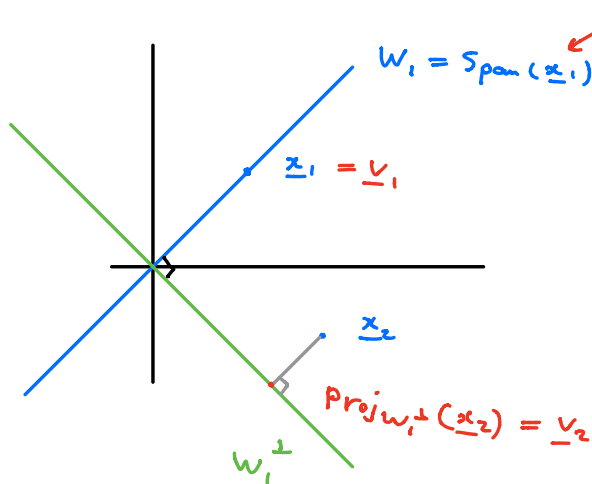


The Gram-Schmidt Process

Aim : Given $W \subset \mathbb{R}^n$ a subspace find $\{\underline{v}_1, \dots, \underline{v}_p\}$ an orthogonal basis.

Gram-Schmidt Process : Algorithm to construct $\{\underline{v}_1, \dots, \underline{v}_p\}$ starting from a basis $\{\underline{x}_1, \dots, \underline{x}_p\} \subset W$.

Example $W = \mathbb{R}^2$, $W = \text{Span} \left(\begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ -1 \end{pmatrix} \right)$



Set

$$\underline{v}_1 = \underline{x}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\underline{v}_2 = \text{Proj}_{W_1^\perp}(\underline{x}_2)$$

$$= \underline{x}_2 - \text{Proj}_{W_1}(\underline{x}_2)$$

$$= \underline{x}_2 - \frac{\underline{x}_2 \cdot \underline{v}_1}{\underline{v}_1 \cdot \underline{v}_1} \underline{v}_1$$

$$= \begin{pmatrix} 2 \\ -1 \end{pmatrix} - \frac{\begin{pmatrix} 2 \\ -1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix}}{\begin{pmatrix} 1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} 2 \\ -1 \end{pmatrix} - \begin{pmatrix} 1/2 \\ 1/2 \end{pmatrix} = \begin{pmatrix} 3/2 \\ -3/2 \end{pmatrix}$$

Observe

$$\text{Span}(\underline{x}_1) = \text{Span}(\underline{v}_1) \quad \text{and}$$

$$\text{Span}(\underline{x}_1, \underline{x}_2) = \text{Span}(\underline{v}_1, \underline{v}_2) = W$$

General Procedure: Build $\{\underline{v}_1, \dots, \underline{v}_p\}$ starting from $\{\underline{x}_1, \dots, \underline{x}_p\}$

Starting from $\underline{v}_1 = \underline{x}_1$ construct \underline{v}_k using $\underline{v}_1, \dots, \underline{v}_{k-1}$ and \underline{x}_k as follows:

1) Let $W_{k-1} = \text{Span}(\underline{v}_1, \dots, \underline{v}_{k-1})$

orthogonal basis of W_k

$$\underline{v}_k = \text{Proj}_{W_{k-1}^\perp}(\underline{x}_k) = \underline{x}_k - \text{Proj}_{W_{k-1}}(\underline{x}_k)$$

$$= \underline{x}_k - \frac{\underline{x}_k \cdot \underline{v}_1}{\underline{v}_1 \cdot \underline{v}_1} \underline{v}_1 - \dots - \frac{\underline{x}_k \cdot \underline{v}_{k-1}}{\underline{v}_{k-1} \cdot \underline{v}_{k-1}} \underline{v}_{k-1}$$

Very Explicitly :

$$\underline{v}_1 = \underline{x}_1$$

$$\underline{v}_2 = \underline{x}_2 - \frac{\underline{x}_2 \cdot \underline{v}_1}{\underline{v}_1 \cdot \underline{v}_1} \underline{v}_1$$

$$\underline{v}_3 = \underline{x}_3 - \frac{\underline{x}_3 \cdot \underline{v}_1}{\underline{v}_1 \cdot \underline{v}_1} \underline{v}_1 - \frac{\underline{x}_3 \cdot \underline{v}_2}{\underline{v}_2 \cdot \underline{v}_2} \underline{v}_2$$

⋮

$$\underline{v}_p = \underline{x}_p - \frac{\underline{x}_p \cdot \underline{v}_1}{\underline{v}_1 \cdot \underline{v}_1} \underline{v}_1 - \dots - \frac{\underline{x}_p \cdot \underline{v}_{p-1}}{\underline{v}_{p-1} \cdot \underline{v}_{p-1}} \underline{v}_{p-1}$$

Facts

1/ $\{\underline{u}_1, \dots, \underline{u}_p\}$ a basis for W

$\Rightarrow \{\underline{v}_1, \dots, \underline{v}_p\}$ an orthogonal basis for W

2/ $\text{Span}(\underline{u}_1, \dots, \underline{u}_k) = \text{Span}(\underline{v}_1, \dots, \underline{v}_k)$ for all $k \leq p$

3/ To apply Gram-Schmidt Process we must start with a linearly independent set. If \underline{x}_k in $\text{span}(\underline{x}_1, \dots, \underline{x}_{k-1})$

$\Rightarrow \underline{x}_k$ in $\text{Span}(\underline{v}_1, \dots, \underline{v}_{k-1}) \Rightarrow \underline{v}_k = 0 \Rightarrow$ Cannot proceed further.

Theorem Any subspace $W \subset \mathbb{R}^n$ has an orthogonal basis.

Proof Choose a basis $\{\underline{x}_1, \dots, \underline{x}_p\}$ for W . Apply the Gram-Schmidt process to get $\{\underline{u}_1, \dots, \underline{u}_p\}$ an orthogonal basis for W . □

Remark Once we have $\{\underline{v}_1, \dots, \underline{v}_p\}$ we can always scale to get an orthonormal basis $\{\underline{u}_1, \dots, \underline{u}_p\}$ for W .

Interesting consequence of Gram-Schmidt: QR-factorization

$$A = \underbrace{(\underline{x}_1 \dots \underline{x}_p)}_{\text{L.I.}} \xrightarrow{\text{G.S.}} Q = \underbrace{(\underline{u}_1 \dots \underline{u}_p)}_{\text{orthonormal set}}$$

\swarrow $n \times p$ matrix
 \swarrow $n \times p$ matrix

Observe $\text{Span}(\underline{x}_1, \dots, \underline{x}_k) = \text{Span}(\underline{u}_1, \dots, \underline{u}_k)$ for $k \leq p$

$$\Rightarrow \underline{x}_k = \lambda_{1k} \underline{u}_1 + \lambda_{2k} \underline{u}_2 + \dots + \lambda_{kk} \underline{u}_k + 0 \cdot \underline{u}_{k+1} + \dots + 0 \cdot \underline{u}_p$$

Define $R = \begin{pmatrix} \lambda_{11} & \lambda_{12} & & \lambda_{1p} \\ 0 & \lambda_{22} & & \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & & \lambda_{pp} \end{pmatrix}$ \swarrow $p \times p$ upper triangular matrix

\underline{r}_1
 \underline{r}_2
 \underline{r}_p

Observe $Q \underline{r}_k = \lambda_{1k} \underline{u}_1 + \lambda_{2k} \underline{u}_2 + \dots + \lambda_{kk} \underline{u}_k + 0 \cdot \underline{u}_{k+1} + \dots + 0 \cdot \underline{u}_p = \underline{x}_k$

$$\Rightarrow QR = (Q \underline{r}_1 \quad Q \underline{r}_2 \quad \dots \quad Q \underline{r}_p) = A$$

Remark Columns of Q are orthonormal set $\Rightarrow Q^T Q = I_p$

$$QR = A \Rightarrow Q^T QR = Q^T A \Rightarrow R = Q^T A$$

Conclusion Given A an $n \times p$ matrix with L.I. columns there exists Q , an $n \times p$ matrix, with orthonormal columns, and R , a $p \times p$, upper triangular matrix such that

$$A = QR \quad (\Rightarrow R = Q^T A)$$

Example

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \\ 0 & 0 & 4 \end{pmatrix}$$

\underline{x}_1
 \underline{x}_2
 \underline{x}_3

$$\underline{v}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \quad \underline{v}_2 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} - \frac{\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}}{\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$$

$$\underline{v}_3 = \begin{pmatrix} 1 \\ 0 \\ 3 \\ 4 \end{pmatrix} - \frac{\begin{pmatrix} 1 \\ 0 \\ 3 \\ 4 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}}{\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} - \frac{\begin{pmatrix} 1 \\ 0 \\ 3 \\ 4 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}}{\begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}} \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 3 \\ 4 \end{pmatrix} - \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 3 \\ 4 \end{pmatrix}$$

$$\underline{u}_1 = \underline{v}_1, \quad \underline{u}_2 = \underline{v}_2, \quad \underline{u}_3 = \begin{pmatrix} 0 \\ 3/5 \\ 4/5 \end{pmatrix} \quad \left(\|\underline{v}_3\| = \sqrt{3^2 + 4^2} = 5 \right)$$

$$\underline{x}_1 = 1 \cdot \underline{u}_1 + 0 \cdot \underline{u}_2 + 0 \cdot \underline{u}_3$$

$$\underline{x}_2 = 1 \cdot \underline{u}_1 + 1 \cdot \underline{u}_2 + 0 \cdot \underline{u}_3$$

$$\underline{x}_3 = 1 \cdot \underline{u}_1 + 0 \cdot \underline{u}_2 + 5 \cdot \underline{u}_3$$

$$\Rightarrow A = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \\ 0 & 0 & 4 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3/5 \\ 0 & 0 & 4/5 \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 5 \end{pmatrix}$$

\mathbb{Q}
 $=$
 \mathbb{R}