

Math 54 Section Worksheet 15 Solutions

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1 Warm-Up

True or False? If W is a subspace with basis $\{\mathbf{x}_1, \dots, \mathbf{x}_p\}$ and $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ is another basis of W that is also orthogonal, then $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ was gotten from $\{\mathbf{x}_1, \dots, \mathbf{x}_p\}$ by Gram-Schmidt. **False.**

2 Virtually Together

This might be the moment everyone has been waiting for... a first “real world” application. Let’s see how orthogonal projections can be used to find *best fit lines* for data.

Say we’re given data points $(x_1, y_1), \dots, (x_n, y_n)$. Technically in the “real world” our data points are usually high-dimensional, which means instead of our data points being vectors in \mathbb{R}^2 , they are data points in \mathbb{R}^N for some large N . We will stick with \mathbb{R}^2 for now, as the process easily generalizes.¹ We would like to find a line that goes through all the data points at once. Unfortunately, this is typically impossible, due to factors such as round-off error and noise in the data collection. There is a method, known as *linear regression* of finding the best line possible. We should first define what it means to be “best”, which we do by reframing the question more linear-algebraically.

A line is determined by its slope and intercept, so we wish to find m, b that satisfy $\mathbf{y} = m\mathbf{x} + b$, or

$$\mathbf{y} = A \begin{pmatrix} m \\ b \end{pmatrix}, \quad \text{where} \quad A = \begin{pmatrix} x_1 & 1 \\ x_2 & 1 \\ \vdots & \vdots \\ x_n & 1 \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}$$

Like we said though, this is not possible if \mathbf{y} is not in $\text{Col} A$. But what vector is in $\text{Col} A$ and is as close as possible to \mathbf{y} ? That’s right, the orthogonal projection of \mathbf{y} onto $\text{Col} A$. Thus, we seek vectors $\begin{pmatrix} m \\ b \end{pmatrix}$ that instead satisfy

$$\text{proj}_{\text{Col} A} \mathbf{y} = A \begin{pmatrix} m \\ b \end{pmatrix}$$

We call this vector $\begin{pmatrix} m \\ b \end{pmatrix}$ a **least-squares solution**. Note that this solution is not necessarily unique! The orthogonal projection is unique, but if A has a nonzero null space, then there could be several least-squares solutions. Now, here’s a slick way to find a least-square solution: we know that $\mathbf{y} - \text{proj}_{\text{Col} A} \mathbf{y}$ must be orthogonal to $\text{Col} A$, and we know that the orthogonal complement of $\text{Col} A$ is $\text{Nul} A^T$. So, a least-squares solution $\begin{pmatrix} m \\ b \end{pmatrix}$ must satisfy

$$0 = A^T(\mathbf{y} - \text{proj}_{\text{Col} A} \mathbf{y}) = A^T \left(\mathbf{y} - A \begin{pmatrix} m \\ b \end{pmatrix} \right) \implies A^T A \begin{pmatrix} m \\ b \end{pmatrix} = A^T \mathbf{y}$$

which we call the **normal equations**. Solving the normal equations solves for the least-squares solution, which in this particular case solves for the slope m and intercept b of the best-fit line. The reason we call this the “least-squares” solution is because this line minimizes the squared distance $\|\mathbf{y} - (m\mathbf{x} + b)\|^2$.

¹Alternatively, instead of doing linear regression on a high-dimensional data set, do you think you might know a good way to reduce a high dimensional vector to a vector in \mathbb{R}^n for some much smaller n ? That’s right, you can orthogonally project! But what space should you project onto? Choosing the right space is at the center of PCA or *principal component analysis*, which in this class goes under the guise of SVD, or *singular value decomposition*.

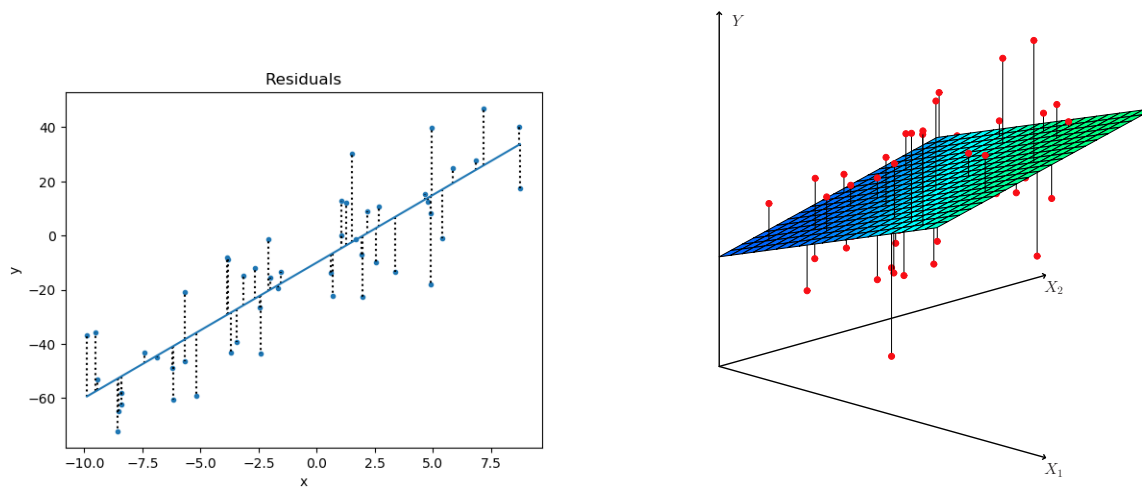


Figure 1: Left: A plot of a least-squares line fit to two-dimensional data points. Following the dashed lines from each point to the line gives the prediction $\hat{y}_i := mx_i + b$. The line shown minimizes the sum of the squares of the lengths of the dashed lines. Right: In a three-dimensional setting the least squares line becomes a plane.

3 Problems

1. Let $\mathbf{b} = \begin{pmatrix} 4 \\ 0 \\ 2 \end{pmatrix}$ and let $A = \begin{pmatrix} 1 & 0 & -2 \\ 2 & 1 & -1 \\ 0 & -1 & -3 \end{pmatrix}$.

- (a) Find an orthonormal basis for the column space of A .

(If I had known this calculation was so messy, I wouldn't have assigned it.. oops!) Gram-Schmidt on the columns gives the orthogonal basis $\left\{ \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} -2/5 \\ 1/5 \\ -1 \end{pmatrix} \right\}$. Note that the basis consists of only 2 vectors, since the 3rd column is in the span of the first two. To get an orthonormal basis, we divide the first vector by $\sqrt{5}$ and the second by $\sqrt{6/5}$.

- (b) Find a least squares solution to $A\mathbf{x} = \mathbf{b}$.

We solve $A^T A \mathbf{x} = A^T \mathbf{b}$, which gives $\mathbf{x} = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} + t \begin{pmatrix} 2 \\ -3 \\ 1 \end{pmatrix}$ for any $t \in \mathbb{R}$. Note the infinite number of least squares solutions!

- (c) Find the shortest distance from \mathbf{b} to the column space of A .

Let $\hat{\mathbf{b}} = A\hat{\mathbf{x}}$ where $\hat{\mathbf{x}}$ is any answer from part (b). Then, $\hat{\mathbf{b}} = \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix}$ and so the shortest distance is

$$\|\mathbf{b} - \hat{\mathbf{b}}\| = \|(2, -1, -1)^T\| = \sqrt{6}$$

Note that no matter our choice of $\hat{\mathbf{x}}$, the vector $\hat{\mathbf{b}}$ is always the same. This is because $\hat{\mathbf{b}}$ is the orthogonal projection of \mathbf{b} onto $\text{Col } A$, and so is unique.

2. Let $A = \begin{pmatrix} 1 & 5 \\ 3 & 1 \\ -2 & 4 \end{pmatrix}$ and $\mathbf{b} = \begin{pmatrix} 4 \\ -2 \\ -3 \end{pmatrix}$.

(a) Find a least-squares solution of $A\mathbf{x} = \mathbf{b}$.

$$\widehat{\mathbf{x}} = \begin{pmatrix} 2/7 \\ 1/7 \end{pmatrix}.$$

(b) Find the orthogonal projection of \mathbf{b} onto $\text{Col } A$.

The columns of A are already orthogonal, so we don't need to do Gram-Schmidt. If $\mathbf{a}_1, \mathbf{a}_2$ denote the columns of A , then the projection is

$$\text{proj}_{\text{Col } A} \mathbf{b} = \frac{\mathbf{b} \cdot \mathbf{a}_1}{\mathbf{a}_1 \cdot \mathbf{a}_1} \mathbf{a}_1 + \frac{\mathbf{b} \cdot \mathbf{a}_2}{\mathbf{a}_2 \cdot \mathbf{a}_2} \mathbf{a}_2 = \frac{2}{7} \begin{pmatrix} 1 \\ 3 \\ -2 \end{pmatrix} + \frac{1}{7} \begin{pmatrix} 5 \\ 1 \\ 4 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

(c) Check your answer to part (a) using part (b). We note that

$$A\widehat{\mathbf{x}} = A \begin{pmatrix} 2/7 \\ 1/7 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = \text{proj}_{\text{Col } A} \mathbf{b}$$

3. True or False?

- T (a) A least-squares solution of $A\mathbf{x} = \mathbf{b}$ is a vector $\widehat{\mathbf{x}}$ that satisfies $A\widehat{\mathbf{x}} = \widehat{\mathbf{b}}$, where $\widehat{\mathbf{b}}$ is the orthogonal projection of \mathbf{b} onto $\text{Col } A$.
- F (b) A least-squares solution of $A\mathbf{x} = \mathbf{b}$ is a vector $\widehat{\mathbf{x}}$ such that $\|\mathbf{b} - A\mathbf{x}\| \leq \|\mathbf{b} - A\widehat{\mathbf{x}}\|$ for all \mathbf{x} in \mathbb{R}^n .
- T (c) Any solution of $A^T A\mathbf{x} = A^T \mathbf{b}$ is a least-squares solution of $A\mathbf{x} = \mathbf{b}$.
- T (d) If the columns of A are linearly independent, then the equation $A\mathbf{x} = \mathbf{b}$ has exactly one least-squares solution.
- T (e) If \mathbf{b} is in the column space of A , then every solution of $A\mathbf{x} = \mathbf{b}$ is a least squares solution.
- F (f) The least-squares solution of $A\mathbf{x} = \mathbf{b}$ is the point in the column space of A closest to \mathbf{b} .
- F (g) If $\widehat{\mathbf{x}}$ is a least-squares solution of $A\mathbf{x} = \mathbf{b}$, then $\widehat{\mathbf{x}} = (A^T A)^{-1} A^T \mathbf{b}$.