

Lecture 4. Poisson Lie groups

Note Title

1/27/2009

Def. The Lie bialgebra structure induced by the Poisson Lie structure on $\mathfrak{g} = \text{Lie}(G)$ is called the tangent Lie algebra to a Poisson Lie group.

Theorem Let (\mathfrak{g}, δ) be Lie bialgebra and G be a connected Lie group with $\mathfrak{g} = \text{Lie}(G)$. There exists unique Poisson Lie structure p on G s.t. (\mathfrak{g}, δ) is the tangent Lie bialgebra to (G, p) .

Proof. h.w.

Let (G, ρ) , (H, η) be two Poisson Lie groups

Def. A Lie group homomorphism $\varphi: G \rightarrow H$

which is also a Poisson mapping ($\varphi^*: C(H) \rightarrow C(G)$ is a homom. of Poisson algebras) is called a homom. of Poisson Lie groups.

Def Let $(\mathcal{G}_1, \delta_1)$ and $(\mathcal{G}_2, \delta_2)$ be two Lie bialgebras. A linear map $\varphi: \mathcal{G}_1 \rightarrow \mathcal{G}_2$ is a Lie bialgebra homomorphism if φ and φ^* are Lie algebra homom.

Thm. A Poisson Lie group homom. induces a homom. of tangent Lie bialgebras.

Let (\mathfrak{g}, δ) be a Lie bialgebra

Def. $(\mathfrak{g}^*, \delta_*)$ where $\delta_* : \mathfrak{g}^* \rightarrow \wedge^2 \mathfrak{g}^*$ is dual to the Lie bracket on \mathfrak{g} , is called a dual Lie bialgebra to (\mathfrak{g}, δ) .

Let $(G, \rho) = T(G, p)$

$(G^*, \rho_*) = T(G^*, p_*)$

The pair (G, ρ) , (G^*, ρ_*) is called a dual pair of Poisson Lie groups.

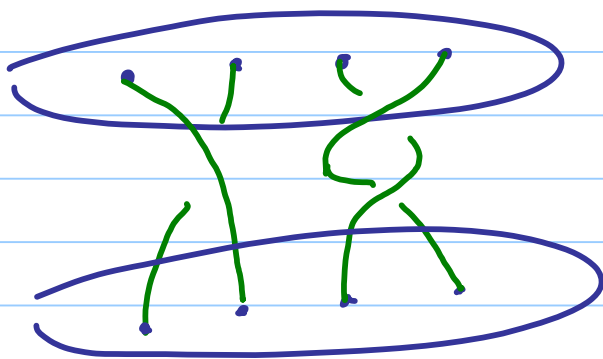
Remark. $\exists!$ Poisson Lie dual to any connected simply connected Poisson Lie group.

Braid groups

$$X_n = \{(z_1, \dots, z_n) \mid z_i \in \mathbb{C}, z_i \neq z_j\}$$

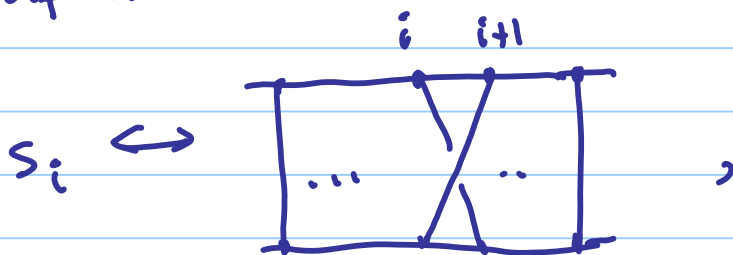
S_n acts on X_n permuting points.

Def. $B_n = \pi_1(X_n/S_n)$



Thm. $B_n \cong \langle S_i, i=1, 2, \dots, n-1 \mid \begin{array}{l} S_i S_j = S_j S_i \\ |i-j| \neq \pm 1 \\ S_i S_{i\pm 1} S_i = S_{i\pm 1} S_i S_{i\pm 1} \end{array} \rangle$

Proof. ...



Tensor product representations of B_n :

$$\pi: B_n \rightarrow \text{Aut}(V^{\otimes n}), \quad V = \text{vector space}$$

$$\pi(s_i) = 1 \otimes \cdots \otimes \underset{i+1}{S} \otimes \cdots \otimes 1$$

is a representation if

$$(S \otimes 1)(1 \otimes S)(S \otimes 1) = (1 \otimes S)(S \otimes 1)(1 \otimes S)$$

the (quantum) Yang-Baxter equation,
an over-determined system ($(\dim V)^6$ equations
for $(\dim V)^2$ unknowns). But there are many
solutions.

Example: $S = P, \quad P(x \otimes y) = y \otimes x$

Assume we have a family of such
solutions $S(h)$, s.t.

$$S(h) = P(1 + hZ + O(h^2)), \quad h \rightarrow 0$$

Thm. Then

$$[z_{12}, z_{13}] + [z_{13}, z_{23}] + [z_{12}, z_{23}] = 0$$

where $z_{12} = z \otimes 1$, $z_{23} = 1 \otimes z$, $z_{13} = \dots$

(classical) Yang-Baxter equation. (cYBE)

Proof h.w.

In the cYBE we have only commutators.
This motivates the definition:

Def. $z \in \mathfrak{g} \otimes \mathfrak{g}$ satisfies the classical Yang-Baxter equation if

$$[z_{12}, z_{13}] + [z_{12}, z_{23}] + [z_{13}, z_{23}] = 0$$

in $U\mathfrak{g} \otimes U\mathfrak{g} \otimes U\mathfrak{g}$, assuming $\mathfrak{g} \hookrightarrow U\mathfrak{g}$ as order 1 elements.