

Householder's Method

Idea: We have an arbitrary symmetric matrix A .
 A would be a lot nicer to work with if it were TRIDIAGONAL (for example, we have marvelous ways of inverting, or finding eigenvalues for, a TRIDIAGONAL matrix.)

But A isn't tridiagonal. Bummer...?

Householder's method is a way of finding a tridiagonal matrix \tilde{A} , which is SIMILAR to A .

Here's what A looks like:

$$\begin{pmatrix} x & x & x & \dots & x \\ x & x & x & \dots & x \\ x & & & \dots & \\ x & & & \dots & \\ x & x & \dots & & x \end{pmatrix}$$

everything is potentially non-zero!

Here's what \tilde{A} looks like:

$$\begin{pmatrix} x & x & 0 & 0 & \dots & 0 \\ x & x & x & 0 & \dots & 0 \\ 0 & x & x & x & \dots & 0 \\ \vdots & 0 & x & & \dots & \vdots \\ 0 & 0 & 0 & \dots & x & x \end{pmatrix}$$

only non-zero entries are on main diagonal, or immediately next to it!

To find \tilde{A} , we will apply a series of Householder Transformations to A .

* Think of these as successively zeroing out the bits we don't like *

Consider the first column of A : $a_{:,1} = \begin{pmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{n1} \end{pmatrix}$

We can alter it by acting some matrix Q_1^T on it: 2

$$Q_1^T a_{:,1} \Rightarrow \tilde{a}_{:,1}$$

↑ transpose so notation is consistent w/ slides

We want $\tilde{a}_{:,1}$ to have this form:

$$\tilde{a}_{:,1} = \begin{pmatrix} a_{11} \\ \text{stuff} \\ 0 \\ \vdots \\ 0 \end{pmatrix} \left. \begin{array}{l} \text{unchanged} \\ \text{a multiple of } e_{n+1} = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \end{array} \right\}$$

So Q_1^T has this form:

want identity here so we don't touch a_{11} !

$$\begin{pmatrix} I_{1 \times 1} & 0 & \dots & 0 \\ \vdots & F_{n-1} & & \\ \vdots & & & \\ 0 & & & \end{pmatrix} \left. \begin{array}{l} \\ \\ \\ \end{array} \right\} n+1$$

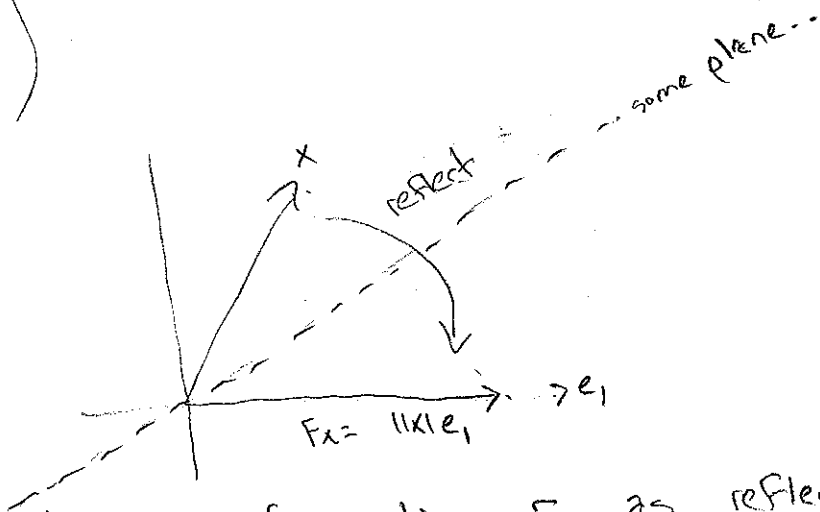
$n-1$

F_{n-1} acts on the last $n-1$ components of $a_{:,1}$

Let $x = \begin{pmatrix} a_{21} \\ \vdots \\ a_{n1} \end{pmatrix}$ (so $a_{:,1} = \begin{pmatrix} a_{11} \\ x \\ 1 \end{pmatrix}$)

want: $Fx = \begin{pmatrix} \|x\| \\ 0 \\ \vdots \\ 0 \end{pmatrix}$

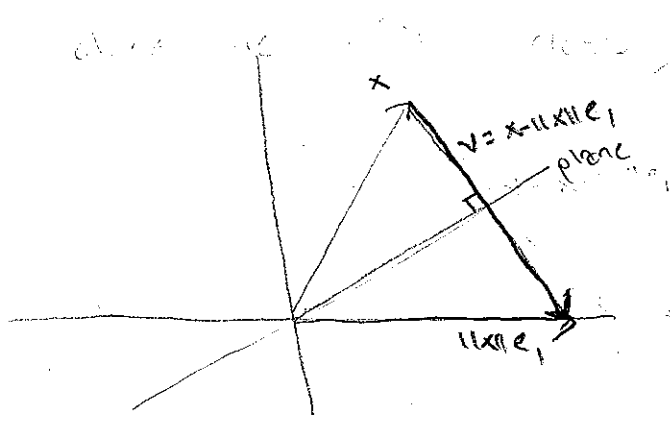
graphically:



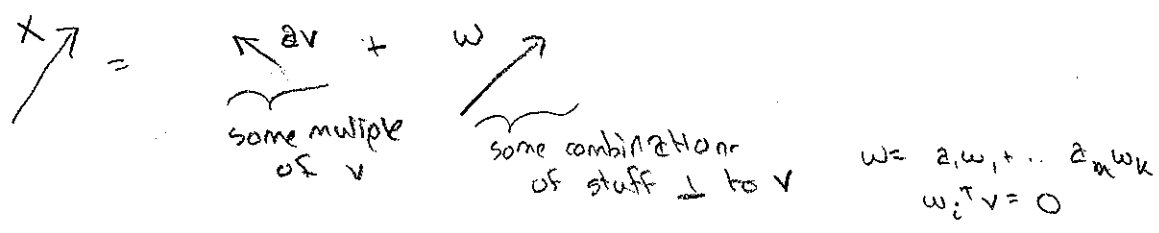
We can think of the transformation F as reflecting x across some plane so that the end result is a multiple of $e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$. Since the length is preserved,

the result will be $\begin{pmatrix} \|x\|_2 \\ 0 \\ \vdots \\ 0 \end{pmatrix} = \|x\|_2 e_1$

This kind of reflection has a name - its a Householder reflection.



the plane we want is orthogonal to $v = ||x||e_1 - x$
 So to construct the right reflection, we need to flip the sign on anything in the v direction.



we want $x \rightarrow -2v + w$
 ↑ sign flips ↑ stays the same

The matrix

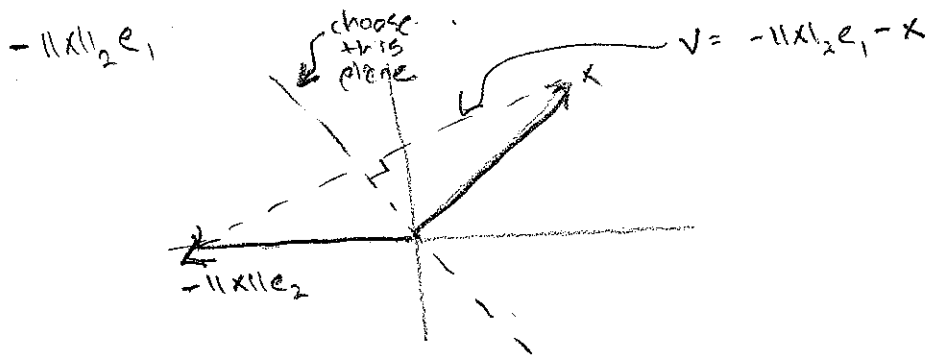
$F = I - \frac{2vv^T}{v^T v}$ achieves this.

$$F x = \left(I - \frac{2vv^T}{v^T v} \right) (2v + a_1 w_1 + \dots + a_n w_n)$$

$$= 2v + a_1 w_1 + \dots + a_n w_n - \frac{2a_1 v v^T w_1}{v^T v} - \dots - \frac{2a_n v v^T w_n}{v^T v}$$

$F x = -2v + w \quad \checkmark$

Note we could also have reflected $\|x\|$ on to



It turns out the method is more numerically stable

if we choose $v = \begin{cases} -\|x\|_2 e_1 + x & \text{if } x_1 < 0 \\ \|x\|_2 e_1 + x & \text{if } x_1 \geq 0 \end{cases}$

so we sum this up as

$$v = \text{sign}(x_1) \|x\|_2 e_1 + x$$

So this gives us what we need to deal with the first column. To deal with the first row, we can think of applying Q^T to $A^T \dots$ and then transposing back

$$Q_1^T A \rightarrow \begin{pmatrix} x & x & x \\ x & x & x \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$Q_1^T A^T \rightarrow \begin{pmatrix} x & x & \dots \\ x & x & \dots \\ 0 & 0 & \dots \\ \vdots & \vdots & \dots \\ 0 & 0 & \dots \end{pmatrix}$$

$$(Q_1^T A^T)^T = \begin{pmatrix} x & x & 0 & \dots & 0 \\ x & x & & & \\ \vdots & \vdots & & & \\ 0 & 0 & & & \end{pmatrix} = A^T Q_1^T = A Q_1$$

zeroed out the first row entries we didn't want!

so in total, if we take

$$Q_1^T A Q_1$$

we get $Q_1^T A Q_1 = \begin{pmatrix} x & x & 0 & \dots & 0 \\ x & x & x & x & x \\ 0 & x & & & \\ \vdots & \vdots & & & \\ 0 & x & & & \end{pmatrix}$

Now we do it again, only we want

$$Q_2^T = \left(\begin{array}{cc|c} I_{2 \times 2} & 0 & \\ \hline 0 & \underbrace{F_{n-2}}_{n-2} & \end{array} \right) \}_{n-2}$$

where F_{n-2} acts on the last $n-2$ entries of A
 of the second column of A

$$F_{n-2} \begin{pmatrix} a_{32} \\ a_{42} \\ \vdots \\ a_{n2} \end{pmatrix} = \begin{pmatrix} * \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$\Rightarrow F_{n-2}$ is a Householder reflection made with

$$x = \begin{pmatrix} a_{32} \\ \vdots \\ a_{n2} \end{pmatrix} \quad \text{and} \quad v = \frac{\text{sign}(x) \|x\|_2 e_1 + x}{\| \text{now an } n-2 \times 1 \text{ vector!} \|}$$

... and so on for Q_3, Q_4, \dots, Q_{n-2} .

Example (textbook # 2C)

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \quad 3 \times 3 \Rightarrow \text{only need to do 1 step!}$$

$$Q_1^T = \begin{pmatrix} 1 & 0 & 0 \\ 0 & F_2 & \\ 0 & & \end{pmatrix}$$

F_2 is a householder reflection formed with $x = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$$\text{so } v = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} \sqrt{2}+1 \\ 1 \end{pmatrix} \quad \|v\| = v^T v = (\sqrt{2}+1)^2 + 1 = 2(2+\sqrt{2})$$

$$\text{And } F_2 = I - \frac{2vv^T}{v^T v} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \frac{2}{2(2+\sqrt{2})} \begin{pmatrix} \sqrt{2}+1 & \sqrt{2}+1 \\ \sqrt{2}+1 & 1 \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}-1}{2} & \frac{\sqrt{2}-1}{2} \\ \frac{\sqrt{2}-1}{2} & \frac{\sqrt{2}+3}{2} \end{pmatrix}$$

$$Q_1 = (\text{algebra... verify on your own}) \quad Q_1^T = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{\sqrt{2}-1}{2} & 0 \\ 0 & \frac{\sqrt{2}-1}{2} & \frac{\sqrt{2}+3}{2} \end{pmatrix}$$

$$\text{so } Q_1^T A Q_1 = \begin{pmatrix} 1 & \sqrt{2} & 0 \\ -\sqrt{2} & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$