

# Welcome to Lecture 11! Changes of

Coordinates

Wed No Office Hours  
this week

Fri Quiz through § 4.6



I don't  
But to finish  
want to grant  
my proposal!

" Everything should be made as simple  
as possible, but not simpler. "

Albert Einstein

Abstract Challenge Suppose  $T: V \rightarrow W$

is lin transf, and  $\dim V = n < \infty$   
 $\dim W = m < \infty$

Suppose  $\beta = \{y_1, \dots, y_n\}$  is basis of  $V$

$\gamma = \{w_1, \dots, w_m\}$  is basis of  $W$   
 $w = c_1 w_1 + \dots + c_m w_m$

$$a_1 y_1 + \dots + a_n y_n$$

$$\begin{array}{ccc} V & \xrightarrow{T} & W \\ \uparrow T_\beta^{-1} & & \downarrow T_\gamma \\ \mathbb{R}^n & \xrightarrow{\text{matrix } A} & \mathbb{R}^m \end{array}$$

Find  $m \times n$  matrix  $A$

$$T_\gamma(w)$$

$$[w]_\gamma$$

$$[c]_m$$

$$T_\beta^{-1} \left( \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} \right)$$

$$\mathbb{R}^n$$

$$\mathbb{R}^m$$

Soln

$$A = \begin{bmatrix} 1 & & & \\ & [T(y_1)]_{\mathcal{R}} & & \\ & & \dots & \\ & & & [T(y_n)]_{\mathcal{R}} \\ & & & & 1 \end{bmatrix}$$

$$y_i \xrightarrow{\quad} T(y_i)$$



$$[T(y_i)]_{\mathcal{R}}$$

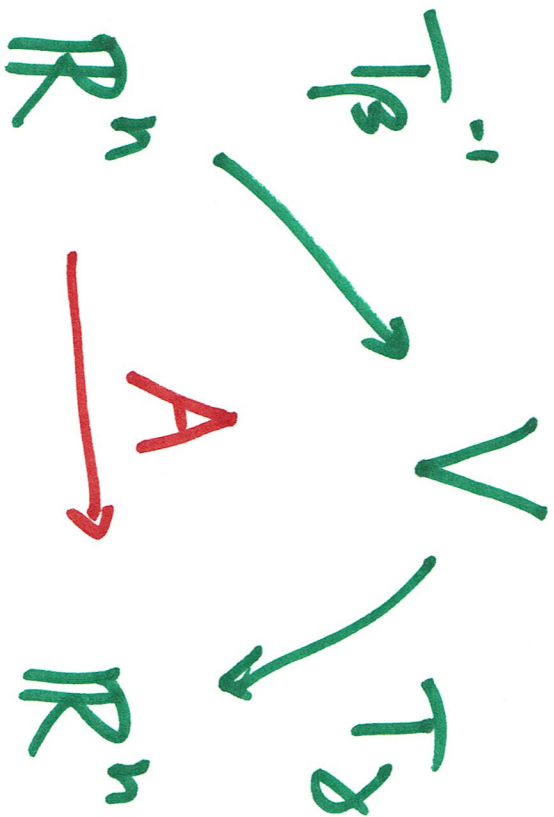
$$e_i = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix}$$



Special case  $V = W$ ,  $T = I =$  identity map  
= "do nothing"

Then

$$A = \begin{bmatrix} | & & | \\ [y_1] & \dots & [y_n] \\ \hline | & & | \end{bmatrix}$$





## Def Change of coord matrix

from basis  $\beta = \{y_1, \dots, y_n\}$  of  $V$   
to basis  $\gamma = \{w_1, \dots, w_n\}$

$$P_{\gamma \leftarrow \beta} = \begin{bmatrix} | & & | \\ [y_1]_{\gamma} & \dots & [y_n]_{\gamma} \\ | & & | \end{bmatrix}$$

Similarly

$$P_{\beta \leftarrow \gamma} = \begin{bmatrix} | & & | \\ [w_1]_{\beta} & \dots & [w_n]_{\beta} \\ | & & | \end{bmatrix}$$

Change of coords matrices satisfy

$${}_{\beta}P_{\alpha} [y]_{\beta} = [y]_{\alpha}, \quad y \in V$$

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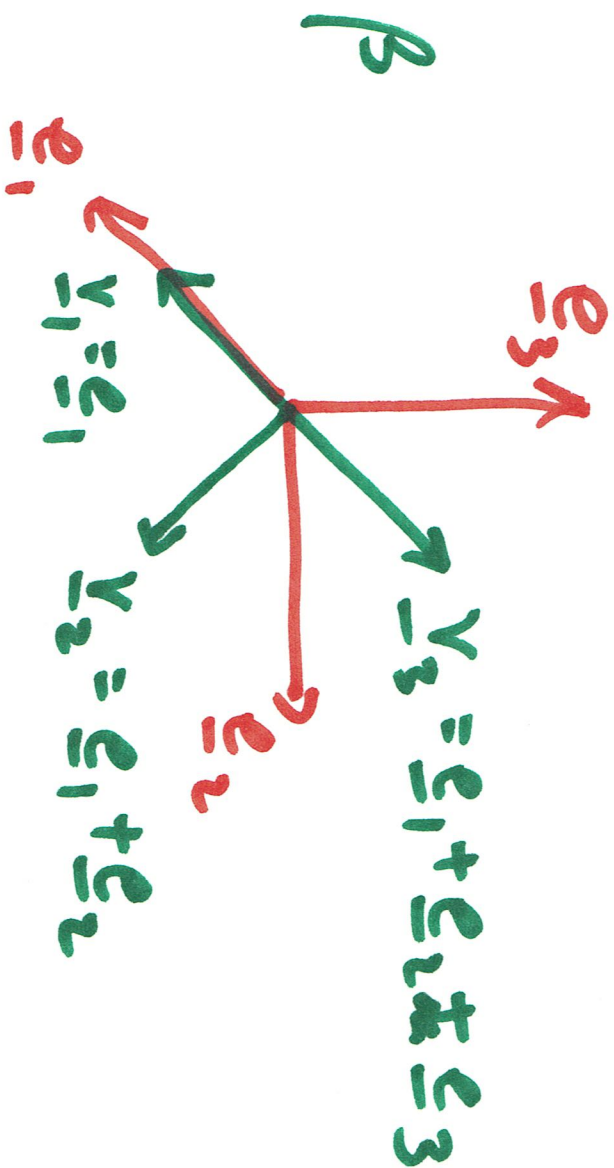
Note  $({}_{\alpha}P_{\beta})^{-1} = {}_{\beta}P_{\alpha}$   
 $({}_{\beta}P_{\alpha})^{-1} = {}_{\alpha}P_{\beta}$

Exer Take  $V = \mathbb{R}^3$

Consider bases

$$\beta = \{ \bar{y}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \bar{y}_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \bar{y}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \}$$

$$\gamma = \{ \bar{w}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \bar{w}_2 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \bar{w}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \}$$



Convert following  $\beta$ -coords to  $\gamma$ -coords

$$1) [\underline{y}]_{\beta} = \begin{bmatrix} \underline{0} \\ \underline{0} \\ \underline{1} \end{bmatrix}$$

$$\underline{y} = 0 \cdot \underline{y}_1 + 0 \underline{y}_2 + 1 \cdot \underline{y}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

these are coords  $\rightarrow$

of  $\underline{y}$  wrt std basis!

$$[\underline{y}]_{\gamma} = \begin{bmatrix} \underline{0} \\ \underline{0} \\ \underline{1} \end{bmatrix} \text{ since } \underline{y} = 0 \cdot \underline{w}_1$$

$$+ 0 \cdot \underline{w}_2 + 1 \underline{w}_3$$



$$2) [\underline{v}]_{\beta} = \begin{bmatrix} \underline{0} \\ \underline{1} \\ \underline{0} \end{bmatrix}$$

$$\underline{v} = \underline{0} \cdot \underline{v}_1 + \underline{1} \cdot \underline{v}_2 + \underline{0} \cdot \underline{v}_3$$

$$= \begin{bmatrix} \underline{1} \\ \underline{1} \\ \underline{0} \end{bmatrix}$$

again these are  $\rightarrow$   
coords of  $\underline{v}$  wrt std basis

$$[\underline{v}]_{\gamma} = \begin{bmatrix} \underline{a} \\ \underline{b} \\ \underline{c} \end{bmatrix}$$

so that

$$\underline{v} = \begin{bmatrix} \underline{1} \\ \underline{1} \\ \underline{0} \end{bmatrix} = \underline{a} \cdot \underline{w}_1 + \underline{b} \cdot \underline{w}_2 + \underline{c} \cdot \underline{w}_3$$

$$= \underline{a} \begin{bmatrix} \underline{0} \\ \underline{1} \\ \underline{1} \end{bmatrix} + \underline{b} \begin{bmatrix} \underline{1} \\ \underline{0} \\ \underline{1} \end{bmatrix} + \underline{c} \begin{bmatrix} \underline{1} \\ \underline{1} \\ \underline{1} \end{bmatrix}$$

this is a lin syst

$$\begin{bmatrix} 0 & 0 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 0 \end{bmatrix}$$

$$\rightsquigarrow [\bar{y}]_8 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

$$3) [y]_{\beta} = \begin{bmatrix} 2017 \\ e \\ \pi \end{bmatrix}$$

$$[y]_{\alpha} = ? = P [y]_{\beta}$$

$$P = \begin{bmatrix} 1 & 1 & 1 \\ [y_1]_{\alpha} & [y_2]_{\alpha} & [y_3]_{\alpha} \\ 1 & 1 & 1 \end{bmatrix}$$

We need to solve 3 lin systs!

$$y_1 = a_1 \cdot \underline{w}_1 + b_1 \underline{w}_2 + c_1 \underline{w}_3$$

$$y_2 = a_2 \underline{w}_1 + b_2 \underline{w}_2 + c_2 \underline{w}_3$$

$$y_3 = a_3 \underline{w}_1 + b_3 \underline{w}_2 + c_3 \underline{w}_3$$

$$\begin{bmatrix} 1 & 1 & 1 & \vdots & 1 & 1 & 1 \\ \underline{w}_1 & \underline{w}_2 & \underline{w}_3 & \vdots & y_1 & y_2 & y_3 \\ 1 & 1 & 1 & \vdots & 1 & 1 & 1 \end{bmatrix}$$



$$= \begin{bmatrix} 0 & 0 & 1 & \vdots & 1 & 1 & 1 \\ 0 & 1 & 1 & \vdots & 0 & 1 & 1 \\ 1 & 1 & 1 & \vdots & 0 & 0 & 1 \end{bmatrix}$$

row  
reduce  
→

$$\begin{bmatrix} 1 & 0 & 0 & \vdots & 0 & -1 & 0 \\ 0 & 1 & 0 & \vdots & -1 & 0 & 0 \\ 0 & 0 & 1 & \vdots & 1 & 1 & 1 \end{bmatrix}$$

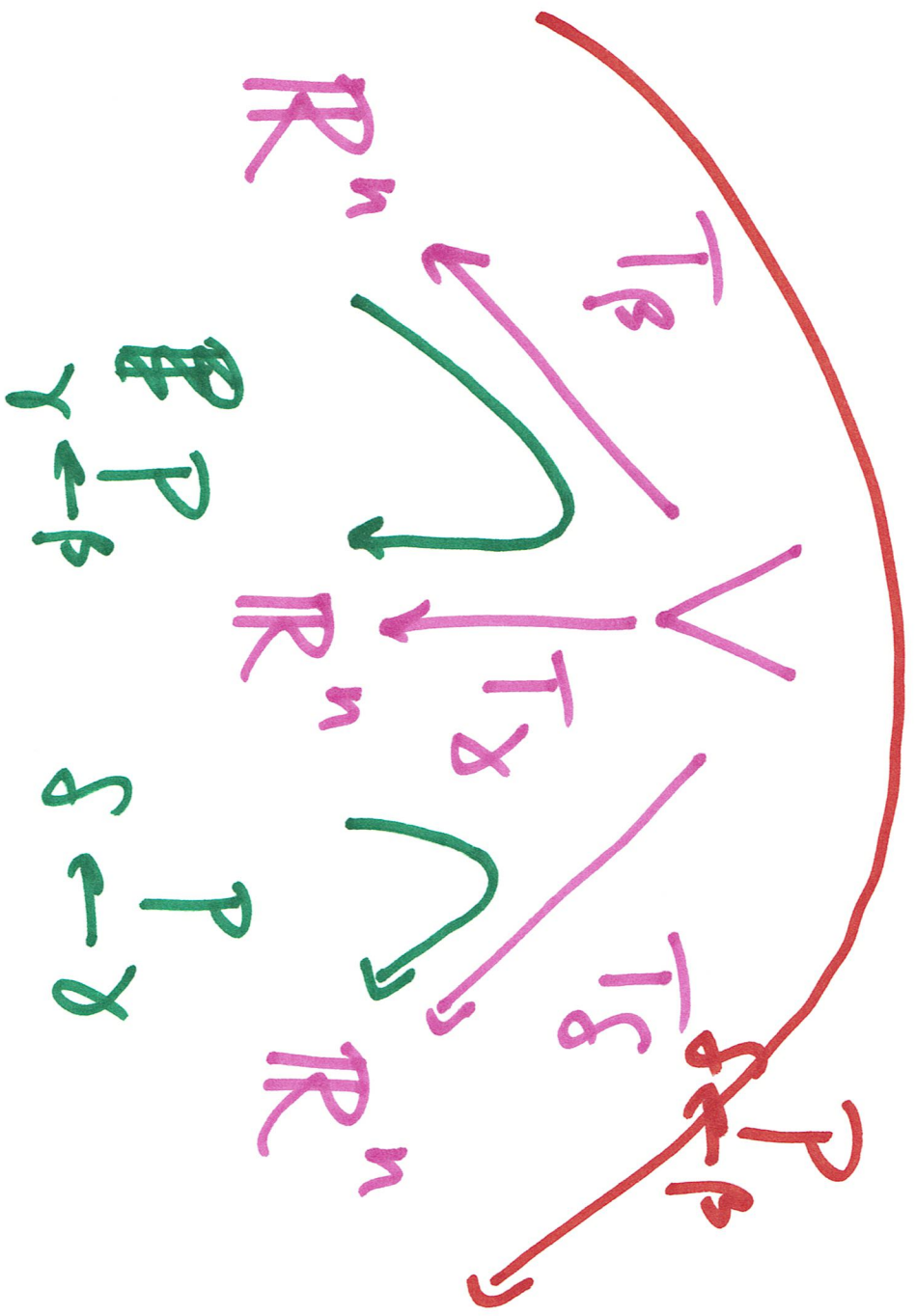
$$= \begin{bmatrix} I_3 & \\ & \vdots \\ & & \rho \leftarrow \beta \end{bmatrix}$$

Conclude

$$[y]_t = P \leftarrow \beta [y]_t = \begin{bmatrix} 0 & -1 & 0 \\ -1 & 0 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2017 \\ e \\ \pi \end{bmatrix}$$

$$= \begin{bmatrix} -e \\ -2017 \\ 2017 + e + \pi \end{bmatrix}$$

Suppose  $V$  has 3 bases  $\beta, \gamma, \delta$



$$P_{\beta} = P_{\gamma} P_{\delta}^{-1}$$

Special case  $V = \mathbb{R}^n$ ,  $\gamma = \text{std basis}$

$$\beta_{\text{std}} = \{e_1, \dots, e_n\}$$

$$\mathcal{P} = \mathcal{P} \quad \mathcal{P} = \mathcal{P} \quad \mathcal{P} = \mathcal{P}$$
$$\mathcal{P} \leftarrow \beta \quad \mathcal{P} \leftarrow \beta \quad \mathcal{P} \leftarrow \beta$$

Notation  $\mathcal{P} \leftarrow \beta = \mathcal{P} \leftarrow \beta = \begin{bmatrix} | & & | \\ \gamma_1 & \dots & \gamma_n \\ | & & | \end{bmatrix}$

where  $\beta = \{\gamma_1, \dots, \gamma_n\}$



Conclusion

$$P \leftarrow \beta \quad P = P_S^{-1} P_\beta$$

$$\begin{bmatrix} P_S \\ \vdots \\ P_\beta \end{bmatrix} \rightsquigarrow [I_n \mid P_S^{-1} P_\beta]$$

Exer Suppose  $\beta = \{ \underline{v}_1 = \begin{bmatrix} -1 \\ 2 \\ -1 \end{bmatrix}, \underline{v}_2 = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix},$

basis for  $\mathbb{R}^3$   $\underline{v}_3 \}$

Find  $\underline{v}_3$  so that  $\begin{bmatrix} \underline{v}_1 \\ \underline{v}_2 \\ \underline{v}_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$

Soln  $1 \cdot \underline{v}_1 + 2 \cdot \underline{v}_2 + 3 \cdot \underline{v}_3 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

$$\begin{bmatrix} -1 \\ 2 \\ -1 \end{bmatrix} + 2 \cdot \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} + 3 \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 + 2 + 3x \\ 2 + 2 + 3y \\ -1 + 4 + 3z \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 3x \\ 3y \\ 3z \end{bmatrix} = \begin{bmatrix} 0 \\ -4 \\ -3 \end{bmatrix}$$

$$\vec{y}_3 = \begin{bmatrix} 0 \\ -4/3 \\ -1 \end{bmatrix}$$