

Math 54 Final Exam (Practice 3)

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Name: Answer Key

SSID: _____

Instructions:

- This exam is **110 minutes** long.
- No calculators, computers, cell phones, textbooks, notes, or cheat sheets are allowed.
- All answers must be justified. Unjustified answers will be given little or no credit.
- You may write on the back of pages or on the blank page at the end of the exam. No extra pages can be attached.
- There are 7 questions.
- The exam has a total of **200 points**.
- Good luck!

Problem 1 (30 points)

Part (a)

Let U be the subset of 3 by 3 matrices with integer entries. Is U a subspace of $M_{3 \times 3}$? Prove your answer. [10 points]

No, not closed under scalar multiplication.

$$\frac{1}{2} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix} \notin U.$$

Part (b)

Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be the translation map, $T(x, y, z) = (x + 1, y + 1, z + 1)$. Is T a linear transformation? Prove your answer. [10 points]

No. $T(0, 0, 0) = 0$ for any linear transformation T
 (Since $T(0, 0, 0) = T(0 \cdot (0, 0, 0)) = 0T(0, 0, 0) = 0$)
 but here, $T(0, 0, 0) = (1, 1, 1)$.

Part (c)

Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be the matrix multiplication map given by

$$T \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right) = \begin{bmatrix} -1 & 0 & 0 \\ 0 & \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ 0 & -\frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

Is T an isometry? Prove your answer. [10 points]

Yes. A is an orthogonal matrix.

$$AA^T = \begin{bmatrix} -1 & 0 & 0 \\ 0 & \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ 0 & -\frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix} \begin{bmatrix} -1 & 0 & 0 \\ 0 & \frac{1}{\sqrt{5}} & -\frac{2}{\sqrt{5}} \\ 0 & \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

So T is an isometry.

Problem 2 (30 points)**Part (a)**

Show that there is no one-to-one linear transformation T from $M_{2 \times 2}$ to P_2 . [15 points]

$$\dim(M_{2 \times 2}) = 4, \dim(P_2) = 3.$$

Let $T: M_{2 \times 2} \rightarrow P_2$ be a linear transformation.

$$\text{Then } \dim(\text{range}(T)) + \dim(\text{ker}(T)) = \dim(M_{2 \times 2}) = 4.$$

Since $\dim(P_2) = 3$, $\dim(\text{range}(T)) \leq 3$. So

$\dim(\text{ker}(T)) \geq 1$ so $\text{ker}(T)$ is nontrivial.

So T is not one-to-one.

Part (b)

Is there a bijective linear transformation T from $M_{2 \times 2}$ to P_3 ? Either prove that one does not exist, or find an example of one. [15 points]

Yes. Consider $T: M_{2 \times 2} \rightarrow P_3$ defined by

$$T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = a + bx + cx^2 + dx^3.$$

Problem 3 (30 points)

Consider the linear transformation $T: P_4 \rightarrow P_4$ given by

$$T(p(x)) = \frac{d^2}{dx^2}((x-1)p(x))$$

Find the trace, determinant, and characteristic polynomial of T . Find all eigenvalues and eigenvectors of T . Is T diagonalizable?

$$\mathcal{B} = \{1, x, x^2, x^3, x^4\}$$

$$T(1) = \frac{d^2}{dx^2}(x-1) = 0 \quad T(x) = \frac{d^2}{dx^2}(x^2-x) = 2$$

$$T(x^2) = \frac{d^2}{dx^2}(x^3-x^2) = 6x-2 \quad T(x^3) = \frac{d^2}{dx^2}(x^4-x^3) = 12x^2-6x$$

$$T(x^4) = \frac{d^2}{dx^2}(x^5-x^4) = 20x^3-12x^2$$

$$[T]_{\mathcal{B} \rightarrow \mathcal{B}} = \begin{bmatrix} 0 & 2 & -2 & 0 & 0 \\ 0 & 0 & 6 & -6 & 0 \\ 0 & 0 & 0 & 12 & -12 \\ 0 & 0 & 0 & 0 & 20 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \begin{array}{l} \det(T) = 0 \text{ (upper triangular)} \\ \operatorname{tr}(T) = 0 \end{array}$$

$$\boxed{\operatorname{char}_T(x) = -x^5}$$

$$\lambda = 0 \quad v = c_1 \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \boxed{p(x) = c_1, \lambda = 0}$$

T is not diagonalizable.

Problem 4 (30 points)

Consider the subspace W of \mathbb{R}^4 spanned by $(1, 2, 1, 0)$ and $(0, 1, 1, 1)$.

Part (a)

Find an orthonormal basis for W . [10 points]

$$w_1 = \frac{1}{\sqrt{3}} \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

$$v_2 - \langle v_2, w_1 \rangle w_1 = \begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \end{pmatrix} - \frac{1}{3}(3) \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 0 \\ -1 \end{pmatrix}$$

$$w_2 = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 0 \\ -1 \end{pmatrix}$$

$$w_1 = \frac{1}{\sqrt{3}} \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix}, w_2 = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 0 \\ -1 \end{pmatrix}$$

Part (b)

Find an orthonormal basis for W^\perp . [20 points]

A vector $(x_1, x_2, x_3, x_4) \in W^\perp$ if

$$(x_1, x_2, x_3, x_4) \cdot (1, 2, 1, 0) = 0$$

$$(x_1, x_2, x_3, x_4) \cdot (0, 1, 1, 1) = 0 \quad (\text{def of } W^\perp)$$

$$\begin{cases} x_1 + 2x_2 + x_3 = 0 \\ x_2 + x_3 + x_4 = 0 \end{cases}$$

$$\begin{bmatrix} 1 & 2 & 1 & 0 \\ 0 & 1 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1 & -2 \\ 0 & 1 & 1 & 1 \end{bmatrix}$$

$$\rightarrow x_3 \begin{pmatrix} -1 \\ 1 \\ 1 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -2 \\ 1 \\ 0 \\ 1 \end{pmatrix}$$

$$\text{Basis for } W^\perp = \begin{pmatrix} -1 \\ 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 1 \\ 0 \\ 1 \end{pmatrix}$$

$$w_1 = \frac{1}{\sqrt{3}} \begin{pmatrix} -1 \\ 1 \\ 1 \\ 0 \end{pmatrix}$$

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$$v_2 - \langle v_2, w_1 \rangle w_1 = \begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \end{pmatrix} - \frac{1}{3}(3) \begin{pmatrix} -1 \\ 1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 0 \\ -1 \end{pmatrix}$$

$$w_2 = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 0 \\ -1 \end{pmatrix}$$

Problem 6 (30 points)

Problem 5 (30 points)

Find a particular solution to the differential equation

$$y'' - 3y' + 2y = 2xe^{2x} - x$$

such that $y(0) = 1$ and $y'(0) = 0$.

$$y'' - 3y' + 2y = 0$$

$$r^2 - 3r + 2 = 0 \quad (r-1)(r-2) = 0 \quad r = 1, 2$$

$$y_{\text{hom}} = C_1 e^x + C_2 e^{2x}$$

$$y'' - 3y' + 2y = 2xe^{2x}$$

Basic guess: $y_p = (Ax + B)e^{2x}$

$$= ACxe^{2x} + BCe^{2x}$$

$$\Rightarrow Ax^2 e^{2x} + \underbrace{Bx}_{\text{in } y_h} e^{2x}$$

$$\Rightarrow y_p = Ax^2 e^{2x} + Bx e^{2x} \checkmark$$

$$= (Ax^2 + Bx)e^{2x}$$

$$y_p' = 2(Ax^2 + Bx)e^{2x} + (2Ax + B)e^{2x}$$

$$= (2Ax^2 + (2A + 2B)x + B)e^{2x}$$

$$y_p'' = 2(2Ax^2 + (2A + 2B)x + B)e^{2x}$$

$$+ (4Ax + (2A + 2B))e^{2x}$$

$$= (4Ax^2 + (8A + 4B)x + (2A + 4B))e^{2x}$$

$$\cancel{4Ax^2 e^{2x}} + (8A + 4B)xe^{2x} + (2A + 4B)e^{2x}$$

$$\cancel{-6Ax^2 e^{2x}} - (6A + 6B)xe^{2x} - 3Be^{2x} + \cancel{2Ax^2 e^{2x}} + 2Bxe^{2x} = 2xe^{2x}$$

$$2Axe^{2x} + (2A + B)e^{2x} = 2xe^{2x}$$

$$2A = 2 \quad 2A + B = 0 \quad A = 1, B = -2$$

$$y_p = x^2 e^{2x} - 2xe^{2x} - \frac{1}{2}x - \frac{3}{4}$$

$$y = x^2 e^{2x} - 2xe^{2x} - \frac{1}{2}x - \frac{3}{4}$$

$$+ C_1 e^x + C_2 e^{2x}$$

$$y' = 2x^2 e^{2x} + 2xe^{2x} - 4xe^{2x} - 2e^{2x} - \frac{1}{2}$$

$$+ C_1 e^x + 2C_2 e^{2x}$$

$$y(0) = 1 \quad -\frac{3}{4} + C_1 + C_2 = 1$$

$$y'(0) = 0 \quad -2 - \frac{1}{2} + C_1 + 2C_2 = 0$$

$$\begin{cases} C_1 + C_2 = \frac{7}{4} \\ C_1 + 2C_2 = \frac{5}{2} \end{cases} \quad C_1 + 2C_2 = \frac{5}{2}$$

$$C_2 = \frac{3}{4} \quad C_1 = 1$$

$$y = x^2 e^{2x} - 2xe^{2x} - \frac{1}{2}x - \frac{3}{4} + e^x + \frac{3}{4} e^{2x}$$

Problem 6 (30 points)

Find the Fourier series expansion for

$$f(\theta) = -1, \quad -\pi < x < 0 \quad f(\theta) = 1, \quad 0 < x < \pi$$

Write the expansion as both an infinite sum of complex exponentials, and also as an infinite sum of sines and cosines.

$$\hat{f}(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(\theta) e^{-in\theta} d\theta$$

$$\hat{f}(n) = \frac{1}{2\pi} \int_{-\pi}^0 -e^{-in\theta} d\theta + \frac{1}{2\pi} \int_0^{\pi} e^{-in\theta} d\theta$$

$$\text{So } \hat{f}(0) = \frac{1}{2\pi} \int_{-\pi}^0 -1 d\theta + \frac{1}{2\pi} \int_0^{\pi} 1 d\theta = 0.$$

$$\begin{aligned} n \neq 0 \quad \hat{f}(n) &= \frac{1}{2\pi} \left(\frac{e^{-in\theta}}{-in} \right) \Big|_{-\pi}^0 + \frac{1}{2\pi} \left(\frac{e^{-in\theta}}{-in} \right) \Big|_0^{\pi} \\ &= \frac{1}{2\pi} \frac{1}{in} (1 - e^{in\pi}) + \frac{1}{2\pi} \left(\frac{-1}{in} \right) (e^{-in\pi} - 1) \\ &= \frac{1}{\pi} \frac{1}{in} + \left(-\frac{1}{2\pi in} \right) (e^{in\pi} + e^{-in\pi}) \\ &= \frac{1}{\pi} \frac{1}{in} + \left(-\frac{1}{2\pi in} \right) (\cos(n\pi) + i\sin(n\pi) + \cos(n\pi) - i\sin(n\pi)) \\ &= \frac{1}{\pi in} + \frac{(-1)^{n+1}}{\pi in} = \frac{1}{\pi in} (1 + (-1)^{n+1}) \end{aligned}$$

$$\text{So } f(\theta) \sim \sum_{\substack{n \neq 0 \\ n \in \mathbb{Z}}} \frac{1 + (-1)^{n+1}}{\pi in} e^{in\theta}$$

$$= \sum_{n=1}^{\infty} \frac{1 + (-1)^{n+1}}{\pi in} e^{in\theta} + \sum_{n=1}^{\infty} \frac{1 + (-1)^{-n+1}}{-\pi in} e^{-in\theta}$$

$$= \sum_{n=1}^{\infty} \frac{1 + (-1)^{n+1}}{\pi in} (\cos(n\theta) + i\sin(n\theta)) + \sum_{n=1}^{\infty} -\frac{1 + (-1)^{n+1}}{\pi in} (\cos(n\theta) - i\sin(n\theta))$$

$$= \sum_{n=1}^{\infty} \frac{1 + (-1)^{n+1}}{\pi in} (2i\sin(n\theta)) = \sum_{n=1}^{\infty} \frac{2(1 + (-1)^{n+1})}{\pi n} \sin(n\theta)$$

Problem 7 (20 points)

Match the systems of differential equations to the appropriate phase portrait on the next page. Note that not every figure on the next page will be used¹.

D $x_1'(t) = x_2(t)$
 $x_2'(t) = -x_1(t)$ $\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ $\begin{vmatrix} -x & 1 \\ -1 & -x \end{vmatrix} = x^2 + 1$ (1)
 $\lambda = 0 + i, 0 - i$ elliptic

E $x_1'(t) = 2x_1(t) + x_2(t)$
 $x_2'(t) = -x_1(t) + 2x_2(t)$ $\begin{bmatrix} 2 & 1 \\ -1 & 2 \end{bmatrix}$ $\begin{vmatrix} 2-x & 1 \\ -1 & 2-x \end{vmatrix} = x^2 - 4x + 5$ (2)
 $\lambda = \frac{4 \pm \sqrt{4}}{2} = 2 \pm i$ unstable spiral

A $x_1'(t) = -x_1(t)$
 $x_2'(t) = -x_2(t)$ $\begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$ stable, every vector is an eigenvector (3)

H $x_1'(t) = x_1(t) + 2x_2(t)$
 $x_2'(t) = 2x_1(t) + x_2(t)$ $\begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ $\begin{vmatrix} 1-x & 2 \\ 2 & 1-x \end{vmatrix} = x^2 - 2x - 3$ (4)
 $\lambda = 3, -1$ = $(x-3)(x+1)$
saddle pt

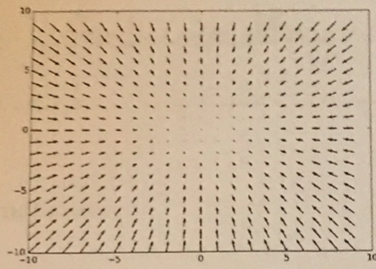
C $x_1'(t) = -3x_1(t) + x_2(t)$
 $x_2'(t) = -x_1(t) - 3x_2(t)$ $\begin{bmatrix} -3 & 1 \\ -1 & -3 \end{bmatrix}$ $\begin{vmatrix} -3-x & 1 \\ -1 & -3-x \end{vmatrix}$ (5) $= x^2 + 6x + 10$
 $\lambda = \frac{-6 \pm \sqrt{-4}}{2} = -3 \pm i$
stable spiral (6)

G $x_1'(t) = -x_1(t) + x_2(t)$
 $x_2'(t) = -x_1(t) - 3x_2(t)$
 $\begin{bmatrix} -1 & 1 \\ -1 & -3 \end{bmatrix}$ $\begin{vmatrix} -1-x & 1 \\ -1 & -3-x \end{vmatrix}$
 $= x^2 + 4x + 4$
 $= (x+2)^2$ repeated
 $\lambda = -2$ stable

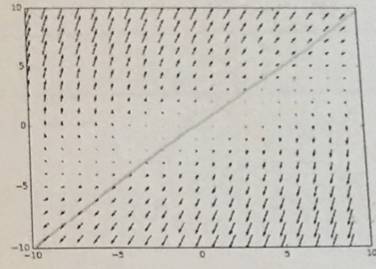
END OF EXAM

(Figures on next page)

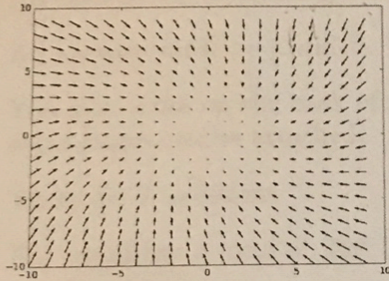
¹Figures generated using Matplotlib



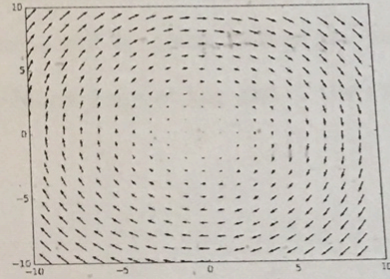
(a) Graph (A)



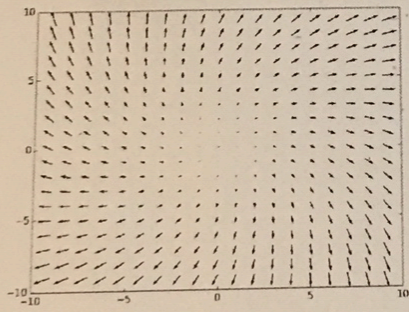
(b) Graph (B)



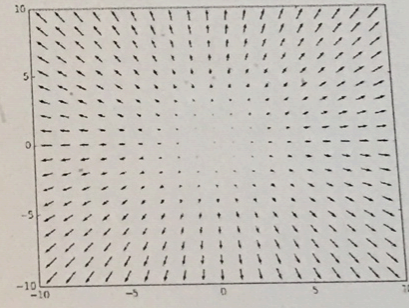
(c) Graph (C)



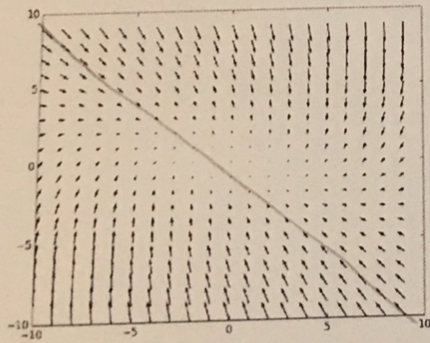
(d) Graph (D)



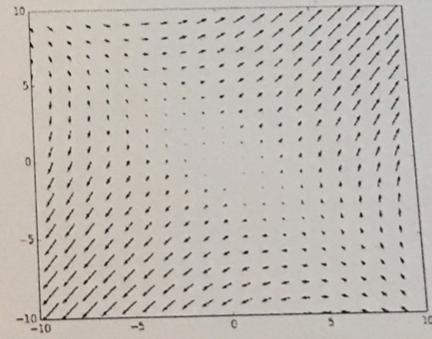
(e) Graph (E)



(f) Graph (F)



(g) Graph (G)



(h) Graph (H)