

# TOPICS IN ENUMERATIVE ALGEBRAIC GEOMETRY

## LECTURE 17

A. GIVENTAL

The last time we discussed the mirror conjecture for  $\mathbb{CP}^4$  and quintics in  $\mathbb{CP}^4$ . The formulas which we mentioned can be extended to the case of complete intersections in toric varieties.

### 1. DEFINITIONS

The basic definition is as follows.

**Definition 1.** An  $n$ -dimensional compact complex manifold  $X$  is called toric if it is equipped with an action of an  $n$ -dimensional complex torus  $T_{\mathbb{C}}^n$  s. t. there exists a dense orbit isomorphic to  $T_{\mathbb{C}}^n$ .

Consider  $\mathbb{C}^n$  with coordinates  $x_1, x_2, \dots, x_n$  and the standard symplectic form  $\Omega = -\frac{1}{2i}(\sum_{j=1}^n dx_j \wedge d\bar{x}_j)$  on it. There is a natural action of the real  $n$ -dimensional torus  $T^n$  on  $\mathbb{C}^n$ , namely the diagonal action

$$\text{diag}(e^{it_1}, \dots, e^{it_n})(x_1, \dots, x_n) = (e^{it_1}x_1, \dots, e^{it_n}x_n).$$

Recall that:

**Definition 2.** A vector field  $v$  on a symplectic manifold  $(M, \Omega)$  is called Hamiltonian if there exists a function  $H$  s. t.:

$$\Omega + dH = 0.$$

$H$  is called a Hamiltonian function of  $v$ . An action of a Lie group  $G$  on  $M$  is called Hamiltonian if the vector fields corresponding to the elements of  $\text{Lie}G$  are Hamiltonian.

The above mentioned action of  $T^n$  on  $\mathbb{C}^n$  is Hamiltonian and the associated moment map  $\tilde{J} : \mathbb{C}^n \rightarrow \mathbb{R}_+^n \subset \text{Lie}^*T^n$  is given by:

$$\tilde{J}(x_1, \dots, x_n) = (|x_1|^2, \dots, |x_n|^2).$$

(We fix coordinates on  $\text{Lie}^*T$ ).

Consider a subtorus  $T^r \subset T^n$ . The moment map  $J$  for its action on  $\mathbb{C}^n$  fits in the following commutative diagram:

$$\mathbb{C}^n \longrightarrow \mathbb{R}_+^n$$

where  $\mathbb{R}_+^r \subset \mathbb{R}^r = \text{Lie}^*T^r$  and the map  $M$  is determined by the projection  $\text{Lie}^*T^n \rightarrow \text{Lie}^*T^r$ . A point  $\omega \in \text{Im}M \subset \mathbb{R}^r$  will be called generic if it is not situated on the image under  $M$  of any  $r-1$ -dimensional coordinate subspace in  $\mathbb{R}^n$ . For such an  $\omega$

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consider  $J^{-1}(\omega) \subset \mathbb{C}^n$ . It is invariant w.r.t.  $T^n$  and one can consider the quotient  $X_{J,\omega}^{n-r} = J^{-1}(\omega)/T^r$ . There is a natural action of  $T^{n-r} = T^n/T^r$  on  $X_{J,\omega}^{n-r}$ .

*Example.* If  $T \subset T^n$  is the diagonal embedding  $e^{it} \mapsto \text{diag}(e^{it}, \dots, e^{it})$ ,  $t \in \mathbb{R}$  then

$$J(x_1, \dots, x_n) = |x_1|^2 + \dots + |x_n|^2,$$

$\omega$  is generic if  $\omega \neq 0$  and  $J^{-1}(\omega)/T^1 = \mathbb{CP}^{n-1}$ .

The form  $\Omega$  is degenerated on  $J^{-1}(\omega)$  (along the orbits of  $T^r$ ) but on the quotient  $X_{J,\omega}^{n-r}$  it is symplectic. The action of  $T^{n-r}$  on  $X_{J,\omega}^{n-r}$  is Hamiltonian w.r.t. this form.

So far  $X_{J,\omega}^{n-r}$  is only a real manifold. It is not clear at all that it can be equipped with a compatible complex structure. But let us consider the connected component of  $\{\mathbb{R}^r \setminus \text{images of } r-1\text{-dimensional coordinate subspaces in } \mathbb{R}^n\}$ , containing  $\omega$ . Denote it  $K$  and also let us denote

$$J^{-1}(K) = \mathbb{C}^n \setminus \cup (\text{Coordinate subspaces which miss } K \text{ under } J)$$

(here the inverse is only formal). Then  $J^{-1}(K)$  is  $T_{\mathbb{C}}^n$ -invariant and the quotient  $J^{-1}(K)/T_{\mathbb{C}}^r$  is isomorphic to  $X_{J,\omega}^{n-r}$  (as real a manifold). Besides this obviously it comes equipped with an action of  $T_{\mathbb{C}}^{n-r}$ .

## 2. MAIN PROPERTIES

In this section we will collect some properties of the the toric manifolds  $X_{J,\omega}^{n-r}$ .

**2.1 Compactness.** The following theorem answers the question when  $X_{J,\omega}^{n-r}$  is compact.

**Theorem 1.**  $X_{J,\omega}^{n-r}$  is compact iff one of the following 3 equivalent conditions holds:

- 1.)  $M^{-1}(0) = 0$
- 2.)  $M^{-1}(\omega)$  is compact
- 3.)  $J(\mathbb{C}^n)$  fits into a half space in  $\mathbb{R}^r$

**2.2 Smoothness.** In general  $X_{J,\omega}^{n-r}$  is a nonsingular orbifold (it is nonsingular because  $\omega$  does not lie on the images under  $M$  of the  $r-1$  dimensional coordinate subspaces of  $\mathbb{R}^n$  and therefore it is a regular value of  $J$ ). Let the embedding of  $T^r$  in  $T^n$  be given by a matrix

$$M = (m_{ij})_{i=1,\dots,r;j=1,\dots,n}.$$

This is also the matrix of the projection  $M$  and that is why we use the same letter, hoping that it will not cause any confusion. Consider all  $r$ -dimensional faces  $\mathbb{R}^I$  of  $\mathbb{R}_+^n$ ,  $I \subset \{1, \dots, n\}$   $|I| = r$ , whose image under  $M$  contains  $K$ . Each such face determines a point on  $X_{J,\omega}^{n-r}$  (or rather on its complex version) whose stabilizer in  $T_{\mathbb{C}}^r$  has order  $|\det M^I|$ . Here  $M^I$  is the minor associated with the subset  $I \subset \{1, \dots, n\}$ . This implies the next theorem.

**Theorem 2.**  $X_{J,\omega}^{n-r}$  is a manifold, i.e. not an orbifold iff  $|\det M^I| = 1$  for all minors  $M^I$ ,  $I \subset \{1, \dots, n\}$   $|I| = r$ , s.t.  $M(\mathbb{R}_+^I)$  contains  $K$ .

**2.3 Minimal representation of a toric manifold.** Here we will show that arbitrary Kähler toric manifold can be obtained by Hamiltonian reduction, described in Sect. 1. Suppose  $X^m$  is such a manifold, on which acts the complex torus  $T_{\mathbb{C}}^m$ . Averaging the Kähler form of  $X$  along the orbits of  $T_{\mathbb{C}}^m$  one gets an invariant Kähler form on  $X$ .

It is not difficult to prove that the action of  $T_{\mathbb{C}}^m$  is Hamiltonian w.r.t. it. Indeed suppose that  $H$  is a Hamiltonian function of a vector field corresponding to an element of  $\text{Lie}T_{\mathbb{C}}^m$  which is multivalued along a closed curve. The complement in  $X$  of the open orbit of  $T_{\mathbb{C}}^m$  isomorphic to  $T_{\mathbb{C}}^m$  has a real codimension 2 and the curve can be deformed to lie entirely on this orbit. If we restrict the Kähler form of  $X$  to this orbit we will get a translationally invariant Kähler form on  $T_{\mathbb{C}}^m$  for which the action of  $T_{\mathbb{C}}^m$  on itself is not Hamiltonian, which is impossible.

The image under the associated moment map of  $X$  is an  $m$ -dimensional convex polyhedron (Atiyah, Bott). It can be embedded in  $\mathbb{R}_+^n$  for sufficiently large  $n$  and for those  $n$ 's  $X$  can be obtained by Hamiltonian reduction from  $\mathbb{C}^n$ . The minimal possible  $n$  gives a *minimal representation* of  $X$ .

**2.4  $H^2(X_{J,\omega}^{n-r}, \mathbb{Z})$  and the Kähler cone of  $X_{J,\omega}^{n-r}$ .** Recall the construction of  $X_{J,\omega}^{n-r} = J^{-1}(\omega)/T^r$ . To each character of  $T^r$  one can associate a line bundle on  $X_{J,\omega}^{n-r}$  glueing the trivial bundle over  $J^{-1}(\omega)$  using this character. The Chern classes of these bundles can be identified with the integer points in the standard lattice in  $\mathbb{R}^r = \text{Lie}^*T^r$ . So  $H^2(X_{J,\omega}^{n-r}, \mathbb{Z})$  coincides with this lattice and

$$H^2(X_{J,\omega}^{n-r}, \mathbb{R}) = \text{Lie}^*T^r.$$

The Kähler cone of  $X_{J,\omega}^{n-r}$  is precisely  $K$ .

**2.5  $c_1(T_X)$ .** It is given by the formula

$$c_1(T_X) = Me_1 + \dots + Me_n,$$

where the RHS is viewed as an element in  $H^2(X_{J,\omega}^{n-r}, \mathbb{Z})$  (cf. the previous subsection).

Consider  $n-r$  coordinate vectors  $e_{j_1}^*, \dots, e_{j_{n-r}}^*$  in  $\text{Lie}T^n \cong (\mathbb{R}^n)^*$ , that form a basis in  $\text{Lie}T^n/\text{Lie}T^r$ . They correspond to  $n-r$  vector fields  $\partial_1, \dots, \partial_{n-r}$  on the toric variety  $X_{J,\omega}^{n-r}$ . The wedge product  $\partial_1 \wedge \dots \wedge \partial_{n-r}$  is a section of the anticanonical bundle on  $X_{J,\omega}^{n-r}$ .  $\partial_1, \dots, \partial_{n-r}$  are linearly independent on an open subset of  $X_{J,\omega}^{n-r}$  and the pull back of the divisor where the above section is 0 on  $J^{-1}(\omega)$  is a union of hyperplanes. The homology class of this divisor can be identified with the RHS of the formula for  $c_1(T_X)$ .

**2.6 The cohomology algebra  $H^*(X_{J,\omega}^{n-r}, \mathbb{C})$ .** Here we will give a description of  $H^*(X_{J,\omega}^{n-r}, \mathbb{C})$  which is due to Kirwan. It is multiplicatively generated by  $H^2(X_{J,\omega}^{n-r}, \mathbb{C})$ . First we need some notation. Denote by  $\Sigma$  the union of all  $n-r$ -dimensional coordinate subspaces in  $\text{Lie}T^n$  which are orthogonal complements to those  $r$ -dimensional subspaces of  $\text{Lie}^*T^n$  whose image under  $M$  contains  $K$ . By  $\mathbb{C}[u_1, \dots, u_n]$  will be denoted the algebra of polynomial functions on the complexification  $(\text{Lie}T^n)_{\mathbb{C}}$  of  $\text{Lie}T^n$  and by  $\mathbb{C}[p_1, \dots, p_r]$  the algebra of polynomial functions on  $(\text{Lie}T^r)_{\mathbb{C}}$ . Denote by  $I_{\Sigma}$  the ideal of  $\Sigma$  in  $\mathbb{C}[u_1, \dots, u_n]$  and let  $I$  be the ideal in  $\mathbb{C}[u_1, \dots, u_n, p_1, \dots, p_r]$  generated by

$$u_j - \sum_{i=1}^r p_i m_{ij} \quad j = 1, \dots, n.$$

Then the formula of Kirwan says that

$$H^*(X_{J,\omega}^{n-r}, \mathbb{C}) = \frac{\mathbb{C}[u_1, \dots, u_n, p_1, \dots, p_r]}{I + I_\Sigma}$$

There is also a more explicit description of  $I_\Sigma$ . It coincide with the ideal  $\mathcal{J}$  in  $\mathbb{C}[u_1, \dots, u_n]$  generated by all monomials  $u_{j_1}, \dots, u_{j_s}$  s.t.  $Me_{j_1}, \dots, Me_{j_s}$  is a maximal coordinate subset whose convex hull does not intersect  $K$ .

Finally one can see that the Kirwan formula respects the fact that we mentioned: that  $H^*(X_{J,\omega}^{n-r}, \mathbb{C})$  is generated by  $H^2(X_{J,\omega}^{n-r}, \mathbb{C})$ . In view of Subsect. 2.5  $H^*(X_{J,\omega}^{n-r}, \mathbb{C})$  should be a quotient of  $\mathbb{C}[p_1, \dots, p_r]$  and that is the case because using the relations from  $I$  we can express  $u$  variables in terms of  $p$  variables and also the monomials generating  $\mathcal{J}$  as polynomials in  $p$ .

The proofs of the facts in this Subsection will be given in Lect. 19.

**2.7 Example.** Consider two toric manifolds  $X_1$  and  $X_2$  which are projectivizations of the bundles  $\mathcal{O} \oplus \mathcal{O}(-1) \oplus \mathcal{O}(-1)$  and  $\mathcal{O} \oplus \mathcal{O} \oplus \mathcal{O}(-2)$  respectively over  $\mathbb{CP}^1$ . The matrices of the minimal representation of these two toric varieties are

$$M_1 = \begin{pmatrix} 1 & 1 & 0 & -1 & -1 \\ 0 & 0 & 1 & 1 & 1 \end{pmatrix}$$

and

$$M_2 = \begin{pmatrix} 1 & 1 & 0 & 0 & -2 \\ 0 & 0 & 1 & 1 & 1 \end{pmatrix}$$

where the first row comes from the induced action of  $T^1$  on the basis  $\mathbb{CP}^1$  and the second from the diagonal action on the fiber. The projections of the coordinate vectors in  $\mathbb{R}^5 = \text{Lie}^*T^5$  on  $\mathbb{R}^2$  and the cone  $K$  in the two cases are as follows:

(Here  $e_1, \dots, e_5$  and  $f_1, f_2$  are the coordinate vectors in  $\mathbb{R}^5$  and  $\mathbb{R}^2$  respectively.), i.e.

Case 1:  $e_1 \mapsto f_1, e_2 \mapsto f_1, e_3 \mapsto f_2, e_4 \mapsto f_1 - f_2, e_5 \mapsto f_1 - f_2,$

Case 2:  $e_1 \mapsto f_1, e_2 \mapsto f_1, e_3 \mapsto f_2, e_4 \mapsto f_1 - 2f_2, e_5 \mapsto f_1 - 2f_2.$

The cone  $K$  is exactly as shown because when we forget the second row of  $M$  this construction must give  $\mathbb{CP}^1$ . One easily computes that  $I_1$  is generated by the equations  $u_1 = u_2 = p_1, u_3 = p_2, u_4 = u_5 = p_2 - p_1$  and  $I_2$  is generated by  $u_1 = u_2 = p_1, u_3 = p_2, u_4 = u_5 = p_2 - 2p_1$ . In both cases  $I_\Sigma$  is generated by  $u_1 u_2$  and  $u_3 u_4 u_5$ . Expressing the  $u$  variables in terms of the  $p$  variables using the above equations and applying the Kirwan's formula we get:

$$H^*(X_1, \mathbb{C}) = \mathbb{C}[p_1, p_2] / (p_1^2, p_2(p_2 - p_1)^2)$$

and

$$H^*(X_2, \mathbb{C}) = \mathbb{C}[p_1, p_2] / (p_1^2, p_2(p_2 - 2p_1)^2).$$

One can prove that  $X_1$  and  $X_2$  are symplectically equivalent but not isomorphic as complex manifolds.