

From whence do differential  
forms come? ~~from~~

References:

Moerdijk & Reyes: Models for smooth  
1991 Infinite-dimensional analysis

Lavendhomme (1996) Basic Concepts  
of synthetic differential geometry

Kock: 1) Synthetic differential geometry (1981)  
2006  
2) Synthetic geometry of manifolds (2009)

From whence do differential forms come? |

Recall the definition of singular cohomology  $R$

$M$  smooth manifold

~~$C_n = \text{hom}(\Delta^n, M)$~~

$$C_n = \mathbb{R}^{\text{hom}_{\text{top}}(\Delta^n, M)}$$

$$C_n \rightarrow C_{n+1}$$

$$c \mapsto (f: \Delta^{n+1} \rightarrow M \mapsto \sum_{0 \leq i \leq n+1} c(f \circ d^i))$$

$d^i: \Delta^n \rightarrow \Delta^{n+1}$   $i$ th face.

$H_n(C) :=$  the singular cohomology w/ coefficients in  $R$   
 $C_n$  is huge. Canonical example:

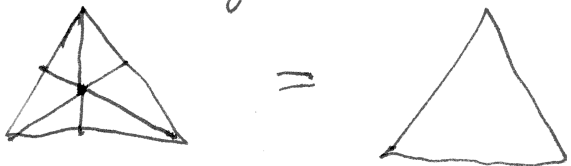
~~Possible ways~~ integration:  $f: \Delta^n \rightarrow M \mapsto \int_{\Delta^n} G \circ f$   
 $M \xrightarrow{G} \mathbb{R}$

Possible ways to cut down on size of  $C_n$ :

1) Require maps  $\Delta^n \rightarrow M$  to be smooth (not just continuous)

2) Require maps  $\text{hom}_{\text{con}}(\Delta^n \rightarrow M) \rightarrow \mathbb{R}$  to be smooth, not arbitrary

3) Require additivity under barycentric subdivision



Theorem (P., Goh, Technov)

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Under (1)-(3),

there is an isomorphism (not just quasi-iso)

$$C \rightarrow D.$$

Explanation: (1), (2) enable to construct a differential form by differentiation

(3): the value on a large simplex can be recovered from values on arbitrarily small simplices

Thus, we can cut down even further by passing to a neighborhood of the diagonal

~~$M \rightarrow M$~~

$$\begin{array}{ccc} M & \longrightarrow & \text{hom}_{\text{co}}(\Delta^n, M) \\ m & \longmapsto & (p \mapsto m). \end{array}$$

Which neighborhood can we take?

- 1) germ
- 2) formal: (meaning we remember all derivatives at  $M \hookrightarrow \text{hom}_{\text{co}}(\Delta^n, M)$ ).
- 3) first-order: (meaning we remember the first derivative at  $M \hookrightarrow \text{hom}_{\text{co}}(\Delta^n, M)$ ).

What is the geometric meaning of (2)? 3

e.g.  $M = \mathbb{R}^n$  or  $M = \mathbb{R}$

A simplex  $\sigma: \Delta^n \rightarrow M$  "belongs" to (3)

if  $\forall i, j \quad 0 \leq i < j \leq n$ :  $\sigma(i) - \sigma(j)$   
are infinitesimally close to first order,  
i.e.,  $(\sigma(i) - \sigma(j))^2 = 0$ .

~~Problem~~ Problem: ~~there are no real numbers  $r$  such that  $r^2 = 0$~~   
If  $r^2 = 0$ , then  $r = 0$ .

Resolution: allow rings of functions with nilpotent elements.

Good notion of ring for smooth differential geometry  
 $C^\infty$ -ring

Def ordinary commutative  $\mathbb{R}$ -algebra  $A$ :

for any real polynomial  $p$  in variables

we have an operation  $A^n \xrightarrow{p} A$

associativity:  $A^{m_1 + \dots + m_k} \xrightarrow{p(q_1, \dots, q_k)} A^k \xrightarrow{p} A$

unitality:

$p = x$   
 $A^1 \xrightarrow{p} A = \text{id}_A$

$p(q_1, \dots, q_k)$ .

Def  $C^\infty$ -ring: replace polynomials by smooth functions. 4

In particular,  $C^\infty$ -rings are comm  $\mathbb{R}$ -alg.

Example!  $C^\infty(M)$  smooth manifold  $M$ .

Example! A fin dim  $n$  local  $\mathbb{R}$ -alg.

$$\Leftrightarrow \forall a \in A \exists! \begin{matrix} u, n \\ u \in \mathbb{R} \\ n \text{ nilpotent} \end{matrix} \\ a = u + n$$

$$f(u_1 + n_1, \dots, u_n + n_n) = \sum_k \partial_{\vec{k}} f(\vec{u}) \cdot \vec{n}^{\vec{k}}$$

Finite sum.



Interpret these geometrically.

Example: 1)  $\text{Spec}(\mathbb{R}) = \text{pt}$   $\text{pt} \xrightarrow{a} M \leftrightarrow C^\infty M \xrightarrow{\text{eva}} \mathbb{R}$

$\text{Spec}(\mathbb{R}^n) = n \times \text{pt}$

2)  $\text{Spec}(\mathbb{R}[\epsilon]/(\epsilon^2))$   
 $= \text{Spec}(\mathbb{R} + \epsilon \cdot \mathbb{R}) = L$

What is  $L$ ?

$$\mathbb{R}[\epsilon]/(\epsilon^2) \xrightarrow{\epsilon=0} \mathbb{R}$$

$$\text{pt} \longrightarrow L$$

What is a map  $L \rightarrow M$ ,  $M \in \text{Manifold}$ ?

$$C^\infty(M) \xrightarrow{\gamma} \mathbb{R}[\epsilon]/(\epsilon^2) \xrightarrow{\epsilon \mapsto 0} \mathbb{R} \quad 5$$

$$f \mapsto \alpha(f) + \beta(f) \cdot \epsilon$$

$\alpha$  is a homomorphism of algebras  $C^\infty(M) \xrightarrow{\text{eval}_a} \mathbb{R}$

$$\gamma(fg) = \alpha(fg) + \beta(fg) \cdot \epsilon$$

$$\begin{aligned} \gamma(f)\gamma(g) &= (\alpha(f) + \beta(f) \cdot \epsilon)(\alpha(g) + \beta(g) \cdot \epsilon) \\ &= \alpha(f)\alpha(g) + (\beta(f)\alpha(g) + \alpha(f)\beta(g)) \cdot \epsilon \end{aligned}$$

$$\beta(fg) = \beta(f)\alpha(g) + \alpha(f)\beta(g).$$

i.e.,  $\beta: C^\infty(M) \rightarrow \mathbb{R}$

is a derivation with respect to  $\alpha$ .

Recall: Want to define

$$IS_n \xrightarrow{\cong} \text{hom}_{C^\infty}(\mathbb{R}^n, M)$$

$\uparrow$   
 $C^\infty$ -locus

consisting of infinitesimal sources

easiest way to define  $IS_n$

is to define maps  $S \rightarrow IS_n$

$\forall C^\infty$ -locus  $S$ .

# Infiniteesimal simplices 6

Def  $M \in \text{Manifold}$ ,  $S \in C^\infty \text{ Locs}$

An  $S$ -indexed family of infiniteesimal  $n$ -simplices is a collection of  $(n+1)$ -morphisms

$$\alpha_i: S \rightarrow M; \text{ i.e., homomorphisms of } \mathbb{R}\text{-algebras, i.e.,}$$

$$0 \leq i \leq n \quad \begin{array}{c} \downarrow h \\ \mathbb{R} \end{array} \quad C^\infty(M) \xrightarrow{C^\infty(\alpha_i)} C^\infty(S)$$

such that  $\forall h: M \rightarrow \mathbb{R} \quad C^\infty(\mathbb{R}) \xrightarrow{C^\infty h} C^\infty(M)$   
 the compositions  $C^\infty \mathbb{R} \xrightarrow{C^\infty h} C^\infty M \xrightarrow{C^\infty \alpha_i} C^\infty S$   
 give elements  $\beta_i \in C^\infty S$   
 such that  $(\beta_i - \beta_j)^2 = 0. \quad \forall i, j.$

Def The de Rham complex of a smooth manifold  $M$  is the infiniteesimal smooth singular cochain complex of  $M$ .

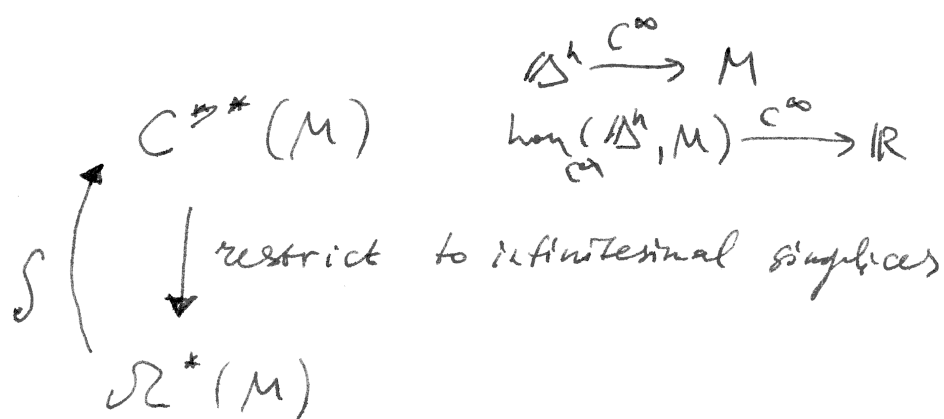
$$\Omega^n M := C^\infty(IS_n(M), \mathbb{R})$$

{that vanishes on  $DIS_n(M) \subset IS_n(M)$

where two consecutive points coincide.

$$\Omega^n M \xrightarrow{d} \Omega^{n+1} M \text{ induced by } \sum_{0 \leq i < n+1} (-1)^i \omega(\alpha_0, \dots, \alpha_i, \dots, \alpha_n)$$

Theorem



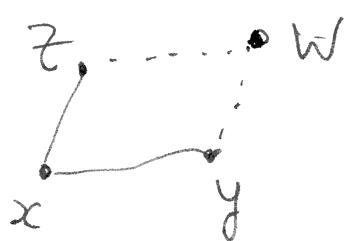
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is a quasi-isomorphism

The image of  $S$  is precisely additive cochains

Other examples

Connection on  $TM$



$$\lambda(x, y, z) \mapsto w$$

torsion-free

$$\lambda(x, y, z) = \lambda(x, z, y)$$

$$\lambda(x, y, z) = y - x + z$$

$$\text{torsion: } b_x(y, z) = \lambda(\lambda(x, y, z), y, z)$$

$$\nabla_{y,x}(z)$$

$$\text{flat: } \nabla_{z,x} = \nabla_{z,y} \circ \nabla_{y,x}$$

