

Math 128a, Chorin, Spring 2013, homework 9, due the week of April 8.

1. Consider the fourth-order Runge-Kutta scheme applied to the differential equation  $y' = y$  with  $y(0) = 1$ . Verify in this special case that the scheme has a truncation error  $O(h^4)$ . (Hint: check first that  $u_{i+1} = u_i e^h + O(h^5)$ ).
2. Consider again the equation  $y' = y, y(0) = 1$ , and the Euler scheme for solving it. In this special case you can solve the equation exactly and can therefore determine the errors exactly. (i) Using the mesh size  $h = 0.2$ , plot the local truncation error and the overall error for  $0 \leq x = ih \leq 1$  as a function of  $i$  (for example for  $i = 1$ , when there is no previous error so that the two errors are equal, they are both equal to  $e^h - (1 + h)$ ). (ii) Repeat this with  $h = 0.1$ , and note that the errors per time step are roughly 4 times smaller but the overall error at  $x = 1$  is only about 1/2 of what it was, and explain why this makes sense.
3. (This problem prepares the way for a computer problem to come). Suppose you want to find the best approximation of a function  $f$  by a polynomial of degree  $\leq n$  on  $[0, 1]$  in the  $\|\cdot\|_2$  norm as follows (in the way you were told is NOT good): Define a function  $G(a_0, a_1, \dots, a_n)$  as follows:

$$G(a_0, \dots, a_n) = \|f - (a_0 + a_1 x + \dots + a_n x^n)\|_2^2,$$

(=the squared distance between  $f$  and a function in the span of the appropriate powers of  $x$ ). To minimize this distance, set up the  $(n + 1)$  equations  $\frac{\partial G}{\partial a_i} = 0$  for  $i = 0, 1, \dots, n$ . Write the resulting linear system in the form  $La = q$ , where  $a$  is the vector whose components are the  $a_i$ ,  $q$  is a known vector, and  $L$  is a matrix. Say clearly what  $L$  and  $q$  are. (In a computer problem to come, I will ask you to actually solve this system).