

Final Exam Review 3

$$ay'' + by' + cy = f(t) \quad - \text{ 2nd-order, linear constant-coefficient differential equation.}$$

$f(t) = \text{zero function} \Rightarrow \text{Homogeneous}$

Fact: Solution to $ay'' + by' + cy = 0$ are a two dimensional vector space

$$ay'' + by' + cy = 0 \rightarrow ax^2 + bx + c = 0 \quad \text{auxiliary equation}$$

r a solution of auxiliary equation $\Rightarrow y(t) = e^{rt}$ a homogeneous solution.

3 cases

1) $r_1 \neq r_2$ are non-repeated roots of $\Rightarrow c_1 e^{r_1 t} + c_2 e^{r_2 t}$ general homogeneous solution
auxiliary equation

2) r_1 , a repeated root of auxiliary $\Rightarrow c_1 e^{r_1 t} + c_2 t e^{r_1 t}$ general homogeneous solution
equation

3) $\alpha \pm i\beta$ non-real roots of $\Rightarrow c_1 e^{\alpha t} \cos(\beta t) + c_2 e^{\alpha t} \sin(\beta t)$ general homogeneous solution
auxiliary equation
perhaps non-zero

Fact: If y_p is a particular solution to $ay'' + by' + cy = f(t)$
 $\Rightarrow y_p + y_h$ is a general solution
general homogeneous solution.

One method to find y_p : Undetermined coefficients

$$ay'' + by' + cy = \left\{ \begin{array}{l} P_m(t) e^{kt} \\ P_m(t) e^{kt} \cos(\ell t) \\ P_m(t) e^{kt} \sin(\ell t) \end{array} \right\}$$

degree m polynomial Try $y_p(t) = t^s (A_0 + \dots + A_m t^m) e^{kt}$
 ↓ $ak^2 + bk + c \neq 0 \Rightarrow s=0$
 $ak^2 + bk + c = 0$ (non-repeated) $\Rightarrow s=1$
 $ak^2 + bk + c = 0$ (repeated) $\Rightarrow s=2$

$a(k+i\ell)^2 + b(k+i\ell) + c \neq 0 \Rightarrow s=0$
 $a(k+i\ell)^2 + b(k+i\ell) + c = 0 \Rightarrow s=1$

Fact : If $\underline{f}(t)$ is a sum of such functions we can find a particular solution for each and add them (superposition principle)

Linear Systems of First-Order Differential Equations

$$\underline{x} : \mathbb{R} \rightarrow \mathbb{R}^n \quad t \mapsto \underline{x}(t) = \begin{pmatrix} x_1(t) \\ \vdots \\ x_n(t) \end{pmatrix} \quad \leftarrow \mathbb{R}^n\text{-valued Function}$$

$$(\underline{x} = \underline{y} \Leftrightarrow \underline{x}(t) = \underline{y}(t) \text{ for all } t)$$

Fact : \mathbb{R}^n -valued functions form a vector space. $\underline{0} = \text{zero function}$
i.e. $\underline{0}(t) = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}$ for all t)

$$\underline{x}'(t) := \begin{pmatrix} x_1'(t) \\ \vdots \\ x_n'(t) \end{pmatrix}, \quad A - n \times n \text{ matrix}$$

$\underline{x}'(t) = A \underline{x}(t)$ — $n \times n$, homogeneous, constant-coefficient, linear system of first-order differential equations.

Facts :

1, $\underline{x}, \underline{y}$ solutions and $\underline{x}(t_0) = \underline{y}(t_0)$ for some $t_0 \Rightarrow \underline{x} = \underline{y}$

2, Solutions form an n -dimensional vector space.

General Facts about any \mathbb{R}^n -valued functions :

$$\{\underline{x}_1, \dots, \underline{x}_n\} \text{ L.D.} \Rightarrow \det(\underline{x}_1(t) \dots \underline{x}_n(t)) = 0 \text{ for all } t$$

~~not in general~~

Hence,

If there exists t_0 such that $\rightarrow \{\underline{x}_1, \dots, \underline{x}_n\}$ L.I.

$$\det(\underline{x}_1(t_0) \dots \underline{x}_n(t_0)) \neq 0$$

Problem :

$$\det(\underline{x}_1(t) \dots \underline{x}_n(t)) = 0 \text{ for all } t \text{ tells us nothing.}$$

Partial Converse : $\{\underline{x}_1, \dots, \underline{x}_n\}$ Solutions to $\underline{x}'(t) = A \underline{x}(t)$

$$\det(\underline{x}_1(t) \dots \underline{x}_n(t)) \neq 0 \text{ for all } t$$

$$\det(\underline{x}_1(t) \dots \underline{x}_n(t)) = 0 \text{ for all } t$$

Important Observation :

\underline{v} an eigenvector of A with eigenvalue $\lambda \Rightarrow \underline{x}(t) = e^{\lambda t} \underline{v}$ a solution.

$\left(\underline{v}_1, \dots, \underline{v}_n \right)$ an eigenbasis of $A \Rightarrow \underline{x}(t) = c_1 e^{\lambda_1 t} \underline{v}_1 + \dots + c_n e^{\lambda_n t} \underline{v}_n$ a general solution

$\lambda = \alpha + i\beta$ a non-real eigenvalue of A (a non-real root of characteristic polynomial)

We can still find complex eigenvectors by calculating

$\text{Nul } (A - (\alpha + i\beta)I_n) \leftarrow$ Do usual row reduction by doing complex arithmetic

$\underline{a} + i\underline{b}$ a complex eigenvector with complex

eigenvalue $\alpha + i\beta$

$$\Rightarrow e^{\alpha t} \cos(\beta t) \underline{a} - e^{\alpha t} \sin(\beta t) \underline{b}, \quad e^{\alpha t} \sin(\beta t) \underline{a} + e^{\alpha t} \cos(\beta t) \underline{b}$$

are L.I. solutions.

Fourier Series

f - piecewise continuous function on $[-L, L]$

$$\text{F. S. of } f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} \left(a_n \cos\left(\frac{n\pi x}{L}\right) + b_n \sin\left(\frac{n\pi x}{L}\right) \right)$$

where $a_n = \frac{1}{L} \int_{-L}^L f(x) \cos\left(\frac{n\pi x}{L}\right) dx \quad n = 0, 1, 2, \dots$

$$b_n = \frac{1}{L} \int_{-L}^L f(x) \sin\left(\frac{n\pi x}{L}\right) dx \quad n = 1, 2, 3, \dots$$

usually calculated using I.B.P.

waves at increasing frequency

amplitudes

f even $\Rightarrow b_n = 0$ for all $n = 1, 2, 3, \dots$

f odd $\Rightarrow a_n = 0$ for all $n = 0, 1, 2, 3, \dots$

Cosine Fourier Series of $f(x)$ on $[0, L]$ = $\frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos\left(\frac{n\pi x}{L}\right)$

where $a_n = \frac{1}{L} \int_{-L}^L f_e(x) \cos\left(\frac{n\pi x}{L}\right) dx = \frac{2}{L} \int_0^L f(x) \cos\left(\frac{n\pi x}{L}\right) dx$

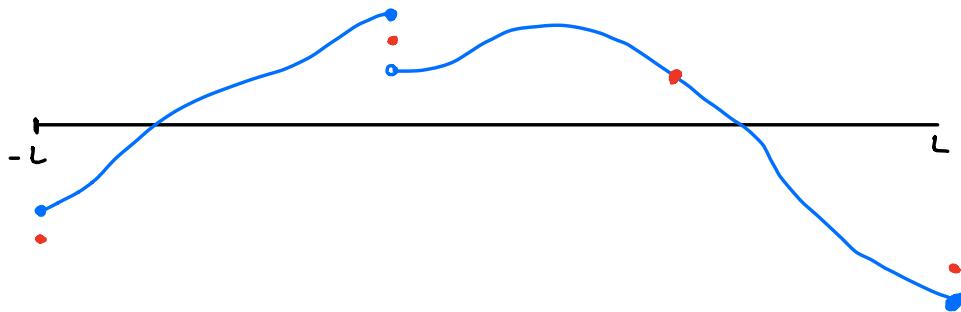
Sine Fourier Series of $f(x)$ on $[0, L]$ = $\sum_{n=1}^{\infty} b_n \sin\left(\frac{n\pi x}{L}\right)$

where $b_n = \frac{1}{L} \int_{-L}^L f_o(x) \sin\left(\frac{n\pi x}{L}\right) dx = \frac{2}{L} \int_0^L f(x) \sin\left(\frac{n\pi x}{L}\right) dx$

Convergence of F.S.

$$\frac{a_0}{2} + \sum_{n=1}^{\infty} (a_n \cos\left(\frac{n\pi x}{L}\right) + b_n \sin\left(\frac{n\pi x}{L}\right)) = \begin{cases} \frac{f(x^+) + f(x^-)}{2} & -L < x < L \\ \frac{f(-L^+) + f(L^-)}{2} & x = \pm L \end{cases}$$

— = $f(x)$
— = F.S.(x)



Finally F.S. is $2L$ -periodic \Rightarrow F.S.(x) = F.S.(x+2L)
for all x.