

Lecture 16 Orthogonality

Fri Quiz through § 6.3

Next week Extra Office Hours
Thurs., 2:00 - 3:30 pm, 740 Evans

Midterm 2 Tues., Oct 31,
during lecture,
through § 6.5

Bo.

Recall To do geom. in \mathbb{R}^n

—
(lengths, angles, ...)

we used dot product

$$\underline{u} \cdot \underline{v} = u_1 v_1 + \dots + u_n v_n$$

Question What $A: \mathbb{R}^n \rightarrow \mathbb{R}^n$ lin trans preserves these quantities?

$$\underline{\underline{Ex}} \quad 1) \quad n = 1 \quad A = [\pm 1]$$

identity or reflection

$$2) \quad n = 2 \quad A = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \quad \text{rotations}$$

$$\text{or } A = \begin{cases} 0 & \\ 1 & \\ -1 & \\ 0 & \end{cases} \quad \text{reflections}$$

or
combinations

Def An $n \times n$ matrix U is orthogonal

$$\text{if } U(u) \cdot U(v) = u \cdot v$$

"
preserves dot product
lengths, angles..."

Exer TFAE = the following are equivalent

- 1) U is an orthog. matrix
- 2) cols of U form orthon. basis
- 3) $U^T = U^{-1}$

$$\bar{f}_1 \Rightarrow (2 \rightarrow 1)$$

$$U = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix}$$

U orthog.

$$\begin{aligned} \underline{x}_i \cdot \underline{x}_j &= U e_i \cdot U e_j \\ &= \{ \dots \}_{i=j}^n = 1 \end{aligned}$$

So cols are unit length
and orthog. hence lin indep
so a basis.

$\Rightarrow \exists$ Suppose $U = \left[\begin{array}{c} u_1 \\ u_2 \\ \vdots \\ u_n \end{array} \right]$

with u_1, \dots, u_n orthon. basis

$$U^T U = \left[\begin{array}{cccc} 1 & u_1 \bar{u}_1 & \cdots & u_n \bar{u}_1 \\ u_1 \bar{u}_1 & 1 & \cdots & u_n \bar{u}_2 \\ \vdots & \vdots & \ddots & \vdots \\ u_n \bar{u}_1 & u_n \bar{u}_2 & \cdots & 1 \end{array} \right] = \left[\begin{array}{cccc} 1 & -u_1 \bar{u}_1 & \cdots & -u_1 \bar{u}_n \\ -u_1 \bar{u}_1 & 1 & \cdots & -u_2 \bar{u}_1 \\ \vdots & \vdots & \ddots & \vdots \\ -u_1 \bar{u}_n & -u_2 \bar{u}_1 & \cdots & 1 \end{array} \right] = U^T U$$

since $\{u_i\}_{i=1}^n$ is orthon. basis.

$$U^T = U^{-1}$$

3) \Rightarrow) Aside what does A^T really mean?

Exer.

$$\underline{u} \cdot A \bar{y} = A^T \underline{u} \cdot \bar{y}$$

Sln

$$\underline{u}^T A \bar{y} = (\underline{A^T u})^T \bar{y}$$

LHS

\uparrow

RHS

Now!

$$(A^T \underline{u})^T = \underline{u}^T A$$

}

Back to 3) \Rightarrow 1)

Suppose $U^\top = U^{-1}$

Calculate $U\bar{u} \cdot U\bar{v} = U^\top U\bar{u} \cdot \bar{v}$

$$= \underline{u} \cdot \bar{v}$$

Done!

Recall from last time why we

use orthonormal bases $\underline{v}_1, \dots, \underline{v}_n$

$\underline{v} = a_1 \underline{v}_1 + \dots + a_n \underline{v}_n$ where

$$a_i = \frac{\underline{v} \cdot \underline{v}_i}{\underline{v}_i \cdot \underline{v}_i}$$

"coefs have simple formula"

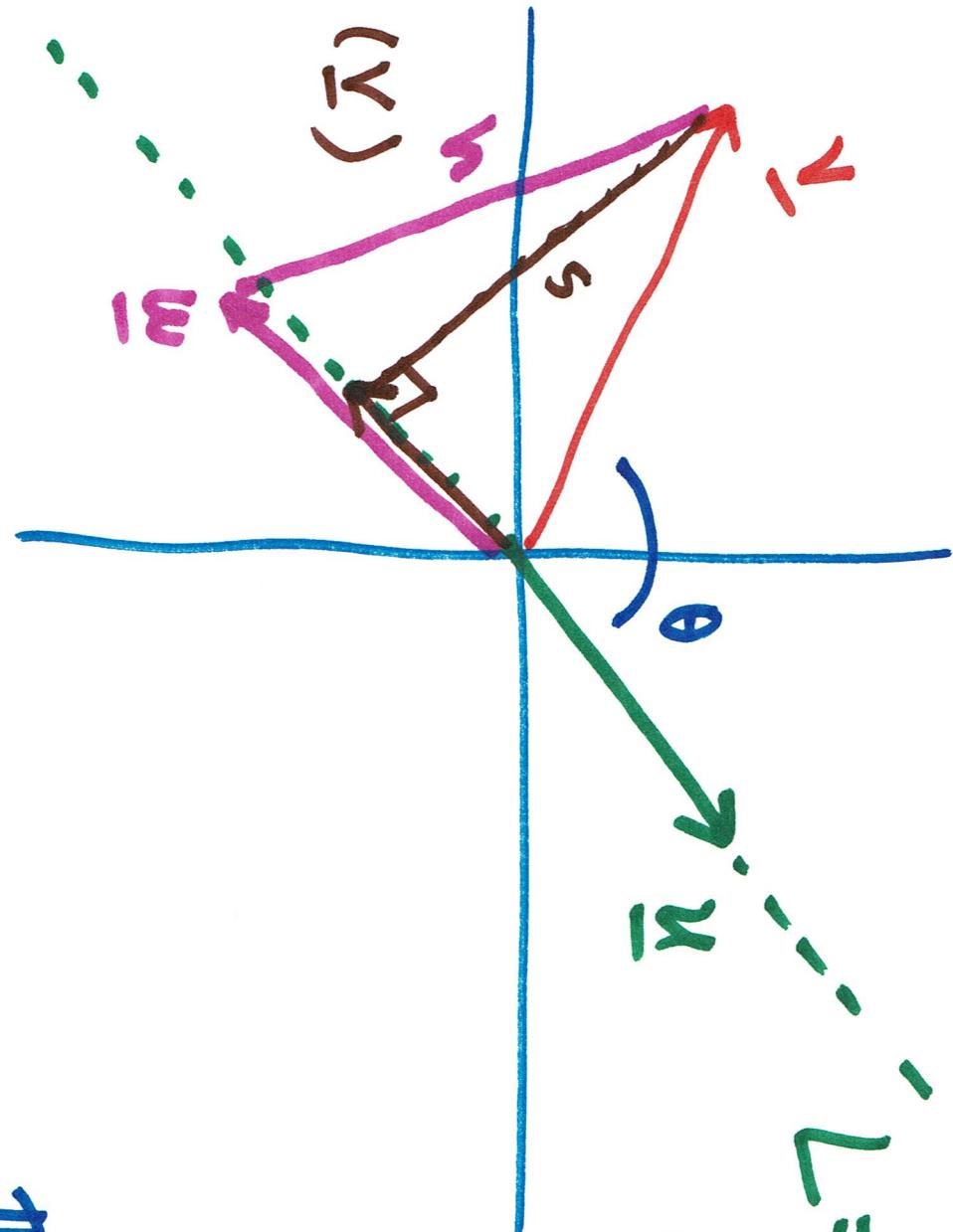
Geom. Interpretation

$$\frac{\bar{u} \cdot \bar{v}}{\bar{u} \cdot \bar{u}}$$

$\{ \bar{u}, \bar{v} \}$ - L = span line

$$\frac{\bar{u} \cdot \bar{v}}{\bar{u} \cdot \bar{u}} = \text{proj}_L(\bar{v})$$

\mathbb{R}^n



Remark When \underline{u} is unit length

$$\text{proj}_L(\underline{v}) = (\underline{v} \cdot \underline{u}) \underline{u}$$
$$= (\|\underline{v}\| \cos \theta) \underline{u}$$

$$\text{Claim 1) } (\mathbf{v} - \text{proj}_L(\mathbf{v}))^\top \mathbf{u} = 0$$

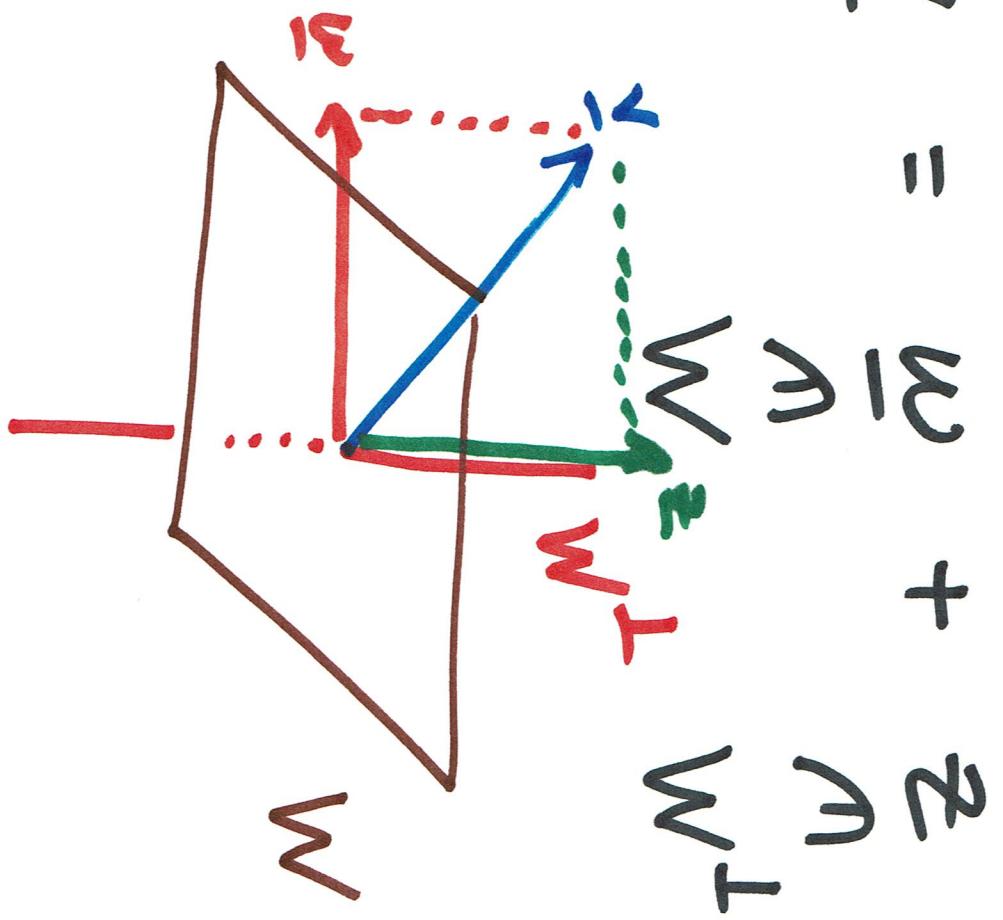
Why? $\because \mathbf{u} \in L$

$$0 = \bar{\mathbf{u}} \cdot \bar{\mathbf{u}} - \bar{\mathbf{u}} \cdot \bar{\mathbf{u}} = \bar{\mathbf{u}} \cdot \left(\frac{\bar{\mathbf{u}} \cdot \mathbf{u}}{\bar{\mathbf{u}} \cdot \bar{\mathbf{u}}} \bar{\mathbf{u}} - \bar{\mathbf{u}} \right) =$$

2) $\text{proj}_L(\mathbf{v})$ is closest vector in L to \mathbf{v}

Why? Pythag. Thm
 $h \leq s$

Then $W \subset \mathbb{R}^n$ any subspace
Any vector $\bar{v} \in \mathbb{R}^n$ has unique decomp.



Def We call \bar{w} from $v = \bar{w} + \bar{z}$

the orthog proj of \bar{v} onto W

$$\bar{w} = \text{proj}_W(v)$$

$\bar{z} = (\bar{v})^{\perp} \cap W$ onto $T_{\bar{v}} M$ Rank
 \bar{z} will be orthog proj of \bar{v} to $T_{\bar{v}} M$

If Suppose $\underline{w}_1, \dots, \underline{w}_k$ is orthog basis
of V

(We'll see in 10mins that orthog basis exists... Gram-Schmidt.)

$$\text{Set } \underline{w} = \frac{\underline{v} \cdot \underline{w}_1}{\underline{w}_1 \cdot \underline{w}_1} \underline{w}_1 + \dots + \frac{\underline{v} \cdot \underline{w}_k}{\underline{w}_k \cdot \underline{w}_k} \underline{w}_k$$

$$\text{Set } \underline{\bar{v}} = \underline{v} - \underline{w}$$

Note 1) $\bar{w} + \bar{z} = \bar{v}$



✓

2) $w \in W$

since

$$W = \text{Span}\{\bar{w}_1, \dots, \bar{w}_k\}$$

and

w is lin comb of
 $\bar{w}_1, \dots, \bar{w}_k$

✓

3) Exer check $\bar{z} \in W^\perp$

by showing $\bar{z} \cdot \bar{w}_i = 0$

✓

Unique? Suppose

$$w = w' + \bar{z}'$$

$$w$$

$$T w$$

$$\text{So } u + \bar{z} = w' + \bar{z}'$$

$$\text{So } u - w' = \bar{z}' - \bar{z}$$

$$w$$

$$T w$$

$$\text{But } w \cap w^\perp = \{0\}$$

since

" $w \in w \cap w^\perp$ satisfies $u \cdot u = 0$ "

$$\text{so } \bar{u} = 0$$

Conclude $\bar{w} - \bar{w}' = 0 = \bar{z} - \bar{z}'$

So $\bar{w} = \bar{w}'$ and $\bar{z} = \bar{z}'$

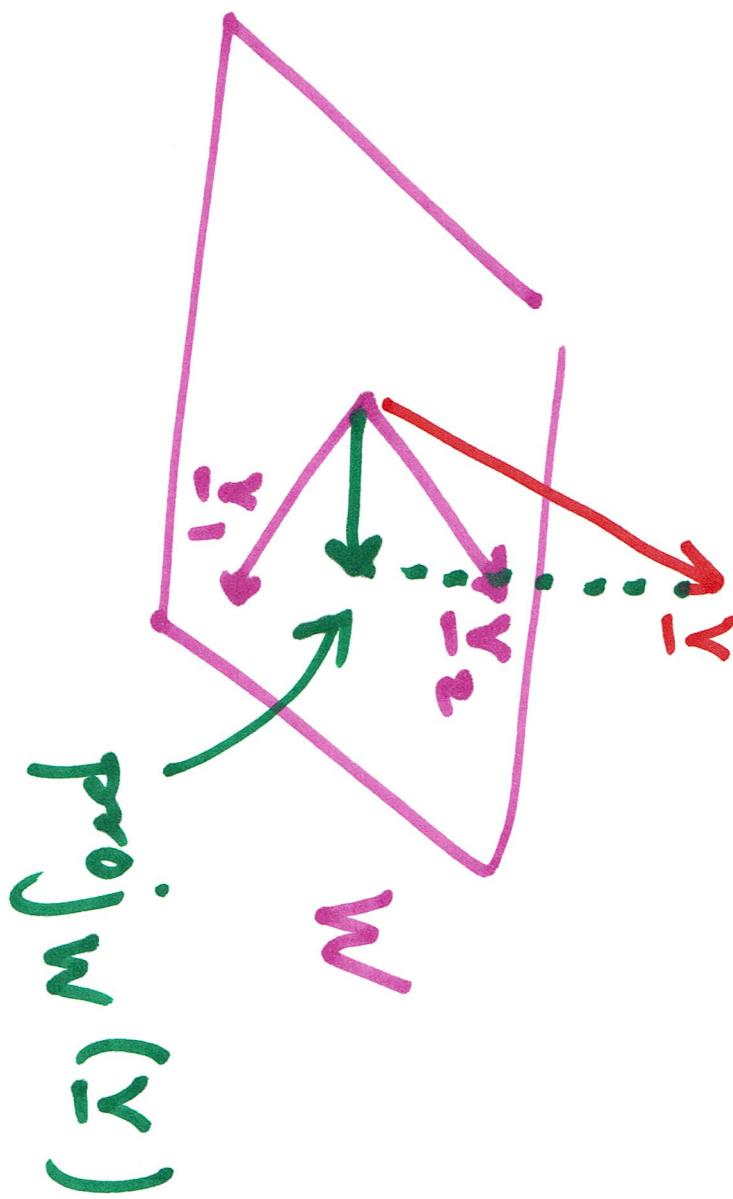
$y_1 = y_1'$

■

Exer $W = \text{Span}\{v_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, v_2 = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}\} \subset \mathbb{R}^3$

Find $\text{proj}_W(\bar{v})$ where $\bar{v} =$

$$\begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix}$$



Soln Want orthon basis \bar{u}_1, \bar{u}_2 of W

$$\text{to apply formula } \text{proj}_W(\psi) = \frac{\bar{u}_1 \cdot \psi}{\bar{u}_1 \cdot \bar{u}_1} \bar{u}_1 + \frac{\bar{u}_2 \cdot \psi}{\bar{u}_2 \cdot \bar{u}_2} \bar{u}_2$$

Method: Gram-Schmidt

$$2\bar{u}_2 = \frac{\bar{u}_1 \cdot \bar{u}_2}{\bar{u}_1 \cdot \bar{u}_1} \bar{u}_1$$

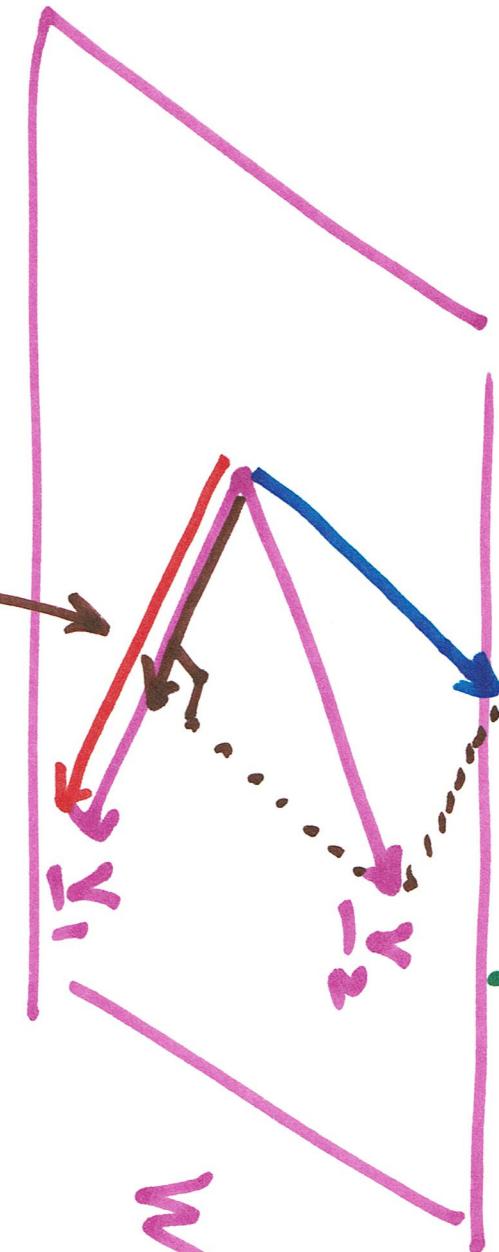
$$\begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} = \bar{u}_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

Set

Take

$$\bar{u}_2 = v_2 - \text{proj}_{\text{Span}\{\bar{u}_1\}}(v_2)$$

$$\text{proj}_{\text{Span}\{\bar{u}_1\}}(v_2)$$



$$S_0 \bar{u}_2 = \bar{v}_2 - \frac{\bar{v}_2 \cdot \bar{u}_1}{\bar{u}_1 \cdot \bar{u}_1} \bar{u}_1$$

$$= \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} -1 & \frac{1}{2} \\ 1 & -\frac{1}{2} \end{bmatrix}$$

2) Span $\{\bar{u}_1, \bar{u}_2\} = W$

Check to be sure!

$$1) \bar{u}_1 \cdot \bar{u}_2 = 0$$

Now calc. $\text{proj}_W(v) /$

$$\text{proj}_W(v) = \frac{v \cdot \bar{u}_1}{\bar{u}_1 \cdot \bar{u}_1} u_1 + \frac{v \cdot \bar{u}_2}{\bar{u}_2 \cdot \bar{u}_2} u_2$$

$$\left[\begin{array}{c} -\frac{1}{\sqrt{3}} \\ -\frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{array} \right] = \dots$$

Check to be sur!

1) $\text{proj}_W(v) \in W$

2) $v - \text{proj}_W(v) \in W^\perp$

Exer Find orthog basis for W^\perp

where $W = \text{Span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right\} \subset \mathbb{R}^4$

Sln Find any basis

Note $W^\perp = \text{Null} \left(\begin{bmatrix} 1 & 2 & 1 & 2 \end{bmatrix} \right)$

(Remember $\text{Row}(A)^\perp = \text{Null}(A)^\perp$)
Remember

Take $\bar{v}_3 = v_3 - \text{proj}_{\text{Span}\{\bar{v}_1, \bar{v}_2\}} v_3$

Take $\bar{v}_2 = v_2 - \text{proj}_{\text{Span}\{\bar{v}_1\}} v_2$.

Set $\bar{v}_1 = v_1$

Now orthogonalize using G-S.

G-S.

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{bmatrix} \bar{v}_3 =$$

$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \bar{v}_2 =$$

$$\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \bar{v}_1 =$$

...

$$\underline{u}_3 = \begin{bmatrix} - & 0 & 0 \\ 0 & - & 2 \\ 0 & 2 & - \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\underline{u}_2 = \begin{bmatrix} 0 & 0 & -2 \\ 0 & 0 & -2 \\ 0 & 0 & -2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\dots$$

$$\underline{u}_1 = \begin{bmatrix} - & 0 & 0 \\ 0 & - & 2 \\ 0 & 2 & - \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

(::) with