

Discussion Week 5: 2/23
MATH 110
GSI: Alex Zorn

- Let V and W be finite-dimensional vector spaces and $T : V \rightarrow W$ be a linear transformation. If $\beta = \{v_1, \dots, v_n\}$ is a basis for V and $\gamma = \{w_1, \dots, w_m\}$ is a basis for W :
 - What is the size of $[T]_\beta^\gamma$?
 - Write a formula for the j th column of $[T]_\beta^\gamma$
- Define the linear transformation $T : P_2(\mathbb{R}) \rightarrow P_2(\mathbb{R})$ by $T(f(x)) = f'(x)$. Let $\beta = \{1 + x, 1 + x^2, x + x^2\}$. Find $[T]_\beta$ and $[T^2]_\beta$.
- Let V, W, Z be vector spaces, and let $T : V \rightarrow W$ and $U : W \rightarrow Z$ be linear.
 - Prove that if UT is one-to-one and T is onto, then U is one-to-one.
 - Prove that if UT is invertible and U is one-to-one, then U and T are invertible.
- If V and W are vector spaces, what does it mean to say V is **isomorphic** to W ? If V and W are finite-dimensional, when are V and W isomorphic?

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Solutions:

1. $[T]_\beta^\gamma$ is $m \times n$. The j th column of $[T]_\beta^\gamma$ is $[T(v_j)]_\gamma$.

2.

$$T(b_1) = T(1 + x) = 1$$

To find the β coordinate vector of 1, we need to solve:

$$1 = a(1 + x) + b(1 + x^2) + c(x + x^2) = (a + b) + (a + c)x + (b + c)x^2$$

This gives the linear system:

$$1 = a + b$$

$$0 = a + c$$

$$0 = b + c$$

Using your favorite method of solving linear systems (row reduction?), $a = \frac{1}{2}$, $b = \frac{1}{2}$, $c = -\frac{1}{2}$. So:

$$[T(b_1)]_\beta = [1]_\beta = \begin{pmatrix} 1/2 \\ 1/2 \\ -1/2 \end{pmatrix}$$

The same method gives:

$$[T(b_2)]_\beta = [2x]_\beta = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}; \quad [T(b_3)]_\beta = [1 + 2x]_\beta = \begin{pmatrix} 3/2 \\ -1/2 \\ 1/2 \end{pmatrix}$$

So:

$$[T]_\beta = \begin{pmatrix} 1/2 & 1 & 3/2 \\ 1/2 & -1 & -1/2 \\ -1/2 & 1 & 1/2 \end{pmatrix}$$

We can find $[T^2]_\beta$ by matrix multiplication: $[T^2]_\beta = ([T]_\beta)^2$. Or we can do the same thing as before: $T^2(b_1) = (1 + x)'' = 0$, $T^2(b_2) = (1 + x^2)'' = 2$, $T^2(b_3) = (x + x^2)'' = 2$. The answer is:

$$[T^2]_\beta = \begin{pmatrix} 0 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & -1 & -1 \end{pmatrix}$$

3.

(a) Let $\vec{x} \in N(U)$.

Then $U(\vec{x}) = \vec{0}_Z$.

Since T is onto, there exists $\vec{y} \in V$ such that $T(\vec{y}) = \vec{x}$.

Then $UT(\vec{y}) = U(T(\vec{y})) = U(\vec{x}) = \vec{0}_Z$.

Since UT is one-to-one, $\vec{y} = \vec{0}_V$.

So $\vec{x} = T(\vec{0}_V) = \vec{0}_W$.

Therefore, $N(U) = \{\vec{0}_W\}$, so U is one-to-one.

(b) We need to show:

U is one-to-one. This is given.

U is onto:

Let $\vec{z} \in Z$.

Since UT is onto, there exists $\vec{x} \in V$ such that $UT(\vec{x}) = \vec{z}$.

Let $\vec{y} = T(\vec{x})$. Then $U(\vec{y}) = U(T(\vec{x})) = UT(\vec{x}) = \vec{z}$.

So $\vec{z} \in R(T)$.

Therefore, $R(T) = Z$, so U is onto.

T is one-to-one.

Let $\vec{x} \in N(T)$.

Then $T(\vec{x}) = \vec{0}_W$.

Then $UT(\vec{x}) = U(T(\vec{x})) = U(\vec{0}_W) = \vec{0}_Z$.

Since UT is one-to-one, $\vec{x} = \vec{0}_V$.

Therefore, $N(T) = \{\vec{0}_V\}$, so T is one-to-one.

T is onto.

Let $\vec{y} \in W$.

Let $\vec{z} = U(\vec{y})$.

Since UT is onto, there exists $\vec{x} \in V$ such that $UT(\vec{x}) = \vec{z}$.

Then $U(\vec{y}) = U(T(\vec{x})) = \vec{z}$.

Since U is one-to-one, $\vec{y} = T(\vec{x})$, so $\vec{y} \in R(T)$.

Therefore, $R(T) = W$, so T is onto.

4. V and W are isomorphic if there exists an isomorphism $T : V \rightarrow W$. If V and W are finite-dimensional, V and W are isomorphic if and only if $\dim(V) = \dim(W)$.