

MATH 128A Numerical Analysis Discussion Section

Raehyun Kim*

* Department of Mathematics, UC Berkeley

Brief Review

- Order of Convergence
 - Modified Newton's method
- Accelerating Convergence
 - Aitken's Δ^2 Method
 - Steffensen's Method
- Lagrange Interpolation Polynomial
 - $p_{n,i}(x_j) = \delta_{i,j}$

Brief Review

- Order of Convergence
 - Modified Newton's method
- Accelerating Convergence
 - Aitken's Δ^2 Method
 - Steffensen's Method
- Lagrange Interpolation Polynomial
 - $p_{n,i}(x_j) = \delta_{i,j}$

Newton's method

- $f(x)$ is continuous and differentiable

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

- Converging very fast.
- Q. What if $f'(p) = 0$?
 - A. Can not guarantee fast convergence.
Indeed, it merely linearly converges.

Modified Newton's method

- $f(x)$ is continuous and differentiable
- multiplicity m of root x
 - Simply $f(a) = f'(a) = \dots = f^{(m-1)}(a) = 0$
- $$x_{n+1} = x_n - \frac{f(x_n)f'(x_n)}{f'(x_n)^2 - f(x_n)f''(x_n)}$$
- Quadratically convergent but impractical

Brief Review

- Order of Convergence
 - Modified Newton's method
 - Another measurement
- Accelerating Convergence
 - Aitken's Δ^2 Method
 - Steffensen's Method
- Lagrange Interpolation Polynomial
 - $p_{n,i}(x_j) = \delta_{i,j}$

Aitken's Δ^2 Method

$$\widehat{p_n} = p_n - \frac{(p_{n+1} - p_n)^2}{p_{n+2} - 2p_{n+1} + p_n}$$

- Accelerate the convergence of a sequence that is linearly convergent.
- How to use?

Calculate p_n until the error is \sqrt{Tol} and apply Aitken's Δ^2 Method

Steffensen's Method

$$p_0^{(i)} = \{\Delta^2\} (p_0^{(i-1)})$$

$$p_1^{(i)} = g(p_0^{(i)})$$

$$p_2^{(i)} = g(p_1^{(i)})$$

$$p_0^{(i+1)} = \{\Delta^2\} (p_0^{(i)})$$

- Accelerate the order of convergence of the given fixed point method using Aitken's method

Brief Review

- Order of Convergence
 - Modified Newton's method
 - Another measurement
- Accelerating Convergence
 - Aitken's Δ^2 Method
 - Steffensen's Method
- Lagrange Interpolation Polynomial
 - $p_{n,i}(x_j) = \delta_{i,j}$

Lagrange polynomial

- Polynomials s.t. $p_{n,i}(x_j) = \delta_{i,j}$ for given $\{x_j\}_{j=0,\dots,n}$

$$p_{n,i}(x) = \prod_{\substack{j=0 \\ j \neq i}}^n \frac{x - x_j}{x_i - x_j}$$

- Interpolation result

$$Q(x) = \sum f(x_i)p_{n,i}(x)$$

Programming Exercises

- Goal : Use code in the web
- <http://persson.berkeley.edu/math128a/>
- Example problem

4. Let $g(x) = 1 + (\sin x)^2$ and $p_0^{(0)} = 1$. Use Steffensen's method to find $p_0^{(1)}$ and $p_0^{(2)}$.

- Exercise
 - Solve following problem using [steffensen_table.m](#)
7. Use Steffensen's method to find, to an accuracy of 10^{-4} , the root of $x^3 - x - 1 = 0$ that lies in $[1, 2]$ and compare this to the results of Exercise 8 of Section 2.2.