## Answers to HW10

- 1. For a fixed  $k \times n$ -matrix A, consider det AB as a k-linear totally anti-symmetric function F (i.e. as an exterior k-form) of the columns of the  $n \times k$ -matrix B. Just as any such function, it is a linear combination  $F = \sum_{I} F_{I} \det B_{I}$  with the coefficients  $F_{I} = F(e_{i_{1}}, \ldots, e_{i_{k}}) = \det A_{I}$ .
- **2.** Consider det A with fixed last n-k rows of the  $n \times n$ -matrix A as an k-linear totally anti-symmetric function of the first k rows. Just as any such function it is a linear combination of  $\det A_I$ ,  $I = \{i_1 < \cdots < i_k\}$ , with coefficients  $c_I$  which are the values of this function when the first k rows are (transposed) unit coordinate vectors  $e_{1_1}, \ldots, e_{i_k}$ . Performing  $(i_1 1) + (i_2 1) + \cdots + (i_k 1)$  transpositions, move the columns  $i_1, \ldots, i_k$  to the positions  $1, \ldots, k$ . Then the matrix assumes the block-triangular form  $\begin{bmatrix} I_k & 0 \\ * & A'_I \end{bmatrix}$  with the determinant equal to  $\det A'_I$ . Thus  $c_I = (-1)^{|I|} \det A'_I$ .

Remark: Another proof:  $x_1 \wedge \cdots \wedge x_n = (x_1 \wedge \cdots \wedge x_k) \wedge (x_{k+1} \wedge \cdots \wedge x_n)$ .

- **3.** Let  $\alpha$  be a linear form taking value 1 on the vector v. Then for any exterior k-form  $\omega$ , we have  $i_v(\alpha \wedge \omega) = \omega \alpha \wedge (i_v\omega)$ . Therefore, when  $i_v\omega = 0$ , we have  $\omega = i_v(\alpha \wedge \omega)$ .
  - **4.2.2.** WLOG, assume that  $\phi_n = \sum_{i=1}^n c_i \phi_i$ . Then

$$\phi_1 \wedge \cdots \wedge \phi_n = \sum_{i=1}^n c_i \phi_1 \wedge \cdots \wedge \phi_{n-1} \wedge \phi_i = 0$$

since the *i*th summand contains the wedge product  $\phi_i \wedge \phi_i$ .

- **4.2.6.** (a) If  $v_i' = \sum_j a_{ij}v_j$ , then  $T(v_1', \ldots, v_k') = \det[a_{ij}]T(v_1, \ldots, v_k)$ , i.e. the transition matrix between the bases has positive determinant whenever  $T(v_1, \ldots, v_k)$  and  $T(v_1', \ldots, v_k')$  have the same sign.
- (b) When  $V^k$  is oriented, declare a basis element T in the 1-dimensional space  $\Lambda^k V^*$  right-oriented if  $T(v_1, \ldots, v_k) > 0$  for right-oriented bases  $(v_1, \ldots, v_k)$ . Obviously the same condition holds for any positive multiple of T (instead of T), and by (a) for any right-oriented basis when it holds for one of them.
- (c) Conversely, given one of positive-proportional non-zero elements  $T \in \Lambda^k V^*$ , call a basis  $(v_1, \ldots, v_k)$  of V right-oriented if  $T(v_1, \ldots, v_n) > 0$ . By (a) the condition holds for all same-oriented bases when it holds for one of them.

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