

HW 4 Selected solutions

1a. Let H be normal in G . Let $g \in G$.

Then $gHg^{-1} = H$, i.e. $\{ghg^{-1} \mid h \in H\} = H$.

$$\begin{aligned} Hg &= \{hg \mid h \in H\} \text{ by definition.} \\ &= \{hg \mid h \in gHg^{-1}\} \text{ since } H = gHg^{-1} \\ &= \{gh'g^{-1} \cdot g \mid h' \in H\} \text{ by definition of } gHg^{-1} \\ &= \{gh' \mid h' \in H\} \\ &= gH. \end{aligned}$$

Conversely, suppose that $gH = Hg$ ^{for all $g \in G$} . Then, by definition

$$\begin{aligned} gHg^{-1} &= \{ghg^{-1} \mid h \in H\} \\ &= \{xg^{-1} \mid x \in gH\} \text{ by definition of } gH \\ &= \{xg^{-1} \mid x \in Hg\} \text{ since } gH = Hg \\ &= \{hg \cdot g^{-1} \mid h \in H\} \\ &= H \text{ since } gg^{-1} = e. \end{aligned}$$

~~Since~~ ^{since} this holds for all $g \in G$, H is normal

b. Let $\phi: A \times B \rightarrow B$ be defined by $\phi(a, b) = b$.

Claim: ϕ is a homomorphism. Proof: $\phi((a_1, b_1)(a_2, b_2)) = \phi(a_1 a_2, b_1 b_2) = b_1 b_2$
 $= \phi(a_1, b_1) \phi(a_2, b_2)$

$$\text{Ker}(\phi) = \{(a, b) \in A \times B \mid \phi(a, b) = 1_B\} = \{(a, 1_B) \mid a \in A\}.$$

Since kernels are normal subgroups, $\{(a, 1_B) \mid a \in A\}$ is a normal subgroup.

2. DF 3.1

$$\begin{aligned} \#9. \quad \phi((a+bi)(c+di)) &= \phi(ac-bd + (ad+bc)i) = (ac-bd)^2 + (ad+bc)^2 \\ &= a^2c^2 + b^2d^2 + a^2d^2 + b^2c^2 \end{aligned}$$

$$\begin{aligned} \phi(a+bi) \phi(c+di) &= (a^2+b^2)(c^2+d^2) \\ &= a^2c^2 + a^2d^2 + b^2c^2 + b^2d^2 = \phi((a+bi)(c+di)) \end{aligned}$$

so ϕ is a homomorphism.

$\text{Ker}(\phi) = \{ (a+bi) \in \mathbb{C}^\times \mid a^2+b^2=1 \}$ this is a circle of radius 1 in the plane.

Fibers: $\phi^{-1}(r) = \{ (a+bi) \in \mathbb{C}^\times \mid a^2+b^2=r \}$
this is the circle of radius \sqrt{r} in the complex plane.

3. a) $\sigma(x_1, x_2, x_3, x_4) = (x_4, x_3, x_2, x_1)$

" σ moves the k^{th} coordinate to position $\sigma(k)$ "

$$\begin{aligned} \text{b) } (\sigma \circ \tau) \bullet (x_1, \dots, x_n) &= (x_{(\sigma \circ \tau)^{-1}(1)}, \dots, x_{(\sigma \circ \tau)^{-1}(n)}) \\ &= (x_{\tau^{-1} \circ \sigma^{-1}(1)}, \dots, x_{\tau^{-1} \circ \sigma^{-1}(n)}) \end{aligned}$$

$$\sigma \bullet (\tau \bullet (x_1, \dots, x_n)) = \sigma \bullet (x_{\tau^{-1}(1)}, \dots, x_{\tau^{-1}(n)})$$

this is the vector that has $x_{\tau^{-1}(k)}$ in the position $\sigma(k)$

equivalently, ~~now~~ with $x_{\tau^{-1}(m)}$ in the position m

$$= (x_{\tau^{-1} \circ \sigma^{-1}(m)}, \dots, x_{\tau^{-1} \circ \sigma^{-1}(m)})$$

4a. Identity = I (check)

Associativity follows from associativity of matrix multiplication:

$$\begin{aligned} A * (B * C) &= A * (CB) = CBA \\ &= (BA) * C \\ &= (A * B) * C \end{aligned}$$

Inverses: the inverse of A is A^{-1} (usual matrix inverse)

$$\text{since } A * A^{-1} = A^{-1} * A = I = A^{-1} * A = A * A^{-1} .$$

(Remark: Given any group, one can build a new group by multiplying in the opposite order!)

4b. You need to check that $\phi(ab) = \underbrace{\phi(a) * \phi(b)}_{\text{multiplied in } \mathbb{R}_n \text{ LG}}$ for all elements a and b in S_3 .

For example: in S_3 , $(12)(23) = (123)$

$$\phi(123) = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

$$\phi(12)\phi(23) = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} * \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} \text{ which is what you needed to show.}$$

see next page:

4b (continued)

Some hints for shortcuts: (optional)

Option 1: systematic shortcut.

Let $A = \{(12) (23)\}$. Then A generates S_3 .

Check by hand that for each element $b \in S_3$ and $a \in A$

$$\phi(ab) = \phi(a) * \phi(b). \quad [\text{this is not so many things to check}]$$

Now given any product xy , write $x = a_1 a_2 \dots a_k$ where $a_i \in A$

By what you just checked

$$\phi(xy) = \phi(a_1 a_2 \dots a_k y)$$

$$= \phi(a_1) * \phi(a_2 \dots a_k y)$$

$$= \phi(a_1) * \phi(a_2) * \phi(a_3 \dots a_k y)$$

$$\vdots$$
$$= \phi(a_1) * \dots * \phi(a_k) * \phi(y)$$

$$= \phi(a_1 a_2) * \phi(a_3) \dots * \phi(a_k) * \phi(y)$$

$$\vdots$$

$$= \phi(a_1 a_2 \dots a_k) * \phi(y)$$

$$= \phi(x) * \phi(y).$$

(note that elements of A
are their own inverses,
so we don't have to
worry about inverses)

← officially, this
should be an inductive
argument

Option 2: Ad-hoc shortcuts.

• Use the fact that $\phi(e)$ is the identity matrix,

and that $\phi((12))$, $\phi((13))$ & $\phi((23))$ all are matrices of order 2
(they're row-switching matrices!)

Option 3: Explain facts about matrices that do elementary row & column operations to convince me that ϕ is a homomorphism.

$$\begin{aligned}\text{So } \det(\phi(\sigma)) &= \det(\phi(t_{2m})) \cdots \det(\phi(t_1)) \\ &= (-1)^{2m} \\ &= 1.\end{aligned}$$

Conversely, suppose $\det(\phi(\sigma)) = 1$.

Since transpositions generate, we can write $\sigma = t_1 \cdots t_k$
where each t_i is a transposition. (or its inverse, but $t_i^{-1} = t_i$.)

$\det(\phi(\sigma)) = (-1)^k$ by the computation above,

so k must be even.