

Lecture 17: Orthogonality!

Today: Review 11:30 - 1:30  
736 Evans

Thursday Midterm 2 through 6.3

Friday: No quiz.

Warmup! Is the following list

orthogonal? orthonormal?

$$\underline{v}_1 = \begin{pmatrix} 1 \\ 2 \\ 0 \\ -1 \end{pmatrix} \quad \underline{v}_2 = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \quad \underline{v}_3 = \begin{pmatrix} -1 \\ 1 \\ 3 \\ 1 \end{pmatrix}$$

$$\underline{v}_1 \cdot \underline{v}_3 = (1)(-1) + (2)(1) + (0)(3) + (-1)(1) \\ = 0 \quad \underline{v}_1 \text{ is orthogonal to } \underline{v}_3$$

$\underline{v}_2$  orthogonal to everything.

Orthogonal!  Not orthonormal!  $\|\underline{v}_2\| = 0$ .

Warmup 2 a) Show following list is

orthog. basis

$$\underline{v}_1 = \begin{bmatrix} 2 \\ -1 \\ 0 \end{bmatrix}$$

$$\underline{v}_2 = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

$$\underline{v}_3 = \begin{bmatrix} -1 \\ -2 \\ 5 \end{bmatrix}$$

Check:  $\underline{v}_1 \cdot \underline{v}_2 = 0$ ,  $\underline{v}_1 \cdot \underline{v}_3 = 0$

$$\underline{v}_2 \cdot \underline{v}_3 = 0$$

So orthog.

Thus lin indep. So span  
Basis as well.

b) Find coeffs of vector

$$\underline{v} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

w.r.t. previous basis.

$$\underline{v} = x_1 \underline{v}_1 + x_2 \underline{v}_2 + x_3 \underline{v}_3$$

Traditional method:

$$A = \begin{bmatrix} 1 & 1 & 1 \\ y_1 & y_2 & y_3 \\ 1 & 1 & 1 \end{bmatrix}$$

Solve  $A\underline{x} = \underline{v}$

Easier method since basis is orthog.

$$v \cdot \underline{v}_1 = x_1 \underbrace{\underline{v}_1 \cdot \underline{v}_1} + x_2 \underbrace{\underline{v}_2 \cdot \underline{v}_1} + x_3 \underbrace{\underline{v}_3 \cdot \underline{v}_1} \\ = 0 \quad = 0$$

Since basis is orthog

$$\text{So } x_1 = \frac{v \cdot \underline{v}_1}{\underline{v}_1 \cdot \underline{v}_1} = \frac{2}{5}$$

Similarly we find

$$\underline{v} = \frac{v \cdot \underline{v}_1}{\underline{v}_1 \cdot \underline{v}_1} \underline{v}_1 + \frac{v \cdot \underline{v}_2}{\underline{v}_2 \cdot \underline{v}_2} \underline{v}_2 + \frac{v \cdot \underline{v}_3}{\underline{v}_3 \cdot \underline{v}_3} \underline{v}_3$$

$$\bar{y} = \frac{2}{5} \bar{y}_1 + \frac{2}{6} \bar{y}_2 + \frac{4}{30} \bar{y}_3$$

$x_1$        $x_2$        $x_3$

Warmup 3 Suppose  $U$  is an  $n \times n$  matrix  
When does  $U$  preserve inner prod?

Show  $(U\bar{x}) \cdot (U\bar{y}) = \bar{x} \cdot \bar{y}$  all  $\bar{x}, \bar{y}$   
if and only if cols of  $U$  are  
orthonormal basis

Proof: Suppose  $(U\bar{x}) \cdot (U\bar{y}) = \bar{x} \cdot \bar{y}$   
all  $\bar{x}, \bar{y}$ .

In particular, let's take  $\bar{x} = \underline{e}_i$   
 $\bar{y} = \underline{e}_j$

$$U \underline{e}_i = \underline{v}_i \quad \text{ith col}$$

$$U \underline{e}_j = \underline{v}_j \quad \text{jth col}$$

$$\underline{v}_i \cdot \underline{v}_j = (U \underline{e}_i) \cdot (U \underline{e}_j) = \underline{e}_i \cdot \underline{e}_j = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$$

Conclude cols of  $U$  are orthonormal  
so form orthonormal basis

Exer. prove converse part  
of assertion.



Def A  $n \times n$  matrix  $U$  with  
orthonormal cols is called  
an orthogonal matrix

Ex)  $U = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$  is orthogonal.

(rotation by  $\frac{\pi}{2}$ )

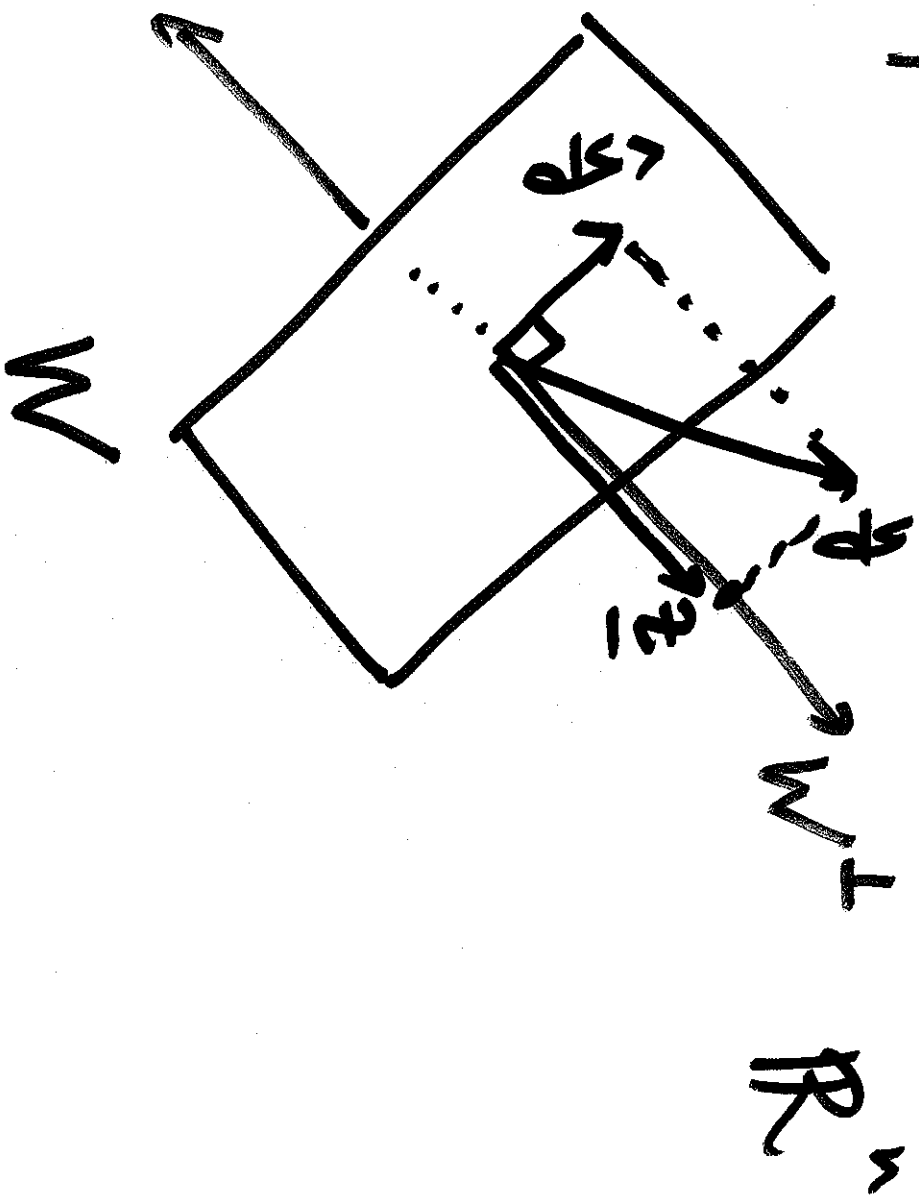
2)  $A = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$  is not orthogonal

Remark  $U$  is orthogonal if and only if

$$U^{-1} = U^T$$

and

Orthog projections recall given  
Subspace  $W$  in  $\mathbb{R}^n$ , we have  
Subspace  $W^\perp$  in  $\mathbb{R}^n$



Thm Every vector  $y$  in  $\mathbb{R}^n$  can be uniquely expressed as

$$y = \hat{y} + \underline{z}$$

where  $\hat{y}$  is in  $W$ ,  $\underline{z}$  is in  $W^\perp$

Moreover, if  $\bar{u}_1, \dots, \bar{u}_k$  is an orthog basis for  $W$ , then

$$\hat{y} = \frac{y \cdot \bar{u}_1}{\bar{u}_1 \cdot \bar{u}_1} \bar{u}_1 + \dots + \frac{y \cdot \bar{u}_k}{\bar{u}_k \cdot \bar{u}_k} \bar{u}_k$$

Proof Choose orthonog basis of  $W$

$$\underline{u}_1, \dots, \underline{u}_k$$

$$\text{Set } \hat{\underline{y}} = \frac{\underline{y} \cdot \underline{u}_1}{\underline{u}_1 \cdot \underline{u}_1} \underline{u}_1 + \dots + \frac{\underline{y} \cdot \underline{u}_k}{\underline{u}_k \cdot \underline{u}_k} \underline{u}_k$$

$$\text{Set } \underline{z} = \underline{y} - \hat{\underline{y}}$$

Note  $\hat{\underline{y}}$  in  $\text{Span}\{\underline{u}_1, \dots, \underline{u}_k\} = W$

Check:  $\underline{z}$  in  $W^\perp$

$$\underline{z} \cdot \underline{u}_i = (\underline{y} - \hat{\underline{y}}) \cdot \underline{u}_i = \underline{y} \cdot \underline{u}_i - \underline{y} \cdot \underline{u}_i = 0.$$

So far we have expressed

$$y = \underbrace{\hat{y}}_{\text{in } W} + \underbrace{z}_{\text{in } W^\perp}$$

given by  
desired formula

Exer complete proof by showing

$\hat{y}$ ,  $z$  are unique

so that  $y = \hat{y} + z$  with  $\hat{y}$  in  $W$   
 $z$  in  $W^\perp$

Def. Given subspace  $W$  in  $\mathbb{R}^n$   
and vector  $y$  in  $\mathbb{R}^n$   
 $y$  orthog.  
Projection of  
 $y$  onto  $W$

We've seen if  $\bar{u}_1, \dots, \bar{u}_k$  is  
orthog basis of  $W$  then

$$\text{proj}_W(y) = \hat{y} = \frac{y \cdot \bar{u}_1}{\bar{u}_1 \cdot \bar{u}_1} \bar{u}_1 + \dots + \frac{y \cdot \bar{u}_k}{\bar{u}_k \cdot \bar{u}_k} \bar{u}_k$$

Exer. Let  $W = \text{span} \left\{ \underline{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \underline{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}$  in  $\mathbb{R}^3$

Find orthog proj. of  $\underline{y} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$  to  $W, W^\perp$ .

Soln Find orthog basis of  $W$   
Apply formula for  $\underline{v}$

$$\text{Take } \underline{w}_1 = \underline{v}_1$$

$$\underline{w}_2 = \underline{v}_2 - \frac{\underline{v}_2 \cdot \underline{v}_1}{\underline{v}_1 \cdot \underline{v}_1} \underline{v}_1 \quad \left. \vphantom{\underline{w}_2} \right\} \text{orthog basis}$$



$$\dots = \begin{bmatrix} \frac{2}{3} \\ \frac{2}{3} \\ \frac{1}{3} \\ \frac{1}{3} \end{bmatrix} \begin{bmatrix} \frac{93}{36} \\ \frac{99}{36} \\ \frac{10}{6} \\ \frac{10}{6} \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} = \frac{-2}{6} = \frac{-2}{3}$$

$$\frac{2\bar{u} \cdot u_2}{2\bar{u} \cdot u_2} + \frac{1\bar{u} \cdot u_1}{1\bar{u} \cdot u_1} = \rho$$

$$\begin{bmatrix} \frac{2}{3} \\ \frac{2}{3} \\ \frac{1}{3} \\ \frac{1}{3} \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix} - \frac{1}{6} \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} = 2\bar{u}$$

$$= 1\bar{u} \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$$

$$\begin{aligned} \text{Take } \text{proj}_{W^\perp}(y) &= y - \text{proj}_W(y) \\ &= y - \hat{y} = \dots \end{aligned}$$