

# Math 261B Tues. 9/29

$$T \subset B \subset G = GL_n$$

$$gl_n = \mathbb{M}_n = \mathfrak{t} \oplus \bigoplus g_\alpha$$

$$\begin{pmatrix} & \cdot & \cdot & \cdot \\ & t & & \\ \cdot & & \cdot & \cdot \\ & & & t \end{pmatrix}$$

$$\begin{pmatrix} t_1 & & & \\ & \ddots & & \\ & & t_n & \\ & & & \downarrow j \end{pmatrix} \mapsto \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & b & \\ & & & 1 \end{pmatrix} = u_\alpha$$

$b \neq$

T normalizes  $U_\alpha$

$$T \times U_\alpha \subset G$$

$$b \neq b' \neq t'$$

$$(b, t) \cdot (b', t')$$

$$b \cdot t b' t^{-1} \neq t' t'$$

$$(b + t^\alpha b', t + t')$$

$$t^\alpha b'$$

$$t_i/t_j$$

$$G \cong V$$

$$T \cong V$$

$$V = \bigoplus_{\lambda \in X} V_\lambda$$

$$v \in V_\lambda$$

$$t \cdot v = t^\lambda v$$

$U_\alpha v \subset V$  is T-invariant

$$t \cdot b v = t b t^{-1} \cdot t v$$

$$(t^\alpha b) \cdot t^\lambda v$$

$$\alpha = e_i - e_j \implies E_{ij} \in g_\alpha$$

$$t_i/t_j \mapsto \begin{pmatrix} 1 \\ \vdots \\ i \\ \vdots \\ j \\ 1 \end{pmatrix}$$

$$g_\alpha \oplus g_\alpha \oplus kh_\alpha \cong sl_2$$

$$SL_2 \rightarrow G \quad \begin{pmatrix} t & \\ & t^{-1} \end{pmatrix} \cong G_m$$

$$SL_2 \subset U \quad \begin{pmatrix} 1 & b \\ & 1 \end{pmatrix} \cong G_a$$

$$\begin{pmatrix} 1 & \\ & 1 \end{pmatrix}$$

unipotent

$$\underline{t} = (t_1, \dots, t_n)$$

$X = X(\tau)$  character lattice of  $\tau$

$$X = \mathbb{Z}^n$$

$$(\lambda_1, \dots, \lambda_n) \rightarrow \underline{t} \mapsto t^{\lambda_1} \cdots b^{\lambda_n}$$

$$\lambda \in X \quad t^\lambda = \lambda(\underline{t})$$

$$U_\alpha \times U_{\alpha v} \rightarrow U_{\alpha v}$$

← action is tautologically  $\tau$ -invariant

$$(b, w) \rightarrow bw$$

$$\sim O(U_\alpha)$$

$$(\underline{t} \cdot b \underline{t}^{-1}, \underline{t} w) \mapsto \underline{t} \cdot bw$$

$$U_\alpha v \xrightarrow{\rho} U_\alpha v \otimes k[z] \quad z(b) = b$$

.

must be  $\tau$ -invariant

$$(\underline{t} \cdot z)(b) = z(\underline{t}^{-1} b \underline{t})$$

$$v \mapsto \sum_{i=0} v_i \otimes z^i \quad \text{for some } v_i \in U_\alpha v$$

$$= z(\underline{t}^\lambda b) = \underline{t}^{-\lambda} b$$

fininitely many  $v_i \neq 0$

$$\underline{t} \cdot z = \underline{t}^{-\lambda} z$$

$$b \cdot v = \sum b^i v_i$$

⇒ weights of  $U_\alpha v$

are in  $\lambda + \mathbb{N}\alpha$

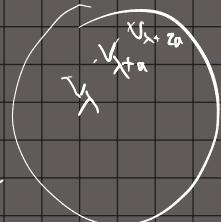
(and 1-dimensional).

$$v \mapsto \sum v_i \otimes z^i$$

↑                      ↑                      ↑

weight  $\lambda$     weight  $t^{\lambda + \alpha i}$     weight  $t^{-\alpha i}$

$$\underline{t} v = t^\lambda v \quad \left( \begin{matrix} 1 & b \\ 1 & 1 \end{matrix} \right)$$



$$\Rightarrow \text{SL}_2 V_\lambda \subseteq \sum_{k \in \mathbb{Z}} V_{\lambda + k\alpha} \quad \langle \alpha^\vee, \lambda + k\alpha \rangle = \langle \alpha^\vee, \lambda \rangle + 2k$$

$t \xrightarrow{\alpha^2} \begin{pmatrix} t & \\ & t^{-1} \end{pmatrix}$

$s \in W(\text{SL}_2) = N(T)/T = \langle t^{-1} \rangle \sqcup \langle t^{-1} \rangle^T / T \cong S_2$

acts on weights  $\alpha \mapsto -\alpha$

$$s(\lambda) - \lambda = m\alpha \quad m \in \mathbb{Z}$$

$$\langle \alpha^\vee, s(\lambda) - \lambda \rangle = 2m \quad s(\alpha) = -\alpha$$

$\begin{matrix} \langle \alpha^\vee, \lambda \rangle \\ \parallel \\ -2 \langle \alpha^\vee, \lambda \rangle \end{matrix}$

$$\alpha^\vee = 0 \quad m = -\langle \alpha^\vee, \lambda \rangle \quad \langle \alpha^\vee, s(\lambda) \rangle = -\langle \alpha^\vee, \lambda \rangle$$

$$X_R = (\ker \alpha^\vee) \oplus \mathbb{R}\alpha$$

$\uparrow \quad \uparrow$

$s_\alpha$  acts as a reflection on  $X$   
lattice

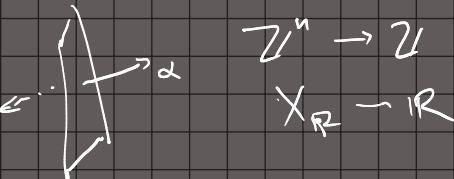
$$s_\alpha^2 = i\alpha$$

also acts on  $X^*$   
 $s_{\alpha^\vee}$  on  $X$   $s_{\alpha^\vee, \alpha}$  on  $X^*$

$W N(T)/T$  in  $G$  acts on  $X$ , contains  $s_\alpha$  for each root.

(They generate it)

$$\beta \in X^* \quad s(\beta) = \beta - \langle \beta, \alpha \rangle \alpha^\vee$$



$$\text{Gln} \quad \alpha = e_i - e_j \quad i \begin{pmatrix} & a & b \\ & c & d \\ j & & \end{pmatrix} \quad \begin{pmatrix} & -t \\ t^1 & \cdot \\ & \cdot \\ & 1 \end{pmatrix}$$

$e_i \leftrightarrow e_j$

$$w = S_n \curvearrowright X = \mathbb{Z}^n$$

$$\curvearrowright R = \{e_i - e_j\}$$

$$S_i^2 = 1$$

$$S_i \circ S_j = S_j \circ S_i$$

$$\text{if } |i-j| > 1$$

2

$$S_i \circ S_{i+1} \circ S_i = S_{i+1} \circ S_i \circ S_{i+1} \text{ if } |i-j|=1$$

3

$$(S_i \circ S_j \circ S_i \circ \dots) = (S_j \circ S_i \circ \dots)$$

$\underbrace{\quad}_{m}$

$$(S_i \circ S_j)^m = 1$$

$$\mathbb{R}_+ \quad e_i - e_j \quad i < j$$

$$S_i \quad e_i - e_{i+1}$$

↓

$$S_i = (i, i+1)$$

generate  $w = S_n$  as a Coxeter

$$e_2 - e_5$$

$$= e_2 - e_3$$

$$+ e_3 - e_4$$

$$+ e_4 - e_5$$

$$\begin{matrix} 1 & 2 & 3 \\ 2 & 1 & 3 \\ 3 & 2 & 1 \\ 3 & 2 & 1 \end{matrix} \quad \begin{matrix} S_1 S_2 S_1 \\ = S_2 S_1 S_2 \end{matrix}$$

"roots"      "coroots"

Carter-Datum Lattice  $X, X^*$ , finite  $R \subset X, \tilde{R} \subset X^*$

$$\alpha \leftrightarrow \check{\alpha}$$

st.  $i>$   $\langle \alpha^\vee, \alpha \rangle = 2$ , so have reflection  $s_\alpha$

2)  $R$  is invariant under group  $w$  gen. by the  $S_i$

3) only multiples of  $\alpha$  in  $\mathbb{R}$  are  $\pm \alpha$

Thm. Cartan-Dafa classify:

- Reductive alg. gps over any alg. closed  $K$

- Reductive Lie gps over  $\mathbb{C}^G$  = semisimple  $\times (\mathbb{C}^\times)^n$

- Compact real Lie groups: as  $n_{\mathbb{R}} \otimes_{\mathbb{R}}$  forms of the preceding  $G$

$$C \subset G$$

$$\xrightarrow{\text{Lie}/\mathbb{C}}$$

$$\xrightarrow{\text{Lie}/\mathbb{R}}$$

$$\text{Lie}(C) \subset \text{Lie}(G)_{\mathbb{R}}$$

$\mathbb{R}$  form

$$\text{Lie}(C) = \text{Lie}(\mathbb{C}) \oplus i\text{Lie}(\mathbb{C})$$

$$SO_n(\mathbb{C})$$

$$AA^T = I$$

$$M + M^T = 0$$

$$SO_n(\mathbb{R})$$

$$AA^T = I$$

$$M + M^T = 0$$

" rotations  
of unit ball in  $n$  space

$$\det(A)^2 = 1$$

$$\det(A) = \pm 1$$

$U_n \subset GL_n(\mathbb{C})$  is a compact real form.

More classical examples  $SO_n$   $Sp_n$

$SO_n(k) \subset SL_n(k) \cong k^\times$  subgroup preserving a non-degenerate symmetric bilinear form  $(,)$  on  $k^n$ .

(Disregard char = 2)

Choose  $(,)$  so  $(e_i, e_j) = \delta_{i+j, n+1}$ :  $e_1, \dots, e_n$  dual basis to  $e_n, \dots, e_1$

Matrix of form is  $J = \begin{pmatrix} & & & 1 \\ & \ddots & & \\ & & \ddots & \\ 1 & & & \end{pmatrix}$   $x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$   $(x, y) = y^T J x$

$A \in SL_n$  preserves  $(,)$  if

$$(Ay, Ax) = y^T A^T J A x = (y, x) = y^T J x \\ = A^T J A = J \quad J^2 = I$$

$$A^R = J A^T J = \begin{pmatrix} & & & \\ & \ddots & & \\ & & \ddots & \\ A^T & A^R & & \end{pmatrix}$$
 $\uparrow \begin{pmatrix} & 1 \\ & \ddots \\ 1 & \end{pmatrix} \leftrightarrow \begin{pmatrix} & & & \\ & \ddots & & \\ & & \ddots & \\ A^T & & & \end{pmatrix}$

$$J A^T J A = I \quad AA^R = I \quad (\text{rather than usual } AA^T = I)$$

$$T = \begin{pmatrix} t_1 & & & \\ & \ddots & & \\ & & t_n & t_n^{-1} \\ & & & \ddots t_1^{-1} \end{pmatrix}$$

$$SO_{2n} \begin{pmatrix} t_1 & & & \\ & \ddots & & \\ & & t_n & t_n^{-1} \\ & & & \ddots t_1^{-1} \end{pmatrix}$$

$B$  = upper Dar subgroups

$$so_m = \{ M_n \mid M + M^T = 0 \}$$

$$\begin{pmatrix} x & & & \\ & \ddots & & \\ & & x & -x \\ & & & \ddots x \end{pmatrix}$$

Why?