

## Problem 26, §16.7

We're trying to integrate  $\mathbf{F}(x, y, z) = (xz, x, y)$  over  $S$ , the hemisphere of radius 5 centered at the origin in the positive  $y$  half of  $\mathbb{R}^3$ , oriented in the positive  $y$  direction.

In my 8 AM section, I tried to use  $y$  and  $\theta$  (in the  $xz$  plane) in section. But this doesn't work, since  $r$  depends on  $y$ .  $S$  is a sphere of radius 5, so we have the following relationship between  $r$  (in the  $xz$  plane) and  $y$ :

$$(x^2 + z^2) + y^2 = 25 \Leftrightarrow r^2 + y^2 = 25 \Leftrightarrow r = \sqrt{25 - y^2}$$

therefore the parameterization I should have used is

$$\mathbf{r}(y, \theta) = \left( \sqrt{25 - y^2} \cos \theta, y, \sqrt{25 - y^2} \sin \theta \right)$$

but this is kind of nasty to calculate derivatives and cross products for. We use  $\mathbf{r}_y \times \mathbf{r}_\theta$  because it gives the correct orientation. We'd get

$$\mathbf{r}_y \times \mathbf{r}_\theta = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -\frac{y}{\sqrt{25-y^2}} \cos \theta & 1 & -\frac{y}{\sqrt{25-y^2}} \sin \theta \\ -\sqrt{25-y^2} \sin \theta & 0 & \sqrt{25-y^2} \cos \theta \end{vmatrix} = \left( \sqrt{25-y^2} \cos \theta, y, \sqrt{25-y^2} \sin \theta \right)$$

giving us a full integral of

$$\begin{aligned} \iint_S \mathbf{F}(x, y, z) \cdot d\mathbf{S} &= \int_0^{2\pi} \int_0^5 \left( (25 - y^2) \cos \theta \sin \theta, \sqrt{25 - y^2} \cos \theta, y \right) \\ &\quad \cdot \left( \sqrt{25 - y^2} \cos \theta, y, \sqrt{25 - y^2} \sin \theta \right) dy d\theta \\ &= \int_0^{2\pi} \int_0^5 (25 - y^2)^{\frac{3}{2}} \cos^2 \theta \sin \theta + \sqrt{25 - y^2} y \cos \theta + \sqrt{25 - y^2} y \sin \theta dy d\theta \\ &= 0 \end{aligned}$$

because every term contains a factor of a trig function, cosine or sine, integrated from zero to  $2\pi$ , giving zero.

I could have done the problem that way. However, I think when spheres are involved, choosing a parameterization based on spherical coordinates might be a better idea. While it may be difficult to do all the trig derivatives and manipulations, it is easier to be confident that your parameterization is correct. In this case,  $\rho = 5$ , so we can use

$$\mathbf{r}(\phi, \theta) = (5 \sin \phi \cos \theta, 5 \sin \phi \sin \theta, 5 \cos \phi)$$

We use  $\mathbf{r}_\phi \times \mathbf{r}_\theta$  because it gives the correct orientation. The cross product term is

$$\mathbf{r}_\phi \times \mathbf{r}_\theta = \begin{pmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 5 \cos \phi \cos \theta & 5 \cos \phi \sin \theta & -5 \sin \phi \\ -5 \sin \phi \cos \theta & 5 \sin \phi \sin \theta & 0 \end{pmatrix} = (25 \sin^2 \phi \cos \theta, -25 \sin^2 \phi \cos \theta, 25 \sin \phi \cos \theta)$$

giving us a full integral of

$$\begin{aligned}
\iint_S \mathbf{F}(x, y, z) \cdot d\mathbf{S} &= \int_0^\pi \int_0^\pi (25 \sin \phi \cos \phi \cos \theta, 5 \sin \phi \cos \theta, 5 \sin \phi \sin \theta) \\
&\quad \cdot (25 \sin^2 \phi \cos \theta, -25 \sin^2 \phi \cos \theta, 25 \sin \phi \cos \theta) d\phi d\theta \\
&= \int_0^\pi \int_0^\pi 25 \sin^3 \phi \cos \phi \cos^2 \theta - 125 \sin^3 \phi \cos^2 \theta + 125 \sin^2 \phi \sin \theta \cos \theta d\phi d\theta \\
&= 0
\end{aligned}$$

because every term integrates to something with a factor of sine, which, when evaluated at zero and  $\pi$  gives zero.

There is another way to solve this problem, using symmetries. Note that

$$\mathbf{F}(x, y, z) = (xz, x, y) \text{ and } \mathbf{n}(x, y, z) = \frac{(x, y, z)}{5} \text{ so } \mathbf{F}(x, y, z) \cdot \mathbf{n}(x, y, z) = \frac{(x^2z, xy, yz)}{5}$$

where  $\mathbf{n}$  denotes the unit normal to  $S$ . Therefore

$$\begin{aligned}
\mathbf{F}(-x, y, -z) &= (xz, -x, y) \text{ and } \mathbf{n}(-x, y, -z) = \frac{(-x, y, -z)}{5} \\
\text{so } \mathbf{F}(-x, y, -z) \cdot \mathbf{n}(-x, y, -z) &= \frac{(-x^2z, -xy, -yz)}{5} = -\mathbf{F}(x, y, z) \cdot \mathbf{n}(x, y, z)
\end{aligned}$$

Since sending  $(x, y, z)$  to  $(-x, y, -z)$  consists of a rotation by  $\pi$  in the  $xz$  plane, and  $S$  is symmetric under rotations,  $(x, y, z)$  and  $(-x, y, -z)$  occur in canceling pairs, so the integral will be zero.