

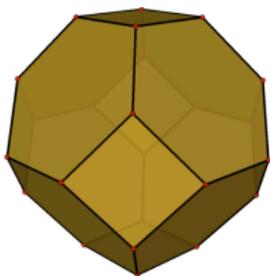
# Orbitopes and Theta bodies

Raman Sanyal (UC Berkeley)

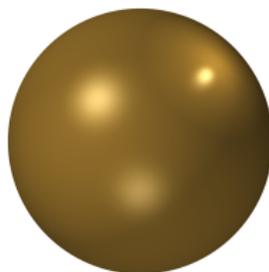
based on joint work with  
Bernd Sturmfels and Frank Sottile  
and ongoing work with  
Philipp Rostalski

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$$\text{conv}(G \cdot v) = \text{conv}\{g \cdot v : g \in G\} \subset V.$$



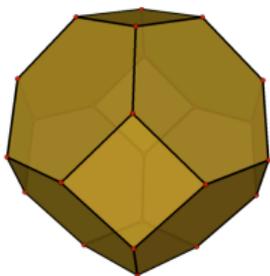
$\mathfrak{S}_n$ -orbitope



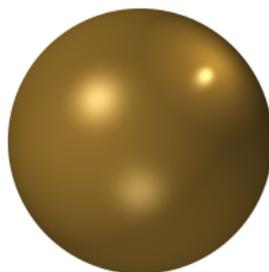
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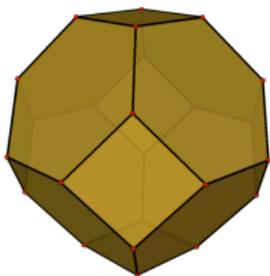
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**here:**  $G$  linear algebraic group,  $V$  rational representation

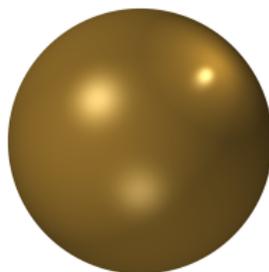
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## Perspectives of **Convex Algebraic Geometry**

**Convex geometry:** faces, face lattices, dual bodies

**Algebraic geometry:** algebraic boundary, its equation, Whitney stratification

**Optimization:** How to optimize over an orbitope?

# Why do we care?

## finite groups

- ▶ classic geometry  
platonic solids, Permutahedra, Birkhoff polytopes, ...
- ▶ combinatorial optimization (see [Onn'93])  
matching polytope, traveling salesman polytope, graph isomorphism, ...

## compact groups

- ▶ protein structure prediction [Longinetti-Sgheri-Sottile'08]  
magnetic susceptibility of folding proteins  $\rightarrow SO(3)$ -orbitopes
- ▶ Calibrated geometries à la [Harvey-Lawson'82]  
'local geometry' of area-minimizing smooth manifolds  
faces of Grassmann orbitopes: convex hull of Grassmann manifold
- ▶ norm balls with transitive  $G$ -action  
balls, ellipses, operator norms, nuclear norms,...
- ▶ non-negative trigonometric polyn. are dual to *Carathéodory* orbitopes
- ▶ non-negative  $k$ -forms are dual to *Veronese* orbitopes

**fascinating objects – plenty in supply!**

# How to compute with orbitopes? How to represent them?

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**Easy**, if orbitope can be represented as **spectrahedron**, i.e. feasible region of semidefinite program:

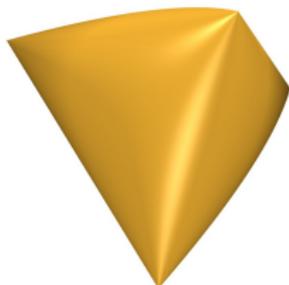
$$S = \{ y : A_0 + y_1 A_1 + \dots + y_d A_d \succeq 0 \} \text{ (positive semidefinite)}$$

$A_0, \dots, A_d$  symmetric  $n \times n$ -matrices.

$S$  is a **polyhedron** if the  $A_i$  are commuting.

**Example:** Set of symmetric matrices  $A$  with eigenvalues at most  $\lambda$

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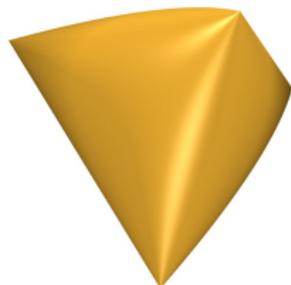
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## Further Benefits

- ▶ information about facial structure; e.g. all faces exposed!
- ▶ readily available presentation for algebraic boundary

**Caveat:** Class of spectrahedra not closed under projection!

**Alternatives:** **spectrahedral shadows** such as **Theta bodies**



## 60 second commercial: Project proposals (with Philipp)

### When is a spectrahedron a polytope?

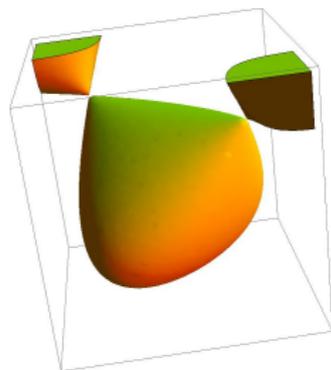
$$S = \{ y : A_0 + y_1 A_1 + \dots + y_d A_d \succeq 0 \}$$

If the  $A_i$  do not commute, it might still be a polytope.

How do you check that **algorithmically**?

How do you prove that **theoretically**?

### Is there such a 3-dim'l spectrahedron?



I.e. smooth boundary except for a single edge?

If **No** then this has interesting consequences for hyperbolic polynomials...

Degtyarev and Itenberg construct interesting/extremal 3-spectrahedra with 10 singular points in the boundary. Maybe degenerations thereof?

Kind of a sub-project to Anand Kulkarni projects regarding the combinatorial types of 3-spectrahedra.

# In this talk

## Tautological orbitopes for $O(n)$ and $SO(n)$

$$\mathcal{O} = \text{conv}\{ \text{(special) orthogonal matrices} \} \subset \mathbb{R}^{n \times n}$$

(Tautological orbitope is convex hull over the representation  $G \subset \text{End}(V)$ )

$\mathcal{O}$  is the norm ball in the operator norm for  $\mathbb{R}^{n \times n}$

## Grassmann orbitopes

$$\mathcal{G}(k, n) = \text{conv}\{ \text{oriented } k\text{-dim subspaces of } \mathbb{R}^n \} \subset \wedge_k \mathbb{R}^n$$

Known as the mass ball in differential geometry

# Tautological orbitope for the orthogonal group

$$\mathcal{O}_n = \text{conv}(O(n)) = \text{conv}\{ g \in \mathbb{R}^{n \times n} : g \cdot g^T = \text{Id} \}$$

- ▶  $\mathcal{O}_n$  convex body of dimension  $n^2$
- ▶ all faces are **exposed** and isomorphic to  $\mathcal{O}_k$  for  $k \leq n$
- ▶ equation **algebraic boundary** is  $f(A) = \det(A \cdot A^T - \text{Id})$
- ▶  $\mathcal{O}_n$  is the spectrahedron

$$A : \begin{pmatrix} \text{Id} & A \\ A^T & \text{Id} \end{pmatrix} \succeq 0$$

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## Key observation

$T^n$  diagonal matrices,  $\text{Pr}_{T^n} : \mathbb{R}^{n \times n} \rightarrow T^n$  orthogonal projection

$$\mathcal{O}_n \cap T^n = \text{Pr}_{T^n}(\mathcal{O}_n) = [-1, +1]^n \text{ (n-cube)}$$

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- ▶  $\mathcal{O}_n$  is the unit ball for the **operator norm** (=max singular value  $\leq 1$ )  
→ projects to unit ball for  $\ell_\infty$ -norm
- ▶ dual body  $\mathcal{O}_n^\circ$  is the unit ball for the **nuclear norm** (=sum of sing. vals  $\leq 1$ )  
→ projects to unit ball for  $\ell_1$ -norm

# Tautological orbitope for the **special** orthogonal group

$$\mathcal{SO}_n = \text{conv}(SO(n)) = \text{conv}\{ g \in \mathbb{R}^{n \times n} : g \cdot g^T = \text{Id}, \det(g) = 1 \}$$

- ▶  $\mathcal{SO}_n$  convex body of dimension  $n^2$ , for  $n \geq 3$
- ▶ faces are linearly isomorphic to  $\mathcal{SO}_k$  for  $k \leq n$  or **free spectrahedra**

$$\mathcal{F}_k = \text{conv}\{uu^T : \|u\| = 1\} = \text{PSD}_k \cap \{ \text{trace} = 1 \} \subset \mathbb{R}^{k \times k}$$

- ▶ equation of the **algebraic boundary** is **not known**
- ▶ is  $\mathcal{SO}_n$  a spectrahedron???

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$n$ -Halfcube

$$H_n = \text{conv}\{x \in \{-1, +1\}^n : \text{even number of } x_i = -1\}$$

for  $n = 1, 2, 3, 4$  the halfcubes are: point, segment, tetrahedron, octahedron

## Grassmann orbitopes

Exterior algebra  $\wedge_k \mathbb{R}^n = \mathbb{R}\{e_J : J \subseteq [n], |J| = k\} \cong \mathbb{R}^{\binom{n}{k}}$

$$\mathbb{R}^{k \times n} \ni (v_1, \dots, v_k) \mapsto v_1 \wedge \dots \wedge v_k = \sum_J p_J e_J$$

$SO(n)$  acts on  $\wedge_k \mathbb{R}^n$  by  $g \cdot v_1 \wedge \dots \wedge v_k = gv_1 \wedge \dots \wedge gv_k$

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Grassmannian of oriented  $k$ -planes

$$G(k, n) := SO(n) \cdot e_1 \wedge e_2 \wedge \dots \wedge e_k$$

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$v_1 \wedge \dots \wedge v_k$  decomposable and  $p = (p_J)_J$  decomposable iff  $p$  satisfies the Plücker relations  $I_{k,n} \subset \mathbb{R}[x_J : |J| = k]$

$$\left\{ \begin{array}{l} L \subset \mathbb{R}^n \\ \text{oriented} \\ k\text{-plane} \end{array} \right\} \xleftrightarrow{1:1} \left\{ \begin{array}{l} v_1 \wedge \dots \wedge v_k \\ \text{decomposable} \\ \text{unit length} \end{array} \right\} \xleftrightarrow{1:1} \left\{ \begin{array}{l} p = (p_J)_J \in \mathbb{R}^{\binom{n}{k}} \\ \text{Plücker relations} \\ \sum_J p_J^2 = 1 \end{array} \right\}$$

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Grassmannian  $G(k, n) = V(I_{k,n}) \cap \{\text{unit sphere}\}$  is a compact real variety

## The Grassmannian $G(2, 4)$ of 2-planes in 4-space

$\wedge_2 \mathbb{R}^4 = \mathbb{R}\{e_i \wedge e_j : 1 \leq i < j \leq 4\} = \mathbb{R}\{p_{12}, p_{13}, p_{14}, p_{23}, p_{24}, p_{34}\}$  6-dim'l vector space

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for  $u, v \in \mathbb{R}^4$

$$u \wedge v = p_{12} e_{12} + \cdots + p_{34} e_{34} \quad \text{with} \quad p_{ij} = \det \begin{pmatrix} u_i & v_i \\ u_j & v_j \end{pmatrix}$$

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Plücker relations + unit sphere determine unit decomposable vectors

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A linear change of coordinates

$$\begin{aligned} u &= \frac{1}{\sqrt{2}}(p_{12} + p_{34}), & v &= \frac{1}{\sqrt{2}}(p_{13} - p_{24}), & w &= \frac{1}{\sqrt{2}}(p_{14} + p_{23}), \\ x &= \frac{1}{\sqrt{2}}(p_{12} - p_{34}), & y &= \frac{1}{\sqrt{2}}(p_{13} + p_{24}), & z &= \frac{1}{\sqrt{2}}(p_{14} - p_{23}). \end{aligned}$$

yields

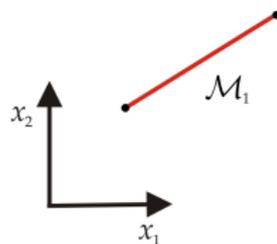
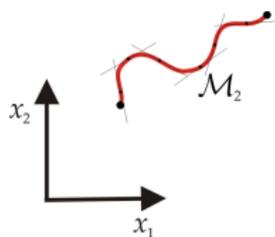
$$\langle u^2 + v^2 + w^2 - \frac{1}{2}, x^2 + y^2 + z^2 - \frac{1}{2} \rangle \subset \mathbb{R}[x, y, z, u, v, w]$$

So,  $G(2, 4) = S^2 \times S^2$  is the Cartesian product of two 2-spheres.

$\mathcal{G}(2, 4) = \text{conv}G(2, 4)$  is the Cartesian product of two 3-balls.

# Area-minimizing manifolds and Grassmann orbitopes

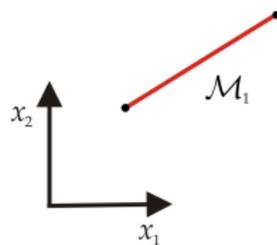
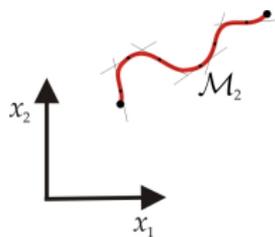
**Audience participation:** Which 1-manifold is area-minimizing?



a smooth  $k$ -dim'l manifold  $M$  is **area-minimizing** if it has the least volume among all manifolds with the same boundary.

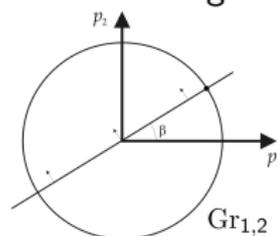
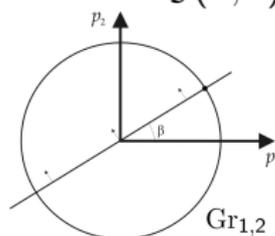
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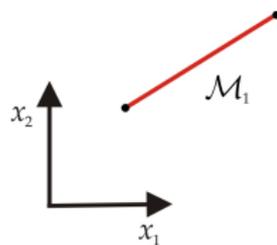
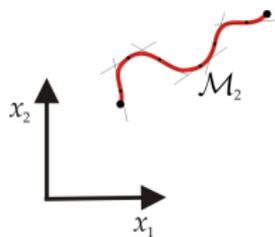
a smooth  $k$ -dim'l manifold  $M$  is **area-minimizing** if it has the least volume among all manifolds with the same boundary.

**Theorem** [Harvey-Lawson'82]. If all tangent  $k$ -planes of  $M \subset \mathbb{R}^n$  lie in a common proper face  $F$  of  $\mathcal{G}(k, n)$ , then  $M$  is area-minimizing.



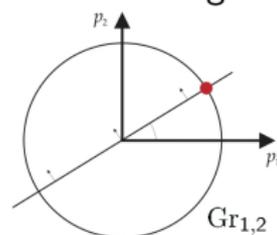
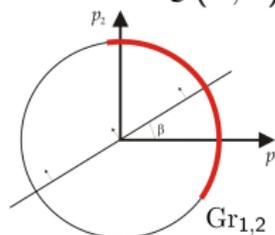
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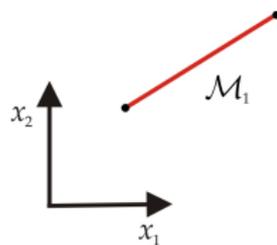
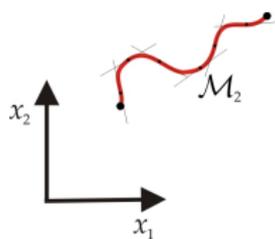
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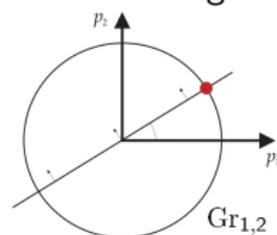
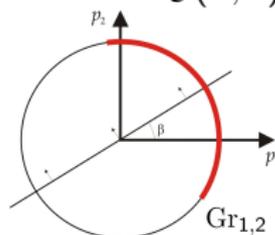
# Area-minimizing manifolds and Grassmann orbitopes

**Audience participation:** Which 1-manifold is area-minimizing?



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The collection of extreme points  $F \cap G(k, n)$  is called a **calibrated geometry**. Elements of the dual face  $F^\diamond$  are **calibrations**.

# What we know about Grassmann orbitopes

$\mathcal{G}(n, k)$  is a convex body of dimension  $\dim \mathcal{G}(k, n) = \binom{n}{k}$

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**What about computer experimentation?**

## Back to the Basic Question

**Basic question:** What is the dimension of a face of  $\mathcal{O}_v$  in direction  $\ell(\mathbf{x})$ ?

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**Rephrased:** What is the affine dimension of set of solutions to the **optimization problem**  $\max \ell(x)$  subject to  $x \in V_{\mathbb{R}}(I)$ ?

- ▶ Polynomial optimization is hard **but** powerful relaxations (SOS, moment) are available [Parrilo, Lasserre, Laurent...]!
- ▶ The geometry behind (particular) relaxations are called **Theta bodies** [Gouveia, Parrilo, Thomas'08].
- ▶ In particular, Theta bodies are **projected spectrahedra**.

**If** the relaxation is exact, then local information about  $\mathcal{O}_v$  are **computable!**

## SOS relaxations and Theta bodies

Sum-of-Squares relaxation of degree  $k$  for  $\ell(\mathbf{x})$  and  $I \subset \mathbb{R}[\mathbf{x}]$

$$\min \delta$$

$$s.t. \delta - \ell(\mathbf{x}) = \sum_{i=1}^m h_i(\mathbf{x})^2 \pmod{I}$$

for  $h_1, \dots, h_m \in \mathbb{R}[\mathbf{x}]$  polynomials of degree  $\leq k$ .  $\delta - \ell(\mathbf{x})$  is called  $k$ -SOS mod  $I$

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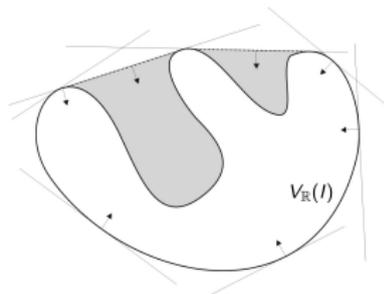
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Chain of convex bodies

$$\text{TH}_1(I) \supseteq \text{TH}_2(I) \supseteq \dots \supseteq \overline{\text{conv } V_{\mathbb{R}}(I)}$$

$I$  is  **$\text{TH}_k$ -exact** if  $\text{TH}_k(I) = \overline{\text{conv } V_{\mathbb{R}}(I)}$

The **Theta rank**  $\text{TH-rank}(I)$  is the least  $k$  for which  $I$  is  $\text{TH}_k$ -exact

## Theta ranks

Let  $V \subset \mathbb{R}^n$  be a **finite set** and  $I = I(V) \subset \mathbb{R}[\mathbf{x}]$  its ideal.

A linear function  $\ell(\mathbf{x})$  has  **$m$ -levels** with respect to  $V$  if  $\ell(\mathbf{x})$  takes  $m$  distinct values on  $V$ .  $V$  is  **$m$ -level** if every facet direction is.

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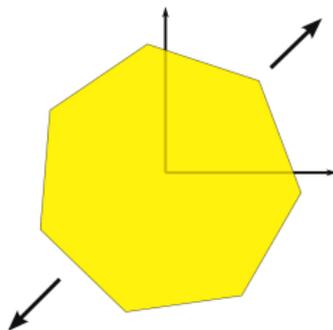
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**Example.** TH-rank of the regular heptagon. For what  $k$  is  $\delta \pm \ell(x)$   $k$ -SOS?



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$V \subset \mathbb{R}^n$  arbitrary real variety with  $I = I(V)$ ,  $\text{TH}_1$ -exact is particularly desirable: geometry determined by **convex quadrics**, projection of spectrahedron of tractable size.

**Theorem.**[Gouveia,Parrilo,Thomas'08] If  $I$  is  $\text{TH}_1$ -exact, then

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A useful tool for bounding Theta rank is

**Lemma.** If  $L \subset \mathbb{R}^n$  is a linear space such that

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- ▶ Theta-rank can be bounded from above by special **cross-sections**
- ▶ Both  $O(n)$  and  $SO(n)$  have such special cross-sections
- ▶  $G(3,6)$  has such a special cross section, the **Segre orbitope**

# Theta ranks for some Orbitopes

## Theta rank for $O(n)$

- ▶ cross-section with diagonal matrices  $L = T^n$

$$\text{conv}(O(n)) \cap L = [-1, +1]^n = \text{conv}\{-1, +1\}^n = \text{conv}(O(n) \cap L)$$

the  $n$ -cube is 2-level  $\rightarrow$  TH-rank( $O(n)$ )  $\geq 2$  (ok, trivial)

- ▶ up to symmetry only one facet direction:  $\ell(X) = X_{11}$

$$1 - X_{11} \equiv \frac{1}{2}(X_{11} - 1)^2 + \frac{1}{2}X_{21}^2 + \cdots + \frac{1}{2}X_{n1}^2 \text{ on } O(n)$$

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**Proposition.** The  $n$ -dim'l halfcube  $H_n$  has Theta rank  $\lceil \frac{n}{2} \rceil$ . In particular,  $H_n$  and  $SO(n)$  have the same Theta rank.

Slightly simpler yoga as in the case for the heptagon...

## Theta rank of Grassmann orbitopes

**Theorem.** The Grassmann orbitopes  $\mathcal{G}(2, n)$  and  $\mathcal{G}(n - 2, n)$  are  $\text{TH}_1$ -exact.

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based on computer experiments we

**Conjecture.** All Grassmann orbitopes  $\mathcal{G}(k, n)$  are  $\text{TH}_1$ -exact.

For  $\mathcal{G}(3, 6)$  there are up to symmetry only finitely many special Lagrangian faces but infinitely many doubletons (edges).

→ show that the family doubleton directions is 1-SOS.

For  $\mathcal{G}(3, 7)$  and  $\mathcal{G}(4, 8)$  we recover 'all' known faces.

Experimentation is fast: For  $\mathcal{G}(3, 9)$  the ideal has  $1050 + 1$  generators on 84 variables. Computations in  $< 10\text{min}$  on laptop

## Conjecture of Harvey-Lawson

In their 1982 paper we found that Harvey and Lawson conjecture that if

$$\lambda - \ell(x) \geq 0 \text{ on } \mathcal{G}(k, n)$$

then there are **linear** polynomials  $h_1(\mathbf{x}), \dots, h_m(\mathbf{x})$  such that

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**Theorem.** H-L conjecture is equivalent to  $G(n, k)$  being TH<sub>1</sub>-exact.

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- ▶ appealing convex, algebraic, and combinatorial properties
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**Theta bodies of Orbitopes**

- ▶  $O(n)$  is  $\text{TH}_1$ -exact,  $SO(n)$  is  $\text{TH}_{\lceil \frac{n}{2} \rceil}$ -exact
- ▶  $\mathcal{G}(2, n)$  and  $\mathcal{G}(n-2, n)$  are  $\text{TH}_1$ -exact
- ▶ **strong** computational evidence that  $\mathcal{G}(3, 6)$  is  $\text{TH}_1$ -exact, but no proof yet...
- ▶ we **conjecture** that all Grassmann orbitopes are  $\text{TH}_1$ -exact
- ▶ Do orbitopes have finite Theta rank? 'small' Theta rank?