

## Lecture 2-5 and 2-7

Wednesday, January 31, 2018 11:57 AM

Where we left off,

- A linear transformation,  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ ,  
 can be represented by an  $m \times n$  matrix,  
 $A$ , where  $T(\underline{x}) = A\underline{x}$ .

domain  $\mathbb{R}^n$  codomain  $\mathbb{R}^m$   
 rows columns

Fact. Suppose  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  and let  $T(\underline{x}) = A\underline{x}$ . The matrix  $A$  can be computed by,

$$A = [T(\underline{e}_1) \cdots T(\underline{e}_n)]$$

Where  $\underline{e}_1, \dots, \underline{e}_n$  are the standard basis vectors in  $\mathbb{R}^n$ .

Ex 1. Let  $T(\underline{x}) = A\underline{x}$  be the map that sends a vector  $\underline{x} \in \mathbb{R}^3$  to a corresponding point on the x-y plane  
 ("smash" 3 space to a plane.)  
 $(\underline{x} = (x, y, z) \rightarrow (x, y, 0))$ , where the x-y plane is thought of as  $\mathbb{R}^2$ .

$$T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$

$$\left. \begin{array}{l} T(\underline{e}_1) = \underline{e}_1 \\ T(\underline{e}_2) = \underline{e}_2 \\ T(\underline{e}_3) = \underline{0} \end{array} \right\} \Rightarrow A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

Is the above map **onto**?

Yes, for any  $y \in \mathbb{R}^2$  we can find an  $x \in \mathbb{R}^3$  such that  $T(x) = y$  (i.e. if  $y = (x, y)$  let  $x = (x, y, 0)$ ).

Is the above map **one-to-one**?

No, let  $x_1 = (x, y, 0)$  and  $x_2 = (x, y, 1)$ , then  $T(x_1) = T(x_2) = (x, y)$ .

For the following let  $T(x) = Ax$ . For the specified  $A$ , determine if  $T(x)$  is one-to-one and onto.

Ex 2.  $A = \begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix}$

$$\begin{aligned} \left[ \begin{array}{cc|c} 2 & 1 & 0 \\ 0 & 3 & 0 \end{array} \right] &\rightarrow \left[ \begin{array}{cc|c} 2 & 1 & 0 \\ 0 & 1 & 0 \end{array} \right] \\ &\rightarrow \left[ \begin{array}{cc|c} 2 & 0 & 0 \\ 0 & 1 & 0 \end{array} \right] \rightarrow \left[ \begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & 0 \end{array} \right] \end{aligned}$$

(\*) Sol'n of  $T(x) = 0$  is unique.

So by theorem 11,  $T$  is one-to-one. Also,  $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$  span  $\mathbb{R}^2 \Rightarrow T$  is onto.

Ex 3.  $A = \begin{bmatrix} 2 & 2 & 0 \\ 3 & 2 & 1 \end{bmatrix}$

3 vectors,  $\begin{bmatrix} 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ , in  $\mathbb{R}^2$  are not linearly independent  $\Rightarrow$  (thm 12)  $T$  is not one-to-one.

$$\begin{bmatrix} 2 & 2 & 0 \\ 3 & 2 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 \\ 3 & 2 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$$

these columns  
clearly span  $\mathbb{R}^2$   
 $\Rightarrow T$  is onto.

Ex 4.  $\begin{bmatrix} 2 & 3 & 5 \\ 1 & 3 & 4 \\ 0 & 1 & 1 \end{bmatrix}$

$\text{col}(1) + \text{col}(2) = \text{col}(3) \Rightarrow$  not linearly independent  
 $\Rightarrow T$  is not one-to-one

Also since we have 3 vectors that are linearly dependent in  $\mathbb{R}^3 \Rightarrow$  they don't span  $\mathbb{R}^3 \Rightarrow T$  is not onto.

Now onto 2.1 Matrix Operations.

$$\left\{ \begin{array}{l} \text{Linear transformations} \\ \text{from } \mathbb{R}^n \text{ to } \mathbb{R}^m \end{array} \right\} = \left\{ (m \times n) \text{ Matrices} \right\}$$

Add transformations =  $A+B$

$$\begin{array}{ccc} T_A(x) + T_B(x) = T_{A+B}(x) & = & A+B \\ \uparrow \quad \uparrow & & \uparrow \quad \uparrow \\ \text{both } \mathbb{R}^n \rightarrow \mathbb{R}^m & & \text{both } m \times n \end{array}$$

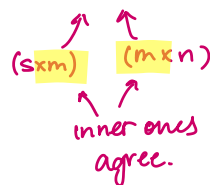
Multiply by a constant -  $\lambda A$

$$\lambda T_A(x) = T_{\lambda A}(x)$$

Composition of transformations -  $AB$  new matrix is  $s \times n$

$$(T_A \circ T_B)(x) = T_{AB}(x)$$

$\mathbb{R}^m \rightarrow \mathbb{R}^s$      $\mathbb{R}^n \rightarrow \mathbb{R}^m$      $\mathbb{R}^n \rightarrow \mathbb{R}^s$



Ex 5. Prove that, in general,  $(A^k)_{ij} \neq (A_{ij})^k$ .

Give an example where  $(A^k)_{ij} = (A_{ij})^k$ .

Find a counter example:  $A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$

$$A^2 = A \cdot A$$

$$= \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$$

It is true for any diagonal matrix,

$$A = \begin{bmatrix} a_1 & 0 & \dots & 0 \\ 0 & a_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & a_n \end{bmatrix}$$

$$A^k = \begin{bmatrix} a_1^k & 0 & \dots & 0 \\ 0 & a_2^k & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & a_n^k \end{bmatrix}$$

Ex Let  $A = \begin{bmatrix} 1 & 3 \\ 0 & 2 \end{bmatrix}$   $B = \begin{bmatrix} 2 & k \\ 0 & -1 \end{bmatrix}$ , for what value of  $k$  (if any) does  $AB = BA$ ?

$$AB = \begin{bmatrix} 1 & 3 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 2 & k \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 2 & k-3 \\ 0 & -2 \end{bmatrix}$$

$$\begin{bmatrix} 2 & k-3 \\ 0 & -2 \end{bmatrix} = \begin{bmatrix} 2 & k \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 0 & 2 \end{bmatrix}$$

$$BA = \left[ \begin{array}{c|c} \begin{matrix} 6 & -k \\ 0 & -1 \end{matrix} & \begin{matrix} 1 & 3 \\ 0 & 2 \end{matrix} \end{array} \right] = \left[ \begin{array}{cc} 6 & 6+2k \\ 0 & -2 \end{array} \right]$$

$$BA = AB \text{ when } 6+2k = k-3$$

$$k = -9$$

Ex. Same as above,

$$A = \begin{bmatrix} 2 & 2 \\ 1 & k \end{bmatrix} \quad B = \begin{bmatrix} 0 & -1 \\ 3 & 1 \end{bmatrix}$$

$$AB = \begin{bmatrix} 6 & 0 \\ 3k & k \end{bmatrix} \quad BA = \begin{bmatrix} -1 & -k \\ 7 & 6+k \end{bmatrix}$$

impossible

$$\text{Ex. } A = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 \\ k & 1 \end{bmatrix}$$

$$AB = \begin{bmatrix} 2 & 0 \\ 3k & 3 \end{bmatrix} \quad BA = \begin{bmatrix} 2 & 0 \\ 2k & 3 \end{bmatrix}$$

$$k = 0$$

Recall the augmented matrix form we produced for  $A\mathbf{x} = \mathbf{b}$ . We can use the same form for problems of the type  $AB = I$ .

$$\text{Ex. Let } A = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \text{ and suppose } AB = I. \text{ Find } B?$$

the matrix that  
... on this side

$$\left[ \begin{array}{ccc|ccc} 3 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 & 0 & 1 \end{array} \right]$$

appears on this one  
after elementary row  
operations is B

$$\rightarrow \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & \frac{1}{3} & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 & 0 & 1 \end{array} \right] \rightarrow \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & \frac{1}{3} & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & -\frac{1}{3} & 0 & 1 \end{array} \right]$$

$$\rightarrow \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & \frac{1}{3} & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & -\frac{1}{3} & -1 & 1 \end{array} \right]$$

B!

What are the limitations of the above?

A & B must be square

in general for A to have  
an inverse it must be square,  
but don't confuse this with the  
fact that  $AB=I$  is possible for  
non-square A and B.

Let  $AB=I$ . Compute B for the following As,

(1)  $A = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$

(2)  $A = \begin{bmatrix} 0 & 2 \\ 1 & 2 \end{bmatrix}$

$$(3) \quad A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 2 \\ 1 & 0 & -1 \end{bmatrix}$$

$$(4) \quad A = \begin{bmatrix} 0 & 2 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$