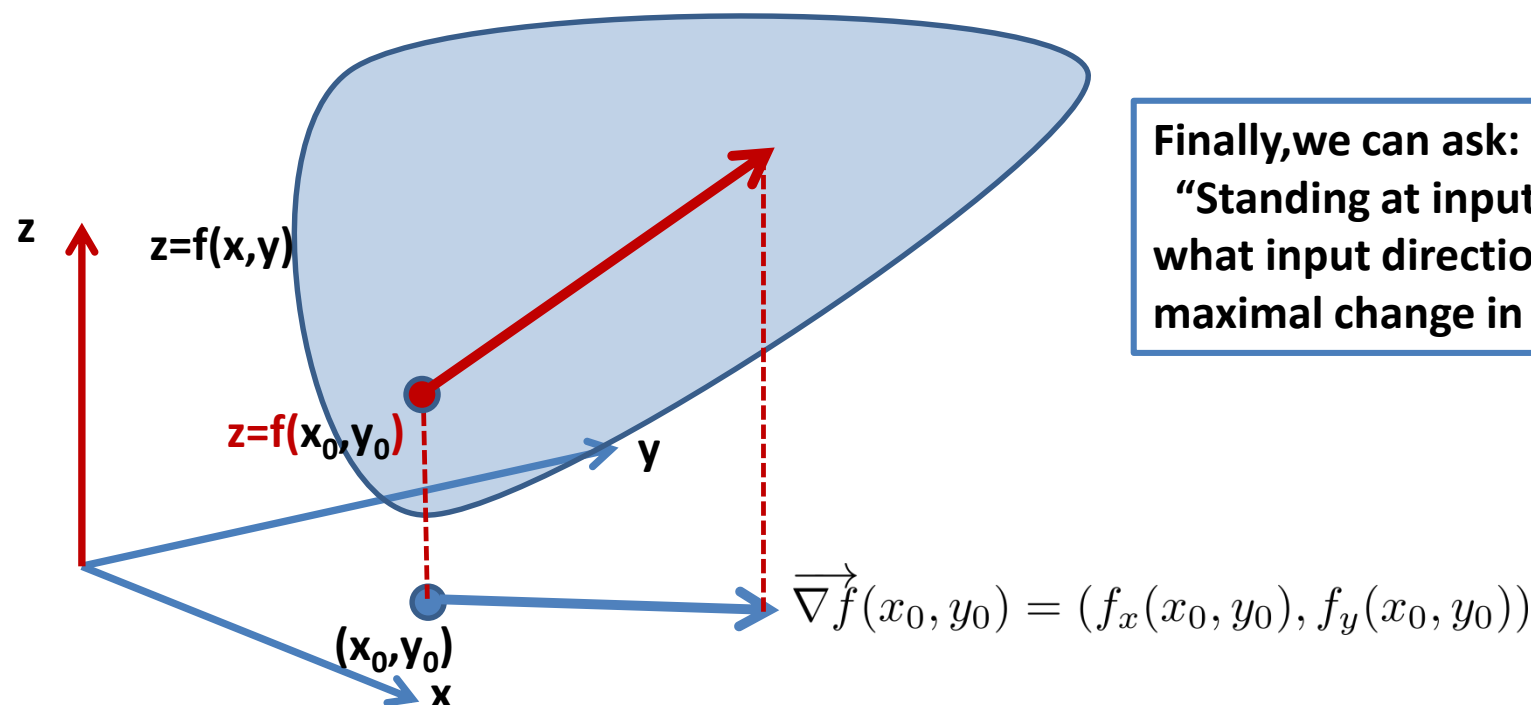
# Direction Derivatives



And we proved that:

$$D_{\mathbf{u}}(x_0, y_0) = a * f_x(x_0, y_0) + b * f_y(x_0, y_0) = \vec{\nabla} f \cdot \vec{u} \quad \text{At } x_0, y_0$$

# The gradient



Finally, we can ask:

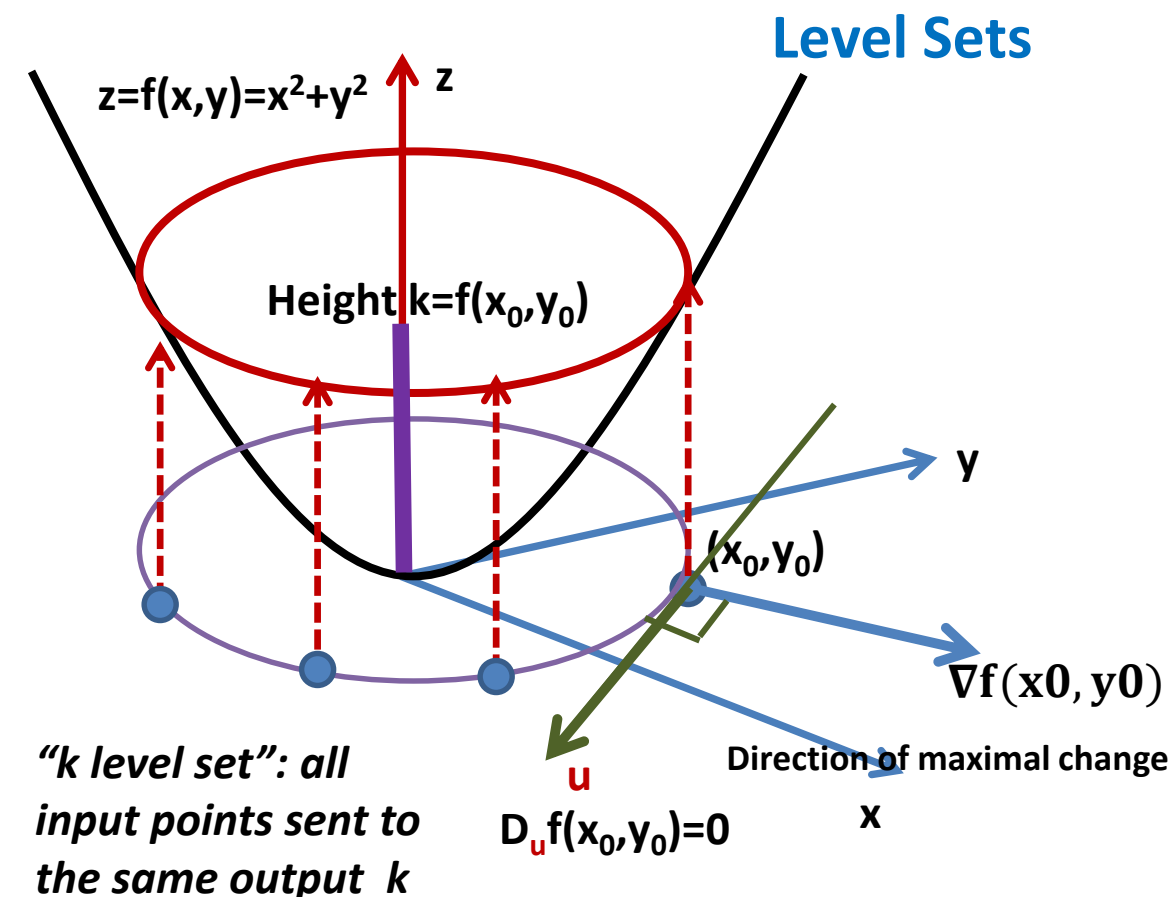
"Standing at input point  $(x_0, y_0)$ , what input direction gives the maximal change in  $f(x, y)$ ?"

The answer is to move in the gradient direction

$$\vec{\nabla} f(x_0, y_0) = (f_x(x_0, y_0), f_y(x_0, y_0))$$

**Why? Because**  $D_{\vec{u}} f(x_0, y_0) = \vec{\nabla} f(x_0, y_0) \cdot \vec{u} = |\vec{\nabla} f| |\vec{u}| \cos \theta$  **is biggest when**  $\cos \theta = 1$

And when  $\cos \theta = 1$ , then  $\theta = 0$  so  $\vec{\nabla} f$  and  $\vec{u}$  point in the same direction



Start with a function  $f(x, y)$   
The graph is 2D surface in  $\mathbb{R}^3$

Level set with value  $k$  is the set of all input points sent to the value  $k$ .

Moving along the  $k$  level set in input space, the function  $f(x, y)$  doesn't change

So, if  $\mathbf{u}$  is a direction along the  $k$  level set, then  $D_{\mathbf{u}} f(x_0, y_0) = 0$

The gradient at  $f(x_0, y_0)$  is the direction of maximal change

Since  $D_{\mathbf{u}} f(x_0, y_0) = 0$  and since  $0 = D_{\mathbf{u}} f(x_0, y_0) = \nabla f(x_0, y_0) \cdot \mathbf{u}$

Then  $\mathbf{u}(x_0, y_0)$  is perpendicular to  $\nabla f(x_0, y_0)$

So the gradient  $\nabla f(x_0, y_0)$  is normal to the tangent to the level set going through  $(x_0, y_0)$

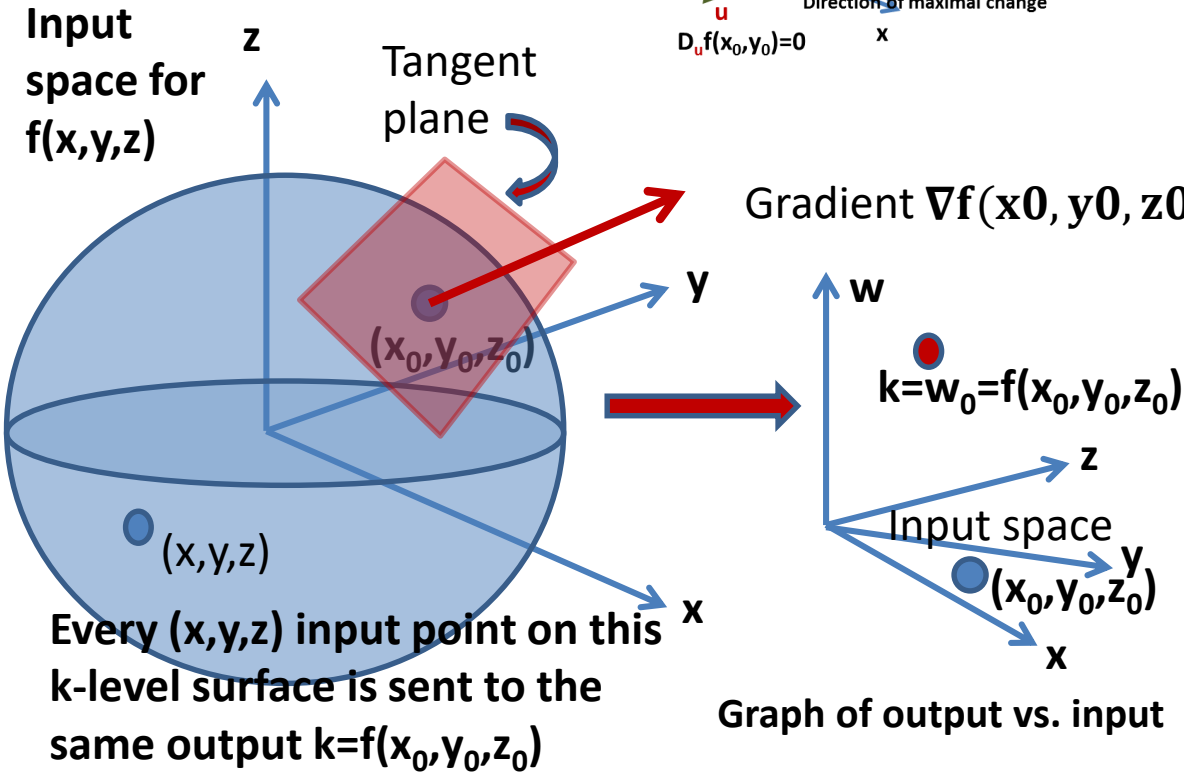
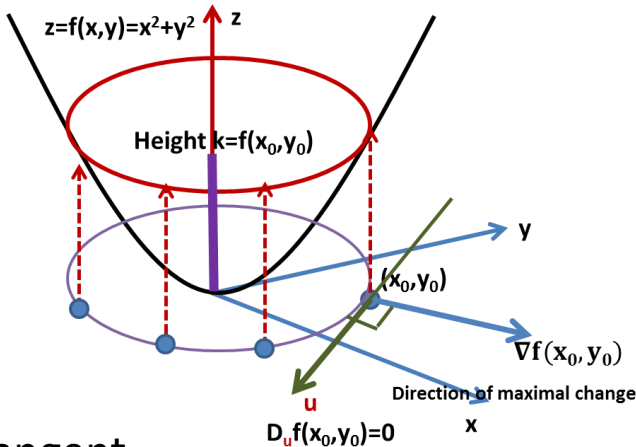
# Level Sets in Higher Dimensions

Again. At input  $(x_0,y_0)$  the gradient is normal to the line tangent to the  $k=f(x_0,y_0)$  level curve passing through  $(x_0,y_0)$ .

This same idea is true in higher dimensions. For a function  $w=f(x,y,z)$ , the input space is three-dimensional.

At input  $(x_0,y_0,z_0)$ , the gradient is normal to the \*plane tangent\* to the  $k=f(x_0,y_0,z_0)$  level set passing through  $(x_0,y_0,z_0)$ .

So we have an equation for the tangent plane at the point  $(x_0,y_0,z_0)$ , since we know a point and the normal  $\nabla f(x_0,y_0,z_0)$



Finally, there is some (understandable) confusion about tangent planes. Let me try to sort it out

**Suppose  $y=f(x)$ . Find the tangent at input  $x_0$**     **Example:  $y=x^2$   $x_0 = 3$**     **\*Two\* ways to do this:**

**Way #1: Interpret  $y=f(x)$  as the graph of output against input:**

A mapping from  $\mathbb{R}^1 \rightarrow \mathbb{R}^1$

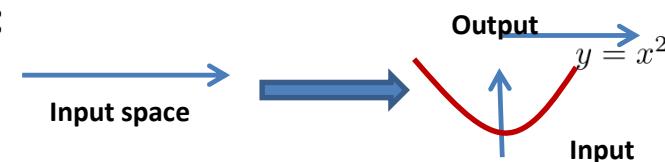
**Step 1: Draw the output against input**

**Step 2: Want the tangent point at  $(3, f(3)) = (3, 9)$**

**Step 3: We need the slope to use the formula  $(y - y_0) = (slope) * (x - x_0)$**

**Step 4: Slope is  $= df/dx = 2x$ : at input  $x_0=3$ , slope is 6.**

**So answer is  $y-9 = 6(x-3)$  which we can rewrite as  $y = 6x - 9$**



**Way #2: Consider a new function  $w(x,y) = y-f(x)$ :  $w(x,y)=y-x^2$  is a mapping from  $\mathbb{R}^2 \rightarrow \mathbb{R}^1$**

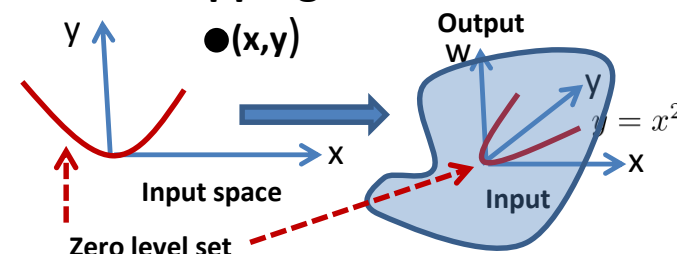
**Step 1: Realize that the zero level set of function  $w(x,y)$**

**is the red curve, which is the set of all  $(x,y)$  sent to output 0, in other words, whenever  $y=f(x)$**

**Step 2: So, the input  $x_0=3$ ,  $y_0=9$  gets sent to  $w = 0$**

**Step 3: That means that at the input  $(3,9)$  the gradient  $\nabla w(x,y) = (-2x, 1) = (-6, 1)$  is normal to the tangent to the level set  $0=y-x^2$**

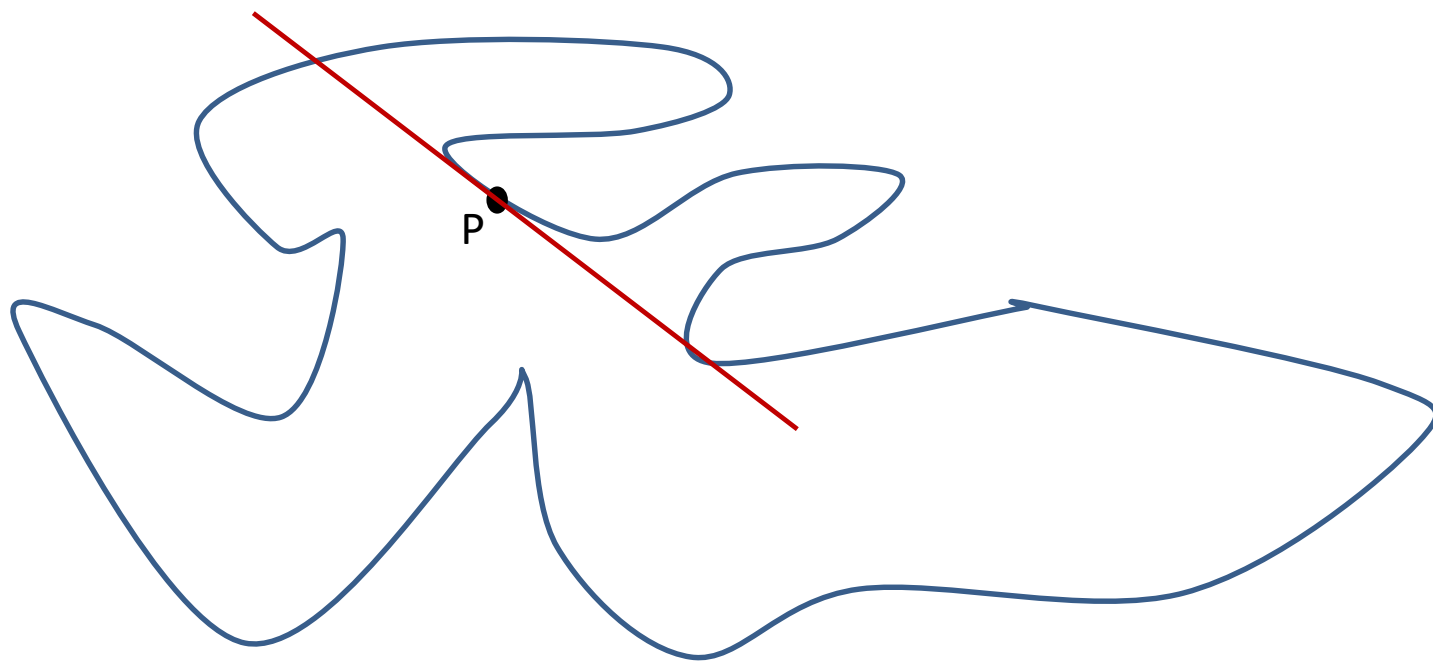
**Step 4: So, using the normal equation for a line  $\vec{n} \cdot (x - x_0, y - y_0) = 0$**



$$(-6, 1) \cdot (x - 3, y - 9) = 0 \rightarrow -6x + 18 + y - 9 = 0 \rightarrow y = 6x - 9$$

**Final question: Why would you ever use the second way?**

**Answer: because you might get asked to find the tangent to the following funky curve at point P –it's not a function....**



**Example: Find the tangent to  $w=f(x,y,z) = x^2 + y^2 + z^2$  at the input  $(1,2,3)$**

**Way #1: Interpret  $w=f(x,y,z)$  as the graph of output against input: A mapping from  $\mathbb{R}^3 \rightarrow \mathbb{R}^1$**

**Step 1: Want the tangent object at the point  $(1,2,3,f(1,2,3)) = (1,2,3,14)$**

**Step 2: We need the various partials to use the formula**

$$f(x, y, z) = f(a, b, c) + \left. \frac{\partial f}{\partial x} \right|_{a,b,c} (x - a) + \left. \frac{\partial f}{\partial y} \right|_{a,b,c} (y - b) + \left. \frac{\partial f}{\partial z} \right|_{a,b,c} (z - c)$$

Equation for hyperplane tangent to  $f(a, b, c)$

**Step 4:  $f_x=2x, f_y=2y, f_z=2z$ ---so  $(f_x, f_y, f_z) = (2, 4, 6)$ .**

**So tangent object is  $w=14 + (2)(x-1)+(4)(y-2)+(6)(z-3)= 2x+4y+6z+14$**

**Way #2: Think of the equation  $w=f(x,y,z)$  as a particular level set of a new function**

**$U(x,y,z,w) = w-f(x,y,z)=w-(x^2+y^2+z^2)$  is a mapping from  $\mathbb{R}^4 \rightarrow \mathbb{R}^1$**

**Step 1: Realize that the zero level set of function  $U(x,y,z,w)$**

**is the set of all  $(x,y,z,w)$  sent to output 0**

**Step 2: So, the input  $x_0=1, y_0=2, z_0=3, w_0=14$  gets sent to  $U = 0$**

**Step 3: That means that at the input  $(1,2,3,14)$  the gradient**

**is normal to the tangent to the level set  $0= w-(x^2+y^2+z^2)$**

**Step 4: The gradient at input  $(1,2,3,14)$  is**

$$\nabla U(x, y, z, w) = (-2x, -2y, -2z, 1) = (-2, -4, -6, 1) = \vec{n}$$

$$\vec{n} \cdot (x - x_0, y - y_0, z - z_0, w - w_0) = 0$$

$$(-2, -4, -6, 1) \cdot (x - 1, y - 2, z - 3, w - 14) = 0 \rightarrow w = 2x + 4y + 6z + 14$$