# Image of big Galois representations and modular forms mod *p*

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## 1 Introduction

This will be a talk about modular forms mod *p*, specifically:

- the coefficients,
- Hecke algebra, an attached Galois representation, and the image of the Galois representation.

Fix a prime  $p > 2$  and let F be a finite extension of  $\mathbb{F}_p$ . Let  $N \ge 1$  and  $k \in \mathbb{Z}/(p-1)\mathbb{Z}$ . Let  $M = M_{\Gamma_0(N), k}(\mathbb{F})$  be the space of modular forms with coefficients in  $\mathbb{F}$ , e.g. in the sense of Katz. This is a subspace of F[[*q*]]. Let

$$
\mathcal{M}_0 := \{ f = \sum_n a_n q^n \in \mathcal{M} \colon a_n \neq 0 \implies (n, Np) = 1 \} = \bigcap_{\ell \mid Np} \ker(U_\ell \colon \mathcal{M} \to \mathcal{M}).
$$

**Proposition 1.1.** *For*  $f = \sum a_n q^n \in M_0$ ,

$$
\#\{\ell \le x, a_{\ell} \neq 0\} \sim \delta(f) \frac{x}{\log x}.
$$

*If*  $f \neq 0$  *then*  $\delta(f) > 0$ *.* 

**Corollary 1.2.** *If*  $f = \sum a_n q^n$  and  $g = \sum b_n q^n \in M_0$ , and  $a_\ell = b_\ell$  for almost all  $\ell$ , then  $f = a$  $f = g$ .

This would be trivial if *<sup>f</sup>*, *<sup>g</sup>* were eigenforms, but we want to stay away from that assumption.

We would like to understand how  $\delta(f)$  changes as f varies over the space of modular forms. We will focus on a special class of modular forms.

## 2 Cyclotomic forms

*Definition* 2.1. We say that  $f \in M_0$  is cyclotomic if there exists *q* such that  $a_\ell$  depends only on  $\ell$  mod  $q$ .

It is true but nontrivial that  $T_{\ell} f$  depends on  $\ell$  mod *N*. The converse is immediate, so the two notions are in fact equivalent.

**Fact.** There exists a sequence of cyclotomic forms  $f_n \in M_0$  such that  $\delta(f_n) \to 0$ . So we cannot hope for any uniform control of  $\delta(f)$  if we allow sequences of cyclotomic forms.

*Remark* 2.2*.* The name comes from analogy with *dihedral forms*, which have analogous definition with target being a dihedral group instead.

Let *A* be a closed subalgebra generated by the  $T_\ell$  in End<sub>F</sub>( $\mathcal{M}_0$ ). Then *A* is a semi-local ring. If  $F$  is large enough, then

$$
A = \prod_{\overline{\rho} \in \mathcal{R}} A_{\overline{\rho}}
$$

where each  $A_{\overline{Q}}$  is a local ring and the index set R is a finite set of semi-simple Galois representations  $G_{\mathbb{Q},Np} \to GL_2(\mathbb{F})$ . This induces a decomposition

$$
\mathcal{M}_0 = \bigoplus_{\rho \in R} \mathcal{M}_{\overline{\rho}}
$$

where  $M_{\overline{\rho}} = A_{\overline{\rho}} M_0$  is the set of generalized eigenforms f for the  $T_\ell$  with eigenvalue  $Tr \overline{\rho}(Frob_{\ell}).$ 

We have a pairing

$$
A\times\mathcal{M}_0\to\mathbb{F}
$$

sending  $(t, f) \mapsto a_1(tf)$ , and it is perfect.

We will shortly define a subspace  $M_{\overline{\rho},\text{special}} \subset M_{\overline{\rho}}$ . The punchline is that

**Theorem 2.3.** *For all*  $\overline{\rho}$ *, there exists c* > 0 *such that for all*  $f \in M_{\overline{\rho}}$  –  $M_{\overline{\rho}, special}$ *, we have*  $\delta(f) > c$ .

**Theorem 2.4.**  $M_{\overline{o},\text{special}}$  *is of infinite codimension in*  $M_{\overline{o}}$ *.* 

Classification of  $\overline{\rho}$  according to the projective image. Recall that the projectivization of the image can be

- cyclic,
- dihedral,
- *(exceptional image)*  $A_4$ ,  $S_4$ ,  $A_5$ ,
- *(large image)*  $PGL_2(\mathbb{F}_q)$ ,  $PSL_2(\mathbb{F}_q)$  for  $\mathbb{F}_q \subset \mathbb{F}$ .

The representation  $\bar{\rho}$  is irreducible except in the cyclic case.

**Theorem 2.5.** *If*  $\overline{\rho}$  *has exceptional or large image, then*  $M_{\overline{\rho}, special}$  *is of finite dimension. If*  $\overline{\rho}$  *is reducible and the projectivization of* Im  $\overline{\rho} \neq \mathbb{Z}/2$ *, then*  $M_{\overline{\rho}, special}$  *consists of the cyclotomic forms.*

The goal for the rest of the talk is to explain the definition of a special modular form.

# 3 Pseudorepresentations

Recall that a *pseudorepresentation* of a group *G* on an algebra *A* consists of the data of

- $t: G \rightarrow A$ ,
- $d: G \rightarrow A^*$
- $t(1) = 2$
- $t(xy) = t(yx)$
- *t*(*xy*) + *d*(*y*)*t*(*xy*−<sup>1</sup> ) = *t*(*x*)*t*(*y*).

Proposition 3.1. *There exists a unique pseudo-representation*

$$
t, d \colon G_{\mathbb{Q}, Np} \to A_{\overline{\rho}}
$$

*such that t*(Frob<sub> $\ell$ </sub>) =  $T_{\ell} \in A_{\overline{\rho}}$  *and d* = det  $\overline{\rho}$  *(meaning that d takes image in*  $\mathbb{F} \subset A_{\overline{\rho}}$ *). Moreover, this is a deformation of*  $\overline{\rho}$  *in the sense that* 

$$
t \mod \mathfrak{m}_{A,\overline{\rho}} = \text{Tr}\overline{\rho}
$$
  

$$
d \mod \mathfrak{m}_{A,\overline{\rho}} = \text{det}\overline{\rho}
$$

**Proposition 3.2.**  $A_{\overline{\rho}}$  *is generated as a closed vector space by the T<sub>* $\ell$ *</sub>.* 

This implies the first Proposition I stated that  $\delta(f) > 0$ .

#### 4 Generalized Matrix Algebras (GMA)

Let *B*, *C* be *A*-modules (in this talk they will be finite), with a multiplication

$$
m\colon B\otimes C\to A
$$

satisfying some properties. Then we can form

$$
R = \begin{pmatrix} A & B \\ C & A \end{pmatrix}
$$

and the properties are rigged to make *R* an associative algebra.

We say that *R* is *faithful* if *m* is a perfect pairing. There are maps

$$
Tr: R \to A
$$
  
det:  $R \to A$ 

with the same formulas as usual.

**Theorem 4.1.** *There exists a faithful GMA R and morphism*  $\rho: G_{\mathbb{Q},Np} \to R^*$  *such that*  $\Gamma$ **F**  $\rho = t$  *and det*  $\rho = d$ , *It can be assumed that*  $\partial(G_{\mathbb{Q},N})$  *agregates R as an A module, in* Tr $\rho = t$  and  $\det \rho = d$ . It can be assumed that  $\rho(G_{\mathbb{Q},Np})$  generates R as an A-module, in *which case* (ρ, *<sup>R</sup>*) *is unique.*

## 5 Pink's theory

Let  $\mathcal A$  be a local complete ring with residue field  $\mathbb F$  finite of characteristic  $p > 2$ . Let  $R$  be a GMA; we will be interested in  $R = M_2(A)$  or  $\begin{pmatrix} A & B \\ C & A \end{pmatrix}$  with  $BC \subset \mathfrak{m}_A$ .

*Definition* 5.1. Define  $SR^1 = \{x \in R^*$ , det  $x = 1, x \equiv \text{Id} \mod \mathfrak{m}_R\}$ . This is a pro-*p* group.<br>Define  $\left(\text{rad } R\right)^0 = \left\{y \in \text{rad } R \mid \text{tr}(y) = 0\right\}$ . This is the Lie algebra of  $SR^1$ . Define  $(\text{rad } R)^0 = \{y \in \text{rad } R, \text{tr}(y) = 0\}$ . This is the Lie algebra of  $S R^1$ .

Pink defined a logarithm

$$
\theta\colon SR^1 \to (\operatorname{rad} R)^0
$$

sending  $x \mapsto x - \frac{\text{tr}\rho(x)}{2}$ . This is a homeomorphism with inverse

$$
\theta^{-1}(y) = y + \sqrt{1 + \frac{\text{Tr}(y^2)}{2}} \,\text{Id}\,.
$$

Theorem 5.2. *Let* Γ *be a closed subgroup of S R*<sup>1</sup> *. Let L be the closed additive subgroup of* (rad *R*) <sup>0</sup> *generated by* θ(Γ)*. Then L is a Lie subring of* (rad *<sup>R</sup>*) 0 *. (This means a subgroup stable by Lie bracket.)*

*Proof.* Check that

$$
\theta(x)\theta(y) - \theta(y)\theta(x) = \theta(xy) - \theta(yx).
$$

 $\Box$ 

We have  $\Gamma \subset \theta^{-1}(L)$ , but this is not always an equality.

**Theorem 5.3.** *If*  $L_2 = \overline{[L, L]}$  *and*  $\Gamma_2 = \overline{(\Gamma, \Gamma)}$  *then*  $\Gamma_2 = \theta^{-1}(L_2)$ *.* 

#### 6 Large image

Let  $\overline{\rho}$ :  $G_{\mathbb{Q},Np} \to R^*$  and *G* be the image. Let  $\Gamma = G \cap SR^1$ . We have an exact sequence (using constancy of the determinant) (using constancy of the determinant)

$$
1 \to \Gamma \to G \to \text{Im } \overline{\rho} \to 1.
$$

Let *L* be the assocsiated Pink algebra.

**Theorem 6.1.** *Suppose*  $\overline{\rho}$  *is exceptional or large image. Then there exists a closed subgroup I* of  $A_{\overline{\rho}}$  *with*  $I^2 \subset I$ *, such that*  $\mathbb{F}I = \mathfrak{m}_{A,\overline{\rho}}$  *and* 

$$
\mathbb{F}_{p^2}L = \begin{pmatrix} I & I \\ I & I \end{pmatrix}^0
$$

 $and \Gamma = \theta^{-1}(L)$ .

**Theorem 6.2.** *Suppose*  $\overline{\rho}$  *is reducible,*  $R =$  $\begin{pmatrix} A & B \\ C & A \end{pmatrix}$ . Then there exists a subgroup  $I \subset A$ *with*  $I^3 \subset I$  *and*  $BC \subset I$  *such that* 

$$
\mathbb{F}L = \begin{pmatrix} I & B \\ C & I \end{pmatrix}^0.
$$

We can finally explain what a special form is.

*Definition* 6.3. *f* is *special* if for all  $g \in G$  with  $g^2 = 1$ , *f* is orthogonal to  $Tr(gL_2) \subset A$ .