

## Elimination

We can do this with a Groebner Basis

Def: Given  $I = (f_1, \dots, f_s) \subseteq k[x_1, \dots, x_n]$  the  $d^{th}$  elimination ideal in  $k[x_{d+1}, \dots, x_n]$  is

$$I_d = I \cap k[x_{d+1}, \dots, x_n].$$

## Theorem (The Elimination Theorem)

Let  $I \subseteq k[x_1, \dots, x_n]$  be an ideal and let  $G$  be a Gröbner basis of  $I$  w.r.t lex  $x_1 > \dots > x_n$ . Then for every  $0 \leq d \leq n$

$$G_d = G \cap k[x_{d+1}, \dots, x_n]$$

is a Gröbner basis of  $I_d$   $\leftarrow$   $d^{th}$  elim. ideal.

Proof: Fix  $d$ .  $G_d \subseteq I_d$  by construction, so

$$\text{need to check } (\text{LT}(I_d)) = (\text{LT}(G_d))$$

Certainly  $(\text{LT}(G_d)) \subseteq (\text{LT}(I_d))$ . Show other direction.

Let  $f \in I_d$  Show  $\text{LT}(f)$  is divisible by  $\text{LT}(g)$  for some  $g \in G_d$

$$f \in I_d \Rightarrow f \in I \therefore \text{LT}(g) \mid \text{LT}(f) \text{ for some } g \in G$$

Since  $G$  is a GB of  $I$ .

$f \in I_d \Rightarrow \text{LT}(f)$  only has var.  $x_{d+1}, \dots, x_n$  appearing

$\Rightarrow \text{LT}(g)$  only has var.  $x_{d+1}, \dots, x_n$  appearing

$$\text{LT}(g) \in k[x_{d+1}, \dots, x_n]$$

we are using Let  $x_1 \rightarrow x_n \therefore$  any monomials

in  $x_1, \dots, x_n$  is greater than all monomials in  $K[x_{l+1}, \dots, x_n]$

$\therefore$  since  $LT(g) \in K[x_{l+1}, \dots, x_n] \Rightarrow g \in K[x_{l+1}, \dots, x_n]$

$\therefore g \in G_l \therefore LT(f) \in (LT(G_l))$

$$\boxed{Ex} I_2 = I \cap \mathbb{C}[z] = (z^6 - 4z^4 + 11z^3 - z^2)$$

↑ solutions for  $g(z)$  are called partial solutions for  $V(I)$

$$I_1 = I \cap \mathbb{C}[y, z] = (z^6 - 4z^4 + 11z^3 - z^2, 2yz^2 + z^4 - z^2, y^2 - y - z^2 + z)$$

$$I_0 = I$$

Our procedure of solving  $I_2$ , then using for  $I_1$ , etc  
is called "Extension"

- To describe points in  $V(I)$  work one coordinate at a time  $\Rightarrow$  at the  $l^{th}$  step we have  $(a_{l+1}, \dots, a_n) \in V(I_l)$  is a partial solution. Now want to find  $a_l$  s.t.  $(a_l, a_{l+1}, \dots, a_n) \in V(I_{l-1})$

$$\text{i.e. if } I_{l-1} = (g_1, \dots, g_r) \subseteq K[x_l, \dots, x_n]$$

want  $x_l = a_l$  which solve

$$g_1(x_l, a_{l+1}, \dots, a_n) = \dots = g_r(x_l, a_{l+1}, \dots, a_n) = 0$$

Problem  $\uparrow$  this might not have a solution.

i.e. want to find roots of  $\gcd(g(x_1), \dots, g_r(x_r))$

Ex)  $I = (x^2 - 1, xz - 1)$

$$I = (y - z, xz - 1) \quad \leftarrow G.B.$$

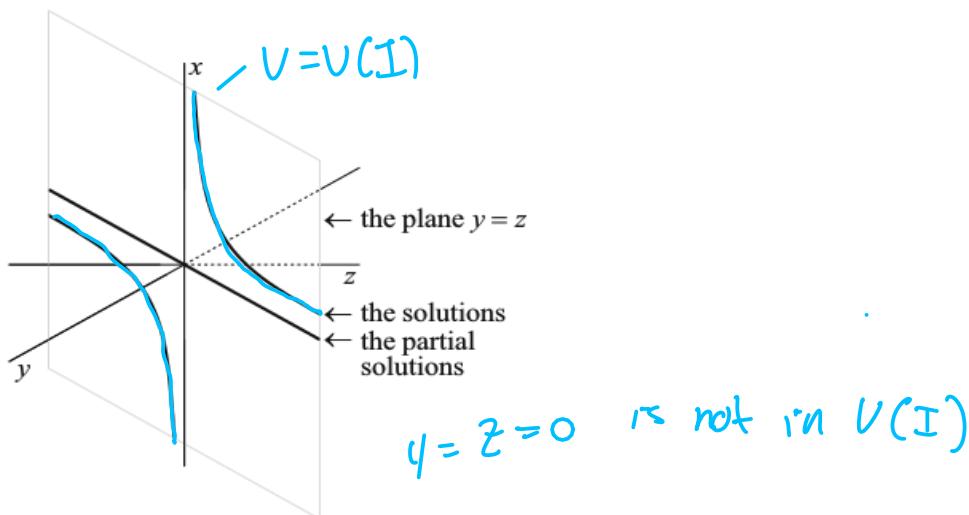
$$I_1 = I \cap \mathbb{C}[y, z] = (y - z)$$

$(y, z) = (a, a) \quad a \in \mathbb{R}$  is a partial solution.

$$x = \frac{1}{z}$$

this extends to a complete solution

$$\left(\frac{1}{a}, a, a\right) \quad a \in \mathbb{R}, \text{ but not for } a=0$$



Focus on the case where we eliminate just the first variable

Q: Can  $(a_2, \dots, a_n) \in V(I_1)$  be extended to a solution  $(a_1, \dots, a_n) \in V(I)$ ?

A:

Theorem (Extension Thm.) Let  $I = (f_1, \dots, f_s) \subseteq \mathbb{C}[x_1, \dots, x_n]$  this is needed ↴

and let  $I_1$  be the first elimination ideal.

For each  $1 \leq i \leq s$  write

$$f_i = c_i(x_2, \dots, x_n) x_1^{N_i} + \text{terms with deg in } x_1 < N_i.$$

( $N_i \geq 0$ )  $c_i \neq 0 \in \mathbb{C}[x_2, \dots, x_n]$ . Suppose  $(a_2, \dots, a_n) \in V(I_1)$

If  $(a_2, \dots, a_n) \notin V(c_1, \dots, c_s)$  then there exists  $a_1 \in \mathbb{C}$  such that  $(a_1, a_2, \dots, a_n) \in V(I)$ .

Proof: Section 3.5 (and 3.6)

Geometrically = we are "lifting a projection"

Why we need ①

$$I = (x^2 - y, x^2 - z) \quad \text{Eliminating } x$$

we get  $y = z \Rightarrow (a, a) \in V(I_1)$  is a point/solution

the L.C. of  $x^2 - y, x^2 - z$  are 1  
↑  
Coefficients of  $x^2$

$\Rightarrow V(I)$  is empty  
so all points extend

∴ Extension theorem says  $(a, a) \in V(I_1)$

always extends to  $(\sqrt{a^2}, a, a) \in V(I)$

If  $K = \mathbb{R}$  negative  $a$  do not extend

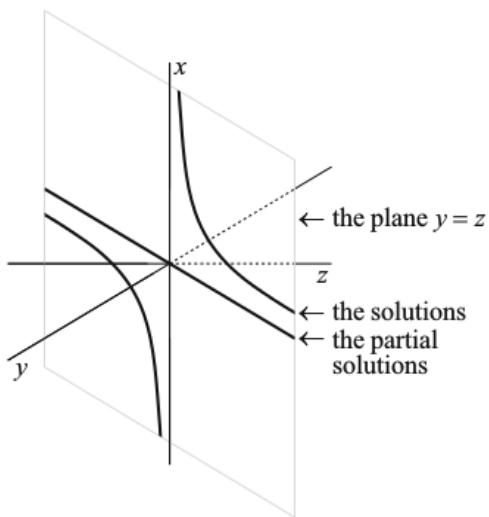
∴ we need ①.

Why we must avoid  $V(c_1, \dots, c_s)$

$$I = (x^y - 1, xz - 1)$$

L.L. of  $x$  are

$$c_1 = y, c_2 = z$$



∴ we need to avoid

$$V(y, z) = \{(0, 0)\}$$

Note  $V(c_1, \dots, c_s)$  depends on the basis  $(f_{1,r}, \dots, f_s)$  of  $I$ .

In Projective Space all solutions extend.