

1. For which values of a is the following matrix invertible?

$$\begin{pmatrix} a & 0 & 1 \\ -1 & a & 0 \\ 0 & 1 & 1 \end{pmatrix}$$

Solution: We compute the determinant and find when it is zero. Expanding across the top row gives:

$$\begin{vmatrix} a & 0 & 1 \\ -1 & a & 0 \\ 0 & 1 & 1 \end{vmatrix} = a \cdot (a \cdot 1 - 0 \cdot 1) + 1 \cdot (-1 \cdot 1 - a \cdot 0) = a^2 - 1$$

So the matrix is invertible unless $a = \pm 1$.

2. Label the following statements as either true or false.

- (a) $\det A^T = \det A$
- (b) A matrix A is invertible if there is another matrix B such that $AB = I$.
- (c) The dimension of a subspace of \mathbb{R}^n is at most n .
- (d) If A and B are invertible $n \times n$ matrices, then $(AB)^{-1} = A^{-1}B^{-1}$.
- (e) If A is a square matrix, then after adding 2 times the first row of A to the second row, the determinant is multiplied by 2.
- (f) Every subspace of \mathbb{R}^n contains at most n vectors.
- (g) If a 3×5 matrix A represents a surjective linear transformation, then $\text{Null}(A)$ must be exactly 2-dimensional.
- (h) If A and B are $n \times n$ matrices and AB is invertible, then BA must be invertible too.

Solution: a) is true. For example, using row reduction you can express A as a product of elementary matrices, and then it suffices to verify that $\det E^T = \det E$ where E is an elementary matrix.

b) is false. Either we also need to require that $BA = I$, or we need to require that A and B are square. Otherwise, $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$ and $B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$ gives a counterexample.

c) is true. The dimension of a subspace of \mathbb{R}^n can be computed as the number of pivots in any matrix whose columns span that subspace, and because such a matrix has n rows, it can have at most n pivots.

d) is false. The correct rule is that $(AB)^{-1} = B^{-1}A^{-1}$, because $ABB^{-1}A^{-1} = A(BB^{-1})A^{-1} = AA^{-1} = I$ and similarly for multiplication on the other side. Most pairs of invertible $n \times n$ matrices will give a counterexample, such as $A = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$, $B = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$.

e) is false. The determinant is unchanged. It would be multiplied by 2 if we just multiplied a row by 2.

f) is false: \mathbb{R}^n itself is a subspace of \mathbb{R}^n , and contains infinitely many vectors (if $n > 0$).

g) is true. If the linear transformation $T : \mathbb{R}^5 \rightarrow \mathbb{R}^3$ is surjective, then its rank is 3, so the null space has dimension $5 - 3 = 2$ by the rank theorem.

h) is true. A matrix is invertible if and only if its determinant is nonzero. But since $\det(AB) = \det(A)\det(B) = \det(B)\det(A) = \det(BA)$, if AB has nonzero determinant, so does BA .

3. A linear transformation, $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$, has the following effect:

$$T \left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right) = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}, T \left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right) = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}, T \left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right) = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}.$$

- (a) What is the standard matrix of the transformation?
 (b) Is the transformation one-to-one? Is it onto?
 (c) Find a basis for the column and null spaces.

Solution:

(a) Standard matrix $\begin{bmatrix} 1 & 0 & 1 \\ -1 & -1 & 1 \\ 2 & 1 & 0 \end{bmatrix}$

(b) Row-reduce $\begin{bmatrix} 1 & 0 & 1 \\ -1 & -1 & 1 \\ 2 & 1 & 0 \end{bmatrix} [R_3 - 2R_1]R_2 + R_1 \begin{bmatrix} 1 & 0 & 1 \\ 0 & -1 & 2 \\ 0 & 1 & -2 \end{bmatrix} [R_3 + R_2]R_2 \div -1 \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix}$

This is neither one-to-one nor onto.

(c) The basis for the column space $\left\{ \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \right\}$ is formed by the linearly independent columns of A . Rank=2

Basis for the null space found by solving $A\mathbf{x} = \mathbf{0}$. x_3 is the free variable. Basis: $\left\{ \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} \right\}$.

Dim(Nul(A))= 1

4. (a) Let A be a $n \times n$ matrix. Relate $\det(-A)$ to $\det(A)$. (Be careful)

Solution: We can pull out a scalar row by row, and since there are n rows we get $\det(-A) = (-1)^n \det(A)$

- (b) Suppose A, B are $n \times n$ matrices. If AB is invertible show A and B must both be invertible.

Solution: $\det(AB) \neq 0$ and $\det(A)\det(B) = \det(AB)$ so $\det(A), \det(B) \neq 0$. Thus A, B are invertible.

- (c) Suppose $A^k = 0$. Show that A cannot be invertible.

Solution: $\det(A^k) = \det(A)^k = 0$ so $\det(A) = 0$. Thus A cannot be invertible.

5. Let $\mathcal{B} = \{1, t - 1, (t - 1)^2\}$ be a subset of \mathbb{P}_2 .

(a) Show that \mathcal{B} is a basis for \mathbb{P}^2 .

Solution: Under the usual isomorphism $\mathbb{P}_2 \rightarrow \mathbb{R}^3$, this amounts to show that the following determinant is non-zero:

$$\begin{vmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{vmatrix}$$

This is true because the determinant is 1.

(b) Find the \mathcal{B} -coordinate of $1 + 2t + 3t^2$.

Solution: By the Taylor expansion,

$$1 + 2t + 3t^2 = 6 + 8(t - 1) + 3(t - 1)^2$$

Therefore, the \mathcal{B} -coordinate is $(6, 8, 3)$.

6. Let S be the tetrahedron in \mathbb{R}^3 with vertices at $(1, 1, 1)$, $(2, 3, 4)$, $(3, 4, 5)$, and $(4, 5, 7)$. Find its volume.

Solution: After translating $(1, 1, 1)$ to the origin, the other vertices are $(1, 2, 3)$, $(2, 3, 4)$, and $(3, 4, 6)$. The volume of the parallelepiped with these vertices is the absolute value of the following determinant

$$\begin{vmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 6 \end{vmatrix} = -1$$

Therefore, the volume of S is $\frac{1}{6}$.

7. Let $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the linear transformation given by rotating points $\frac{\pi}{4}$ radians counterclockwise around the origin, then reflecting them across the y axis. What is the standard matrix of T ?

Solution: The columns of the standard matrix of a linear transformation T are given by applying T to the standard basis vectors $e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $e_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$. e_1 transforms as follows:

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} \xrightarrow{\text{rotate}} \begin{bmatrix} \frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} \end{bmatrix} \xrightarrow{\text{reflect}} \begin{bmatrix} -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} \end{bmatrix} \quad (1)$$

e_2 transforms as follows:

$$\begin{bmatrix} 0 \\ 1 \end{bmatrix} \xrightarrow{\text{rotate}} \begin{bmatrix} -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} \end{bmatrix} \xrightarrow{\text{reflect}} \begin{bmatrix} \frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} \end{bmatrix} \quad (2)$$

Hence the standard matrix of T is $\begin{bmatrix} -\frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{bmatrix}$.

8. $\mathbb{R}[x]$ is the set of polynomials with real coefficients. It is a (real) vector space with the usual addition and scalar multiplication you know and love from high school. Differentiation, $\frac{d}{dx} : \mathbb{R}[x] \rightarrow \mathbb{R}[x]$ is a linear operator.

(a) What is $\text{Ker} \left(\frac{d}{dx} \right)$?

Solution:

$$\text{Ker} \left(\frac{d}{dx} \right) = \{ \alpha \in \mathbb{R} \},$$

that is, the constant polynomials, since the derivative of a polynomial is zero if and only if the polynomial is constant.

(b) What is $\text{Im} \left(\frac{d}{dx} \right)$?

Solution:

$$\text{Im} \left(\frac{d}{dx} \right) = \mathbb{R}[x].$$

This is true because every polynomial is the derivative of its indefinite integral (where you choose any value for C). For example, $2x$ is in the image because it is the derivative of x^2 , which is the indefinite integral of $2x$ with $C = 0$.

(c) Is $\frac{d}{dx}$ injective? Is $\frac{d}{dx}$ surjective?

Solution: It is not injective as it has nonzero kernel. It is surjective because the image is all of $\mathbb{R}[x]$.

(d) Is $\dim(\mathbb{R}[x])$ finite? If so, what is it? If not, prove that it is not.

Solution: It is not finite because we have exhibited a linear operator on $\mathbb{R}[x]$ which is surjective but not injective.