Recent developments of Discontinuous Galerkin Density functional theory

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Numerical Methods for Quantum Chemistry Tromsø, January, 2015

Brief description of DGDFT

- Kohn-Sham DFT (LDA/GGA)
- Discontinuous basis functions
 - Continuous density?

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- Finite kinetic energy?
- Relatively simple control of accuracy
- Relatively small number of basis per atom





Feature of DGDFT

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- Real space formulation (Discontinuous Galerkin)
- Exchange-correlation used by libxc
- HGH norm conserving pseudopotential.
- Geometry optimization
- Molecular dynamics (NVE/NVT)
- Massively parallel (>50000 procs)
- Compatible with the Pole Expansion and Selected Inversion method (PEXSI) for overcoming O(N^3) wall

[LL-Lu-Ying-E, J. Comput. Phys. 231, 2140 (2012)]

Why another basis set

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Example: electron density of Si (HGH pseudopotential)

Our goal: Automatic dimension reduction

- Construct the local basis functions adaptively by solving a small part of the system, and obtain discontinuous basis functions.
- Discontinuous Galerkin (DG) framework to patch basis functions together.



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Density (nearly continuous)

Adaptive local basis functions

• Element: E_k , Extended element: Q_k .

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 Solving the linear eigenvalue problem (NO pseudohydrogen saturation etc.) inside the extended element region with periodic boundary conditions.



$$H_{\mathrm{eff},Q_k}\widetilde{\varphi}_{k,j}=\varepsilon_{k,j}\widetilde{\varphi}_{k,j}.$$

Here
$$Q_2 = E_1 \cup E_2 \cup E_3$$

Adaptive local basis functions

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- Restrict $\tilde{\varphi}_{k,j}$ from extended element to element $\varphi_{k,j}$
- Orthogonalize $\varphi_{k,j}$ (via singular value decomposition): adaptive local basis functions.



$$H_{\mathrm{eff},Q_{k}}\widetilde{\varphi}_{k,j}=\varepsilon_{k,j}\widetilde{\varphi}_{k,j}.$$

$$\varphi_{k,j} = \widetilde{\varphi}_{k,j}|_{E_k}.$$

Discontinuous Galerkin method

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- Finite element method with discontinuous basis functions.
- Inter-element continuity (consistency): e.g. Penalty on the inter-element jump [Arnold, 1982]



Kohn-Sham energy functional

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Fix the electron density ρ , and consider the linear problem (i.e. one step SCF iteration)

$$H_{\rm eff} = -\frac{1}{2}\Delta + V_{\rm eff} + \sum_{\ell} \gamma_{\ell} |b_{\ell}\rangle \langle b_{\ell}|$$

with orthonormality constraints $\langle \psi_i, \psi_j \rangle = \delta_{ij}$. The effective one-body potential

$$V_{\text{eff}}[\rho](x) = V_{\text{ext}}(x) + \int \frac{\rho(y)}{|x - y|} \, \mathrm{d}y + \epsilon'_{\text{xc}}[\rho(x)].$$

Kohn-Sham energy functional

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The linear problem minimizes the following quadratic functional

$$\begin{aligned} E_{\text{eff}}(\{\psi_i\}) = &\frac{1}{2} \sum_{i=1}^N \int |\nabla \psi_i(x)|^2 \, \mathrm{d}x + \int V_{\text{eff}}(x) \rho(x) \, \mathrm{d}x \\ &+ \sum_{\ell} \gamma_\ell \sum_{i=1}^N |\langle b_\ell, \psi_i \rangle|^2, \end{aligned}$$



New terms

- [LL-Lu-Ying-E, J. Comput. Phys. 231, 2140 (2012)]
- Interior penalty method [Arnold, 1982]

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Flowchart of adaptive local basis functions

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Different dimensional systems

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Two level parallelization in DGDFT

1. Intra-element parallelization numBasis: 10 ~ 100 procs

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- 2. Inter-element parallelization numElement: 4 ~ 1,000 procs
- Scale to 100,000 procs or more



DG matrix as a block finite difference stencil



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Sparsity pattern of a DG matrix for a graphene system with 128 atoms (40 basis per atom) Pole EXpansion and Selected Inversion Pole expansion, $Q \sim O(\log(\beta \Delta E))$; $Q = 40 \sim 80$ in practice $\rho(x) \approx \sum_{i=1}^{Q} \frac{\omega_i}{H - z_i I}(x, x)$

Selected Inversion

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- Scale at most as $O(N^2)$ even for metals (zero gap).
- Rely on sparsity of H rather than near-sightedness

[LL-Lu-Ying-E, Chin. Ann. Math. 30B 729, 2009]
[LL-Lu-Ying-Car-E, Commun. Math. Sci. 7, 755, 2009]
[LL-Yang-Meza-Lu-Ying-E, ACM Trans. Math. Software 37, 40, 2011]
[LL-Chen-Yang-He, J. Phys. Condens. Matter 25, 295501, 2013]
[LL-Garcia-Huhs-Yang, J. Phys. Condens. Matter 26, 305503, 2014]

http://www.pexsi.org/

- Work with sparse H, S matrices
- Integrated with SIESTA as SIESTA-PEXSI

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[LL-Garcia-Huhs-Yang, J. Phys. Condens. Matter 26, 305503, 2014]

Scale to >10,000 processors for over 20000 atoms solved in DZP basis set.

PEXSI

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Main Page			

Welcome to the documentation of PEXSI (current version: v0.7.2)

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DGDFT for the same system but with different partitioning



Three kinds of partition: 1D, 2D and 3D

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PartitionnumBasis/elementnumProcessors1D 6*1*1600 (12 basis/atom)6*600= 36002D 6*6*1300 (34 basis/atom)36*300= 108003D 6*6*6100 (68 basis/atom)216*100= 21600

1D, 2D and 3D Partition

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Energy can be as accurate as 1×10^{-5} au/atom. Compared to converged planewave calculation using ABINIT

PhosphoreneNanoribbons

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ACPNR4_3: 54 atoms ACPNR4_60: 1080 atoms ACPNR4_120: 2160 atoms ACPNR4_240: 4320 atoms





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DGDFT P54		DIAG		PEXSI	
Ecut	ALB	ΔE	ΔF	ΔE	ΔF
10	28	1.94E-02	4.81E-02	1.94E-02	4.81E-02
20	28	6.49E-04	5.12E-03	5.39E-04	1.67E-02
40	10	1.28E-03	1.52E-02	1.21E-03	4.19E-03
40	12	5.54E-04	2.17E-03	6.45E-04	2.17E-03
40	15	1.87E-04	9.54E-04	1.16E-04	9.57E-04
40	19	7.00E-05	4.00E-04	7.12E-05	4.13E-04
40	28	9.64E-06	2.90E-04	4.21E-05	2.84E-04
100	28	8.25E-06	1.24E-04	2.90E-05	1.31E-04
200	28	6.62E-06	9.43E-05	3.66E-05	9.09E-05

All units are atomic unit. Accuracy compared to converged ABINIT results.

Efficiency: Construction of basis (a) and Hamiltonian (b)

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Efficiency: Diagonalization (c) and Total wall clock time (d)



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Empty: DIAG Filled: PEXSI

Molecular dynamics

- Single level Nose-Hoover thermostat. Temperature: 300 K
- Time step: 2 fs

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Conserved quantity

$$H = \sum_{I=1}^{M} \frac{p_I^2}{2M_I} + V + \frac{p_{\eta}^2}{2Q} + 3Nk_B T\eta$$

•
$$Drift = \frac{|H(t) - H(0)|}{|H(0)|}$$

or 2.6 × 10⁻⁴ au/ps per atom



Molecular dynamics

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Edge reconstruction of ACPNR

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Conclusion

- Adaptive local basis functions (ALB). Automatic dimension reduction
- Atomic and environmental effect
- Accurate and small number of basis per atom.
- Local Hamiltonian matrix. Parallel computing.
- Combined with the pole expansion and selected inversion algorithm for low order scaling computation (at most O(N²) scaling) of KSDFT.

Joint work with

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Thank you for your attention!

Support from DOE Alvarez fellowship, SciDAC, CAMERA funding