The Asymptotic Behavior of Finite Energy Symplectic Vortices with Admissible Metrics

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Assume (X, ω) is a compact symplectic manifold with a Hamiltonian compact Lie group action and the zero in the Lie algebra is a regular value of the moment map μ . We prove that a finite energy symplectic vortex exponentially converges to (un)twisted sectors of the symplectic reduction at cylinder ends whose metrics grow up at least cylindrically fast, without assuming the group action on the level set $\mu^{-1}(0)$ is free. It generalizes the corresponding results by Ziltener [23, 24] under the free action assumption.

The result of this paper is the first step in setting up the quotient morphism moduli space induced by the authors in [6]. Necessary preparations in understanding the structure of such moduli spaces are also introduced here. The quotient morphism constructed in [6] is a part of the project on the quantum Kirwan morphism by the authors (see [3, 4, 5]).

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1 Introduction and main results

Assume (X, ω) is a compact smooth symplectic manifold and G is a connected compact Lie group whose Lie algebra is denoted by \mathfrak{g} . By a Hamiltonian G-action on (X, ω) with a moment map μ , we mean that

(1) The Lie group G acts on X smoothly and we use

$$\ell: G \times X \to X, \quad (g, x) \mapsto \ell_g(x) := gx$$

to denote this action;

(2) The moment map $\mu: X \to \mathfrak{g}$ is a proper smooth map and it is *G*-equivariant with respect to the *G*-action on *X* and the adjoint action on \mathfrak{g} , i.e.,

$$\mu(\ell_g(x)) = \operatorname{Ad}_g(\mu(x)), \quad \text{for any } g \in G, x \in X;$$

(3) The *G*-action is Hamiltonian in the sense that $\iota_{X_{\xi}}\omega = \langle d\mu(\cdot), \xi \rangle$, where X_{ξ} denotes the infinitesimal action generated by $\xi \in \mathfrak{g}$ on X, i.e.,

$$X_{\xi}(x) := \frac{d}{d\epsilon}|_{\epsilon=0} \ell_{\exp(\epsilon\xi)}(x),$$

and $\langle \cdot, \cdot \rangle$ denotes the Killing inner product on the Lie algebra g.

It is clear from definition that associated to a Hamiltonian G-action on (X, ω) , the moment map μ is not unique but can be shifted up to some element $\tau \in C(\mathfrak{g})$, where $C(\mathfrak{g})$ denotes the center of the Lie algebra \mathfrak{g} . Throughout this paper, we fix a moment map μ and assume $0 \in \mathfrak{g}$ is a regular value. All results in this paper apply to any $\tau \in C(\mathfrak{g})$ which is regular.

The level set $\mu^{-1}(0)$ is compact and G-invariant. The assumption that 0 is a regular value ensures that $\mu^{-1}(0)$ is a compact smooth submanifold of X with codimension $\dim G$ and the G-action on it is locally free. Moreover, $(\mu^{-1}(0), \omega|_{\mu^{-1}(0)})$ is coisotropic, with $\ker \omega|_{\mu^{-1}(0)}$ the same as the subbundle spanned by vector fields generated by infinitesimal \mathfrak{g} -actions. It follows the quotient space $M:=\mu^{-1}(0)/G$ endows a symplectic orbifold structure, which is referred as the well-known Marsden-Weinstein symplectic reduction in literature.

To do the Hamiltonian Gromov-Witten or Floer theory for (X,ω) and its symplectic reductions, one needs to assign an almost complex structure J on X which is compatible with the Hamiltonian group action. In this paper, we choose and fix a such J such that it is G-invariant and ω -compatible (such almost complex structure always exists due to the compactness of the G and the existence of compatible almost complex structure for any symplectic manifold). The almost complex structure J then reduces to a compatible almost complex structure on the symplectic orbifold M. From now on, we use the sextuple (X,ω,J,G,μ,M) to denote the geometric structure described above, and use $(\bar{\omega},\bar{J})$ to denote the reduced almost Kähler structure on the orbifold M.

In general, on a symplectic orbifold and in particular now on the symplectic reduction $(M, \bar{\omega})$, the corresponding orbifold Gromov–Witten theory was developed by Chen-Ruan, which is now referred as the quantum Chen-Ruan orbifold theory (see [2] and the references therein). Chen-Ruan orbifold theory is a theory for the inertia orbifold which includes the information also from twisted sectors besides the orbifold itself. Any possible moduli space theory adapted to a symplectic *orbifold* must satisfy the property that any finite energy curve should converge to (un)twisted sectors at ends. (The Fan-Jarvis-Ruan-Witten theory [7] which is analogous to the orbifold Gromov–Witten theory is another strong evidence for the importance of considering the twisted sectors.)

In the paper [3], the authors set up a new quantum cohomology ring structure for the symplectic reduction $(M, \bar{\omega})$ using the symplectic vortex equations attached to $(X, \omega, J, G, \mu, M)$. In particular, they prove that a finite energy L^2 -symplectic vortex (i.e., a symplectic vortex with cylinder metric at each punctured end) (exponentially) converges to (un)twisted sectors at ends after some gauge transformations. This is an essential step in setting up the L^2 -HGW (HGW is short for Hamiltonian Gromov–Witten) moduli space which is used to define a quantum cohomology field theory for the symplectic reduction $(M, \bar{\omega})$ ([4]). In this paper, we generalize the results on the asymptotic convergence of a finite energy symplectic vortex to more general types of metrics which we name admissible metrics, i.e., the Kähler metrics on the Riemann surface which are of the form

$$e^{2bt}(dt^2 + d\theta^2), \quad b > 0$$

on each cylinder end $[0, \infty) \times S^1$.

By a critical loop (see Definition 4.3) of a constant connection, we mean a loop in $X \times \mathfrak{g}$ of the form

$$x_{\infty} = (\exp(-\theta \eta_{\infty})z_0, \eta_{\infty}), \quad z_0 \in \mu^{-1}(0), \eta_{\infty} \in \mathfrak{g},$$

which can be identified with a point in an (un)twisted sector of the symplectic orbifold M. We prove in this paper that

Theorem 1.1 Assume (P, w) = (P, u, A) is an admissible finite energy symplectic vortex over the punctured Riemann surface $(\dot{\Sigma}, j, h)$ with k-punctures. Then there exist some gauge transformation $\Phi \in \mathcal{G}_P$, k critical loops $x_{\infty}^i = (z_{\infty}^i, \eta_{\infty}^i)$ of constant connections, $i = 1, \dots, k$, and some constants C > 0, $\delta_i > 0$, $i = 1, \dots, k$, which only depend on $(X, \omega, G, \mu, J, M)$, such that $\Phi \cdot w = (\Phi^* u, \Phi^* A)$ is temporal and for any $\theta \in S^1$

- $(1) |d_{\Phi^*A}\Phi^*u(t,\theta)| \leq Ce^{-\delta t},$
- (2) $|\mu(\Phi^*u)(t,\theta)| \le Ce^{-\delta t bt}$,
- (3) $|F_{\Phi^*A}(t,\theta)| \leq Ce^{-\delta t + bt}$,
- $(4) \quad \|\operatorname{dist}(\Phi \cdot u(t,\cdot), z_{\infty}(\cdot))\|_{L^{p}(S^{1})} + \|\Phi^{*}A(t,\cdot) \eta_{\infty}(\cdot)\|_{L^{p}(S^{1})} \leq Ce^{-(\delta + b(\frac{2}{p} 1))t}, \text{ for } p \geq 2 \text{ and } \delta + b(\frac{2}{p} 1) > 0.$

Here we use z_{∞} , η_{∞} , δ , b to denote the ones with corresponding superscripts i's, $i = 1, \dots, k$.

Moreover, such δ_i 's can be taken as any positive number which is smaller than $\frac{1}{|\text{Hol}_{\eta_i}|}$, where $|\text{Hol}_{\eta_i}|$ is the order of the holonomy of the connection form η_i .

In particular, this proves the convergence of a finite energy symplectic vortex with admissible metric to the (un)twisted sectors of the symplectic reduction M at punctured ends after some gauge transformation. The convergence is exponentially fast with some rate related to the first non-vanishing eigenvalue of certain (formal) Hessian operator (see Proposition 4.8). We refer readers to Proposition 4.8, Proposition 6.1 and Corollary 6.2 for more concrete and detailed results for Theorem 1.1.

By using an approach which is different from Ziltener's [23, 24] together with the study of the orbifold structure of symplectic reduction, from the technical point of view, Theorem 1.1 generalizes the following existed results for finite energy symplectic vortices:

- (1) It generalizes Ziltener's asymptotic convergence results in [23, 24] by removing the assumption that the Lie group G-action on $\mu^{-1}(0)$ is free. (We remark that a proof for affine vortices in compact Kähler manifolds or \mathbb{C}^n was sketched by Venugopalan-Woodward in [16, Section 4, 5].)
- (2) It generalizes the authors' results in [3] (which corresponds to b = 0) by including other admissible metrics with b > 0. In particular, the current result includes the affine metric, i.e., the case of b = 1.

In fact, it is well-known to experts that one can expect certain exponential convergence of finite energy solutions from evolution type elliptic PDEs which are translation invariant, under the Morse–Bott condition. The translation invariant property corresponds to the cylindrical metric, i.e., b=0, here. For such case, usually one obtains a subsequence convergence first and then recover the C^0 exponential convergence with the help of the Morse–Bott condition. However, this method fails for non-translation invariant equations, which correspond to the case b>0. In this paper, to deal with all admissible metrics, i.e., $b\geq 0$, we present a general strategy which is different from [23, 24]. In particular in the proof we emphasize the only two ingredients in obtaining the exponential convergence: the a priori estimates and the Morse–Bott condition. This framework can be also applied to other evolution type elliptic PDEs than the one considered in this paper, though the interplay of these two ingredients might need to be modified.

From the application point of view, Theorem 1.1 is a basic step in constructing the quantum Kirwan morphism proposed by the authors (see [3, 4, 5]). Besides, the general setup in the proof, in particular the geometric understanding near the level set $\mu^{-1}(0)$, is necessary in constructing various moduli space theories related to symplectic reductions, including in the authors' work on the construction of quotient morphism moduli space in [6].

Remark 1.2 (Historical remark on symplectic vortices in symplectic topology) Using symplectic vortices to study the symplectic topology for symplectic manifolds admitting Hamiltonian Lie group action starts from the pioneering work by Cieliebak-Gaio-Salamon [1] and independently by Mundet-i-Riera [11, 12] around 2000. In particular, a proposal on quantum Kirwan morphism was suggested by Gaio-Salamon in [10] and then was developed by Ziltener [25], Woodward [19, 20, 21] in algebraic geometry setup and claimed recently by Tian-Xu in the expository article [14] for Kähler manifolds with reductive group actions. (Other related work on symplectic vortices, e.g., on gauged Hamiltonian Floer theory and gauged Lagrangian Floer theory, see also [8, 9, 22, 17].)

We remark that our approach in quantum Kirwan morphism proposed in [3, 4, 5] is essentially different from the approach above based on [10], though some technical results, including the current one, are recyclable.

The organization of the paper is as follows:

- In Section 2, we introduce the definition of finite energy symplectic vortices with admissible metrics.
- In Section 3, we set-up a normal form near the regular level set $\mu^{-1}(0)$ using the equivaraint Darboux theorem.
- In Section 4, we explain the structure of the space of critical loops and its relation to (un)twisted sectors of the orbifold *M*.
- In Section 5, based on the normal form induced in Section 3, we introduce an action function for a fixed map and derive an isoperimetric type inequality for it. Then we relate this action function to the Yang-Mills-Higgs energy for a symplectic vortex. After these preparations, one is able to obtain the exponential energy density decay for finite energy symplectic vortices with admissible metrics. The derivation is included in Section 6.

• In Section 6, we state and prove another useful interpretation for the asymptotic convergence result as Proposition 6.1, and then give the proof of Theorem 1.1.

The conventions we use in this paper are as follows:

- For the Lie group G, its Lie algebra structure on $\mathfrak{g} = T_e G$ is defined via the Lie bracket of left invariant vector fields on G. Any G-principal bundle is a right principal bundle, so the action of G is from the right.
- The group G-action on X is from the left, denoted by ℓ_g . The tangent map of the G-action on X is denoted by $\ell_{g*}: T_xX \to T_{gx}X$.
- We use $\exp: \mathfrak{g} \to G$ to denote the exponential map for the Lie group G. The infinitesimal vector field generated by $\xi \in \mathfrak{g}$ is defined as

$$X_{\xi}(x) := \frac{d}{d\epsilon}\Big|_{\epsilon=0} \exp(\epsilon \xi)x.$$

Note that $[X_{\xi}(x), X_{\eta}(x)] = -X_{[\xi, \eta]}(x)$ as $X_{\xi}(x)$ is defined by the right invariant field associated to $\xi \in \mathfrak{g}$.

• For $\Phi \in \operatorname{Aut}(P)$, where $\operatorname{Aut}(P)$ is the gauge transformation group of the G-principal bundle P, it acts on any pair of a G-equivariant map $u_G : P \to X$ and a connection A via pulling back, i.e.,

$$\Phi \cdot (u_G, A) = (\Phi^* u_G, \Phi^* A).$$

In particular, when $P \cong D \times G$ is trivial, here D could be a surface or S^1 in this paper, Φ will be identified with a map $g: D \to G$ and the (u_G, A) pair will be identified with the pair $(u, \eta) \in C^{\infty}(D, X) \times \Omega^1(D, \mathfrak{g})$. Then

$$g \cdot (u, \eta) = (\ell_{g^{-1}}(u), Ad_{g^{-1}}\eta + g^{-1}dg).$$

The Lie algebra of Aut(P) is $\Omega^0(P^{\mathrm{Ad}})$, the section of the associated bundle for the adjoint action Ad : $G \to GL(\mathfrak{g})$. The infinitesimal action of $\xi \in \Omega^0(P^{\mathrm{Ad}})$ at (u, η) is given by $(-X_{\xi}, d\xi + [\eta, \xi])$.

2 The finite energy symplectic vortices with admissible metrics

2.1 The symplectic vortices with admissible metrics

Assume (Σ, j) is a genus g_{Σ} smooth closed Riemann surface with k ordered marked points. Denote by $(\dot{\Sigma}, j)$ the punctured one by removing all marked points.

Definition 2.1 A Kähler metric h on $(\dot{\Sigma},j)$ is called *admissible*, if for each marked point p_i in Σ , $i=1,\cdots,k$, there exists a neighborhood U_i of p_i in Σ such that the Kähler structure of the end $(E_i:=U_i\setminus\{p_i\},j,h|_{E_i})$ is isometric to $([0,\infty)\times S^1,j_0,e^{2b_it}(dt^2+d\theta^2))$ with $b_i\geq 0$, $i=1,\cdots,k$. Here j_0 denotes the standard complex structure on cylinder, i.e., $j_0(\frac{\partial}{\partial t})=\frac{\partial}{\partial \theta},j_0(\frac{\partial}{\partial \theta})=-\frac{\partial}{\partial t}$ with $t\in[0,\infty),\theta\in S^1$.

Assume P is a principal G-bundle over $\dot{\Sigma}$. Denote by $C_G^{\infty}(P,X)$ the set of smooth G-equivariant maps from P to X, and by A(P) the set of connection 1-forms on P. Denote by $Y = P \times_G X$ the associated bundle of X over $\dot{\Sigma}$, and by $P^{\mathrm{Ad}} := P \times_G \mathfrak{g}$ the adjoint bundle. Then one can identify $C_G^{\infty}(P,X)$ with the set of smooth sections of $Y \to \dot{\Sigma}$, and identify A(P) with $\Omega^1(\dot{\Sigma}, P^{\mathrm{Ad}})$.

A connection $A \in \mathcal{A}(P)$ induces a splitting of the tangent bundle of Y as

$$TY = H_A P \oplus (P \times_G TX),$$

with $H_AP := \ker A$ as the horizontal distribution of TP. Here the G-action on TX is induced from the G-action on X. Denote by Π_A the endomorphism of TY induced by the projection $\pi_A : TY \to P \times_G TX$ from this splitting.

The vector bundle $P \times_G TX \to \dot{\Sigma}$ carries the complex structure induced from the almost complex structure J, since J is assumed to be G-invariant. We still use J to denote this complex structure. Together with the horizontal lifting j_A on H_AP from the complex structure j on $\dot{\Sigma}$, Y carries an almost complex structure defined as

$$J_A := j_A \oplus J$$
.

For any map $u_G \in C_G^{\infty}(P, X)$, denote by u the corresponding section of $Y \to \dot{\Sigma}$. The A-twisted tangent map of u_G is defined as the u^*TY -valued 1-form over $\dot{\Sigma}$

$$d_A u := \Pi_A \circ du$$
.

Denote by $\overline{\partial}_A u$ the (0,1)-part of $d_A u$ with respect to the pair of complex structures (j,J_A) . In the context below, we do not distinguish u_G and u and readers should not be confused.

Remark 2.2 For a (local) trivialization $P|_U = U \times G$ with holomorphic coordinates (t, s) for U, locally

$$d_{A}u(\frac{\partial}{\partial t}) = \frac{\partial u}{\partial t} + X_{A(\frac{\partial}{\partial t})}, \quad d_{A}u(\frac{\partial}{\partial s}) = \frac{\partial u}{\partial s} + X_{A(\frac{\partial}{\partial s})}$$

and

$$\partial_{A}u = \frac{1}{2}(d_{A}u - J \circ d_{A}u \circ j)
= \frac{1}{2}[(\frac{\partial u}{\partial t} + X_{A(\frac{\partial}{\partial t})}) - J(\frac{\partial u}{\partial s} + X_{A(\frac{\partial}{\partial s})})]dt + \frac{1}{2}J[(\frac{\partial u}{\partial t} + X_{A(\frac{\partial}{\partial t})}) - J(\frac{\partial u}{\partial s} + X_{A(\frac{\partial}{\partial s})})]ds
\overline{\partial}_{A}u = \frac{1}{2}(d_{A}u + J \circ d_{A}u \circ j)
= \frac{1}{2}[(\frac{\partial u}{\partial t} + X_{A(\frac{\partial}{\partial t})}) + J(\frac{\partial u}{\partial s} + X_{A(\frac{\partial}{\partial s})})]dt + \frac{1}{2}J[(\frac{\partial u}{\partial t} + X_{A(\frac{\partial}{\partial t})}) + J(\frac{\partial u}{\partial s} + X_{A(\frac{\partial}{\partial s})})]ds.$$

Definition 2.3 A symplectic vortex over $(\dot{\Sigma}, j, h)$ is a smooth principal G-bundle P over $\dot{\Sigma}$ together with a pair of maps $w := (u, A) \in C^{\infty}_{G}(P, X) \times \mathcal{A}(P)$ which satisfies the following nonlinear PDEs

$$\overline{\partial}_A u = 0$$

$$(2) F_A + *_h \mu(u) = 0,$$

where $*_h$ is the Hodge * operator with respect to the Kähler metric h.

If moreover h is admissible, we say (P, w) is a symplectic vortex with admissible metric.

2.2 The Yang-Mills-Higgs (YMH) energy

The Yang-Mills-Higgs (YMH) energy is a functional defined for pairs (P, w) with P a G-principal bundle over $\dot{\Sigma}$ and $w = (u, A) \in C_G^{\infty}(P, X) \times \mathcal{A}(P)$ as

(3)
$$E(P, u, A) := \int_{\hat{\Sigma}} e(P, u, A) \nu_h$$
$$e(P, u, A) := \frac{1}{2} (|d_A u|_h^2 + |F_A|_h^2 + |\mu \circ u|_h^2),$$

where ν_h is the volume form of $(\dot{\Sigma}, h)$, and $|\cdot|_h$ denotes the norm induced by the Kähler metric h and the corresponding target metrics for (vector valued) forms over $\dot{\Sigma}$. We omit YMH and only call it the energy if no confusion could happen. The function $e(P, u, A) : \dot{\Sigma} \to [0, \infty)$ is called the (YMH) energy density.

The equality

(4)
$$e(P, u, A)\nu_h = (|\overline{\partial}_A u|_h^2 + \frac{1}{2}|F_A + *_h \mu(u)|_h^2)\nu_h + (u^*\omega - d\langle \mu(u), A\rangle)$$

characterizes the key feature of the YMH energy density and in particular indicates that the YMH energy is the right energy in studying symplectic vortices. To be more concrete,

- (1) The first term $(|\overline{\partial}_A u|_h^2 + \frac{1}{2}|F_A + *_h \mu(u)|_h^2)\nu_h$ in (4) vanishes if and only if (P, u, A) is a symplectic vortex over $(\dot{\Sigma}, j, h)$;
- (2) The integral of the second term $u^*\omega d\langle \mu(u), A \rangle$ in (4) is a topological invariant, whenever the pair (P, w) have a nice asymptotic behavior (e.g., as the asymptotic convergence proved in this paper).

The derivation of (4) which is given in [1, Proposition 3.1] is based on the following two identities whose proofs are straightforward. In particular, when take trivial connection A = 0, this recovers the corresponding identities for symplectic manifolds.

Lemma 2.4 (1)
$$|d_A u|_h^2 = |\partial_A u|_h^2 + |\overline{\partial}_A u|_h^2 + 2\langle F_A, *_h(\mu \circ u) \rangle$$
;

(2)
$$u^*\omega - d\langle \mu \circ u, A \rangle = \frac{1}{2}(|\partial_A u|_h^2 - |\overline{\partial}_A u|_h^2)\nu_h.$$

By a *finite energy symplectic vortex* over $(\dot{\Sigma}, j, h)$, we mean that a symplectic vortex (P, w) whose YMH energy is finite.

2.3 The gauge action

From now on, we fix a punctured Riemann surface $(\dot{\Sigma}, j)$ with a chosen Kähler metric h as domain. Moreover, we fix a principal G-bundle $P \to \dot{\Sigma}$, and so we omit P from the pair (P, w) if there is no danger of confusion. Denote by $\mathcal{G} := \mathcal{G}_P$ the gauge transformation group of P, and denote by

$$\mathcal{B} := \mathcal{B}_P := C_G^{\infty}(P, X) \times \mathcal{A}(P).$$

The gauge action on P induces the \mathcal{G} -action on \mathcal{B} as

$$\Phi \cdot w = (\Phi^* u, \Phi^* A).$$

Regarding this gauge action, it is clear that

Lemma 2.5 For any $w \in \mathcal{B}$ and any $\Phi \in \mathcal{G}$,

- (1) $E(\Phi \cdot w) = E(w)$;
- (2) $\Phi \cdot w$ is a symplectic vortex if w is a symplectic vortex.

Assume (P, u, A) is a symplectic vortex over $(\dot{\Sigma}, j, h)$. Over each end E_i identified with $[0, \infty) \times S^1$, $i = 1, \dots, k$, where k is the number of punctures, we can take a global trivialization of $P|_{E_i} \to E_i$ and after this trivialization, the connection on $P|_{E_i}$ can be identified with some $A_i = A_{i,1}(t,\theta) dt + A_{i,2}(t,\theta) d\theta$, $(t,\theta) \in [0,\infty) \times S^1$, where

$$A_{i,1}, A_{i,2}: [0,\infty) \times S^1 \to \mathfrak{g}.$$

It is clear from the ODE theory that one can always find a (unique) smooth gauge transformations $\Phi_i \in \mathcal{G}_{P|E_i} \cong C^{\infty}([0,\infty) \times S^1, G)$ and some $\eta_i : [0,\infty) \times S^1 \to \mathfrak{g}$, such that

$$\Phi_i^* A_i = \eta_i(t, \theta) d\theta, \quad \Phi_i(0, \cdot) \equiv e.$$

Such connection of the form $\eta(t,\theta) d\theta$ is called a temporal connection over $[0,\infty) \times S^1$. Obviously, one can always find a gauge transformation $\Phi \in \mathcal{G}_P$ whose restriction on each end is Φ_i . Then for every connection $A \in \mathcal{A}(P)$, there exists some gauge transformation to make A be temporal at each end. In particular, when w = (u,A) is a symplectic vortex and A is temporal at each end, we call w a temporal symplectic vortex.

3 The normal form near $\mu^{-1}(0)$

In this section, we describe a normal form for the symplectic manifold (X, ω) that admits the Hamiltonian G-action with moment map μ near a small G-invariant tubular neighborhood of $\mu^{-1}(0)$. The construction will be used for a better understanding of the formal Hessian operator defined in Section 4 as well as in the later definition of the local functional in Section 5.

For every $x \in X$, we denote by $L_x : \mathfrak{g} \to T_x X$ the infinitesimal action of the Lie algebra \mathfrak{g} , i.e.,

$$L_{x}(\xi) := X_{\xi}(x)$$

to emphasize the role as a linear operator.

The assumption that 0 is a regular value of the moment map leads to the following well-known decomposition of $T_z\mu^{-1}(0)$ at any $z \in \mu^{-1}(0)$. We summarize them as in the following lemma and also fix some notations.

Lemma 3.1 Assume 0 is a regular value of the moment map μ . Then for any $z \in \mu^{-1}(0)$, L_z is injective and

$$T_z \mu^{-1}(0) = \ker d_z \mu = (\operatorname{Img}(JL_z))^{\perp},$$

where \perp denotes the orthogonal complement with respect to the metric $\omega(\cdot, J \cdot)$ for X. Further, $T_z \mu^{-1}(0)$ has the decomposition

$$(5) T_z \mu^{-1}(0) = \operatorname{Img}(L_z) \oplus H_z,$$

where $H_z := \ker(d_z \mu \circ J) = (\operatorname{Img}(L_z))^{\perp} \cap T_z \mu^{-1}(0)$. The splitting (5) is *G*-invariant.

We use $\operatorname{pr}_G: T_z\mu^{-1}(0) \to \operatorname{Img}(L_z)$ to denote the projection from the decomposition (5).

Now we consider the vector bundle

$$N := \operatorname{Img}(JL) \to \mu^{-1}(0),$$

and denote by N^{ϵ} a tubular neighborhood of the zero section, where $0 < \epsilon < \inf_{z \in \mu^{-1}(0)} i_z$ with i_z the injective radius of the exponential map defined using the metric $\omega(\cdot, J \cdot)$. Here, $\inf_{z \in \mu^{-1}(0)} i_z > 0$ due to the properness of moment map μ .

It follows that the exponential map \exp^{∇} induced from the Levi-Civita connection defines a local diffeomorphism

$$\exp^{\nabla}: N^{\epsilon} \to X, \quad JL_z(\xi) \mapsto \exp^{\nabla}_z(JL_z(\xi)).$$

We use $\mathcal{U}^{\epsilon} \subset X$ to denote its image. In particular the image of the zero section is $\mu^{-1}(0) \subset \mathcal{U}^{\epsilon}$. Notice that the pull-back *G*-action on *X* behaves as

(6)
$$g(z, JL_z(\xi)) = (gz, JL_{gz}(Ad_g(\xi)))$$

due to the G-variance of the almost Kähler structure. By suitable shrinking of ϵ , we can further assume \mathcal{U}^{ϵ} (so is N^{ϵ}) is G-invariant.

By the pulling back of the exponential map, we identify $(\mathcal{U}^{\epsilon} := \exp^{\nabla}(N^{\epsilon}), \omega|_{\mathcal{U}^{\epsilon}}, G, \mu|_{\mathcal{U}^{\epsilon}}, J)$ with

$$(N^{\epsilon}, (\exp^{\nabla})^*(\omega|_{\mathcal{U}^{\epsilon}}), G, (\exp^{\nabla})^*(\mu|_{\mathcal{U}^{\epsilon}}), (\exp^{\nabla})^*J).$$

To simplify notations, we omit the notation of pull-backs by \exp^{∇} and use $(N^{\epsilon}, \omega, G, \mu, J)$ to denote the corresponding structures on the tubular neighborhood N^{ϵ} .

Now we construct a symplectic form on N^{ϵ} as follows. Denote by \mathcal{F}_G the foliation on $\mu^{-1}(0)$ defined by the vector field Img(L), and notice that there is a natural bundle map

$$\iota_G: \operatorname{Img}(JL) \to T^*\mathcal{F}_G, \quad \iota_G(z, JL_z(\xi)) = \iota_{JL(\xi)}\omega|_z := (z, \omega(JL_z(\xi), \cdot)).$$

We use it to pull back the canonical one-form Θ_G on $T^*\mathcal{F}_G$ and then obtain

$$\Omega_G := \iota_G^*(d\Theta_G) \in \Omega^2(\mathrm{Img}(JL)).$$

Define a closed two-form on N^{ϵ} as

$$\omega_0 := \pi^* \omega|_{\mu^{-1}(0)} + \Omega_G.$$

From the construction, we have the following lemma.

Lemma 3.2 (1) $\omega_0|_{\mu^{-1}(0)} = \omega|_{\mu^{-1}(0)}$, hence ω_0 is a symplectic form whenever ϵ is a small enough;

(2) The G-action on N^{ϵ} is Hamiltonian with respect to ω_0 , whose moment map μ_0 satisfies $\mu_0(JL_z(\xi)) = \xi$.

We call $(N^{\epsilon}, \omega_0, G, \mu_0)$ the normal form near the level set $\mu^{-1}(0)$. Regarding it, we have the following equivariant Weinstein-Darboux theorem.

Proposition 3.3 For sufficiently small $\epsilon > 0$, there exists a G-equivariant diffeomorphism

$$\phi: N^{\epsilon} \to N^{\epsilon}$$
,

such that

(7)
$$\phi^* \omega = \omega_0, \quad \phi^* \mu = \mu_0, \quad \phi|_{\mu^{-1}(0)} = \mathrm{id}_{\mu^{-1}(0)},$$

(8)
$$d\phi|_{TN^{\epsilon}|_{\mu^{-1}(0)}} = \mathrm{id}|_{TN^{\epsilon}|_{\mu^{-1}(0)}}.$$

Proof Equalities in (7) immediately follow from the standard equivariant Darboux theorem (e.g., see [18]) and only (8) is based on the current symplectic reduction condition whose proof we are giving now.

To show (8), we take $\{\xi_i\}_{i=1,\cdots,\dim(G)}$ as a chosen basis for \mathfrak{g} . Because $\phi^*\mu=\mu_0$ on $\mu^{-1}(0)$, we can find smooth functions $f_i:\mathcal{U}^\epsilon\to\mathbb{R}$ for $i=1,\cdots,\dim(G)$ with $f_i|_{\mu^{-1}(0)}\equiv 1$, such that

$$\langle \phi^* \mu, \xi_i \rangle = f_i \langle \mu_0, \xi_i \rangle, \quad i = 1, \cdots, \dim(G).$$

Then by taking differential, we obtain

$$\langle \phi^* d\mu, \xi_i \rangle = d \langle \phi^* \mu, \xi_i \rangle = \langle \mu_0, \xi_i \rangle df_i + f_i \langle d\mu_0, \xi_i \rangle.$$

When restricted to $\mu^{-1}(0) = \mu_0^{-1}(0)$, the first term of right hand side vanishes, and the second term of right hand side becomes $\langle d\mu_0, \xi_i \rangle$. Hence it follows

$$\phi^* d\mu|_{\mu^{-1}(0)} = d\mu_0|_{\mu^{-1}(0)},$$

and then $d\phi|_{TN^{\epsilon}|_{\mu^{-1}(0)}}=\operatorname{id}|_{TN^{\epsilon}|_{\mu^{-1}(0)}}$ since $d_{z}\mu$ is an isomorphism when restricted to $\operatorname{Img}(JL)$.

Proposition 3.3 guarantees us to assume the target space as

$$(N^{\epsilon}, \omega_0, G, \phi^* J, \mu_0)$$

by looking at the map (ϕ^*u, A) , whenever u falls into the tubular neighborhood N^{ϵ} of $\mu^{-1}(0)$. In particular, we notice (8) ensures that $\phi^*J = J$ on $\mu^{-1}(0)$. Later in Section 5, when we work under such normal form, we assume everything is pulled back via some ϕ and omit such ϕ .

4 The gauge theory over S^1

4.1 The gauged loops and the holonomy

We fix a principal G-bundle P_{S^1} over S^1 . It is always trivial since G is connected. Denote by $\mathcal{B}_{S^1} := C_G^\infty(P_{S^1}, X) \times \mathcal{A}(P_{S^1})$, which can be identified with the space of loops in $X \times \mathfrak{g}$ after fixing a trivialization. Denote by \mathcal{G}_{S^1} the gauge transformation group of P_{S^1} , which can be identified with the loop space of G. We use $LX, LG, L\mathfrak{g}$ to denote loop spaces of X, G, \mathfrak{g} respectively, and use L_0G to denote the based gauge group, i.e, the normal subgroup of LG whose elements satisfy g(0) = e.

The gauge group LG acts on $LX \times L\mathfrak{g}$ as

$$g \cdot y = g \cdot (x, \eta) = (g^{-1}x, \mathrm{Ad}_{g^{-1}}\eta + g^{-1}\dot{g}).$$

For a fixed $g \in LG$, the tangent map is

$$dg|_{y}(v,\xi) = ((\ell_{g^{-1}})_{*}(v), \mathrm{Ad}_{g^{-1}}\xi),$$

for $v \in C^{\infty}(S^1, z^*TX)$, $\xi \in L\mathfrak{g}$.

The infinitesimal action of the Lie algebra of LG, which is the same as $T_e(LG) = L\mathfrak{g}$, is

(9)
$$\frac{d}{d\epsilon}\Big|_{\epsilon=0} (\exp(\epsilon\tau) \cdot y) = (-X_{\tau}(z), \dot{\tau} + [\eta, \tau]).$$

Here $\dot{\tau}$ is the short notation for $\frac{d\tau}{d\theta}$. Clearly the based gauge L_0G acts freely on $L\mathfrak{g}$ (hence freely on $LX \times L\mathfrak{g}$) by the uniqueness result for ODEs. Moreover, it is well-known that orbit space is in fact G and the quotient map maps every connection to its holonomy. Now for later use, we make this construction explicit.

Consider the horizontal path $\Psi: [0, 2\pi] \to G$ as

(10)
$$d_{\eta}\Psi = \Psi' + \eta\Psi = 0, \quad \Psi(0) = e.$$

It is a linear ODE thus has a unique solution which we denote by $\Psi_{\eta}:[0,2\pi]\to G$. The group element $\Psi_{\eta}(1)=:\operatorname{Hol}_{\eta}$ is the holonomy of the connection η . Notice that $\Psi_{g\cdot\eta}=g^{-1}\Psi_{\eta}$, and in particular this indicates the holonomy is L_0G -invariant.

Since we assume that G is connected and compact, the exponential map of the Lie group G is surjective. We can choose $\log \operatorname{Hol}_{\eta} \in \mathfrak{g}$ such that $\exp(\log \operatorname{Hol}_{\eta}) = \operatorname{Hol}_{\eta}$. Define a based gauge transformation as

(11)
$$h_n(\theta) := \Psi_n(\theta) \exp(-\theta \log \operatorname{Hol}_n) \in L_0 G.$$

It follows

$$h'_{\eta} + \eta h_{\eta} - h_{\eta} \eta = 0$$

$$h_{g \cdot \eta}(\theta) = g^{-1}(\theta) h_{\eta}(\theta)$$

$$h_{\eta} \cdot \eta = -\log(\text{Hol}_{\eta}).$$

In particular, it maps η to the constant connection $-\log(\text{Hol}_{\eta})$ with the same holonomy. Notice that this constant connection may not be unique.

The following remark will be used later in Section 5.

Remark 4.1 Considering the principal L_0G -bundle $L\mathfrak{g}$ over G, for any smooth path $h:(a,b)\to G$, we can take a piecewise smooth path, with at most finitely many non-continuous points, of *constant* loops in $L\mathfrak{g}$ as $\eta:(a,b)\to\mathfrak{g}$ such that

$$\operatorname{Hol}_{\eta(t)} = h(t).$$

We use Log(h) to denote a taken choice though the choice is not canonical.

Next we calculate the slice of the full gauge LG-action on $\mathcal{B}_{S^1} = LX \times L\mathfrak{g}$. Since both the metric on X and the Killing metric on the Lie group are G-invariant, it follows the induced L^2 -metric on \mathcal{B}_{S^1} defined as

$$\|(v,\xi)\|_{L^2}^2 = \int_{S^1} (|v|^2 + |\xi|^2) d\theta$$

for $y = (x, \eta) \in \mathcal{B}_{S^1}$ and $(v, \xi) \in T_y \mathcal{B}_{S^1} = \Gamma(S^1, x^*TX) \times L\mathfrak{g}$, is gauge LG-invariant.

Denote the L^2 -decomposition as

$$T_{\mathcal{V}}\mathcal{B}_{S^1} = \mathcal{V}_{\mathcal{V}} \oplus T_{\mathcal{V}}(\mathrm{Orb}_{\mathcal{G}_{S^1}}(y)),$$

where $\operatorname{Orb}_{\mathcal{G}_{S^1}}(y)$ denotes the gauge orbit at $y = (x, \eta) \in \mathcal{B}_{S^1}$ and \mathcal{V}_y is the L^2 -orthogonal complement of $T_y(\mathcal{G}_{S^1} \cdot y)$. Denote by $\Pi_{\mathcal{V}_y}$ the \mathcal{V}_y -projection.

Lemma 4.2 For any $y = (x, \eta) \in \mathcal{B}_{S^1}$, then

$$\mathcal{V}_{y} = \{(v, \xi) \in \Gamma(S^{1}, x^{*}TX) \times L\mathfrak{g} | d\mu \circ J(v) + \dot{\xi} + [\eta, \xi] = 0\}$$

and it is $\mathcal{G}_{S^1}(y)$ -invariant, where $\mathcal{G}_{S^1}(y)$ denotes the isotropy group (stabilizer) at y which is isomorphic to a subgroup of $G_{x(0)}$. Hence the isotropy group $\mathcal{G}_{S^1}(y)$ is finite whenever $G_{x(0)}$ is finite.

Proof Take any $y = (x, \eta) \in \mathcal{B}_{S^1}$, we have shown that the infinitesimal action of $\tau \in \text{Lie}(\mathcal{G}_{S^1})$ on y is $(-X_{\tau}(x), \dot{\tau} + [\eta, \tau])$. It follows that $(v, \xi) \in \mathcal{V}_v$ if and only if

$$\int_{\mathbb{S}^1} (\omega(-X_\tau(x), J\nu) + \langle \dot{\tau} + [\eta, \tau], \xi \rangle) d\theta = 0$$

for any $\tau \in \text{Lie}(\mathcal{G}_{S^1})$. Using the G-invariance property of the metrics, this is further equivalent to

$$\int_{\mathcal{S}^1} \langle d\mu \circ J(\nu) + \dot{\xi} + [\eta, \xi], \tau \rangle d\theta = 0$$

for any $\tau \in \text{Lie}(\mathcal{G}_{S^1})$, and hence

$$d\mu \circ J(v) + \dot{\xi} + [\eta, \xi] = 0.$$

Since the L^2 metric on \mathcal{B}_{S^1} is \mathcal{G}_{S^1} -invariant, it follows $\mathcal{V} \to \operatorname{Orb}_{\mathcal{G}_{S^1}}(y)$ is a \mathcal{G}_{S^1} -equivariant bundle and \mathcal{V}_y is $\mathcal{G}_{S^1}(y)$ -invariant.

To calculate the isotropy group $\mathcal{G}_{S^1}(y)$, we notice that for any $g \in LG$, g fixes $y = (x, \eta)$ if and only if

$$g(s) \in G_{x(s)}, \quad g' + \eta g - g\eta = 0, \quad s \in [0, 1].$$

By the uniqueness result of ODEs with initial conditions, the group homomorphism

$$\mathcal{G}_{S^1}(y) \mapsto G_{x(0)}, \quad g \mapsto g(0)$$

is injective. Hence $\mathcal{G}_{S^1}(y)$ is a subgroup of $G_{x(0)}$. Here this $0 \in S^1$ can be replaced to any $\theta \in S^1$.

Near the regular level set $\mu^{-1}(0)$, one can find some constant $\epsilon_{\text{reg}} > 0$, such that the ϵ_{reg} neighborhood of $\mu^{-1}(0)$ is *G*-invariant and the *G*-action on it is locally free. Then it follows

$$\mathcal{B}_{S^{1},\epsilon_{\mathrm{reg}}} := \{ y = (x,\eta) \in LX \times L\mathfrak{g} | \mathrm{dist}(x,\mu^{-1}(0)) < \epsilon_{\mathrm{reg}} \}$$

is LG-gauge invariant, and the LG-gauge action is locally free from the above lemma.

Moreover, we can make $\epsilon_{\rm reg}$ small enough so that the isotropy groups of LG on $\mathcal{B}_{S^1,\epsilon_{\rm reg}}$ one-to-one correspond to (a subset of) conjugacy classes $\{\mu^{-1}(0)_{(H)}/G|(H)\in\Lambda\}$, where Λ denotes the set of conjugacy classes of isotropy groups of points in $\mu^{-1}(0)$ by G-action. Notice that the compactness of G and $\mu^{-1}(0)$ ensures that Λ is a finite set

For each $x \in \mu^{-1}(0)$, define

$$d_{x,G} := \inf_{k,k' \in G_x} \operatorname{dist}_G(k,k'),$$

where dist_G denotes the distance on G induced from the Killing metric. Since the Killing metric on G is adjoint invariant, d_x is constant on each conjugacy class (G_x) . Due to the finiteness of orbit types from the discussions above, the number

(12)
$$d_{\mu^{-1}(0),G} := \inf_{x \in \mu^{-1}(0)} d_{x,G} > 0.$$

We are going to use this property in Section 5.

4.2 The critical loops

Definition 4.3 A loop $y = (x, \eta) \in LX \times L\mathfrak{g}$ is called a *critical loop*, if it satisfies the following two equations

$$\mu \circ x \equiv 0, \quad \dot{x} + X_n(x) = 0.$$

Denote by Crit $\subset LX \times L\mathfrak{g}$ the set of all critical loops.

Denote by $\mathcal{E}_{S^1} \to \mathcal{B}_{S^1}$ a vector bundle with fiber at $y = (x, \eta) \in LX \times LG$ as

$$\mathcal{E}_{S^1}|_{v} = \Gamma(S^1, x^*TX \oplus \mathfrak{g}).$$

Define a section

$$\widetilde{\Upsilon}(y) := (\Upsilon(y), \mu(x)) := (\dot{x} + X_{\eta}(x), \mu(x)).$$

Then by definition, $Crit = \widetilde{\Upsilon}^{-1}(0)$.

Lemma 4.4 The section $\widetilde{\Upsilon}$ is gauge equivariant, i.e., for any $g \in LG$ and $y = (x, \eta)$

$$\widetilde{\Upsilon}(g \cdot y) = ((\ell_{g-1})_*(\Upsilon(y)), \operatorname{Ad}_{g^{-1}}\mu).$$

It follows then Crit is LG-invariant.

Proof Since μ is G-equivariant, $\mu(g^{-1}x) = \operatorname{Ad}_{g^{-1}}\mu(x)$. By a direct computation,

$$\begin{split} \Upsilon(g \cdot y) &= \frac{d}{d\theta} (g^{-1}x) + X_{g^{-1}\dot{g} + \mathrm{Ad}_g \eta} (g^{-1}x) \\ &= [(\ell_{g_{-1}})_* (\dot{x}) - X_{g^{-1}\dot{g}} (g^{-1}x)] + X_{g^{-1}\dot{g} + \mathrm{Ad}_g \eta} (g^{-1}x) \\ &= (\ell_{g_{-1}})_* (\dot{x} + X_{\eta}(x)) \\ &= (\ell_{g_{-1}})_* (\Upsilon(y)). \end{split}$$

Lemma 4.5 If $y = (x, \eta) \in \text{Crit}$, then the isotropy group $\mathcal{G}_{S^1}(y) \cong C_{G_{x(0)}}(\text{Hol}_{\eta})$, the centralizer of Hol_{η} in $G_{x(0)}$. In particular, it is finite and the isomorphism is given by

$$C_{G_{z(0)}}(\operatorname{Hol}_{\eta}) \to \mathcal{G}_{S^1}(y), \quad g_0 \mapsto g(\theta) = h_{\eta}(\theta)g_0h_{\eta}^{-1}(\theta),$$

where h_{η} is defined as in (11).

Proof From the proof of Lemma 4.2, we notice that for $g \in \mathcal{G}_{S^1}(y)$ the equation $g' + \eta g - g\eta = 0$ is equivalent to

$$\mathrm{Ad}_{\Psi_n^{-1}(s)}g(s) \equiv g(0)$$

for $\Psi:[0,2\pi]\to G$ satisfying (10). It follows $g(1)=\Psi_\eta(1)g(0)(\Psi_\eta(1))^{-1}$. Hence $g\in LG$ solves the equation $g'+\eta g-g\eta=0$ if and only if

$$\Phi_{\eta}(1)g(0)(\Psi_{\eta}(1))^{-1} = g(0), \text{ i.e., } Ad_{\text{Hol}_{\eta}}g(0) = g(0).$$

On the other hand, notice that whenever $g \in LG$ fixes η , i.e., satisfies the equation $g' + \eta g - g\eta = 0$, it automatically fixes x when $(x, \eta) \in Crit$. Moreover, given $g_0 \in G_{x(0)}$, by a direct calculation, we get

$$g(\theta) = h_{\eta}(\theta)g_0h_{\eta}^{-1}(\theta)$$

is a solution, which must be the unique solution.

Lemma 4.6 Assume $y = (z, \eta) \in \text{Crit}$ is a constant connection loop with $\eta \equiv \eta_0$. Then the linearization of the section Υ at y is

$$D_{\mathbf{v}}\widetilde{\Upsilon}(\mathbf{v},\xi) = (D_{\mathbf{v}}\Upsilon(\mathbf{v},\xi), d_{z}\mu),$$

with

$$D_{x}\Upsilon(v,\xi)(\theta) = (\mathcal{L}_{-X_{\eta_{0}}}v + X_{\xi(\theta)})(z(\theta))$$
$$= \frac{d}{ds}|_{s=0}\varphi_{-s*}v(z(\theta+s)) + X_{\xi(\theta)})(z(\theta)),$$

for any $v \in C^{\infty}(S^1, z^*TX) = T_z(LX)$, $\xi \in L\mathfrak{g} = T_{\eta}\mathfrak{g}$, $\theta \in S^1$. Here φ denotes the flow of the vector field $-X_{\eta_0}$. In particular, when $\eta_0 = 0$,

$$D_{\mathbf{v}}\Upsilon(\mathbf{v},\xi)(\theta) = \dot{\mathbf{v}}(\theta) + X_{\xi(\theta)}(z(\theta)).$$

Proof Clearly, $D_y \widetilde{\Upsilon} = (D_y \Upsilon, d_z \mu)$, and we now calculate $D_y \Upsilon$. We use a torsion free affine connection ∇ on X to do the calculation. The result turns out to be independent of connections when y is a critical loop with constant connection.

For any $v \in C^{\infty}(S^1, z^*TX) = T_z(LX), \xi \in L\mathfrak{g} = T_{\eta}\mathfrak{g}$,

$$D_{y}\Upsilon(v,\xi)(\theta) = \frac{d}{d\epsilon}|_{\epsilon=0} \operatorname{Par}_{z(\theta),z_{\epsilon}(\theta)}^{-1}(\Upsilon(z_{\epsilon},\eta_{\epsilon})(\theta)) \in T_{x(\theta)}X, \text{ for any } \theta \in S^{1},$$

where

$$z_{\epsilon}(\theta) := \exp_{z(\theta)}^{\nabla}(\epsilon v(\theta)), \quad \eta_{\epsilon}(\theta) := \eta(\theta) + \epsilon \xi(\theta),$$

and the parallel transport Par and the exponential map \exp^{∇} are defined by the affine connection ∇ . Further $D_y \Upsilon(\nu, \xi)(\theta)$ contains two terms from the expression of Υ , and they can be calculated using the torsion free property of the connection as follows.

The first term
$$= \frac{d}{d\epsilon}|_{\epsilon=0} \operatorname{Par}_{z(\theta),z_{\epsilon}(\theta)}^{-1}(\frac{d}{d\theta} \exp_{z(\theta)}(\epsilon v(\theta))) = \frac{Dv}{d\theta},$$
The second term
$$= \frac{d}{d\epsilon}|_{\epsilon=0} \operatorname{Par}_{z(\theta),z_{\epsilon}(\theta)}^{-1}(X_{\eta(\theta+\epsilon\xi(\theta))}(\exp_{z(\theta)}(\epsilon v(\theta)))$$

$$= -\frac{Dv}{d\theta} + X_{\xi(\theta)}(z(\theta)) + [\widetilde{\frac{\partial \Phi}{\partial \epsilon}}, X_{\eta(\theta)}]|_{\epsilon=0}(z(\theta)),$$

where $\frac{Dv}{d\theta}$ denotes the covariant derivative of the vector field v along the curve z, and $\frac{\widetilde{\partial \Phi}}{\partial \epsilon}$ denotes the local extension of the vector field $\frac{\partial \Phi}{\partial \epsilon}$ for

$$\Phi(\epsilon, \theta) := \exp^{\nabla}_{\zeta(\theta)}(\epsilon \nu(\theta)).$$

Sum them, we obtain

$$D_{y}\Upsilon(v,\xi)(\theta) = [\widetilde{\frac{\partial \Phi}{\partial \epsilon}}, X_{\eta(\theta)}]|_{\epsilon=0} + X_{\xi(\theta)}(z(\theta)).$$

In particular, when $\eta \equiv \eta_0$ is constant, the Lie bracket term $[\frac{\widetilde{\partial \Phi}}{\partial \epsilon}, X_{\eta(\theta)}]|_{\epsilon=0}$ can be expressed as the Lie derivative

$$[\frac{\widetilde{\partial \Phi}}{\partial \epsilon}, X_{\eta(\theta)}]|_{\epsilon=0} = (\mathcal{L}_{-X_{\eta_0}} \nu)(z(\theta)),$$

since

$$\varphi_t(z(\theta)) := z(\theta + t)$$

is the flow with initial point $z(\theta)$ of the vector field $-X_{\eta_0}$. Further we can write

$$(\mathcal{L}_{-X_{\eta_0}}\nu)(z(\theta)) = \frac{d}{ds}|_{s=0}\varphi_{-s*}\nu(z(\theta+s)).$$

The following lemma is useful for later derivation of the structure of $\ker D_{\nu} \widetilde{\Upsilon}$.

Lemma 4.7 If the vector field v along z is generated by the Lie algebra \mathfrak{g} , i.e.,

$$v(\theta) = X_{\zeta(\theta)}(z(\theta))$$

for some $\zeta: I \to \mathfrak{g}$ on some interval or S^1 , then we have

$$(\mathcal{L}_{-X_{\eta_0}}v)(z(\theta)) = X_{[\eta_0,\zeta(\theta)]}(z(\theta)) + X_{\frac{d\zeta}{d\theta}}(z(\theta)).$$

Proof Continue to the notation and the proof in the above Lemma 4.6. Notice that for our current case, the flow of the vector field $-X_{\eta_0}$ with initial point $z \in X$ can be explicitly expressed as

$$\varphi_t(z) = \exp(-t\eta_0)z, \quad t \in \mathbb{R},$$

hence we are able to calculate out $(\mathcal{L}_{-X_{\eta_0}} v)(z(\theta))$ explicitly as follows.

First, we have

$$\varphi_{-s*}\nu(z(\theta+s)) = \varphi_{-s*}[X_{\zeta(\theta+s)}(z(\theta+s))]$$

$$= \frac{d}{d\epsilon}|_{\epsilon=0}[\exp(s\eta_0)\exp(\epsilon\zeta(\theta+s))z(\theta+s)]$$

$$= X_{\exp(s\eta_0)\zeta(\theta+s)\exp(-s\eta_0)}(z(\theta)).$$

Then it follows

$$(\mathcal{L}_{-X_{\eta_0}} v)(z(\theta)) = \frac{d}{ds}|_{s=0} \varphi_{-s*} v(z(\theta+s))$$

$$= \frac{d}{ds}|_{s=0} X_{\exp(s\eta_0)\zeta(\theta+s)\exp(-s\eta_0)}(z(\theta))$$

$$= X_{\frac{d}{d\theta}\zeta}(z(\theta)) + X_{[\eta_0,\zeta(\theta)]}(z(\theta)).$$

The following proposition is a key observation in [3] and we restate it here.

Proposition 4.8 Assume $y = (z, \eta) \in \text{Crit}$ is a constant connection loop with $\eta \equiv \eta_0$.

(1) The space

$$\mathcal{X}(y) := \{ \mathcal{X}_{\tau} = (-X_{\tau}, \dot{\tau} + [\eta, \tau]) | \tau \in \text{Lie}(LG) = L\mathfrak{g} \}$$

(i.e., the space generated by infinitesimal $\mathrm{Lie}(LG)$ -actions, see (9)) lives in $\ker D_y \widetilde{\Upsilon}$. Decompose

$$\ker D_{y}\widetilde{\Upsilon} = \mathcal{X}(y) \oplus (\ker D_{y}\widetilde{\Upsilon} \cap \mathcal{V}_{y}).$$

Then $\ker D_y \Upsilon \cap \mathcal{V}_y$ is isomorphic to the tangent space of (un)twisted sectors $M^{(\text{Hol}(\eta_0))}$ of the orbifold M at [z(0)]. The isomorphism is explicitly constructed as in the following proof.

(2) The so-defined formal Hessian operator $\operatorname{Hess}_{v}(v,\xi) := (J\Upsilon(v,\xi), d_{z}\mu(v)),$

$$\operatorname{Hess}_{v}: L^{2}(S^{1}, z^{*}TX \oplus \mathfrak{g}) \to L^{2}(S^{1}, z^{*}TX \oplus \mathfrak{g})$$

with domain $W^{1,2}(S^1, z^*TX \oplus \mathfrak{g}) \subset L^2(S^1, z^*TX \oplus \mathfrak{g})$ is an unbounded essentially self-adjoint operator. Moreover, the restriction of Hessy on the L^2 -completion of \mathcal{V}_y is also essentially self-adjoint.

- (3) The spectrum of the restriction of Hess_y on $L^2(\mathcal{V}_y)$ contains only simple real eigenvalues which belong to $\{\frac{k}{|\operatorname{Hol}_n|}|k\in\mathbb{Z}\}.$
- **Proof** (1) The fact $\mathcal{X}(y) \subset \ker D_y \Upsilon$ immediately follows from Lemma 4.7. The elements $(v, \xi) \in \ker D_y \Upsilon \cap \mathcal{V}_v$ satisfy the following three equations:
 - (a) $\mathcal{L}_{-X_{\eta_0}} v + X_{\xi(\theta)} = 0;$
 - (b) $d_z \mu(v) = 0$;
 - (c) $d\mu \circ J(v) + \dot{\xi} + [\eta_0, \xi] = 0.$

Since 0 is a regular value of μ , the equation (b) indicates $v \in T\mu^{-1}(0)$. To make the geometry more clear, we split the proof by considering the trivial holonomy case and the nontrivial holonomy case.

The trivial holonomy case For this case, $\eta_0 = 0$, and the equation (a) and (c) become

$$\dot{v} + X_{\xi(\theta)} = 0$$
 and $d_z \mu(v) = 0$.

The infinitesimal action is free on $\mu^{-1}(0)$ together with ν being defined on S^1 forces $\xi \equiv 0$, and the second equation shows that $\nu \in \ker d_z \mu \circ J = H_{\nu}$.

By this way, such pair (v, ξ) corresponds to a vector living in the untwisted sector of the orbifold M.

The nontrivial holonomy case Denote by $\varphi_t(z) = \exp(-t\eta_0)z$ the flow with initial point z of the vector field $-X_{\eta_0}$ as before.

Define

$$\tilde{v}: S^1 \to T_{z(0)}\mu^{-1}(0), \quad \tilde{v}(t) = \varphi_{-t,*}(v(t)).$$

Here it lives in the subspace $T_{z(0)}\mu^{-1}(0)$ due to $\mu^{-1}(0)$ is G-invariant. The tangent space $T_{z(0)}\mu^{-1}(0)$ splits as

$$T_{z(0)}\mu^{-1}(0) = X_{\mathfrak{g}}(z(0)) \oplus H(z(0)),$$

where $X_{\mathfrak{g}}$ denotes the subspace generated by infinitesimal \mathfrak{g} -action and $H=\ker d\mu\circ J$ is defined as before. We write $\tilde{v}=\tilde{v}_G+\tilde{v}_H$ with respect to the decomposition. Due to the G-equivariance of μ and the G-invariance of J,

$$\begin{aligned}
v_H(\theta) &:= & \varphi_{\theta,*} \tilde{v}_H(\theta) \in H(z(\theta)), \\
v_G(\theta) &:= & \varphi_{\theta,*} \tilde{v}_G(\theta) \in X_{\mathfrak{g}}(z(\theta)), \quad \theta \in S^1.
\end{aligned}$$

As a result, equation (a) indicates $\frac{d}{d\theta}\tilde{v}_H=0$ and so $\tilde{v}_H\equiv \tilde{v}(0)$, which exactly means

$$v_H(0) = d \text{Hol}_{n_0}(v_H(0))$$

by the expression of φ_t , hence $v_H(0)$ lives in the tangent space of the fixed point set $\mu^{-1}(0)^{\text{Hol}_{\eta_0}}$ by Hol_{η_0} .

Next, we show $v_G \equiv 0$ and $\xi \equiv 0$. For this, write $v_G(\theta) = X_{\zeta(\theta)}$ for some $\zeta: S^1 \to \mathfrak{g}$ (by the assumption that 0 is a regular). Then apply Lemma 4.7, the equation (a) can be written as

$$X_{\frac{d}{d\theta}\zeta(\theta)} + X_{[\eta_0,\zeta(\theta)]} + X_{\xi(\theta)} = 0,$$

which is equivalent to

(13)
$$\frac{d}{d\theta}\zeta(\theta) + [\eta_0, \zeta(\theta)] + \xi(\theta) = 0.$$

Consider the $L^2(S^1)$ inner product,

$$0 = \int_{S^1} \langle \xi(\theta), \frac{d}{d\theta} \zeta(\theta) + [\eta_0, \zeta(\theta)] + \xi(\theta) \rangle d\theta$$
$$= -\int_{S^1} \langle \zeta(\theta), \frac{d}{d\theta} \xi(\theta) + [\eta_0, \xi(\theta)] \rangle d\theta + \|\xi\|_{L^2(S^1)}^2$$

Then by the slice equation (c), this becomes

$$0 = \int_{\mathbb{S}^1} \langle \zeta(\theta), d\mu \circ J(X_{\zeta(\theta)}) \rangle d\theta + \|\xi\|_{L^2(S^1)}^2 = \|X_{\zeta(\theta)}\|_{L^2(S^1, X)}^2 + \|\xi\|_{L^2(S^1)}^2,$$

which shows the vanishing of both ζ and ξ .

Clearly from the expression of $D_y\widetilde{\Upsilon}$, $\ker D_y\widetilde{\Upsilon} \cap \mathcal{V}_y$ is $\mathcal{G}_{S^1}(y)$ -invariant. Further recall from Lemma 4.2 (2) that $\mathcal{G}_{S^1}(y) \cong C_{G_{7(0)}}(\operatorname{Hol}_{\eta})$, these finish the proof of the first statement.

(2) Take any $(v_i, \xi_i) \in W^{1,2}(S^1, z^*TX \oplus \mathfrak{g}), i = 1, 2$, we calculate

$$\langle \operatorname{Hess}_{y}(v_{1}, \xi_{1}), (v_{2}, \xi_{2}) \rangle$$

$$= \int_{S^{1}} \langle J(\mathcal{L}_{-X_{\eta_{0}}}v_{1} + X_{\xi_{1}}), v_{2} \rangle + \int_{S^{1}} \langle d_{z}\mu(v_{1}), \xi_{2} \rangle$$

$$= -\int_{S^{1}} \langle \mathcal{L}_{-X_{\eta_{0}}}v_{1}, Jv_{2} \rangle - \int_{S^{1}} \langle X_{\xi_{1}}, Jv_{2} \rangle + \int_{S^{1}} \langle d_{z}\mu(v_{1}), \xi_{2} \rangle$$

$$= -\int_{S^{1}} d\langle v_{1}, Jv_{2} \rangle + \int_{S^{1}} \langle v_{1}, J\mathcal{L}_{-X_{\eta_{0}}}v_{2} \rangle - \int_{S^{1}} \langle X_{\xi_{1}}, Jv_{2} \rangle + \int_{S^{1}} \langle d_{z}\mu(v_{1}), \xi_{2} \rangle$$

$$= 0 + \int_{S^{1}} \langle v_{1}, J\mathcal{L}_{-X_{\eta_{0}}}v_{2} \rangle - \int_{S^{1}} \langle \xi_{1}, d_{z}\mu(v_{2}) \rangle + \int_{S^{1}} \langle \xi_{2}, d_{z}\mu(v_{2}) \rangle$$

$$= \langle \operatorname{Hess}_{v}(v_{1}, \xi_{1}), (v_{2}, \xi_{2}) \rangle.$$

Here we use the metric and J are both G-invariant, and z is the flow of $-X_{\eta_0}$ which is due to $(z,\eta_0) \in C$ rit. This shows $Hess_y$ is essentially self-adjoint as $Hess_y$ is symmetric with a dense domain $W^{1,2}(S^1,z^*TX\oplus \mathfrak{g})$ and $Hess_y:W^{1,2}(S^1,z^*TX\oplus \mathfrak{g})\to L^2(S^1,z^*TX\oplus \mathfrak{g})$ is self-adjoint.

Since $\mathcal{X}_y \subset \ker \operatorname{Hess}_y$ from (1) and Hess_y is self-adjoint, it follows the L^2 -completion \mathcal{V}_y is Hess_y -invariant, and Hess_y is also essentially self-adjoint on the L^2 -completion \mathcal{V}_y .

(3) Denote by

$$v = (v_H, X_{\zeta}(z), JX_{\alpha}(z)) : S^1 \to z^*H \oplus \operatorname{Img}(L_z) \oplus \operatorname{Img}(JL_z), \quad \zeta, \alpha : S^1 \to \mathfrak{g},$$

and notice that $L^2(S^1, z^*H)$ and $L^2(S^1, \operatorname{Img}(L_z) \oplus \operatorname{Img}(JL_z)) \oplus L\mathfrak{g}$ are two Hess_y-invariant subspaces. Over $L^2(S^1, z^*H)$,

$$\operatorname{Hess}_{\mathbf{y}}(v_H) = J \frac{d}{d\theta} \tilde{v}_H,$$

whose spectrum contains only simple real eigenvalues as $\{\frac{k}{|\text{Hol}_{\eta}|}|k \in \mathbb{Z}\}$ since its $|\text{Hol}_{\eta}|$ -multiple covering is conjugate to the self-adjoint operator

$$\frac{\sqrt{-1}}{|\operatorname{Hol}_{\eta}|} \frac{d}{d\theta} : L^{2}(S^{1}, \mathbb{C}^{\dim_{\mathbb{C}} H}) \to L^{2}(S^{1}, \mathbb{C}^{\dim_{\mathbb{C}} H}).$$

To understand the part over $L^2(S^1, \operatorname{Img}(L_z) \oplus \operatorname{Img}(JL_z)) \oplus L\mathfrak{g}$, it turns out to be easier to work on the normal form introduced in Section 3. Write the Hess_{v} into the following expression

$$\operatorname{Hess}_{y}(X_{\zeta}(z), JX_{\alpha}(z), \xi) = (-X_{\frac{d}{d\theta}\alpha + [\eta_{0}, \alpha(\theta)] + \xi(\theta)}, JX_{\frac{d}{d\theta}\zeta + [\eta_{0}, \zeta(\theta)] + \xi(\theta)}, d\mu \circ J(X_{\alpha})(z)),$$

and further write $d\mu \circ J(X_{\zeta}) = \zeta$ via the normal form, after using the flow of $-X_{\eta}$ to pull-back everything, we obtain the following simpler expression as

$$\widetilde{Hess}_{y}(X_{\tilde{\zeta}}(z),JX_{\tilde{\alpha}}(z),\tilde{\xi})=(-X_{\frac{d}{2\alpha}\tilde{\alpha}+\tilde{\xi}(\theta)},JX_{\frac{d}{2\alpha}\tilde{\zeta}+\tilde{\xi}(\theta)},\tilde{\alpha})).$$

As a result, the Hessian operator can be identified with

$$(\tilde{\zeta}, \tilde{\alpha}, \tilde{\xi}) \mapsto (-\frac{d}{d\theta}\tilde{\alpha} - \tilde{\xi}, \frac{d}{d\theta}\tilde{\zeta} + \tilde{\xi}, \tilde{\alpha}),$$

which is a first order elliptic differential operator plus a compact perturbation when restricted to the slice \mathcal{V}_y . It follows that the spectrum of the restricted Hess_y contains only simple real eigenvalues which belong to $\{\frac{k}{|\operatorname{Hol}_\eta|}|k\in\mathbb{Z}\}$.

Remark 4.9 In [3], the authors define a S^1 -valued functional whose critical points corresponds to the critical loops here. Moreover, this functional is infinitesimal $L\mathfrak{g}$ -invariant. From this point of view, the property that the kernel of $D_{\nu}\widetilde{\Upsilon}$ includes the vector fields generated by the infinitesimal gauge action is expected.

In this paper, we don't use this functional out of some technical reason (see Remark 6.6), but the functional we defined in Section 5 is heuristically the same as the functional in [3] (see also Remark 5.6).

5 The local functional on loops in $X \times \mathfrak{g}$ near critical loops

5.1 The canonical gauge transformations along a path of loops

We fix a path of loops

$$w = (u, \eta) : [t_0, \infty) \to L(X \times \mathfrak{g})$$

over some interval $[t_0, \infty) \subset \mathbb{R}$ with $\|\mu \circ u\|_{C^0([t_0,\infty)\times S^1)}$ sufficiently small, so that we are able to work under the normal form $(N^{\epsilon}, \omega_0, G, J, \mu_0)$ as introduced in Section 3. Then for each $t \in [t_0, \infty)$, we can write

$$w(t) = (u(t), \eta(t)) = ((z(t), JL_{z(t)}\xi(t)), \eta(t)),$$

with z(t) as a loop in $\mu^{-1}(0)$ and $\xi(t)$ as a loop in \mathfrak{g} for each $t \in [t_0, \infty)$. In particular, we use y(t) to denote the pair

$$y(t) := (z(t), \eta(t)) : S^1 \to \mu^{-1}(0) \times \mathfrak{g}, \quad t \in [t_0, \infty).$$

Using the notations in Section 4 around (11), and denote by $\tilde{w} = (\tilde{u}, \tilde{\eta})$ the $[t_0, \infty)$ -path of loops after the $[t_0, \infty)$ -family of L_0G -gauge transformations as

$$\tilde{u}(t) := h_{\eta(t)} \cdot u(t) = (h_{\eta(t)}^{-1} z(t), JL_{h_{\eta(t)} - 1} z(t) (Ad_{h_{\eta(t)}^{-1}} \xi(t))),$$

$$\tilde{\eta}(t) := h_{\eta(t)} \cdot \eta(t) \equiv -\text{LogHol}_{\eta(t)}.$$

In particular, we notice that $\tilde{u}(t, 0) = u(t, 0)$.

The following Lemma is obvious due to Lemma 4.4 and the metric is *G*-invariant.

Lemma 5.1 For every $t \in [t_0, \infty)$, $k = 0, 1, \dots$, we have

$$||d_{\tilde{\eta}(t)}\tilde{u}(t)||_{C^k(S^1)} = ||d_{\eta(t)}u(t)||_{C^k(S^1)}.$$

Also, we have

Lemma 5.2

$$\operatorname{dist}(u(t,0),\operatorname{Hol}_{\eta(t)}^{-1}u(t,0)) \leq \|d_{\eta(t)}u(t)\|_{C^0(S^1)}.$$

Proof

$$\begin{split} \operatorname{dist}(u(t,0),\operatorname{Hol}_{\eta(t)}^{-1}u(t,0)) & \leq & \int_0^1 |\frac{\partial}{\partial s}(\Psi_{\eta(t)}^{-1}(s)u(t,s))|ds \\ & = & \int_0^1 |\ell_{\Psi_{\eta(t)}(s)*}(\frac{\partial u}{\partial s}(t,s) + X_{\eta(t)}(u(t,s)))|ds \\ & = & \int_0^1 |\frac{\partial u}{\partial s}(t,s) + X_{\eta(t)}(u(t,s))|ds \\ & \leq & \|d_{\eta(t)}u(t)\|_{C^0(S^1)}. \end{split}$$

Then we obtain the following useful lemma which states that we can smoothly and uniformly perturb $(\tilde{u}(t), \tilde{\eta}(t))$ to obtain a smooth path of critical loops nearby.

Lemma 5.3 There exists some $\epsilon > 0$, such that whenever $\|d_{\eta(t)}u(t)\|_{C^0(S^1)} \le \epsilon$ for any $t \in [t_0, \infty)$ and $|\mu(u(t))| = |\xi(t)| \le \epsilon$, then there exists a unique smooth path $\eta_0 : [t_0, \infty) \to \mathfrak{g}$ with each $\exp(\eta_0(t)) \in G_{u(t,0)}$ satisfying

- (1) $\|\tilde{\eta}(t) \eta_0(t)\|_{C^0([t_0,\infty))}$ is small and controlled by ϵ ;
- (2) the loop $\exp(\theta \eta_0(t))\tilde{u}(t,\theta)$ stays in the injective radius of the initial point $\tilde{u}(t,0) = u(t,0)$.

Proof We first construct η_0 for each $t \in [t_0, \infty)$. As seen from Lemma 5.2,

$$\operatorname{dist}_{G \cdot u(t,0)}(u(t,0),\operatorname{Hol}_{\eta(t)}^{-1}u(t,0)) \leq \|d_{\eta(t)}u(t)\|_{C^{0}(S^{1})} \leq \epsilon,$$

where $G \cdot u(t,0)$ denotes the G-orbit of u(t,0) in $\mu^{-1}(0)$. WLOG, we can assume $G \cdot u(t,0)$ is isometric to $G/G_{u(t,0)}$, and then it follows

$$\operatorname{dist}_{G/G_{u(t,0)}}([e],[\operatorname{Hol}_{\eta(t)}]) \leq \epsilon.$$

Hence there exists some $k_t \in G_{u(t,0)}$ with $\mathrm{dist}_G(k_t,\mathrm{Hol}_{\eta(t)}) \leq \epsilon$. Moreover, whenever we make $\epsilon < d_{\mu^{-1}(0),G}$ where

$$d_{\mu^{-1}(0),G} = \inf_{x \in \mu^{-1}(0)} d_{x,G}$$
 with $d_{x,G} := \inf_{k,k' \in G_x} \operatorname{dist}_G(k,k')$

as introduced in (12), such $k_t \in G_{u(t,0)}$ is unique.

Now as come to the $[t_0, \infty)$ -family of $\eta(t)$'s, since $\eta(t)$ is piecewise smooth in t with only finitely many discontinuous points, and has smooth holonomy in t, by the construction, k_t is also smooth in t. Because G is a connected compact Lie group, we can further take a smooth family $\eta_0(t)$'s such that

$$\exp(\eta_0(t)) = k_t, \quad |\tilde{\eta}(t) - \eta_0(t)| \le C \operatorname{dist}_G(\operatorname{Hol}_{\eta(t)}, k_t) \le C\epsilon$$

for every $t \in [t_0, \infty)$, where C is a constant only depends on the geometry $(X, \omega, G, J, \mu, M)$. Hence we are done with Property (1).

From the construction, we have

$$\exp(\theta \eta_0(t))\tilde{u}(t,\theta) = \exp(\theta(\tilde{\eta}(t) - \eta_0(t)))\Psi_{n(t)}^{-1}(\theta)u(t,\theta).$$

Then we estimate

$$\begin{aligned} \operatorname{dist}(\exp(\theta\eta_0(t))\tilde{u}(t,\theta),z(t,0)) &= \int_0^\theta |\frac{\partial}{\partial s} \exp(s\eta_0(t))\tilde{u}(t,s)| ds \\ &= \int_0^\theta |\frac{\partial}{\partial s} (\exp(s(\tilde{\eta}(t)-\eta_0(t)))\Psi_{\eta(t)}^{-1}(s)u(t,s))| ds \\ &\leq C' |\tilde{\eta}(t)-\eta_0(t)| |d_{\eta(t)}u(t,s)| \end{aligned}$$

with C' some constant determined by the geometry data $(X, \omega, G, J, \mu, M)$. Hence the distance is bounded by ϵ^2 and we can make ϵ small so that $\tilde{u}(t)$ lives in the injective radius of u(t, 0) for every $t \in [t_0, \infty)$.

Denote the open or closed disks of radius r by

$$D(r) = \{ z \in \mathbb{C} | |z| < r \}, \quad \overline{D(r)} = \{ z \in \mathbb{C} | |z| \le r \},$$

and the boundary by $\partial D(r) = \overline{D(r)} \setminus D(r) = \{z | |z| = r\}$. Using above lemmas, we now construct a function (in fact a local functional) as stated in the following lemma.

Lemma 5.4 Assume $||d_{\eta(t)}u(t)||_{C^{\infty}(S^1)} \le \epsilon$ and $||\mu(u(t))||_{C^{\infty}(S^1)} \le \epsilon$ for any $t \in [t_0, \infty)$ as the ϵ given in Lemma 5.3. For each $t \in [t_0, \infty)$, there exists a piecewise smooth map $u_t : D(2) \to X$ with boundary $u(t) = u_t|_{\partial D(2)}$ satisfying

- (1) (a) $\mathbf{u}_t|_{\overline{D(1)}} \subset \mu^{-1}(0)$ and smooth, with $\mathbf{u}_t|_{\partial D(1)} = z(t)$;
 - (b) $u_t|_{\overline{D(2)}-D(1)}(s,\theta) = (z(t,\theta),(s-1)JL_{z(t,\theta)}(\xi(t,\theta)))$, where (s,θ) denotes the polar coordinate for the disk D(2).
- (2) Denote by

$$g_t: S^1 \to G, \quad g_t(\theta) := h_{\eta(t)}(\theta) \exp(-\theta \eta_0(t))$$

a $[t_0, \infty)$ -family of $[0, 2\pi]$ -gauge transformations. Then $g_t^{-1}z(t, \cdot)$ lives in the injective radius of z(t, 0).

Using such u_t , we define the function $\mathcal{L}_w : [t_0, \infty) \to \mathbb{R}$ as

(14)
$$\mathcal{L}_{w}(t) := -\int_{D(2)} \mathbf{u}_{t}^{*} \omega + \int_{\mathcal{S}^{1}} \langle \mu(u(t,\theta)), \eta(t,\theta) \rangle d\theta.$$

Then \mathcal{L}_w is smooth in t and satisfies the following isoperimetric inequality:

(15)
$$\mathcal{L}_{w}(t) \leq c_{0}(\|d_{\eta(t)}u(t)\|_{p}^{2} + c_{1}\|\mu \circ u(t)\|_{\frac{p}{p-1}}^{2}),$$

where $c_0, c_1 > 0$ are constants only depending on $(X, \omega, G, \mu, J, M)$ and $1 \le p \le 2$.

Proof From Lemma 5.3, the loop $g_t^{-1}z(t,\cdot)$ for every $t \in [t_0, \infty)$ lives in the injective radius of z(t,0) and hence contractible. As a result, we can take a smooth bounding disk within the injective radius of z(t,0) as

$$\bar{u}_t^1: D(1) \to \mu^{-1}(0)$$

whose boundary is this loop $g_t^{-1}z(t,\cdot)$. Then define

$$\bar{u}_t^2|_{D(2)-D(1)}(s,\theta) = (g_t^{-1}z(t,\cdot), (s-1)JL_{g_t^{-1}z(t,\cdot)}(Ad_{g_t^{-1}}\xi(t,\theta))).$$

Denote by \bar{u}_t the piecewise smooth map connecting \bar{u}_t^1 and \bar{u}_t^2 . Then $u_t := g_t^{-1}\bar{u}_t : D(2) \to X$ is the piecewise smooth map satisfying the two properties as stated in (1), for every $t \in [t_0, \infty)$.

Next we prove the function $\mathcal{L}_w : [t_0, \infty) \to \mathbb{R}$ defined as (14) satisfies the isoperimetric type inequality (15).

We first prove the following lemma.

Lemma 5.5

(16)
$$\mathcal{L}_{w}(t) = -\int_{D(2)} \bar{u}_{t}^{*} \omega + \int_{S^{1}} \langle \mu(\bar{u}(t,\theta)), (g_{t}^{-1} \cdot \eta)(t,\theta) \rangle d\theta$$

Proof We calculate for every fixed $t \in [t_0, \infty)$,

$$\int_{D(2)} \bar{u}_t^* \omega - \int_{D(2)} \mathbf{u}_t^* \omega$$

$$= \int_{D(2)} (g_t \mathbf{u}_t)^* \omega - \mathbf{u}_t^* \omega$$

$$= -\int_{D(2)} d\langle \mu \circ \mathbf{u}_t, g_t^{-1}(dg_t) \rangle$$

$$= -\int_{\partial D(2)} \langle \mu \circ u(t, \cdot), g_t^{-1}(dg_t) \rangle.$$

On the other hand,

$$\begin{split} &\int_{S^{1}} <\mu(\bar{u}(t,\theta)), (g_{t}^{-1} \cdot \eta)(t,\theta) > d\theta - \int_{S^{1}} <\mu(u(t,\theta)), \eta(t,\theta) > d\theta \\ = &\int_{S^{1}} <\mu(g_{t}\mathbf{u}_{t}(\theta)), (g_{t}^{-1} \cdot \eta)(t,\theta) > d\theta - \int_{S^{1}} <\mu(u(t,\theta)), \eta(t,\theta) > d\theta \\ = &\int_{S^{1}} <\mathrm{Ad}_{g_{t}^{-1}}\mu(\mathbf{u}_{t}), \mathrm{Ad}_{g_{t}^{-1}}\eta - (dg_{t})g_{t}^{-1} > - \int_{S^{1}} <\mu(u(t,\theta)), \eta(t,\theta) > d\theta \\ = &\int_{S^{1}} (<\mu(u(t,\theta)), \eta(t,\theta) > - <\mu(u(t,\theta)), g_{t}^{-1}(dg_{t}) >) d\theta - \int_{S^{1}} <\mu(u(t,\theta)), \eta(t,\theta) > d\theta \\ = &-\int_{S^{1}} <\mu(u(t,\theta)), g_{t}^{-1}(dg_{t}) >) d\theta. \end{split}$$

We are done with this lemma.

Since the right hand side of (16) is independent of choices of \bar{u}_t^1 but only depends on bounding loop \tilde{z}_t which smoothly depends on t, it follows \mathcal{L}_w is smooth in t. On the other hand, using Lemma 5.5 and the metric is G-invariant, we only need to prove (15) for \bar{u}_t since $d_{g \cdot \eta}(g^{-1}u) = \ell_{g^{-1}*}(d_{\eta}u)$ and μ is G-equivariant.

First from the isoperimetric inequality for small symplectic disks living in the injective radius of $\bar{u}(t,0)$, we have the following standard symplectic isoperimetric inequality for any $1 \le p \le 2$,

$$-\int_{D(2)} \bar{u}_t^* \omega \le c \|d\bar{u}_t|_{\partial D(2)}(\theta)\|_p^2.$$

The other term,

$$\int_{S^1} <\mu(\bar{u}(t,\theta)), (g_t \cdot \eta)(t,\theta) > d\theta \le c' \|\mu(\bar{u}_t)\|_{\frac{p}{p-1}}^2 + c' \|g_t \cdot \eta\|_p^2$$

On the other hand, since the infinitesimal action of \mathfrak{g} on X is free near $\mu^{-1}(0)$ when 0 is regular, we have

$$||g_t \cdot \eta||_p^2 \le ||X_{g_t \cdot \eta}(\bar{u}_t)||_p^2.$$

Then by taking c_0, c_1 large enough, we have

$$-\int_{D(2)} \bar{u}_t^* \omega + \int_{S^1} \langle \mu(\bar{u}(t,\theta)), (g_t \cdot \eta)(t,\theta) \rangle d\theta \leq c_0 (\|d_{g_t \cdot \eta} \bar{u}_t|_{\partial D(2)}(\theta)\|_p^2 + c_1 \|\mu(\bar{u}_t)\|_{\frac{p}{p-1}}^2).$$

(The proof of this step, we refer readers to [24, p. 368. Claim 3].) The whole proof is done now.

Remark 5.6 This isoperimetric inequality (15) can be made with sharp constants as in [24]. For example, the constant c in (17) holds for any $c > \frac{1}{4\pi}$. Also, following the scheme as in [24], one is also able to prove this is a well-defined local functional. In fact, this functional is the same as the one introduced in [3] (see also [8, 9]) by using e.g., $z(t_0, \cdot): S^1 \to \mu^{-1}(0)$ with capping $u_{t_0}|_{\overline{D(1)}}$, as the reference loop, since changing the reference loops in the same homotopy class doesn't change the local functional. We leave them to interested readers since these are not needed for our current application.

5.2 An energy equality for symplectic vortices

Using Lemma 5.4, for each pair $w = (u, \eta) : [t_0, \infty) \times S^1 \to X \times \mathfrak{g}$ satisfying

(18)
$$||d_{\eta(t)}u(t)||_{C^0(S^1)} \le \epsilon, \quad ||\mu(u(t))||_{C^0(S^1)} \le \epsilon$$

for any $t \in [t_0, \infty)$ as the ϵ given in Lemma 5.3, we have constructed a function

$$\mathcal{L}_w: [t_0, \infty) \to [0, \infty)$$

as defined in Lemma 5.4, which satisfies the isoperimetric inequality (15). In particular, we remark that the constants in inequality (15) are independent of w but only depend on the geometry $(X, \omega, G, J, \mu, M)$.

Now we further assume $w = (u, \eta)$ with

$$u:[t_0,\infty)\times S^1\to X,\quad \eta:[t_0,\infty)\times S^1\to\mathfrak{g}$$

is a (temporal) symplectic vortex over the half cylinder end $[t_0, \infty) \times S^1$. Then the function \mathcal{L}_w is related to the YMH energy as stated in the following proposition.

Proposition 5.7 Suppose $w = (u, \eta)$ is a (temporal) symplectic vortex satisfying the assumptions (18). Then for any $[t_1, t_2] \subset [t_0, \infty)$,

(19)
$$E(w; [t_1, t_2] \times S^1) := \int_{[t_1, t_2] \times S^1} e(u, \eta) \nu_h = \mathcal{L}_w(t_1) - \mathcal{L}_w(t_2),$$

where $e(u, \eta)$ is the energy density defined as in (3).

Proof Denote by $\tilde{\mathbf{u}}$ the path joining loops u_{t_1} and u_{t_2} by connecting the three pieces $\overline{u_{t_1}^2}, z_t$, and $u_{t_2}^2$, where u_t^2 is as defined in the proof of Lemma 5.4 and the 'overline' of u_t^2 denotes the path by reversing orientation. By construction, u and $\tilde{\mathbf{u}}$ are homotopic relative to boundaries $u(t_1, \cdot)$ and $u(t_2, \cdot)$, and then it follows from (4) that

$$E(w; [t_1, t_2] \times S^1) = \int_{[t_1, t_2] \times S^1} \tilde{\mathbf{u}}^* \omega - d \langle \mu(\tilde{\mathbf{u}}), \eta \rangle.$$

On the other hand, by considering the three parts $\overline{u_{t_1}^2}$, z_t , and $u_{t_2}^2$ that \tilde{u} consists of, we have

$$\int_{[t_1,t_2]\times S^1} \tilde{\mathbf{u}}^* \omega - d\langle \mu(\tilde{\mathbf{u}}), \eta \rangle = [\mathcal{L}_w(t_1) - (\int_{D(1)} (\tilde{\mathbf{u}}_{t_1}^1)^* \omega - d\langle \mu(\tilde{\mathbf{u}}_{t_1}^1), \eta \rangle)]
+ (\int_{D(1)} z^* \omega - d\langle \mu(z), \eta \rangle)
- [\mathcal{L}_w(t_2) - (\int_{D(1)} (\tilde{\mathbf{u}}_{t_2}^1)^* \omega - d\langle \mu(\tilde{\mathbf{u}}_{t_2}^1), \eta \rangle)]
= \mathcal{L}_w(t_1) - \mathcal{L}_w(t_2) + \int_{S^2} (\mathbf{u}^1)^* \omega.$$

Here the notations $\tilde{u}_{t_1}^1$, $\tilde{u}_{t_2}^1$ are the same as in the proof of Lemma 5.4, and u^1 is a path of loops constructed by joining $\overline{u_{t_1}^1}$, z, $u_{t_2}^1$. In particular, u^1 can be transformed to a contractible sphere by a $[t_0, \infty)$ -family of $[0, 2\pi]$ -gauge transformations as in Lemma 5.3 and Lemma 5.4. Notice that u^1 stays in $\mu^{-1}(0)$, it follows the symplectic area from the last term is invariant under such family of gauge transformations and hence is zero. We are done with the proof then.

It follows from Proposition 5.7 that $\lim_{t\to\infty} \mathcal{L}_w(t) =: \mathcal{L}_w(\infty)$ exists when w is a temporal symplectic vortex (notice that we haven't shown the C^0 -convergence of w). Further, together with (15), we obtain

Corollary 5.8 Under the same condition as in Proposition 5.7, $\mathcal{L}_w(\infty) = 0$.

We end this section by remarking that so far we haven't required any property on the metric over $[t_0, \infty) \times S^1$.

6 The asymptotic convergence

In this section, we prove the main theorem 1.1, which we split into the following two statements.

Proposition 6.1 Assume (P, w) = (P, u, A) is a admissible finite energy symplectic vortex over the punctured Riemann surface $(\dot{\Sigma}, j, h)$ with k-punctures. Then there exist some gauge transformation $\Phi \in \mathcal{G}_P$, k critical loops $x^i_{\infty} = (z^i_{\infty}, \eta^i_{\infty})$, $i = 1, \dots, k$, and some constants C > 0, $\delta > 0$ which only depend on $(X, \omega, G, \mu, J, M)$, such that $\Phi \cdot w = (\Phi^* u, \Phi^* A)$ is temporal and for any $\theta \in S^1$

- (1) $|d_{\Phi^*A}\Phi^*u(t,\theta)| \leq Ce^{-\delta t}$
- (2) $|\mu(\Phi^*u)(t,\theta)| \leq Ce^{-\delta t bt}$,
- $(3) |F_{\Phi^*A}(t,\theta)| \le Ce^{-\delta t + bt},$

- (4) $\operatorname{dist}(\Phi \cdot u(t,\theta), z_{\infty}(\theta)) \leq Ce^{-\delta t}$,
- (5) $\|\Phi^*A(t,\cdot) \eta_{\infty}(\cdot)\|_{L^p(S^1)} \le Ce^{-(\delta + b(\frac{2}{p} 1))t}$, for $p \ge 2$ and $\delta + b(\frac{2}{p} 1) > 0$.

Here we use $z_{\infty}, \eta_{\infty}, \delta, b$ to denote the ones with corresponding superscripts i's, $i = 1, \dots, k$.

Corollary 6.2 Under the same assumption as in Proposition 6.1, Then there exist some gauge transformation $\Phi \in \mathcal{G}_P$, k critical loops $x^i_\infty = (z^i_\infty, \eta^i_\infty)$ of **constant connections**, $i = 1, \dots, k$, and some constants C > 0, $\delta_i > 0$ which only depend on $(X, \omega, G, \mu, J, M)$, such that $\Phi \cdot w = (\Phi^* u, \Phi^* A)$ is temporal and for any $\theta \in S^1$

- $(1) |d_{\Phi^*A}\Phi^*u(t,\theta)| \le Ce^{-\delta t},$
- (2) $|\mu(\Phi^*u)(t,\theta)| \leq Ce^{-\delta t bt}$,
- (3) $|F_{\Phi^*A}(t,\theta)| \leq Ce^{-\delta t + bt}$,
- (4) $\|\operatorname{dist}(\Phi \cdot u(t,\cdot), z_{\infty}(\cdot))\|_{L^{p}(S^{1})} + \|\Phi^{*}A(t,\cdot) \eta_{\infty}(\cdot)\|_{L^{p}(S^{1})} \leq Ce^{-(\delta + b(\frac{2}{p} 1))}t$, for $p \geq 2$ and $\delta + b(\frac{2}{p} 1) > 0$.

Here we use $z_{\infty}, \eta_{\infty}, \delta, b$ to denote the ones with corresponding superscripts i's, $i = 1, \dots, k$.

The rest of this section is devoted to the proof of them.

6.1 The exponential decay of the b-energy density

First we notice that it is enough to prove Theorem 1.1 over one end, so WLOG, we assume $w = (u, \eta)$ is a finite energy temporal symplectic vortex over half cylinder $[0, \infty) \times S^1$ with respect to the metric

$$h = e^{2b(t)}(dt^2 + d\theta^2), \quad (t, \theta) \in [0, \infty) \times S^1.$$

Define the b-energy density as

(20)
$$e_b(w) : [0,\infty) \times S^1 \to \mathbb{R}$$

(21)
$$e_b(w) = \frac{1}{2}(|d_{\eta}u|^2 + e^{-2b(t)}|F_{\eta}|^2 + e^{2b(t)}|\mu \circ u|^2),$$

where $|\cdot|$ denotes the norm with respect to the standard cylinder metric $dt^2 + d\theta^2$. Then it follows that the YMH energy of w over $[0, \infty) \times S^1$ is

$$E(u,\eta) = \int_{[0,\infty)\times S^1} e_b(w)dtd\theta < \infty.$$

The following lemma is proved by Ziltener as [24, Lemma 3.3] based on the a priori estimates given by Gaio-Salamon as in [10, Section 9]. We remark that both [24, Lemma 3.3] and [10, Section 9] assume that the group G-action is free on the level set $\mu^{-1}(0)$. However in fact it applies to the general case by removing the free action assumption without changing any word, since the only assumption needed in the proof is the properness of moment map μ and the infinitesimal Lie algebra $\mathfrak g$ action is free which is satisfied by assuming 0 is a regular value.

Lemma 6.3 There exists some constant c > 0 which only depends on (X, ω, G, μ) , such that for any finite energy temporal symplectic vortex $w = (u, \eta)$ over half cylinder $[0, \infty) \times S^1$ with respect to the metric

$$h=e^{2bt}(dt^2+d\theta^2),\quad (t,\theta)\in [0,\infty)\times S^1,\quad b\geq 0,$$

there exists a constant $t_0 > 1$ such that the *b*-energy density

$$e_b(w)(t,\theta) \le cE(w;[t-1,t+1] \times S^1), \quad \text{for any } t \ge t_0.$$

Remark 6.4 The admissible condition that is required as in [24, Lemma 3.3] is more general than our current admissible condition. We restrict to this relatively simpler condition, i.e., to require the linearity of the exponent function b(t) = bt with b > 0 in the conformal metric, is because such cases are already enough for the expected applications in constructing corresponding moduli spaces.

In particular, followed from this Lemma, by assuming the metric h is admissible, i.e., $b \ge 0$, we can make t_0 large enough, such that the assumptions (18) are satisfied, and as a consequence, the function $\mathcal{L}_w: [t_0, \infty) \to [0, \infty)$ can be defined as given in (14).

Applying Proposition 5.7 and (15) (with p = 2), we estimate

$$E(w; [t, \infty)) = \mathcal{L}_{w}(t)$$

$$\leq c_{0}(\|d_{\eta}u(t)\|_{L^{2}(S^{1})}^{2} + c_{1}\|\mu \circ (u)(t)\|_{L^{2}(S^{1})}^{2})$$

$$\leq \frac{1}{2\delta}(\frac{1}{2}\|d_{\eta}u(t)\|_{L^{2}(S^{1})}^{2} + e^{2b(t)}\|\mu \circ (u)(t)\|_{L^{2}(S^{1})}^{2})$$

$$= -\frac{1}{2\delta}\frac{d}{dt}\int_{t}^{\infty}\int_{S^{1}}e_{b}(w)d\theta dt$$

$$= -\frac{1}{2\delta}\frac{d}{dt}E(w; [t, \infty)),$$

where $\delta > 0$ is some constant determined by c_0, c_1 . We remark here, for the second inequality uses the assumption that the metric h is admissible. As a result,

(22)
$$E(w; [t, \infty)) \le E(w)e^{-2\delta t} \text{ for any } t \ge t_0,$$

where E(w) is the total energy of w over $[0, \infty) \times S^1$.

Then apply Lemma 6.3 again, we obtain that there exists some constant C > 0 which only depends on $(X, \omega, G, J, \mu, M)$, such that

(23)
$$|d_{\eta}u(t,\theta)| \leq Ce^{-\delta t}$$
(24)
$$|\mu(u)(t,\theta)| \leq Ce^{-\delta t - bt}$$

$$|\mu(u)(t,\theta)| < Ce^{-\delta t - bt}$$

(25)
$$|F_{\eta}(t,\theta)| \leq Ce^{-\delta t + bt}.$$

6.2 The exponential convergence of w to a critical loop

To obtain the limiting critical loop, we look at the translated sequences as below. For any sequence $\{t_i\}$ with $t_i \to \infty$ as $i \to \infty$, $i \in \mathcal{I} = \mathbb{Z}$ or \mathbb{R} , define

$$w_i(t,\theta) = (u_i(t,\theta), \eta_i(t,\theta)) := w(t+t_i,\theta), \quad t \in [-t_i,\infty).$$

A moment of checking shows that $\{w_i\}$ satisfy the equations

$$\frac{\partial u_i}{\partial t} + J(u_i)(\frac{\partial u_i}{\partial \theta} + X_{\eta_i}(u_i)) = 0$$
$$\frac{\partial \eta_i}{\partial t} + e^{2bt + 2bt_i}\mu(u_i) = 0,$$

for $(t,\theta) \in [-t_i,\infty) \times S^1$. In another word, each w_i is a temporal symplectic vortex over $([-t_i,\infty) \times S^1)$ $S^1, j_0, e^{2b_i(t)}(dt^2 + d\theta^2)$) with $b_i(t) = b(t + t_i)$. Moreover, they have a uniform energy bound, as for each i the energy

$$E_{b_i}(w_i|_{K\times S^1}) \le E_b(w) \le \infty$$

over any compact subset $K \subset [-t_i, \infty)$. Here we use $E_{(\cdot)}$ to distinguish the energy with respect to different metrics as $e^{2(\cdot)}(dt^2 + d\theta^2)$.

The following lemma follows from [10, Lemma 9.3] by interpreting in cylinder coordinates which is adapted to our current situation. We remark that from [10, Lemma 9.3], one can also obtain higher order L^p bound which we don't list here since they are not used in this paper.

Lemma 6.5 For any $C_0 > 0$, there exist some constants $\epsilon_0 > 0$ and c > 0, such that any temporal (u, η) with $0 < \epsilon \le \epsilon_0$ satisfying the following equations

(26)
$$\frac{\partial u}{\partial t} + J(u)(\frac{\partial u}{\partial \theta} + X_{\eta}(u)) = 0$$
$$\frac{\partial \eta}{\partial t} + e^{2bt} \epsilon^{-2} \mu(u) = 0$$

over $K := [-2, 2] \times S^1$ together with

$$||d_{\eta}u||_{L^{\infty}(K)} + \epsilon^{-1}||\mu(u)||_{L^{\infty}(K)} < C_0,$$

we have over $K_0 := [0, 1] \times S^1$, $2 \le p \le \infty$,

(27)
$$\|\mu(u)\|_{L^{p}(K_{0})} \leq c\epsilon^{\frac{2}{p}+1} \|\frac{\partial u}{\partial t}\|_{L^{2}(K)} + c\epsilon^{\frac{2}{p}} \|\mu(u)\|_{L^{2}(K)}.$$

Here all norms are with respect to the standard cylindrical metric $dt^2 + d\theta^2$.

In particular, if b = 0, one can make $\epsilon_0 = 1$.

Proof We write down the equation in the \mathbb{C} -coordinates as $z=e^{t+i\theta}$ and plug $\lambda=e^{bt-t}$ into the inequality as given in [10, Lemma 9.3], then the desired inequalities follow. In particular, the powers of ϵ stay the same as in [10, Lemma 9.3], since the regions K, K_0 we are considering here are both bounded which makes the coordinate change only effect coefficient c.

Now apply (27) by taking $\epsilon = e^{-bt_i}$, it immediately follows that for each w_i ,

(28)
$$\|\mu(u_i)\|_{L^p(K_0)} \le ce^{-(\delta+b(\frac{2}{p}+1))t_i}.$$

From now on, we assuming that $p \ge 2$ such that $\delta' := \delta + b(\frac{2}{p} - 1) > 0$ and estimate for η_i , $i = 1, 2, \cdots$ as follows. For any $\theta \in S^1$,

$$\begin{aligned} |\eta_i(1,\theta) - \eta_i(0,\theta)| &\leq \int_0^1 |\frac{\partial \eta_i}{\partial t}(t,\theta)| dt \\ &\leq c_b \int_0^1 |e^{2bt_i} \mu(u_i)(t,\theta)| dt \\ &\leq c_b e^{2bt_i} ||\mu(u_i)(\cdot,\theta)||_{L^p([0,1])}, \end{aligned}$$

where c_b is some constant only depending on b. Here the second inequality is due to (26), and the third one is from the Hölder's inequality. Notice that for sequence $t_i = i$, $i = 1, 2, \dots$, $\eta_i(1, \theta) = \eta_{i+1}(0, \theta)$. It follows from the above estimate that

$$\|\eta_{i+1}(0,\cdot) - \eta_{i}(0,\cdot)\|_{L^{p}(S^{1})} = \left(\int_{S^{1}} |\eta_{i}(1,\theta) - \eta_{i}(0,\theta)|^{p} d\theta\right)^{\frac{1}{p}}$$

$$\leq c_{b}e^{2bt_{i}}\|\mu(u_{i})\|_{L^{p}(K_{0})}$$

$$\leq c_{b}e^{-\delta' i},$$

where the last inequality is (28). This leads to the convergence of $\eta_i(0,\theta)$ to some $\eta_\infty \in L^p(S^1,\mathfrak{g})$ in $L^p(S^1)$ -norm as $i \to \infty$ with decay rate δ' . Further applying (26) and (28), we obtain

$$\|\eta(t,\cdot)-\eta_{\infty}(\cdot)\|_{L^p(S^1)}\leq c_b e^{-\delta't}.$$

Similarly, for any $\theta \in S^1$,

$$\operatorname{dist}(u_{i+1}(0,\theta), u_i(0,\theta)) \leq \int_0^1 \left| \frac{\partial u_i}{\partial t}(t,\theta) \right| dt$$

$$\leq ce^{-\delta i},$$

where the last inequality follows from (23) applying to a temporal vortex. This proves that there exists some $z_{\infty} \in C^0(S^1, X)$ such that $u_i(0, \theta)$ converges to $z_{\infty}(\theta)$ exponentially fast with decay rate δ . Further using (23) again, this convergence can be enhanced to

$$\operatorname{dist}(u(t,\theta), z_{\infty}(\theta) \le ce^{-\delta t}, \quad \text{for any } \theta \in S^1,$$

and also we have $\mu(z_{\infty}) = 0$ since (24).

Now we show $(z_{\infty}, \eta_{\infty})$ is a limiting loop. Notice that from the convergences we have shown above, the vector field $X_{\eta(t,\theta)}(u(t,\theta))$ converges to the vector field $X_{\eta_{\infty}(\theta)}(z_{\infty}(\infty))$ via parallel transports. At the same time, we have the exponential decay of $|\frac{\partial u}{\partial \theta}(t,\theta) + X_{\eta(t,\theta)}(u(t,\theta))|$ to 0 with rate δ , it follows that $z_{\infty} \in W^{1,p}(S^1)$ and hence $C^{0,\alpha}(S^1)$ by the Sobolev embedding theorem, and

$$\dot{z}_{\infty} + X_{\eta_{\infty}}(z_{\infty}) = 0.$$

This finishes the proof of Proposition 6.1.

Now we use the canonical gauge transformation defined by (11) and obtain the $W^{1,p}(S^1, G)$ based gauges $h_{\eta(t)}, h_{\eta_{\infty}} \in L_0G$. Clearly, by the exponential $L^p(S^1)$ convergence of $\eta(t, \cdot)$, we have

$$\begin{split} \operatorname{dist}_{L^p(S^1)}(\operatorname{Hol}_{\eta(t)},\operatorname{Hol}_{\eta_{\infty}}) & \leq ce^{-\delta't} \\ \operatorname{dist}_{L^p(S^1)}(h_{\eta(t)},h_{\eta_{\infty}}) + \|\frac{\partial h_{\eta(t)}}{\partial \theta} - \frac{\partial h_{\eta_{\infty}}}{\partial \theta}\|_{L^p(S^1)} & \leq ce^{-\delta't}, \end{split}$$

where c > 0 is some constant (which may be bigger than the constant c before).

Now define the gauge transformation for the trivial bundle over $[0,\infty)\times S^1$ as $\Phi(t,\theta)=h_{\eta_\infty}(\theta)$. It follows

$$\|\Phi^*\eta(t,\cdot) - h_{\eta_{\infty}}^* \eta_{\infty}\|_{L^p(S^1)} \leq ce^{-\delta' t}$$

$$\|\operatorname{dist}(\Phi^*u(t,\cdot), h_{\eta_{\infty}}^* z_{\infty})\|_{L^p(S^1)} \leq ce^{-\delta' t}.$$

In particular, here $h_{\eta_{\infty}}^* \eta_{\infty} = -\text{LogHol}_{\eta_{\infty}}$ is constant, and $(h_{\eta_{\infty}}^* z_{\infty}, h_{\eta_{\infty}}^* \eta_{\infty})$ is a critical loop with constant connection.

This finishes the proof of Corollary 6.2.

We end this section by the following two remarks for the proof.

Remark 6.6 (1) The decay rate δ can be enhanced to the minimal nonzero eigenvalues of the self-adjoint Hessian operator restricted to slices as in Proposition 4.8 (3). The proof can be achieved by mimicking the three-interval method given for the Morse–Bott case in the contact manifold situation (see [13]) under the normal form given in Section 3. We leave details to readers. In particular, the optimal decay rate for δ is in fact the inverse of the order of the holonomy $\operatorname{Hol}_{\eta_{\infty}}$, which is 1 if assuming the action is free on $\mu^{-1}(0)$.

- (2) The technical point which forces us to obtain the higher order exponential decay as in the current proof instead of directly applying the Morse–Bott condition from the result in Proposition 4.8, is that one is not able to obtain a convergent subsequence to localize the operator or the functional near a critical point from the a priori estimates ([10, Lemma 9.3]) for the case $b \neq 0$.
 - This trouble disappears for the standard cylindrical metric, i.e., the case $b \equiv 0$, and an alternative proof direct to the Morse–Bott condition was given in [3] by the authors.

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