

Vectors and Uniqueness of Linear System Solutions

Q, If $A\underline{x} = \underline{b}$ admits a solution what properties of A determine if the solution is unique?

Related Problem: Homogeneous Linear System: $A\underline{x} = \underline{0}$

$$A\underline{x} = \underline{0} \Leftrightarrow x_1 \underline{a}_1 + x_2 \underline{a}_2 + \dots + x_n \underline{a}_n = \underline{0}$$

Observe $\underline{x} = \underline{0}$ is always a solution.

Definition Let $\underline{v}_1, \underline{v}_2, \dots, \underline{v}_k$ be vectors in \mathbb{R}^m .

We say $\{\underline{v}_1, \dots, \underline{v}_k\}$ is linearly independent if

$$\lambda_1 \underline{v}_1 + \lambda_2 \underline{v}_2 + \dots + \lambda_k \underline{v}_k = \underline{0} \Rightarrow \lambda_1 = \lambda_2 = \dots = \lambda_k = 0$$

If not we say $\{\underline{v}_1, \underline{v}_2, \dots, \underline{v}_k\}$ is linearly dependent.

Remark

$\{\underline{v}_1, \underline{v}_2, \dots, \underline{v}_k\}$ linearly dependent \Leftrightarrow There exist $\lambda_1, \dots, \lambda_k$ not all zero such that $\lambda_1 \underline{v}_1 + \dots + \lambda_k \underline{v}_k = \underline{0}$

$$\text{E.g. If } \lambda_1 \neq 0 \Rightarrow \underline{v}_1 + \frac{\lambda_2}{\lambda_1} \underline{v}_2 + \dots + \frac{\lambda_k}{\lambda_1} \underline{v}_k = \underline{0}$$

$$\Rightarrow \underline{v}_1 = \left(-\frac{\lambda_2}{\lambda_1} \right) \underline{v}_2 + \dots + \left(-\frac{\lambda_k}{\lambda_1} \right) \underline{v}_k$$

$$\Rightarrow \underline{v}_1 \text{ is in Span } (\underline{v}_2, \underline{v}_3, \dots, \underline{v}_k)$$

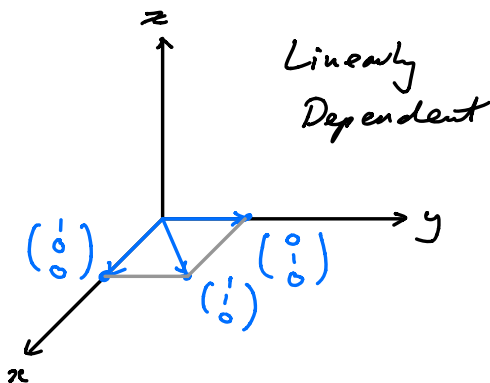
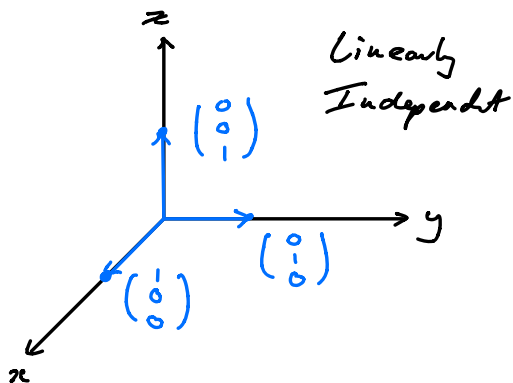
Example $10 \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} - 5 \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix} + 5 \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$

$\Rightarrow \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$ in $\text{Span} \left(\begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} \right)$

Intuition: $\{ \underline{v}_1, \underline{v}_2, \dots, \underline{v}_k \}$ Linearly independent
 $\Leftrightarrow \underline{v}_1, \underline{v}_2, \dots, \underline{v}_k$ are in completely independent directions.

E.g. $\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$ Linearly independent

$\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \right\}$ Linearly dependent



Conclusion

$A\underline{x} = \underline{0}$

has unique solution

(ie $\underline{x} = \underline{0}$)



Reduced $(A|\underline{0})$ has

no free columns



Columns of A are Linearly independent

Nice consequence: $\underline{a}_1, \underline{a}_2, \dots, \underline{a}_n$ vectors in \mathbb{R}^m ($A = (\underline{a}_1 \dots \underline{a}_n)$)

$m < n \Rightarrow$ Reduced $(A | \underline{0})$ has free columns $\Rightarrow \{\underline{a}_1, \underline{a}_2, \dots, \underline{a}_n\}$ Linearly dependent

Makes sense: In \mathbb{R}^n there can't be more than n independent directions intuitively.

Examples: There are not 3 independent directions in \mathbb{R}^2 .

Back to non-homogeneous case: $A\underline{x} = \underline{b}$

$\underline{v}_p =$ particular solution to $A\underline{x} = \underline{b}$ (ie $A\underline{v}_p = \underline{b}$)

\leftarrow solution to homogeneous system

$$A\underline{v} = \underline{b} \Rightarrow A(\underline{v} - \underline{v}_p) = A\underline{v} - A\underline{v}_p = \underline{b} - \underline{b} = \underline{0}$$

\Rightarrow General Solution to $A\underline{x} = \underline{b}$ is

$\underline{v}_p + \underline{v}_h$, where $\underline{v}_h =$ general solution to $A\underline{x} = \underline{0}$

Conclusion

$A\underline{x} = \underline{b}$ has unique solution

$\Leftrightarrow \underline{b}$ in $\text{Span}(\underline{a}_1, \dots, \underline{a}_n)$

and

Last column of reduced $(A | \underline{b})$ not a pivot and

No free columns

Columns of A Linearly independent

Example

$$\begin{pmatrix} 1 & 3 & 5 & | & 1 \\ 0 & -2 & 2 & | & 1 \end{pmatrix} \Rightarrow \begin{aligned} x_1 + 3x_2 + 5x_3 &= 1 \\ -2x_2 + 2x_3 &= 1 \end{aligned}$$

↑
free (\Rightarrow columns of A linearly dependent)

$$\Rightarrow x_2 = x_3 - \frac{1}{2}$$

$$x_1 = \frac{5}{2} - 8x_3$$

$$\Rightarrow \text{General Solution to } A\underline{x} = \underline{b} = \begin{pmatrix} \frac{5}{2} - 8x_3 \\ x_3 - \frac{1}{2} \\ x_3 \end{pmatrix} = \begin{pmatrix} \frac{5}{2} \\ -\frac{1}{2} \\ 0 \end{pmatrix} + x_3 \begin{pmatrix} -8 \\ 1 \\ 1 \end{pmatrix}$$

Overview ($A = (\underline{a}_1 \underline{a}_2 \dots \underline{a}_n)$)

$A\underline{x} = \underline{b}$ has no solutions $\Leftrightarrow \underline{b}$ not in $\text{Span}(\underline{a}_1, \dots, \underline{a}_n)$

$A\underline{x} = \underline{b}$ admits unique solution $\Leftrightarrow \underline{b}$ in $\text{Span}(\underline{a}_1, \dots, \underline{a}_n)$ and $\{\underline{a}_1, \dots, \underline{a}_n\}$ linearly independent.

$A\underline{x} = \underline{b}$ admits infinitely many solutions $\Leftrightarrow \underline{b}$ in $\text{Span}(\underline{a}_1, \dots, \underline{a}_n)$ and $\{\underline{a}_1, \dots, \underline{a}_n\}$ linearly dependent.