

MATH 54 MIDTERM 1
SUMMER 2011 - SECTION 5 - ALEX KRUCKMAN

Please put away everything except scratch paper and pencils/pens.
 You have 110 minutes to complete this exam, which ends at 2pm sharp.
 Write your answers, *including complete justifications*, in the spaces provided below.
 If you finish early or have a question, please make your way to the front of the room,
 taking care not to disturb the other test takers!

- (1) (8 points) For which values of k does the following system of equations have

- (a) No solutions? $k = -1$
- (b) Exactly one solution? $k \neq 1$ or -1 ($k^2 - 1 \neq 0$)
- (c) Exactly three solutions? Impossible
- (d) Infinitely many solutions? $k = 1$

$$\begin{cases} x - ky - 2z = 1 \\ 2x + (1 - 2k)y + (k - 4)z = 3 \\ z - x = -2 \end{cases}$$

Row reduce

$$\left(\begin{array}{ccc|c} 1 & -k & -2 & 1 \\ 2 & (1-2k)(k-4) & 3 \\ -1 & 0 & 1 & -2 \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & -k & -2 & 1 \\ 0 & 1 & k & 1 \\ 0 & -k & -1 & -1 \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & -k & -2 & 1 \\ 0 & 1 & k & 1 \\ 0 & 0 & k^2 - 1 & k - 1 \end{array} \right)$$

inconsistent when $k^2 - 1 = 0$
 and $k - 1 \neq 0$
 unique solution when $k^2 - 1 \neq 0$
 infinitely many solutions when $k^2 - 1 = 0$

In case (d) (if it occurs), describe in parametric form all solution vectors $\begin{pmatrix} x \\ y \\ z \end{pmatrix}$. And $k - 1 = 0$.

For $k = 1$, we have

$$\left(\begin{array}{ccc|c} 1 & -1 & -2 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & 0 & -1 & 2 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

which tells us

$X = 2 + Z$
 $Y = 1 - Z$. Solutions have the form

$$\begin{pmatrix} 2+z \\ 1-z \\ z \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + z \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}, \quad \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + z \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}.$$

Parametric form:

- (2) (8 points) Let V be a vector space. Suppose $\{\bar{v}_1, \bar{v}_2, \bar{v}_3, \bar{v}_4\}$ is a linearly independent set of vectors in V .

- (a) Is $\{(\bar{v}_1 + \bar{v}_2), (\bar{v}_2 + \bar{v}_3), (\bar{v}_3 + \bar{v}_4), (\bar{v}_4 + \bar{v}_1)\}$ linearly independent? Why or why not?

$$(\bar{v}_1 + \bar{v}_2) + -(\bar{v}_2 + \bar{v}_3) + (\bar{v}_3 + \bar{v}_4) + -(\bar{v}_4 + \bar{v}_1) = \bar{0},$$

so these vectors are linearly dependent.

Another way to solve this (other than divine inspiration):

$$\text{Solve } a(\bar{v}_1 + \bar{v}_2) + b(\bar{v}_2 + \bar{v}_3) + c(\bar{v}_3 + \bar{v}_4) + d(\bar{v}_4 + \bar{v}_1) = \bar{0}$$

$$\text{which is } (a+d)\bar{v}_1 + (a+b)\bar{v}_2 + (b+c)\bar{v}_3 + (c+d)\bar{v}_4 = \bar{0}.$$

Since $\{\bar{v}_1, \dots, \bar{v}_4\}$ ^{are} independent, this holds when $\begin{cases} a+d=0 \\ a+b=0 \\ b+c=0 \\ c+d=0 \end{cases}$ only.

This is a system of linear equations, corresponding to the matrix

$$\begin{pmatrix} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \end{pmatrix}. \quad \text{Row reducing provides the solution above}$$

- (b) Is $\{(\bar{v}_1 + \bar{v}_2), (\bar{v}_2 + \bar{v}_3), (\bar{v}_3 + \bar{v}_1)\}$ linearly independent? Why or why not?

$$\text{Suppose } a(\bar{v}_1 + \bar{v}_2) + b(\bar{v}_2 + \bar{v}_3) + c(\bar{v}_3 + \bar{v}_1) = \bar{0},$$

$$\text{then } (a+c)\bar{v}_1 + (a+b)\bar{v}_2 + (b+c)\bar{v}_3 = \bar{0}.$$

Since $\{\bar{v}_1, \bar{v}_2, \bar{v}_3, \bar{v}_4\}$ are independent, $\{\bar{v}_1, \bar{v}_2, \bar{v}_3\}$ are independent,

so we must have $\begin{array}{l} a+c=0 \\ a+b=0 \\ b+c=0 \end{array}$ and Then $a=-c$, and $a=-b$,

so $-b=-c$, but $b+c=0$,

so $2b=2c=0$, and b and c are both 0. Then a is 0 also.

We can also look at this as a system of linear equations corresponding to the matrix $\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix}$. This matrix is invertible ($\det 2$) so the homogeneous system has only the trivial solution $a=b=c=0$.

Hence the vectors are linearly independent.

- (3) (8 points) Let $S : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ be the function which sums the entries of a vector and returns a vector consisting of three copies of that sum. So

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} S \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x+y \\ x+y \\ x+y \end{pmatrix}.$$

Let $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be the function which assigns to a vector the vector consisting of the average of the first two entries and the average of the last two entries. So

$$T \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} \frac{x+y}{2} \\ \frac{y+z}{2} \end{pmatrix}.$$

- (a) Show that S is a linear transformation, and find its standard matrix.

$$\text{Let } \bar{u} = \begin{pmatrix} x \\ y \end{pmatrix} \text{ and } \bar{v} = \begin{pmatrix} x' \\ y' \end{pmatrix}. \text{ Then } S(\bar{u} + \bar{v}) = S\left(\begin{pmatrix} x+x' \\ y+y' \end{pmatrix}\right) = \begin{pmatrix} x+x'+y+y' \\ x+x'+y+y' \\ x+x'+y+y' \end{pmatrix}$$

$$= \begin{pmatrix} x+y \\ x+y \\ x+y \end{pmatrix} + \begin{pmatrix} x'+y' \\ x'+y' \\ x'+y' \end{pmatrix} = S\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) + S\left(\begin{pmatrix} x' \\ y' \end{pmatrix}\right) = S(\bar{u}) + S(\bar{v}).$$

$$S(c\bar{u}) = S(cx) = \begin{pmatrix} cx+cy \\ cx+cy \\ cx+cy \end{pmatrix} = c\begin{pmatrix} x+y \\ x+y \\ x+y \end{pmatrix} = cS(\bar{u}). \text{ So } S \text{ is a linear transformation.}$$

$$S(\bar{e}_1) = \begin{pmatrix} 1+0 \\ 1+0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad S(\bar{e}_2) = \begin{pmatrix} 0+1 \\ 0+1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad \text{So } S \text{ is } \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

- (b) A similar argument shows that T is a linear transformation - you do not need to show it here! Find the standard matrix for T .

$$T(\bar{e}_1) = \begin{pmatrix} 1+0 \\ 0+0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad T(\bar{e}_2) = \begin{pmatrix} 0+1 \\ 1+0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \quad T(\bar{e}_3) = \begin{pmatrix} 0+0 \\ 0+0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\text{So } T \text{ is } \begin{pmatrix} 1/2 & 1/2 & 0 \\ 0 & 1/2 & 1/2 \end{pmatrix}.$$

- (c) Find the standard matrix for $T \circ S : \mathbb{R}^2 \rightarrow \mathbb{R}^2$.

$$T \circ S \text{ is } \begin{pmatrix} 1/2 & 1/2 & 0 \\ 0 & 1/2 & 1/2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

- (d) Find the standard matrix for $S \circ T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$.

$$S \circ T \text{ is } \begin{pmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1/2 & 1/2 & 0 \\ 0 & 1/2 & 1/2 \end{pmatrix} = \begin{pmatrix} 1/2 & 1/2 & 0 \\ 1/2 & 1/2 & 1/2 \\ 1/2 & 1/2 & 1/2 \end{pmatrix}$$

- (4) (9 points) Consider the following matrices:

$$A = \begin{pmatrix} 1 & 2 & 5 & \frac{1}{3} & 0 & 2 \\ 0 & \frac{1}{4} & -1 & 0 & 5 & 0 \\ 0 & 0 & 6 & -\frac{1}{2} & 0 & 2 \\ 0 & 0 & 0 & 3 & 8 & -1 \\ 0 & 0 & 0 & 0 & \frac{1}{9} & 3 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 2 & 0 & 0 & 0 & 0 \\ 0 & 1 & 2 & 0 & 0 & 9 \\ 0 & 0 & 0 & 0 & \frac{1}{2} & 0 \\ 4 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & \frac{1}{2} & 0 & 0 \end{pmatrix}.$$

Compute the determinants:

- (a) $|A|$
 (b) $|B|$
 (c) $|AABA^{-1}BABBBAB^{-1}|$

sistema frakasche ist, soll eine unbestimmtheit resultieren (a)

$$a) 1 \cdot \frac{1}{4} \cdot 6 \cdot 3 \cdot \frac{1}{9} \cdot 1 = \frac{1}{2}$$

$$b) -1 \cdot \begin{vmatrix} 0 & 2 & 0 & 0 & 0 \\ 0 & 1 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{2} \\ 4 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & \frac{1}{2} & 0 \end{vmatrix} = -1 \cdot -2 \cdot \begin{vmatrix} 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{2} \\ 4 & 0 & 1 & 0 \\ 1 & 0 & \frac{1}{2} & 0 \end{vmatrix} = -1 \cdot -2 \cdot -2 \cdot \begin{vmatrix} 0 & 0 & \frac{1}{2} \\ 4 & 1 & 0 \\ 1 & \frac{1}{2} & 0 \end{vmatrix}$$

$$= -1 \cdot -2 \cdot -2 \cdot \frac{1}{2} \cdot \begin{vmatrix} 4 & 1 \\ 1 & \frac{1}{2} \end{vmatrix} = -1 \cdot -2 \cdot -2 \cdot \frac{1}{2} \cdot 1 = -2$$

$$c) \frac{1}{2} \cdot \frac{1}{2} \cdot -2 \cdot 2 \cdot -2 \cdot \frac{1}{2} \cdot -2 \cdot -2 \cdot -2 \cdot \frac{1}{2} \cdot -\frac{1}{2} = 2$$

$$A \quad A \quad B \quad A^{-1} \quad B \quad A^T \quad B \quad B \quad B \quad A \quad B^{-1}$$

- (5) (9 points) Let $C^\infty[0, 1]$ be the vector space of analytic functions (i.e. functions which have derivatives of all orders) $[0, 1] \rightarrow \mathbb{R}$. For each the subsets of $C^\infty[0, 1]$ specified below, determine whether it is or is not a subspace and explain.

- (a) $\{f : f(x) \geq 0 \text{ for all } x \text{ in } [0, 1]\}$, that is, nonnegative functions

No. Not closed under scalar multiplication

If f is a nonnegative function ($f(x) \geq 0$ for all x),
 $-f$ is a nonpositive function ($f(x) \leq 0$ for all x).

- (b) $\{f : f' = 1\}$, that is, functions which differentiate to the constant function 1

No. 0 is not in the subset.

$$0' = 0 \neq 1$$

$$\left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}$$

- (c) $\{f : f'' - f = 0\}$, that is, functions which are equal to their second derivative

Let W be the subset of $C^\infty[0, 1]$ in question.
Yes. • $0'' - 0 = 0 - 0 = 0$, so $0 \in W$.

• If f and g are in W , $(f+g)'' - (f+g) = f'' + g'' - f - g = (f'' - f) + (g'' - g) = 0$, so $f+g \in W$.

• If f is in W and c is a scalar, $(cf)'' - cf = c(f'' - f) = c \cdot 0 = 0$, so $cf \in W$.

- (6) (8 points) Consider the matrix

$$A = \begin{pmatrix} -1 & 0 & 2 \\ 2 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

- (a) Compute A^{-1} .

Row reduce

$$\left(\begin{array}{ccc|ccc} -1 & 0 & 2 & 1 & 0 & 0 \\ 2 & 1 & 1 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 & 0 & 1 \end{array} \right) \rightarrow \left(\begin{array}{ccc|ccc} 1 & 0 & -2 & -1 & 0 & 0 \\ 0 & 1 & 5 & 2 & 1 & 0 \\ 0 & 1 & 3 & 1 & 0 & 1 \end{array} \right)$$

$$\rightarrow \left(\begin{array}{ccc|ccc} 1 & 0 & -2 & -1 & 0 & 0 \\ 0 & 1 & 5 & 2 & 1 & 0 \\ 0 & 0 & -2 & -1 & 1 & 1 \end{array} \right) \rightarrow \left(\begin{array}{ccc|ccc} 1 & 0 & -2 & -1 & 0 & 0 \\ 0 & 1 & 5 & 2 & 1 & 0 \\ 0 & 0 & 1 & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{array} \right)$$

$$\rightarrow \left(\begin{array}{ccc|ccc} 1 & 0 & -2 & -1 & 0 & 0 \\ 0 & 1 & 0 & -\frac{1}{2} & -\frac{3}{2} & \frac{5}{2} \\ 0 & 0 & 1 & \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \end{array} \right) \rightarrow \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 0 & 1 & -1 \\ 0 & 1 & 0 & -\frac{1}{2} & -\frac{3}{2} & \frac{5}{2} \\ 0 & 0 & 1 & \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \end{array} \right)$$

$$A^{-1}$$

- (b) Explain why the following set of vectors is a basis for \mathbb{R}^3 :

$$\left\{ \begin{pmatrix} -1 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} \right\}$$

By the invertible matrix theorem, the columns of A

are linearly independent and span \mathbb{R}^3 .

That is, they are a basis for \mathbb{R}^3 .