### Review

1. Suppose that A is a  $2 \times 2$  matrix with eigenvectors  $\mathbf{v}_1$  and  $\mathbf{v}_2$  and corresponding eigenvalues 5 and -3 and that  $\mathbf{u} = 2\mathbf{v}_1 - 8\mathbf{v}_2$ . If  $\mathbf{y}$  is a function from  $\mathbb{R}$  to  $\mathbb{R}^2$  that satisfies  $\mathbf{y}'(t) = A\mathbf{y}(t)$  and  $\mathbf{y}(0) = \mathbf{u}$ , what is  $\mathbf{y}(10)$ ? When t is very large, in approximately what direction is  $\mathbf{y}(t)$  pointing?

## **Complex Eigenvalues and Nonhomogeneous Systems**

- 1. Suppose **u** and **v** are vector-valued functions whose values are always real (not complex). Also, suppose  $\mathbf{u}(t) + i\mathbf{v}(t)$  is a solution to  $\mathbf{y}'(t) = A\mathbf{y}(t)$  where A is some matrix whose entries are all real numbers. Show that  $\mathbf{u}(t)$  and  $\mathbf{v}(t)$  are both solutions as well. (Hint: try writing down what it means for  $\mathbf{u} + i\mathbf{v}$  to be a solution.)
- 2. Find the general solution of the following ODE.

$$\mathbf{y}'(t) = \begin{bmatrix} 5 & 1\\ -8 & 1 \end{bmatrix} \mathbf{y}(t)$$

3. (If we have time) Find a solution to

$$\mathbf{y}'(t) = \begin{bmatrix} 2 & 2\\ 2 & 2 \end{bmatrix} \mathbf{y}(t) + \begin{bmatrix} -4\cos(t)\\ -\sin(t) \end{bmatrix}$$

4. (a) Draw a picture of all the solutions to the following differential equation.

$$\mathbf{y}'(t) = \begin{bmatrix} 2 & 0\\ 0 & 0 \end{bmatrix} \mathbf{y}(t)$$

(b) Draw a picture of all solutions to  $\mathbf{y}'(t) = A\mathbf{y}(t)$  if A is  $\begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix}$  in the basis  $\left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \end{bmatrix} \right\}$ .

5. (If we have time) Let A, B, and C, and D be the matrices shown below.

$$A = \begin{bmatrix} 2 & 0 \\ 0 & -3 \end{bmatrix} \quad B = \begin{bmatrix} 2 & 1 \\ 0 & 2 \end{bmatrix} \quad C = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \quad D = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

- (a) Compute  $e^A$
- (b) Compute  $e^{tA}$
- (c) If  $H = PAP^{-1}$ , compute  $e^H$  and  $e^{tH}$  (hint:  $tH = P(tA)P^{-1}$ )
- (d) Compute  $e^{tC}$
- (e) Using the fact that  $e^{tD+tC} = e^{tD}e^{tC}$ , compute  $e^{tB}$

# **Definitions and Theorems**

### **Definitions:**

• (If we have time) Matrix exponential

#### Theorems:

• (If we have time) The fundamental matrix of  $\mathbf{y}'(t) = A\mathbf{y}(t)$  is  $e^{tA}$  and the solution to the initial value problem  $\mathbf{y}(0) = \mathbf{v}$  is  $e^{tA}\mathbf{v}$ .

Most important idea today: The most important thing today is to have an intuitive picture of what's going on when we solve a system of first order ODEs by finding eigenvectors of a matrix.

For instance, one intuitive idea is that solving the ODE  $\mathbf{y}'(t) = A\mathbf{y}(t)$  by finding a basis of eigenvectors of A is equivalent to changing to a basis in which the ODE is "decoupled"—i.e. each differential equation in the system does not depend on the others.