

# Homework 8 Solutions

Math 110

## Section 5.1

3. (a) The characteristic polynomial of  $A$  is  $(1-t)(2-t)-6 = t^2-3t-4 = (t-4)(t+1)$ ; therefore, the eigenvalues of  $A$  are 4 and  $-1$ .

For  $\lambda = 4$ , we have

$$E_4 = NS \begin{bmatrix} -3 & 2 \\ 3 & -2 \end{bmatrix} = \text{span}\{(2, 3)\}.$$

Similarly, for  $\lambda = -1$ , we have

$$E_{-1} = NS \begin{bmatrix} 2 & 2 \\ 3 & 3 \end{bmatrix} = \text{span}\{(-1, 1)\}.$$

Thus,  $\{(2, 3), (-1, 1)\}$  is a basis for  $\mathbb{R}^2$  consisting of eigenvectors; we thus get  $Q^{-1}AQ = D$  for

$$Q = \begin{bmatrix} 2 & -1 \\ 3 & 1 \end{bmatrix}, D = \begin{bmatrix} 4 & 0 \\ 0 & -1 \end{bmatrix}.$$

4. (h) Let  $\varepsilon = \{E_{11}, E_{12}, E_{21}, E_{22}\}$  be the standard basis for  $M_{2 \times 2}(\mathbb{R})$ . Then we see  $TE_{11} = E_{22}$ ,  $TE_{12} = E_{12}$ ,  $TE_{21} = E_{21}$ , and  $TE_{22} = E_{11}$ . Thus,

$$[T]_{\varepsilon} = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}.$$

Now the characteristic polynomial of  $T$  is

$$\det \begin{bmatrix} -t & 0 & 0 & 1 \\ 0 & 1-t & 0 & 0 \\ 0 & 0 & 1-t & 0 \\ 1 & 0 & 0 & -t \end{bmatrix}.$$

Expanding by minors along the second and third columns, this is equal to  $(1-t)^2[(-t)^2 - 1^2] = (t-1)^2(t^2-1) = (t-1)^3(t+1)$ . Therefore, the eigenvalues of  $T$  are 1 and  $-1$ .

Now the eigenspace of 1 corresponds to

$$NS \begin{bmatrix} -1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & -1 \end{bmatrix} = \text{span}\{(0, 1, 0, 0), (0, 0, 1, 0), (1, 0, 0, 1)\}.$$

In  $M_{2 \times 2}(\mathbb{R})$ , this corresponds to  $\text{span}\{E_{12}, E_{21}, E_{11} + E_{22}\}$ . On the other hand, the eigenspace of  $-1$  corresponds to

$$NS \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix} = \text{span}\{(-1, 0, 0, 1)\}.$$

In  $M_{2 \times 2}(\mathbb{R})$ , this corresponds to  $\text{span}\{-E_{11} + E_{22}\}$ .

Therefore,

$$\beta = \left\{ \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

diagonalizes  $T$ .

8. (a) We see that zero is an eigenvalue of  $T$  if and only if  $Tx = 0$  for some nonzero vector  $x \in V$ , or in other words if and only if  $T$  is not one-to-one. Thus,  $T$  is one-to-one if and only if zero is not an eigenvalue of  $T$ ; however, since  $V$  is finite-dimensional,  $T$  is invertible if and only if  $T$  is one-to-one.
- (b) ( $\Rightarrow$ ) Suppose  $\lambda$  is an eigenvalue of  $T$ , and find a corresponding eigenvector  $x \in V$ . Then since  $Tx = \lambda x$ , we also have  $T(\lambda^{-1}x) = x$ , so  $T^{-1}x = \lambda^{-1}x$ . Therefore,  $\lambda^{-1}$  is an eigenvalue of  $T^{-1}$ .
- ( $\Leftarrow$ ) If  $\lambda^{-1}$  is an eigenvalue of  $T^{-1}$ , then by the previous part,  $\lambda = (\lambda^{-1})^{-1}$  is an eigenvalue of  $T = (T^{-1})^{-1}$ .
- (c) If  $A \in M_{n \times n}(F)$ , then  $A$  is invertible if and only if 0 is not an eigenvalue of  $A$ . Also, if  $A$  is invertible, then  $\lambda$  is an eigenvalue of  $A$  if and only if  $\lambda^{-1}$  is an eigenvalue of  $A^{-1}$ . (These results follow from the previous parts by letting  $T = L_A$ .)
14. Since  $(A - tI)^t = A^t - tI$ , we have

$$\det(A - tI) = \det[(A - tI)^t] = \det(A^t - tI).$$

15. (a) We prove this by induction on  $m$ ; for  $m = 1$ , the statement is exactly what we are assuming. Now suppose  $x$  is an eigenvector of  $T^m$  with eigenvalue  $\lambda^m$ ; then we calculate

$$T^{m+1}x = T(T^m x) = T(\lambda^m x) = \lambda^m(Tx) = \lambda^m(\lambda x) = \lambda^{m+1}x.$$

Therefore,  $x$  is also an eigenvector of  $T^{m+1}$  with eigenvalue  $\lambda^{m+1}$ , completing the induction.

- (b) Let  $A \in M_{n \times n}(F)$ , and let  $x \in F^n$  be an eigenvector of  $A$  with eigenvalue  $\lambda$ . Then for any positive integer  $m$ ,  $x$  is an eigenvector of  $A^m$  with eigenvalue  $\lambda^m$ . (This follows from the previous part by letting  $T = L_A$ .)
21. (a) The  $ij$ -entry of  $A - tI$  is  $A_{ij} - t\delta_{ij}$ . Therefore, we get

$$f(t) = \det(A - tI) = \sum_{\sigma \in S_n} \text{sgn}(\sigma)(A_{\sigma(1),1} - t\delta_{\sigma(1),1})(A_{\sigma(2),2} - t\delta_{\sigma(2),2}) \cdots (A_{\sigma(n),n} - t\delta_{\sigma(n),n}).$$

If  $\sigma$  is the identity permutation, this term gives exactly  $(A_{11} - t)(A_{22} - t) \cdots (A_{nn} - t)$ . On the other hand, if  $\sigma$  is any other permutation, then  $\sigma(i) \neq i$  for at least *two* values of  $i$ . (This is because if  $\sigma(i) = j \neq i$  for some  $i$ , then  $\sigma(j)$  also cannot be equal to  $j$ .) Therefore, any other term of the sum gives a polynomial of degree at most  $n - 2$ , so the sum of all the other terms is also a polynomial  $q(t)$  of degree at most  $n - 2$ .

- (b) From the previous part, the coefficient of  $t^{n-1}$  in  $f(t)$  is equal to the coefficient of  $t^{n-1}$  in  $(A_{11} - t)(A_{22} - t) \cdots (A_{nn} - t)$ , which is  $(-1)^{n-1}(A_{11} + A_{22} + \cdots + A_{nn})$ . Therefore,  $a_{n-1} = (-1)^{n-1}(\text{tr } A)$ , so  $\text{tr } A = (-1)^{n-1}a_{n-1}$ .

- X1. If  $A$  is the given matrix, then  $A(x_1, x_2, \dots, x_n) = (x_2, \dots, x_n, -a_0x_1 - a_1x_2 - \dots - a_{n-1}x_n)$ . Thus, if  $x = (x_1, \dots, x_n)$  is an eigenvector of  $A$  with eigenvalue  $\lambda$ , we must have  $x_2 = \lambda x_1$ ,  $x_3 = \lambda x_2 = \lambda^2 x_1$ ,  $x_4 = \lambda x_3 = \lambda^3 x_1$ ,  $\dots$ ,  $x_n = \lambda^{n-1} x_1$ . Now plugging in, the last entry of  $Ax$  is  $x_1(-a_0 - a_1\lambda - \dots - a_{n-1}\lambda^{n-1}) = x_1\lambda^n$ . Therefore, for any nonzero scalar  $c$ ,  $c(1, \lambda, \lambda^2, \dots, \lambda^{n-1})$  is an eigenvector of  $A$  (and in fact, every eigenvector corresponding to  $\lambda$  is of this form).
- X2. By the calculations in the previous problem, the eigenspace of each eigenvalue  $\lambda$  has dimension 1. Therefore,  $A$  is diagonalizable if and only if the characteristic polynomial  $(-1)^n(t^n + a_{n-1}t^{n-1} + \dots + a_1t + a_0)$  splits, and each eigenvalue has multiplicity 1. This is equivalent to the condition that the polynomial  $t^n + a_{n-1}t^{n-1} + \dots + a_1t + a_0$  have  $n$  distinct roots.

## Section 5.2

7. If we apply the diagonalization process to  $A$ , we find that  $A$  has eigenvalues 5 and  $-1$ , with corresponding eigenvectors  $(1, 1)$  and  $(-2, 1)$ . Therefore,  $A = QDQ^{-1}$ , where

$$D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix}, Q = \begin{bmatrix} 1 & -2 \\ 1 & 1 \end{bmatrix}, Q^{-1} = \frac{1}{3} \begin{bmatrix} 1 & 2 \\ -1 & 1 \end{bmatrix}.$$

We thus get

$$A^n = QD^nQ^{-1} = \frac{1}{3} \begin{bmatrix} 1 & -2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 5^n & 0 \\ 0 & (-1)^n \end{bmatrix} \begin{bmatrix} 1 & 2 \\ -1 & 1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 5^n + 2(-1)^n & 2[5^n - (-1)^n] \\ 5^n - (-1)^n & 2 \cdot 5^n + (-1)^n \end{bmatrix}.$$

8. From the given assumptions, we see that the multiplicity of  $\lambda_1$  must be at least  $n - 1$ , and the multiplicity of  $\lambda_2$  must be at least 1. However, the sum of these two multiplicities is also at most  $n$ . Therefore, the multiplicity of  $\lambda_1$  is exactly  $n - 1$ , and the multiplicity of  $\lambda_2$  is exactly 1.

This implies that  $\lambda_1$  and  $\lambda_2$  are the only eigenvalues; also,  $(\lambda_1 - t)^{n-1}(\lambda_2 - t)$  must divide the characteristic polynomial. But  $(\lambda_1 - t)^{n-1}(\lambda_2 - t)$  and the characteristic polynomial both have leading term  $(-1)^n t$ , so in fact they are equal. Thus, the characteristic polynomial splits;  $\dim(E_{\lambda_1}) = n - 1$  is equal to the multiplicity of  $\lambda_1$ ; and  $1 \leq \dim(E_{\lambda_2}) \leq 1$  since  $\lambda_2$  has multiplicity 1, so  $\dim(E_{\lambda_2}) = 1$  is equal to the multiplicity of  $\lambda_2$ . Therefore,  $A$  is diagonalizable.

Alternately, taking a basis of  $E_{\lambda_1}$  and adjoining an eigenvector corresponding to  $\lambda_2$  gives a linearly independent subset of  $V$  by theorem 5.8 from the book; this set has  $n$  vectors, so it must be a basis.

11. Since  $A$  is similar to an upper triangular matrix, the characteristic polynomial of  $A$  splits. Therefore, it must be equal to  $f(t) = (\lambda_1 - t)^{m_1}(\lambda_2 - t)^{m_2} \dots (\lambda_k - t)^{m_k}$ . Thus,  $\det A = \det(A - 0 \cdot I) = f(0) = \lambda_1^{m_1} \lambda_2^{m_2} \dots \lambda_k^{m_k}$ . Also, the coefficient of  $t^{n-1}$  in this polynomial is  $(-1)^{n-1}(m_1\lambda_1 + m_2\lambda_2 + \dots + m_k\lambda_k)$ , so by problem 5.1.21, the trace of  $A$  is equal to  $m_1\lambda_1 + m_2\lambda_2 + \dots + m_k\lambda_k$ .
21. We use induction on  $k$ ; the case  $k = 1$  is trivial, and the case  $k = 2$  follows directly from problem 1.6.33 from a previous homework. Now for the general inductive step, let  $W_1 = \text{span}(\beta_1 \cup \dots \cup \beta_{k-1})$ ,  $W_2 = \text{span}(\beta_k)$ . Then by induction,  $W_1 = \text{span}(\beta_1) \oplus \dots \oplus \text{span}(\beta_{k-1})$ , and  $V = W_1 \oplus W_2$ . We claim that this implies  $V = \text{span}(\beta_1) \oplus \dots \oplus \text{span}(\beta_{k-1}) \oplus \text{span}(\beta_k)$ . To see this, first any  $x \in V$  can be written  $y + z$  with  $y \in W_1$ ,  $z \in W_2$ . Also, we can write  $y = y_1 + \dots + y_{k-1}$

with  $y_1 \in \text{span}(\beta_1), \dots, y_{k-1} \in \text{span}(\beta_{k-1})$ . This,  $x = y_1 + \dots + y_{k-1} + z \in \text{span}(\beta_1) + \dots + \text{span}(\beta_{k-1}) + \text{span}(\beta_k)$ .

Also, suppose that  $y_1 + \dots + y_{k-1} + y_k = 0$  with  $y_1 \in \text{span}(\beta_1), \dots, y_k \in \text{span}(\beta_k)$ . Then  $y_k = -y_1 - \dots - y_{k-1} \in W_1 \cap W_2$ , so  $y_k = 0$ . This implies that  $y_1 + \dots + y_{k-1} = 0$ , so  $y_1 = \dots = y_{k-1} = 0$  also since  $W_1 = \text{span}(\beta_1) \oplus \dots \oplus \text{span}(\beta_{k-1})$ .

X1. (a) Let  $x_k$  denote the  $k$ th vector; we then see that  $Ax_k = (\omega^k + \omega^{6k}, 1 + \omega^{2k}, \omega^k + \omega^{3k}, \dots, \omega^{4k} + \omega^{6k}, 1 + \omega^{5k})$ . However, since  $\omega^7 = 0$ , we have  $\omega^{6k} = \omega^{-k}$  and  $1 = \omega^{7k}$ , so  $Ax_k = (\omega^k + \omega^{-k})x_k$ . Therefore,  $x_k$  is an eigenvector of  $A$ , with eigenvalue  $\omega^k + \omega^{-k}$ . However, since  $\omega^k = \cos(\frac{2\pi k}{7}) + i \sin(\frac{2\pi k}{7})$  and  $\omega^{-k} = \cos(\frac{2\pi k}{7}) - i \sin(\frac{2\pi k}{7})$ , this eigenvalue is equal to  $2 \cos(\frac{2\pi k}{7})$ .

(b) For  $k = 1, 2, 3$ , the eigenspace of  $2 \cos(\frac{2\pi k}{7})$  has two linearly independent vectors  $x_k, x_{-k}$ . Therefore,  $\{x_{-3}, x_{-2}, \dots, x_3\}$  is linearly independent by 5.8, so it is a basis of  $\mathbb{C}^7$  consisting of eigenvectors of  $A$ .

(In fact,  $A$  is diagonalizable over  $\mathbb{R}$  as well: all the eigenvalues are real, and for  $k = 1, 2, 3$ ,  $\frac{1}{2}(x_k + x_{-k}) = (1, \cos(\frac{2\pi k}{7}), \dots, \cos(\frac{12\pi k}{7}))$  and  $\frac{1}{2i}(x_k - x_{-k}) = (0, \sin(\frac{2\pi k}{7}), \dots, \sin(\frac{12\pi k}{7}))$  are linearly independent real eigenvectors corresponding to  $2 \cos(\frac{2\pi k}{7})$ . Since  $x_0 = (1, 1, \dots, 1)$ , we thus get a basis of  $\mathbb{R}^7$  consisting of real eigenvectors of  $A$ .)

Alternately,  $A$  is symmetric, and we will see later that any symmetric matrix is diagonalizable.

(c) If we move the top row of  $A$  to the bottom, this does not change the sign of the determinant, while the result is almost upper triangular. We now reduce  $A$  as follows:

$$\begin{aligned} \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} &\rightarrow \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & -1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 1 \end{bmatrix} &\rightarrow \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 \end{bmatrix} \rightarrow \\ \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 \end{bmatrix} &\rightarrow \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 2 \end{bmatrix}. \end{aligned}$$

None of these steps changes the determinant; thus,  $\det A = 2$ .

(d) From part (b), the eigenvectors of  $A$  are 2 with multiplicity 1 and  $2 \cos(\frac{2\pi}{7}), 2 \cos(\frac{4\pi}{7}), 2 \cos(\frac{6\pi}{7})$  each with multiplicity 2. Since the product of the eigenvalues is equal to  $\det A$ , we thus get

$$2^7 \cos^2\left(\frac{2\pi}{7}\right) \cos^2\left(\frac{4\pi}{7}\right) \cos^2\left(\frac{6\pi}{7}\right) = 2.$$

Therefore,  $\cos\left(\frac{2\pi}{7}\right)\cos\left(\frac{4\pi}{7}\right)\cos\left(\frac{6\pi}{7}\right) = \pm\frac{1}{8}$ . However,  $\cos\left(\frac{2\pi}{7}\right)$  is positive, while  $\cos\left(\frac{4\pi}{7}\right)$  and  $\cos\left(\frac{6\pi}{7}\right)$  are negative, so we conclude

$$\cos\left(\frac{2\pi}{7}\right)\cos\left(\frac{4\pi}{7}\right)\cos\left(\frac{6\pi}{7}\right) = \frac{1}{8}.$$

#### Section 5.4

2. (a) If  $f \in W$ , then  $f$  has degree at most 2, so  $f'$  has degree at most  $1 \leq 2$ , which implies  $f' \in W$  also. Therefore,  $W$  is  $T$ -invariant.

(e) In this case,  $W$  is not  $T$ -invariant; for example,  $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \in W$ , but  $T(A) = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \notin W$ .

6. (a) We calculate  $T(e_1) = (1, 0, 1, 1)$ ;  $T^2(e_1) = (1, -1, 2, 2)$ ; and  $T^3(e_1) = (0, -3, 3, 3) = 3T^2(e_1) - 6T(e_1) + 3e_1$ . Therefore, the  $T$ -cyclic subspace generated by  $e_1$  is  $\text{span}\{(1, 0, 0, 0), (1, 0, 1, 1), (1, -1, 2, 2)\}$ . This subspace can also be identified as  $\{(a, b, c, d) : c = d\}$ .

17. We can rewrite any linear combination  $c_0I_n + c_1A + c_2A^2 + \cdots + c_kA^k$  as  $p(A)$ , where  $p(t) = c_kt^k + \cdots + c_1t + c_0$ . We now divide  $p(t)$  by the characteristic polynomial  $f(t)$  of  $A$  to get  $p(t) = q(t)f(t) + r(t)$ , where the degree of  $r(t)$  is less than  $n$ . This implies that  $p(A) = q(A)f(A) + r(A)$ ; however, by the Cayley-Hamilton theorem,  $f(A) = 0$ . Therefore,  $p(A) = r(A)$  is a linear combination of  $I_n, A, A^2, \dots, A^{n-1}$ .

We have thus shown that  $\text{span}\{I_n, A, A^2, \dots\} \subseteq \text{span}\{I_n, A, A^2, \dots, A^{n-1}\}$ ; since the right hand side clearly has dimension at most  $n$ , this implies the desired result.

Alternately, consider the linear transformation  $T : M_{n \times n}(F) \rightarrow M_{n \times n}(F)$  such that  $T(B) = AB$ . Then the  $T$ -invariant subspace generated by  $I_n$  is exactly  $\text{span}\{I_n, A, A^2, \dots\}$ ; but since the Cayley-Hamilton theorem implies that  $A^n$  is a linear combination of  $I_n, A, A^2, \dots, A^{n-1}$ , our general results on  $T$ -cyclic subspaces imply that  $\text{span}\{I_n, A, A^2, \dots\}$  has dimension at most  $n$ .

42. Since  $A$  has rank 1, the null space of  $A$  has dimension  $n - 1$ , which implies that  $A$  has eigenvalue 0 with multiplicity at least  $n - 1$ . On the other hand,  $A$  also has eigenvalue  $n$  with corresponding eigenvector  $x = (1, 1, \dots, 1)$ . Therefore, the characteristic polynomial of  $A$  must be  $(-t)^{n-1}(n - t)$ .