

Spanning, Linear Independence and Dimension

V - vector space (e.g. \mathbb{R}^n , $C(\mathbb{R})$, $P_n(\mathbb{R})$)

$\{\underline{v}_1, \dots, \underline{v}_p\} \subset V$

$$\lambda_1 \underline{v}_1 + \lambda_2 \underline{v}_2 + \dots + \lambda_p \underline{v}_p = \text{Linear combination of } \{\underline{v}_1, \dots, \underline{v}_p\}$$

In \mathbb{R} Just a vector in V

Definition

$\text{Span}(\underline{v}_1, \dots, \underline{v}_p) = \text{Subset of all linear combinations of } \{\underline{v}_1, \dots, \underline{v}_p\}$.

E.g. $\text{Span}(\sin(x), \cos(x)) = \{\lambda_1 \sin(x) + \lambda_2 \cos(x)\} \subset C(\mathbb{R})$

We say $\{\underline{v}_1, \dots, \underline{v}_p\}$ is a Spanning set at V if

$$\text{Span}(\underline{v}_1, \dots, \underline{v}_p) = V.$$

E.g. $\{\underline{e}_1, \dots, \underline{e}_n\} \subset \mathbb{R}^n$, $\{1, x, x^2, \dots, x^n\} \subset P_n(\mathbb{R})$

Fact: $\text{Span}(\underline{v}_1, \dots, \underline{v}_p) \subset V$ is a subspace.

Definition We say V is finite dimensional if there exists a finite spanning set. If not, we say V is infinite dimensional.

E.g. \mathbb{R}^n , $P_n(\mathbb{R})$ are finite dimensional

$C(\mathbb{R})$, $P(\mathbb{R})$ are infinite dimensional.

Q: If V is finite dimensional what is its dimension?

Definition

(L.I.)

$\{\underline{v}_1, \dots, \underline{v}_p\} \subset V$ is linearly independent \Leftrightarrow

$$\lambda_1 \underline{v}_1 + \dots + \lambda_p \underline{v}_p = \underline{0} \Rightarrow \lambda_1 = \lambda_2 = \dots = \lambda_p = 0$$

(L.D.)

$\{\underline{v}_1, \dots, \underline{v}_p\} \subset V$ linearly dependent \Leftrightarrow

There exist $\lambda_1, \dots, \lambda_p$ not all zero such that $\lambda_1 \underline{v}_1 + \dots + \lambda_p \underline{v}_p = \underline{0}$

Example $\{\sin(x), \cos(x)\} \subset C(\mathbb{R})$ L.I.?

Assume $\lambda_1 \sin(x) + \lambda_2 \cos(x) = 0$ equality of functions (true for all x)
zero function

$$\Rightarrow \lambda_1 \tan(x) + \lambda_2 = 0 \quad \text{constant}$$

If $\lambda_1 \neq 0$ then $\tan(x) = \frac{-\lambda_2}{\lambda_1}$ for all x . Contradiction.

$$\Rightarrow \lambda_1 = 0 \Rightarrow \lambda_2 = 0 \Rightarrow \{\sin(x), \cos(x)\} \subset C(\mathbb{R}) \text{ L.I.}$$

Fact : $\{\underline{v}_1, \dots, \underline{v}_p\}$ L.D.

$$\Leftrightarrow \underline{v}_j \text{ in } \text{Span}(\underline{v}_1, \dots, \underline{v}_{j-1}, \underline{v}_{j+1}, \dots, \underline{v}_p)$$

for some j

$$\Leftrightarrow \text{Span}(\underline{v}_1, \dots, \underline{v}_{j-1}, \underline{v}_{j+1}, \dots, \underline{v}_p) = \text{Span}(\underline{v}_1, \dots, \underline{v}_p)$$

E.g. $\text{Span}\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \end{pmatrix}\right) = \text{Span}\left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix}\right)$ in span of others

Fundamental Definition Let V be a finite dimensional vector space. A basis for V is a subset $\{\underline{v}_1, \dots, \underline{v}_p\}$ such that

$$\forall \text{Span}(\underline{v}_1, \dots, \underline{v}_p) = V$$

$$\exists \{\underline{v}_1, \dots, \underline{v}_p\} \text{ L.I.}$$

Example Called the standard basis of \mathbb{R}^n

$\{\underline{e}_1, \dots, \underline{e}_n\}$ in \mathbb{R}^n , $\{1, x, x^2, \dots, x^n\}$ in $P_n(\mathbb{R})$

$\{\sin(x), \cos(x)\}$ in $V = \{\text{solutions to } y'' + y = 0\}$

Remark Bases are not unique. For example

$\left\{\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}\right\}$ and $\left\{\begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix}\right\}$ are both bases for \mathbb{R}^2 .

Important Facts (V a finite dimensional vector space)

A/ If $\{v_1, \dots, v_p\}$ is spanning set of V then it contains a basis

E.g. $\{(1), (3), (0)\}$ contains basis $\{(1), (0)\} \neq \mathbb{R}^2$

B/ If $\{v_1, \dots, v_p\}$ is L.I. then it can be extended to a
basis. in many ways

E.g. $\left\{\begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}\right\}$ L.I. in \mathbb{R}^3 . $\left\{\begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}\right\}$ basis of \mathbb{R}^3

C/ If $\{v_1, \dots, v_p\}$ is L.I. and $\{u_1, \dots, u_k\}$ is spanning
 $\Rightarrow p \leq k$ (Linearly independent sets are smaller than or equal to spanning sets)

Theorem Any finite dimensional vector space has a basis.

Proof Choose $\{v_1, \dots, v_p\}$ a spanning set of V . By A/
it contains a basis

□

Theorem Let V be a finite dimensional vector space. Any
two bases have same size.

Proof Let $\{v_1, \dots, v_p\}$ and $\{u_1, \dots, u_k\}$ be basis for V
 $\{v_1, \dots, v_p\}$ is L.I. and $\{u_1, \dots, u_k\}$ is spanning $\Rightarrow p \leq k$
 $\{u_1, \dots, u_k\}$ is L.I. and $\{v_1, \dots, v_p\}$ is spanning $\Rightarrow k \leq p$
 $\Rightarrow p = k$

□

Definition Let V be a finite dimensional vector space. The
dimension of V , denoted $\dim(V)$, is the size of a basis.

Examples $\dim(\mathbb{R}^n) = n$ ← Thank goodness!, $\dim(\mathbb{P}_n(\mathbb{R})) = n+1$

V = plane in \mathbb{R}^3 containing $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$

$\Rightarrow V = \text{Span}(\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}), \{\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}\} \subset \text{I}$

$\Rightarrow \{\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}\}$ basis for $V \Rightarrow \dim(V) = 2$

Important Intuition (V finite dimensional)

$\{\underline{v}_1, \dots, \underline{v}_p\} \subset \text{I} : B_{\underline{v}} \Rightarrow p \leq \dim(V)$

$\{\underline{v}_1, \dots, \underline{v}_p\}$ spanning : $A_{\underline{v}}$, $\Rightarrow p \geq \dim(V)$

$p = \dim(V)$ then $(\underline{v}_1, \dots, \underline{v}_p) \subset \text{I} \Leftrightarrow \{\underline{v}_1, \dots, \underline{v}_p\}$ spanning

Conclusion :

Basis = Minimal Spanning Set = Maximal L.I. Set

Familiar Example

$\{\underline{a}_1, \dots, \underline{a}_n\}$ in \mathbb{R}^n , L.I. \Leftrightarrow Reduced $A = (\underline{a}_1 \dots \underline{a}_n)$ has pivot in every column

\Leftrightarrow Reduced $A = (\underline{a}_1 \dots \underline{a}_n)$ has pivot in every row

$\Leftrightarrow \text{Span}(\underline{a}_1, \dots, \underline{a}_n) = \mathbb{R}^n$

Theorem Let V be a finite dimensional vector space, with $U \subset V$ a subspace. Then U is also finite dimensional and $\dim(U) \leq \dim(V)$ with equality $\Leftrightarrow U = V$.