

Preliminary version

TOPICS IN ENUMERATIVE ALGEBRAIC GEOMETRY  
LECTURE 29

A. GIVENTAL

Our goal for today is to sketch some applications of localization technique to genus one G-W invariants.

1. GENUS ONE GROMOV-WITTEN INVARIANTS

Define the genus one potential:

$$G(t) := \sum_{n=0}^{\infty} \frac{1}{n!} \sum_{d \in \Lambda} q^d(t, t, \dots, t)_{1,n,d},$$

where  $t = \sum t_\alpha \phi_\alpha$  and  $(n, d) = (0, 0)$  term is defined to be zero. In genus one case, what really matters is not the function  $G(t)$  but rather its differential (the reason will be clear later) :

$$(1) \quad d_t G(t) = \sum_{\alpha} dt_{\alpha} \sum_{n=0}^{\infty} (\phi_{\alpha}, t, \dots, t)_{1,n+1,d}.$$

Now we want to express  $dG(t)$  in terms of the fundamental solution

$$S_{\alpha i} = \langle \phi_{\alpha}, \phi_i \rangle + \sum_{(n,d) \neq (0,0)} \frac{q^d}{n!} (\phi_{\alpha}, t, \dots, t, \frac{\phi_i}{\hbar - c})_{0,n+2,d}.$$

In *singularity theory* (cf. lectures 14-16) we have Morse function  $f_t(x)$  for generic  $t$ . The extra data we have are:

$u_1, \dots, u_N$ : critical points,

$\Delta_1, \dots, \Delta_N$ : Hessians at critical points,

$R_1, \dots, R_N$ :  $\hbar$  order term of diagonal components of the oscillating integrals,

( $R_i = R_{ii}$  in previous notation,

$\omega_t^{m,0}$ : primitive form (of Saito).

The partial derivative of the oscillating integral is:

$$\begin{aligned} & \hbar \frac{\partial}{\partial u_i} \int_{\Gamma_i} e^{f_t(u)(x)/\hbar} \omega_t^{m,0} \\ & \approx \hbar^{m/2} (\text{const}) e^{u_i/\hbar} (1 + \hbar R_i + o(\hbar)) \quad (\text{stationary phase asymptotics}). \end{aligned}$$

**Proposal.**

$$dG := \frac{1}{48} \sum_i \frac{d\Delta_i(u)}{\Delta_i(u)} + \frac{1}{2} \sum_i R_i(u) du_i.$$

**Question.** Does  $dG$  satisfy all axioms of  $g = 1$  Gromov-Witten theory?

So far, no one has checked this. Now we will give the motivation of this proposal in the context of *Gromov-Witten* theory.

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*Date:* Dec. 4, 1997.

Notes taken by Y.-P. Lee.

**Motivation.** Given a concave vector bundle  $E \rightarrow X$  with a torus  $T$  action such that  $X$  has isolated zero and one dimensional orbits. Let us define

$$\begin{aligned} U &:= \text{diag}(u_1, \dots, u_N), u_i \text{ are canonical coordinates,} \\ E &:= \text{diag}(e_1, \dots, e_N), e_i \text{ are the equivariant Euler classes } Euler_T(T_i E), \\ \delta_1, \dots, \delta_N &: p_i\text{-type potentials, } e_i \delta_i^2 = \Delta_i, \text{ see lecture 28 for definition.} \end{aligned}$$

By theorem 2 in lectures 15-16 (in fact, slightly modified version in the case of concave vector bundle), we have

$$(2) \quad (S_{\alpha i}) = (\Psi_{\alpha}^j)(\delta_{ji} + \hbar R_{ji} + o(\hbar))e^{U/\hbar} E^{-1}.$$

Compare this to the recursion relation we found in lecture 28,

$$(3) \quad \begin{aligned} S_{\alpha i} e^{-u_i/\hbar} e_i &=: s_{\alpha i}(\hbar) \\ &= \delta_{\alpha i} + \sum_{j \neq i} \sum_{m=1}^{\infty} \frac{C \equiv (\equiv 0 \pmod{q})}{x_i^j + m\hbar}, \end{aligned}$$

where the numerator  $C$  has no poles at  $\hbar = 0$  and therefore can be expanded as power series in  $\hbar$ . Define  $R_{ii} := R_{ii}$  in equation (2)  $\equiv 0 \pmod{q}$ <sup>1</sup>.

**Theorem 1.** *Under usual assumptions, we have*

$$(4) \quad d_t G(t) = \frac{1}{24} \sum \frac{d\delta_i}{\delta_i} - \frac{1}{24} \sum_i c_{-1}^{(i)} du_i + \frac{1}{2} \sum R_{ii} du_i,$$

where

$$\begin{aligned} c_{-1}^{(i)} &:= \frac{c_{top-1}(T_i E)}{c_{top}(T_i E)} \\ &= \sum_{\chi: \text{characters of } T: T_i E} \frac{1}{\chi} \end{aligned}$$

and  $c_*$  are the equivariant chern classes.

*Remark.* A similar formula holds for convex super-manifolds, but  $c_{-1}^{(i)}$  should be defined differently.

The relation of this theorem (in G-W theory) and the proposal (in singularity theory) is<sup>2</sup>:

$$d_t G = \frac{1}{48} \sum \frac{d\Delta_i}{\Delta_i} + \frac{1}{2} \sum \underbrace{(R_{ii} - \frac{1}{12} c_{-1}^{(i)})}_{R_i} du_i.$$

**Conjecture.** The proposal is true for generic semisimple Frobenius structure of compact symplectic manifolds.

*Proof. (of the theorem)* (Sketch.) The proof will again be based on fixed point localization technique. The fixed points of  $X_{1,n,d}$  can be divided into two types. The first type has an elliptic curve with  $n$  branches out, and the second type contains one cycle of rational components:

<sup>1</sup> $R_{ii}$  are defined only up to constants. But the recursion relation can fix these constants.

<sup>2</sup>Here we might have to readjust the constant of  $R_i$ . But in all worked examples  $R_i = R_{ii} - \frac{1}{12} c_{-1}^{(i)}$ .

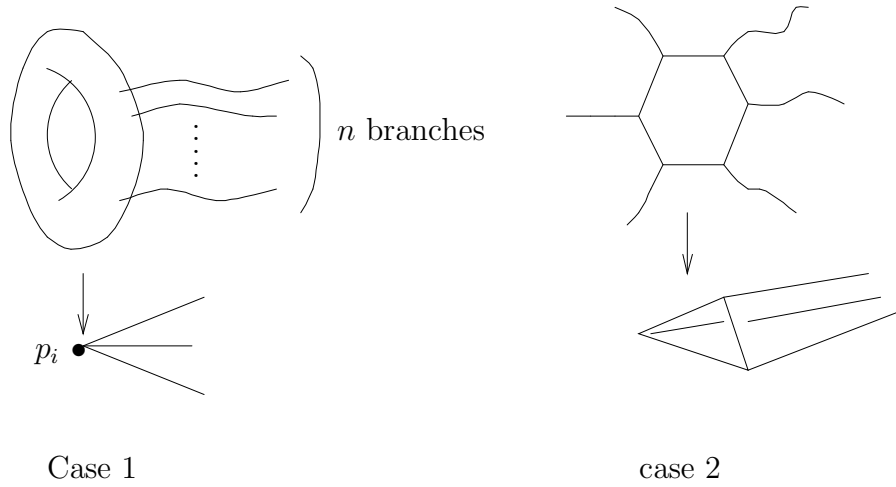


Fig. 1

Our claim now is that the contribution of case 1 is the first two terms of (4) and that of case 2 is the last term.

*Case 1.* The contribution of fixed points of case 2 type to  $dG$  is:

$$(5) \quad e_i^{-1} \sum_{n=0}^{\infty} \int_{\mathcal{M}_{1,n}} (1 - c_{-1}^{(i)} \omega) T(c^{(1)}) \wedge \cdots \wedge T(c^{(n)}) \int_{\mathcal{M}_{0,*}} \cdots \int \cdots$$

Here  $T(c)$  is some function of chern class as usual.  $\omega$  is the first chern class of the Hodge bundle  $\mathcal{H}$  and the term  $(1 - c_{-1}^i \omega)$  comes from the obstruction part. The obstruction is of the form  $H^1(C_e, T_i E) = T_i E \otimes \mathcal{H}^*$  ( $C_e$  is the irreducible component of genus one). The contribution of this to  $dG$  is of the form:

$$\begin{aligned} \frac{Euler_T(T_i E \otimes \mathcal{H})}{Euler_T(T_i E)} &= \frac{chern_T(T_i E)(-\omega)}{Euler_T(T_i E)} \\ (chern_T(T_i E)(-\omega) \text{ is the chern polynomial with variable equal to } -\omega) \\ &= \frac{c_{top} + c_{top-1}(-\omega)}{c_{top}} \\ &= 1 - c_{-1}^{(i)} \omega. \end{aligned}$$

Apart from the obstruction part, it looks very much like the potential  $\nu(T) = \frac{1}{24} \ln \delta_i(T)$  (. The extra part from obstruction is of the form  $c_{-1}^{(i)} \mu(T)$  (see lecture 28 for definitions). Therefore we conclude that case 1 part is equal to  $\frac{1}{24} \ln \delta_i - \frac{1}{24} c_{-1}^{(i)} u_i$  as claimed.

*Case 2.* If we cut the cycle in case 2 (Fig. 1) at a vertex which maps to fixed point  $p_i$ , we will end up with (for  $G$ )

$$\sum_n \frac{1}{n} \left( \begin{array}{c} | \quad | \quad | \quad | \quad | \quad | \quad | \quad | \\ \frac{\phi_i}{x-c} \qquad \qquad \qquad \frac{\phi_i}{y-c} \end{array} \right) n$$

Fig. 2

Here the factor  $1/n$  comes from the choice of the cut vertices. But this series is of the form like log function ( $\sum \frac{1}{n}$ ), it is not very convenient for computation. Therefore we consider the partial derivative  $\frac{\partial G}{\partial t_\alpha}$ :

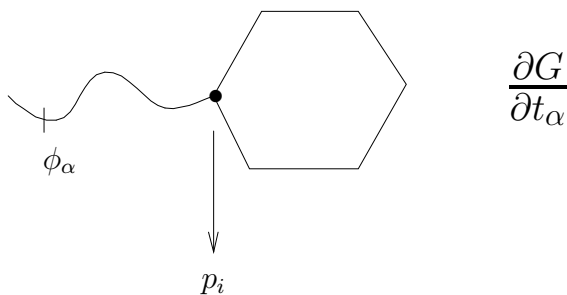


Fig. 3

Then this part is related to the potential

$$V_{ij}(x, y) = \sum_{n=0}^q \frac{q^d}{n!} \left( \frac{\phi_i}{x-c}, t, \dots, t, \frac{\phi_j}{y-c} \right)_{0, n+2, d}$$

which we defined in lecture 10. If we take the limit:

$$(6) \quad \frac{1}{2} \frac{\partial u}{\partial t_\alpha} \lim_{x, y \rightarrow 0} [V_{ii}(x, y) e^{-[(u_i/x)+(u_i/y)]} e_i - \frac{1}{x+y}]$$

which is just  $\frac{\partial G}{\partial t_\alpha}$  (Fig. 3). From an exercise in lecture 10, we have:

$$(7) \quad V_{ij}(x, y) = \frac{1}{x+y} \sum_{\alpha} S_{\alpha i}(x) e_{\alpha}^{-1} S_{\alpha j}(y).$$

Replace  $\hbar$  in (2) by  $x, y$  respectively and substitute into (7). Use the obvious identity

$$\sum_{\alpha} \Psi_{\alpha}^i e_{\alpha}^{-1} \Psi_{\alpha}^j = e_i \delta_{ij}$$

we then have

$$\begin{aligned} V_{ii} &= \frac{e^{u_i(\frac{1}{x} + \frac{1}{y})}}{e_i(x+y)} [1 + R_{ii}(x+y) + \dots] \\ \Rightarrow \lim_{x, y \rightarrow 0} [V_{ii} e^{u_i/x + u_i/y} e_i - \frac{1}{x+y}] &= R_{ii}. \end{aligned}$$

Combined with (6) this then implies that  $dG$  in case 2 is equal to  $\sum_i \frac{1}{2} du_i R_{ii}$  as claimed. □