Daniel Berwick Evans.

Supersymmetries and supercharges.

N is a spacetime (a supermanifold) (a Riemannian or Lorentzian manifold). F is a superspace of fields. Lagrangian $L \in \Omega^{0,n}(F \times N)$.

We have classical solutions $M \subset F$. Variational 1-forms. $\gamma \in \Omega_{\text{loc}}^{1,n-1}(F \times N)$. Pick γ such that $E(L) = \delta L + d\gamma \in \Omega_{\text{loc}}^{1,n}(F \times M)$ does not contain variations of derivatives of fields, just variations of the fields themselves.

Remarks: (1) If L only depends on the 1-jet of fields, γ is uniquely determined. (2) By Taken's theorem γ is generally only determined up to a d-closed (d-exact) form. (3) For the usual mechanics the restriction of γ to M is $\sum_i p_i dq^i$.

Examples: (1) Classical particles on a Riemannian manifold M. $N = \mathbf{R}, F = \operatorname{Map}(\mathbf{R}, M), L =$ $(1/2)|\dot{x}|^2 dt.$

 $\delta L = \langle \delta_{\nabla} \dot{x}, \dot{x} \rangle dt = \langle \delta_{\nabla} dx, \dot{x} \rangle = -\langle d\delta_{\nabla} x, \dot{x} \rangle = -d\langle \delta x, \dot{x} \rangle + \langle \delta x, d_{\nabla} \dot{x} \rangle = \gamma + E(L), E(L) = \langle \delta x, \nabla_{\dot{x}} \dot{x}.$ Here $\dot{x}dt = dx.$

Superparticle. $N = \mathbf{R}, F = \{x: \mathbf{R} \to M, \psi \in \Gamma(x^* \pi T M)\}, L = (1/2)(|\dot{x}|^2 + \langle \psi, \nabla_{\dot{x}} \psi \rangle) dt. \delta L =$ $-d\langle\psi,\delta_{\nabla}\psi\rangle+\langle\delta_{\nabla}\psi,d_{\nabla}\psi\rangle+\langle\delta x,R(\psi,\psi)dx\rangle-d\langle\delta x,\dot{x}\rangle+\langle\delta x,\nabla\dot{x},\dot{x}\rangle.$

Equations of motion: $\nabla_{\dot{x}}\dot{x} = (1/2)R(\psi,\psi)\dot{x}, \ \nabla_{\dot{x}}\psi = 0. \ \gamma_{\rm sp} = \langle \dot{x}, \delta x \rangle + (1/2)\langle \psi, \delta_{\nabla}\psi \rangle.$ Symplectic structures on the space of classical solutions $M. \ \omega = \delta \gamma \in \Omega_{\rm loc}^{2,n-1}(F \times N). \ \omega = (d+\delta)\mathcal{L}$ on $M \times N$, $\mathcal{L} = L + \gamma$. Hence $(d + \delta)\omega = 0$ on $M \times N$.

Classical mechanics: $d\omega = 0$ on M, hence $\omega(t) = \omega$. In general, $\Omega(t) := \int_{\{t\} \times S} \omega$. By Stokes this does not depend on t.