

Example $\begin{pmatrix} \boxed{1} & 0 & 2 & | & 0 \\ 0 & \boxed{1} & 3 & | & 1 \end{pmatrix} \Rightarrow \begin{cases} x_1 + 2x_3 = 0 \\ x_2 + 3x_3 = 1 \end{cases}$

$\begin{matrix} \leftarrow \text{pivot position} \\ \uparrow \uparrow \uparrow \\ \text{Pivot} & \text{Free} \\ \text{Columns} & \text{Column} \end{matrix}$

\Rightarrow General Solution = $\begin{cases} -2x_3 \\ 1 - 3x_3 \\ x_3 \text{ free} \end{cases}$

called vector in \mathbb{R}^m

Vector/Matrix Perspective

$\mathbb{R}^m = \left\{ \begin{pmatrix} v_1 \\ \vdots \\ v_m \end{pmatrix} \text{ such that } v_i \text{ in } \mathbb{R} \right\}$ we write $\underline{v} = \begin{pmatrix} v_1 \\ \vdots \\ v_m \end{pmatrix}$

Key Fact: We can add and scale vectors in \mathbb{R}^m .

$\underline{u} = \begin{pmatrix} u_1 \\ \vdots \\ u_m \end{pmatrix}, \underline{v} = \begin{pmatrix} v_1 \\ \vdots \\ v_m \end{pmatrix} \Rightarrow \underline{u} + \underline{v} := \begin{pmatrix} u_1 + v_1 \\ \vdots \\ u_m + v_m \end{pmatrix}$

$\lambda \text{ in } \mathbb{R} \Rightarrow \lambda \underline{u} = \begin{pmatrix} \lambda u_1 \\ \vdots \\ \lambda u_m \end{pmatrix}$

A $m \times n$ matrix $\Rightarrow A = (\underline{a}_1 \dots \underline{a}_n)$ in \mathbb{R}^m

Notation: $\underline{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$ in \mathbb{R}^n linear combination

$\Rightarrow A\underline{x} := x_1 \underline{a}_1 + x_2 \underline{a}_2 + \dots + x_n \underline{a}_n$

Let $\underline{b} = \begin{pmatrix} b_1 \\ \vdots \\ b_m \end{pmatrix}$ in \mathbb{R}^m

\underline{x} is solution to $(A | \underline{b}) \Leftrightarrow A\underline{x} = \underline{b}$

$\Rightarrow (A | \underline{b})$ consistent $\Leftrightarrow \underline{b}$ a linear combination of $\{\underline{a}_1, \dots, \underline{a}_n\}$

\uparrow
admits a solution

$\Leftrightarrow \underline{b}$ in $\text{Span}(\underline{a}_1, \dots, \underline{a}_n)$
" all linear combinations

Conclusion

\underline{b} in $\text{Span}(\underline{a}_1, \dots, \underline{a}_n) \Leftrightarrow (A|\underline{b})$ consistent \Leftrightarrow Last column of reduced $(A|\underline{b})$ not a pivot

E.g. $\left(\begin{array}{ccc|c} 1 & 1 & 1 & 3 \\ 0 & 1 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{array} \right) \Rightarrow \begin{pmatrix} 3 \\ 4 \\ 0 \end{pmatrix}$ in $\text{Span} \left(\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} \right)$

↑
Not pivot

$\left(\begin{array}{ccc|c} 1 & 1 & 1 & 3 \\ 0 & 1 & 2 & 4 \\ 0 & 0 & 0 & 1 \end{array} \right) \Rightarrow \begin{pmatrix} 3 \\ 4 \\ 1 \end{pmatrix}$ not in $\text{Span} \left(\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} \right)$

Pivot position in every row of reduced $A \Leftrightarrow$ Every row of reduced A is non-zero \Leftrightarrow Last column of reduced $(A|\underline{b})$ is not pivot for any \underline{b} in \mathbb{R}^m

$\text{Span}(\underline{a}_1, \dots, \underline{a}_n) = \mathbb{R}^m \Leftrightarrow$ Reduced A has pivot position in every row

$\{\underline{a}_1, \dots, \underline{a}_n\}$ Linearly independent: (L.I.)

$x_1 \underline{a}_1 + x_2 \underline{a}_2 + \dots + x_n \underline{a}_n = \underline{0} \Rightarrow x_1 = x_2 = \dots = x_n = 0$

" $A\underline{x}$

$\Rightarrow \{\underline{a}_1, \dots, \underline{a}_n\}$ L.I. $\Leftrightarrow A\underline{x} = \underline{0}$ has unique solution $\underline{x} = \underline{0}$

\Leftrightarrow Reduced $(A|\underline{0})$ has no free columns

\Leftrightarrow Reduced A has pivot position in every column

homogeneous linear system

Fact General solution to $A\underline{x} = \underline{b}$ = \underline{v}_p + General Solution to $A\underline{x} = \underline{0}$
fixed particular solution

\Rightarrow Consistent $A\underline{x} = \underline{b}$ has unique solution $\Leftrightarrow A\underline{x} = \underline{0}$ has unique solution $\Leftrightarrow \{\underline{a}_1, \dots, \underline{a}_n\}$ L.I.

Conclusion

$\{\underline{a}_1, \dots, \underline{a}_n\}$ L.I. \Leftrightarrow Reduced A has pivot position in every column

Linear Transformations from \mathbb{R}^n to \mathbb{R}^m

$T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ linear \Leftrightarrow $\forall T(\underline{x} + \underline{y}) = T(\underline{x}) + T(\underline{y})$
 $\forall T(\lambda \underline{x}) = \lambda T(\underline{x})$

$A = (\underline{a}_1 \dots \underline{a}_n)$ - $m \times n$ matrix \Rightarrow

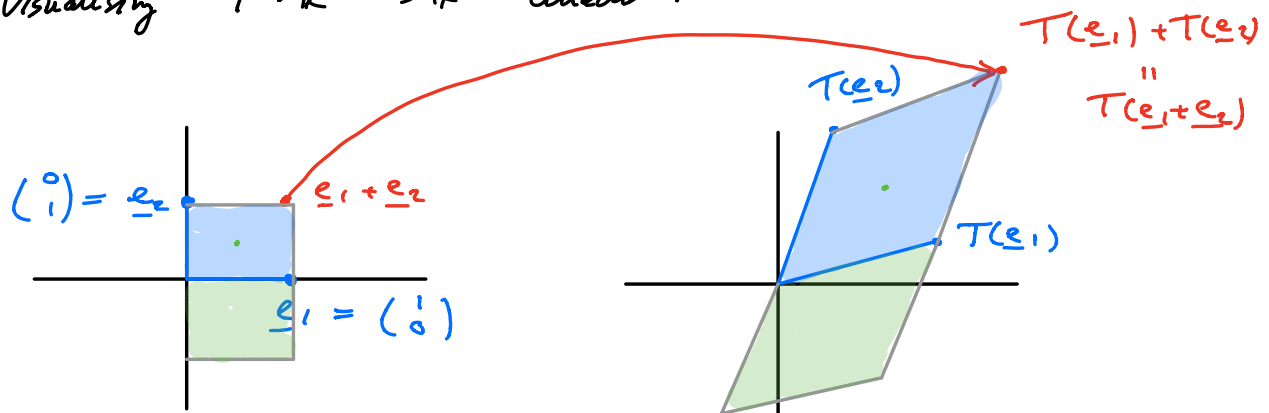
$T_A: \mathbb{R}^n \rightarrow \mathbb{R}^m$
 $\underline{x} \mapsto A\underline{x} = x_1 \underline{a}_1 + \dots + x_n \underline{a}_n$ Linear

Fact: T linear $\Rightarrow T(\underline{x}) = A\underline{x}$ where

$A = (T(\underline{e}_1) \ T(\underline{e}_2) \ \dots \ T(\underline{e}_n))$ = Standard Matrix of T

$\underline{e}_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$, $\underline{e}_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}$, ..., $\underline{e}_n = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ 0 \end{pmatrix}$ If we know $T(\underline{e}_1), \dots, T(\underline{e}_n)$ we know $T(\underline{x})$ for all \underline{x}

Visualising $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ linear:



$$\text{Range of } T_A = \{A\underline{x}\} = \text{Span}(\underline{a}_1, \dots, \underline{a}_n)$$

$$\Rightarrow T_A \text{ onto} \Leftrightarrow \text{Span}(\underline{a}_1, \dots, \underline{a}_n) = \mathbb{R}^m$$

$$T_A \text{ one-to-one} \Leftrightarrow T_A(\underline{x}) = \underline{b} \Leftrightarrow A\underline{x} = \underline{b} \Leftrightarrow \begin{matrix} \{a_1, \dots, a_n\} \\ \text{L.I.} \end{matrix}$$

has at most one solution
has at most one solution

Overview

Linear Transformations

Vectors

Linear Systems

Reduced Echelon Matrices

\underline{b}
in range of T_A

$\Leftrightarrow \underline{b}$
in $\text{Span}(\underline{a}_1, \dots, \underline{a}_n)$

$A\underline{x} = \underline{b}$
has solution

\Leftrightarrow Reduced $(A|\underline{b})$
does not have pivot position in last column

T_A onto

$\Leftrightarrow \text{Span}(\underline{a}_1, \dots, \underline{a}_n) \parallel \mathbb{R}^m$

$A\underline{x} = \underline{b}$
has solution for all \underline{b}

\Leftrightarrow Pivot position in every row of reduced A

T_A one-to-one

$\Leftrightarrow \{a_1, \dots, a_n\}$
L.I.

$A\underline{x} = \underline{b}$
has at most one solution

\Leftrightarrow Pivot position in every column of reduced A .

Matrix Algebra

A, B - $n \times n$ matrices, λ in \mathbb{R}

$$(A+B)_{ij} := (A)_{ij} + (B)_{ij} \quad \leftarrow \text{ij}^{\text{th}} \text{ entry}$$

$$(\lambda A)_{ij} := \lambda (A)_{ij}$$

A - $n \times n$, B - $n \times p$

$$(AB)_{ij} = (A)_{i1}(B)_{1j} + (A)_{i2}(B)_{2j} + \dots + (A)_{in}(B)_{nj}$$

Key Facts :

$$T_{(A+B)} = T_A + T_B$$
$$T_{(\lambda A)} = \lambda T_A$$
$$T_{AB} = T_A \circ T_B$$

Invertible Matrices

A - $n \times n$ matrix

A invertible \Leftrightarrow There exists B , an $n \times n$ matrix, such that $AB = BA = I_n = n \times n$ identity matrix
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denoted A^{-1} , the inverse of A

Fact : A invertible $\Leftrightarrow T_A : \mathbb{R}^n \rightarrow \mathbb{R}^n$ one-to-one and onto

\Leftrightarrow Reduced A has pivot position in every column and every row

Crazy coincidence

in $n \times n$ case

: These are equivalent

$\Leftrightarrow A$ row equivalent to $\begin{pmatrix} \blacksquare & & * \\ & \ddots & \\ 0 & & \blacksquare \end{pmatrix}$

\Leftrightarrow Reduced A equals I_n

Algorithm to Calculate A^{-1}

- 1/ Write $(A | I_n)$
- 2/ Put in reduced echelon form $(I_n | B)$ using row operations
- 3/ $B = A^{-1}$.

Determinant

Given A - $n \times n$ matrix, $\det(A)$ is a number which helps us determine invertibility.

Facts \vee U upper triangular $\Rightarrow \det(U) =$ product of diagonal entries

E.g. $\det \begin{pmatrix} 1 & 1 & 0 \\ 0 & 2 & 3 \\ 0 & 0 & 3 \end{pmatrix} = 1 \cdot 2 \cdot 3 = 6$

- 2/ A/ Switching two rows multiplies determinant by -1
B/ Adding scalar multiple of one row to another does not change determinant
- 3/ Square matrix in echelon form \Rightarrow upper triangular

Algorithm to calculate $\det(A)$

- 1/ Put A in echelon form using only A, and B,
- 2/ Compute product of diagonal entries (This is the determinant)
- 3/ $\det(A) = (-1)^{\uparrow} \times$ Product of diagonal entries in echelon form
Number of row switches

Fact A^{-1} exists $\Leftrightarrow \det(A) \neq 0$