## 9.5: Homogeneous Linear Systems Tuesday, November 15

## Recap

If an  $n \times n$  matrix **A** has *n* linearly independent eigenvectors  $\mathbf{u}_1, \ldots, \mathbf{u}_n$ , then  $\{e^{\lambda_1 t} \mathbf{u}_1, \ldots, e^{\lambda_n t} \mathbf{u}_n\}$  is a fundamental solution set for the homogeneous system  $\mathbf{x}' = \mathbf{A}\mathbf{x}$ .

## **Practice Problems**

- 1. If  $A = \begin{bmatrix} 1 & 3 \\ 12 & 1 \end{bmatrix}$ , find the general solution to  $\mathbf{x}' = \mathbf{A}\mathbf{x}$ .
- 2. If we make the interpretation  $\mathbf{x} = \begin{bmatrix} x \\ y \end{bmatrix}$ , sketch a direction field for the differential equation.
- 3. If a particle starts at the point (-1,2), sketch the trajectory of the solution. What happens to the particle as  $t \to \infty$ ?
- 4. If a particle starts at (-1, 1, ), sketch the trajectory of the solution. What happens to the particle as  $t \to \infty$ ?
- 5. If you have time/space, do the same with  $\mathbf{A} = \begin{bmatrix} -1 & \frac{3}{4} \\ -5 & 3 \end{bmatrix}$ .

For the first matrix given, the eigenvalues are  $\lambda = -5, 7$  with eigenvectors (1, -2) and (1, 2), representively. If the particle starts on the line y = -2x, it will therefore approach the origin as  $t \to \infty$ . If it begins everywhere else, it will move away from the origin and gradually approach the line y = 2x, the path corresponding to the eigenvector with eigenvalue 7.



## Simple Harmonic Oscillator

Say we have an object with mass m = 1 attached to a spring with stiffness k = 1 in a frictionless system. Then we can derive the system of equations

$$\begin{bmatrix} x(t) \\ v(t) \end{bmatrix}' = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x(t) \\ v(t) \end{bmatrix}$$

- 1. Find the eigenvalues and eigenvectors of A.
- 2. Sketch a direction field for the system of differential equations.
- 3. Find the general solution to the system.
- 4. Find the specific solution given the initial conditions x(0) = 2, v(0) = 0.
- 5. If the object has kinetic energy  $\frac{1}{2}mv^2$  and potential energy  $\frac{1}{2}kx^2$ , show that the total energy of the system is constant. Does this hold in a system with friction? How can you interpret this result geometrically with respect to the direction field?

The specific solution is  $x(t) = 2 \cos t$ ,  $v(t) = -2 \sin t$ . The direction field consists of concentric circles going clockwise around the origin. Since  $\frac{1}{2}mv^2 + \frac{1}{2}kx^2$  is a constant for any starting x(0) and v(0), this system always conserves energy. If there is friction, it does not.