

## Solution to Homework 2 by Yuhao Huang

1. (1.4.6)

$$-2 \begin{pmatrix} 7 \\ 2 \\ 9 \\ -3 \end{pmatrix} - 5 \begin{pmatrix} -3 \\ 1 \\ -6 \\ 2 \end{pmatrix} = \begin{pmatrix} 1 \\ -9 \\ 12 \\ -4 \end{pmatrix}$$

2. (1.4.10)

$$x_1 \begin{pmatrix} 8 \\ 5 \\ 1 \end{pmatrix} + x_2 \begin{pmatrix} -1 \\ 4 \\ -3 \end{pmatrix} = \begin{pmatrix} 4 \\ 1 \\ 2 \end{pmatrix}$$
$$\begin{pmatrix} 8 & -1 \\ 5 & 4 \\ 1 & -3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 4 \\ 1 \\ 2 \end{pmatrix}$$

3. (1.4.14) The system  $A\mathbf{x} = \mathbf{u}$  is inconsistent, so  $\mathbf{u}$  is not in the span of the columns of  $A$ .

4. (1.4.16) For example, when

$$\mathbf{b} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

the system  $A\mathbf{x} = \mathbf{b}$  has no solution.

The set of all  $\mathbf{b}$  such that  $A\mathbf{x} = \mathbf{b}$  has a solution can be described as the span of the first two columns (or any two columns of  $A$ ).

Here is another way to describe it:

$$\left\{ \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} \mid b_1 + 2b_2 + b_3 = 0 \right\}$$

5. (1.4.17)  $A$  can be row reduced to

$$\begin{pmatrix} 1 & 3 & 0 & 3 \\ 0 & 2 & -1 & 4 \\ 0 & -4 & 2 & -8 \\ 2 & 0 & 3 & -1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 3 & 0 & 3 \\ 0 & 2 & -1 & 4 \\ 0 & 0 & 0 & 0 \\ 0 & -6 & 3 & -7 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 3 & 0 & 3 \\ 0 & 2 & -1 & 4 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

So it has 3 pivot rows, thus there exist some  $\mathbf{b} \in \mathbb{R}^4$  such that  $A\mathbf{x} = \mathbf{b}$  does not have a solution.

6. (1.5.5) The system can be reduced to

$$\begin{cases} x_1 + 3x_2 + x_3 = 0 \\ x_2 + 2x_3 = 0 \end{cases}$$

and then

$$\begin{cases} x_1 - 5x_3 = 0 \\ x_2 + 2x_3 = 0 \end{cases}$$

So the solutions are

$$\mathbf{x} = x_3 \begin{pmatrix} 5 \\ -2 \\ 1 \end{pmatrix}$$

7. (1.5.6) The system can be reduced to

$$\begin{cases} x_1 + 3x_2 - 5x_3 = 0 \\ x_2 - 3x_3 = 0 \end{cases}$$

and then

$$\begin{cases} x_1 + 4x_3 = 0 \\ x_2 - 3x_3 = 0 \end{cases}$$

So the solutions are

$$\mathbf{x} = x_3 \begin{pmatrix} -4 \\ 3 \\ 1 \end{pmatrix}$$

8. (1.5.12)

$$\mathbf{x} = x_2 \begin{pmatrix} -5 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -8 \\ 0 \\ 7 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_5 \begin{pmatrix} -1 \\ 0 \\ -4 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

9. (1.5.29)

(a) No, because  $A$  has 3 pivot **columns** (= number of columns).

(b) Yes, because  $A$  has 3 pivot **rows** (= number of rows).

10. (1.5.30)

(a) Yes, because  $A$  has 2 pivot **columns** so there is one free variable.

(b) No, because  $A$  has 2 pivot **rows** so there is one row for possible inconsistency.

11. (1.7.6) They are linearly independent because the row reduced echelon form has 3 pivots columns (= number of columns).

12. (1.7.10)

(a) For no values of  $h$  will  $\mathbf{v}_3$  lie in the span of the first two, because  $a\mathbf{v}_1 + b\mathbf{v}_2 = \mathbf{v}_3$  is never consistent.

(b) They are always linearly dependent because  $2\mathbf{v}_1 + \mathbf{v}_2 = \mathbf{0}$ .

13. (1.7.18) The 4 vectors are linearly dependent, because the 3rd and the 4th lie in the span of the first two.

14. (1.7.22)

(a) T. In this case  $a\mathbf{v}_1 = b\mathbf{v}_2$  thus they are linearly dependent.

(b) F. E.g.  $\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$  and  $\begin{pmatrix} 2 \\ 0 \\ 2 \end{pmatrix}$  are linearly dependent.

(c) T. In this case  $a\mathbf{v}_1 + b\mathbf{v}_2 = \mathbf{v}_3$  for some  $a, b$  and thus  $a\mathbf{v}_1 + b\mathbf{v}_2 - \mathbf{v}_3 = \mathbf{0}$ .

(d) F. E.g.  $\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$  and  $\begin{pmatrix} 2 \\ 0 \\ 2 \end{pmatrix}$  are linearly dependent but there are only 2 vectors, while there are 3 entries in each vectors.

15. (1.7.24)  $\begin{pmatrix} \blacksquare & * \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & \blacksquare \\ 0 & 0 \end{pmatrix}$  or  $\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$

16. (1.7.37) True. In this case there will be a linear relation  $c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c_3\mathbf{v}_3 = \mathbf{0}$ , which implies  $c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c_3\mathbf{v}_3 + 0\mathbf{v}_4 = \mathbf{0}$ , thus  $\mathbf{v}_1, \dots, \mathbf{v}_4$  are linearly dependent.

17. (1.8.10) That's equivalent to solve  $A\mathbf{x} = \mathbf{0}$ . We get those  $\mathbf{x}$  of the form

$$\mathbf{x} = x_3 \begin{pmatrix} -3 \\ -2 \\ 1 \\ 0 \end{pmatrix}$$

are mapped to  $\mathbf{0}$ .

18. (1.8.11) Yes because  $A\mathbf{x} = \mathbf{b}$  is consistent.

19. (1.8.20)

$$A = \begin{pmatrix} -2 & 7 \\ 5 & -3 \end{pmatrix}$$

20. (1.8.33)  $T(0, 0) \neq \mathbf{0}$ , so it is not linear.