15.9 Change of Variables in Multiple Integrals

Once again, we start with the single variable integral. Recall that we may write

$$\int_{a}^{b} f(x) \, dx = \int_{c}^{d} f(x(t))x'(t) \, dt = \int_{c}^{d} f(x(t)) \, \frac{dx}{dt} \, dt \tag{1}$$

where x(t) is a function of t, a = x(c), and b = x(d).

Now let's consider functions of two variables. We have already done change of variables when we integrated a function in Cartesian and in polar coordinates.

$$\iint_{R} f(x,y) \ dA = \iint_{S} f(r\cos\theta, r\sin\theta)r \ dr \ d\theta$$

where S is the region in the $r\theta$ -plane that corresponds to the region R in the xy-plane.

The polar-Cartesian change of variables is a special case of the more general transformation T, from the uv-plane to the xy-plane. A transformation is a function that maps a region S in uv-plane to the region R in the xy-plane. Thus R is the image of S under T. We say the image of (u, v) under T is (x, y) = T(u, v). If T is one-to-one, then T has an inverse map T^{-1} that maps (x, y) to (u, v), that is $T^{-1}(x, y) = (u, v)$. We also assume that T is a C^1 transformation, which means that the functions x(u, v) and y(u, v) have continuous first-order partial derivatives.

Consider a small rectangular region S in the uv-plane with lower-right corner (u_0, v_0) and the sides of lengths Δu and Δv . The position vector of the image of the point (u, v) is $\vec{r}(u, v) = x(u, v)\hat{i} + y(u, v)\hat{j}$. The image of the lower side of S, which is

$$u_0 \le u \le u_0 + \Delta u, v = v_0$$

is $\vec{r}(u, v_0)$. The tangent vector at $(x_0, y_0) = T(u_0, v_0)$ to this image curve is

$$\vec{r}_u = \frac{\partial x}{\partial u}\hat{\imath} + \frac{\partial y}{\partial u}\hat{\jmath}.$$

Similarly, the tangent vector at (x_0, y_0) to the image curve of the left side of S,

$$u = u_0, v_0, \le v \le v_0 + \Delta v$$

is

$$\vec{r}_v = \frac{\partial x}{\partial v}\hat{\imath} + \frac{\partial y}{\partial v}\hat{\jmath}$$

When S is small, the region R is also small and we may say R is approximately a parallelogram determined by the vectors

$$\vec{r}(u_0 + \Delta u, v_0) - \vec{r}(u_0, v_0)$$

and

$$\vec{r}(u_0, v_0 + \Delta v) - \vec{r}(u_0, v_0).$$

We know

$$\vec{r}_u = \lim_{\Delta u \to 0} \frac{\vec{r}(u_0 + \Delta u, v_0) - \vec{r}(u_0, v_0)}{\Delta u}$$

Therefore

$$\vec{r}(u_0 + \Delta u, v_0) - \vec{r}(u_0, v_0) \approx \Delta u \vec{r}_u.$$

Similarly,

$$\vec{r}(u_0, v_0 + \Delta v) - \vec{r}(u_0, v_0) \approx \Delta v \vec{r_v}$$

So we are saying that R is approximately a parallelogram with sides $\Delta u \vec{r}_u$ and $\Delta v \vec{r}_v$. The area of R is thus approximately the area of this parallelogram, which is the size of the cross product of the vectors of its sides:

$$|(\Delta u \vec{r}_u) \times (\Delta v \vec{r}_v)| = |\vec{r}_u \times \vec{r}_v| \Delta u \Delta v.$$
⁽²⁾

The cross product is

$$\vec{r}_{u} \times \vec{r}_{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & 0 \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & 0 \end{vmatrix} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} \end{vmatrix} \hat{k} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} \hat{k}$$
(3)

The determinant in Equation (3) is called the Jacobian of the transformation and has a special notation.

Definition 1. The Jacobian of the transformation T given by x(u, v) and y(u, v) is

$$\frac{\partial(x,y)}{\partial(u,v)} = \left| \begin{array}{c} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{array} \right| = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u}$$

Thus the area of R is approximately

$$\Delta A \approx \left| \frac{\partial(x, y)}{\partial(u, v)} \right| \Delta u \Delta v \tag{4}$$

where we evaluate the Jacobian at (u_0, v_0) .

Now we may divide every region S in uv-plane into small rectangles whose images in xy-plane are small parallelograms. We may write

$$\iint_{R} f(x,y) \ dA \approx \sum_{i=1}^{m} \sum_{j=1}^{n} f(x_{i}, y_{j}) \Delta A$$
$$\approx \sum_{i=1}^{m} \sum_{j=1}^{n} f(x(u_{i}, v_{i}), y(u_{j}, v_{j})) \Delta A \approx \left| \frac{\partial(x, y)}{\partial(u, v)} \right| \Delta u \Delta v$$

Thus we have the following theorem.

Theorem 1 (Change of Variables in a Double Integral). Suppose that T is a C^1 transformation whose Jacobian is nonzero and that T maps a region S in the uv-plane onto a region R in the xy-plane. Suppose that f is continuous on R and that R and S are type I or type II plane regions. Suppose also that T is one-to-one, except perhaps on the boundary of S. Then

$$\iint_{R} f(x,y) \ dA = \iint_{S} f(x(u,v), y(u,v)) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| \ du \ dv.$$

The above theorem says that we change from an integral in x and y to an integral in u and v by expressing x and y in terms of u and v and writing

$$dA = \left| \frac{\partial(x,y)}{\partial(u,v)} \right| \, du \, dv.$$

Notice the similarity between this theorem and the one-dimensional formula in Equation (1).

Example 1. Show the formula for integration in polar coordinates using the Jacobian.

Proof. We have

$$x = r\cos\theta$$
 and $y = r\sin\theta$.

Then the Jacobian of T is

$$\frac{\partial(x,y)}{\partial(r,\theta)} = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos\theta & -r\sin\theta \\ \sin\theta & r\cos\theta \end{vmatrix} = r\cos^2\theta + r\sin^2\theta = r.$$

Thus the theorem gives

$$\iint_{R} f(x,y) \, dx \, dy = \iint_{S} f(r\cos\theta, r\sin\theta) \left| \frac{\partial(x,y)}{\partial(r,\theta)} \right| \, dr \, d\theta$$
$$= \int_{\alpha}^{\beta} \int_{a}^{b} f(r\cos\theta, r\sin\theta) r \, dr \, d\theta,$$

which the same formula that we had before.

Example 2. Evaluate the integral

$$\iint_R (4x + 8y) \ dA$$

where R is the parallelogram with vertices (-1,3), (1,-3), (3,-1), (1,5) and $x = \frac{1}{4}(u+v), y = \frac{1}{4}(v-3u)$. Example 3. Evaluate the integral by making an appropriate change of variables.

$$\iint\limits_R \sin(9x^2 + 4y^2) \ dA$$

where R is the region in the first quadrant bounded by the ellipse $9x^2 + 4y^2 = 1$.

Next time we will see triple integrals. For now, just note that the Jacobian for a transformation T that maps a region S in uvw-space onto a region R in xyz-space is a 3×3 determinant:

$$\frac{\partial(x,y,z)}{\partial(u,v,w)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix}.$$