## Worksheet 13

## Sections 207 and 219 MATH 54

## March 7, 2019

Exercise 1. Mark each statement True or False. Justify each answer. For these problems, A, B are  $n \times n$  matrices.

- (a) If A, B are row equivalent, then they have the same eigenvalues.
- (b) If A has n eigenvectors, A is diagonalizable.
- (c) If A has n distinct eigenvalues, it is diagonalizable.
- (d) If A is diagonalizable, then A has n distinct eigenvalues
- (c) If A has n distinct eigenvalues, it is diagonalizable.

A1.

(d) False! See exercise 4 for a counterexample.

**Exercise 2.** Let T be defined by  $T(\mathbf{x}) = A\mathbf{x}$ . Find a basis  $\mathcal{B}$  for  $\mathbb{R}^2$  with the property that  $[T]_{\mathcal{B}}$  is diagonal.

$$A = \begin{bmatrix} 0 & 1 \\ -3 & 4 \end{bmatrix}$$

By Thm, 8, if we write 
$$A = PDP^{-1}$$
, and let B be the columns of P,  
then [T]p is diagonal. We first find the eigenvalues of A:  
 $\begin{vmatrix} -\lambda & i \\ -3 & i + \lambda \end{vmatrix} = \lambda^{n} - 4\lambda + 3 = (\lambda - 3)(\lambda - 1) = 0$ . So  $\lambda = 3, 1$ . We now find the eigenspaces;  
 $\lambda = 1$ . We find the diverspace of A-II:  $\begin{bmatrix} -1 & i \\ -3 & 3 \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 & 3 \end{bmatrix} = \frac{1}{2} \times 2 \begin{bmatrix} 1 \\ 1 & 3 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -1 & i \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 & 3 \end{bmatrix} = \frac{1}{2} \times 2 \begin{bmatrix} 1 \\ 1 & 3 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 & 3 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 & 3 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 & 3 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 & 3 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -1 \\ 1 & 3 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix}$ 

Exercise 3. (a) As a group, discuss why it is useful to be able to diagonalize a matrix!(b) If possible, diagonalize the following matrix:

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$$\begin{bmatrix} 3 & -1 \\ 1 & 5 \end{bmatrix}$$

-4

(b) We first Rind eigenvalues and eigenvectors.  
To find eigenvalues, we solve the characteristic equation  

$$\begin{vmatrix} 3-x & -1 \\ 1 & 5-x \end{vmatrix} = \lambda^2 \cdot 8\lambda + 15 + 1 = (\lambda - 4)^2$$
. So  $\lambda = 4$  is the only  
eigenvalue. We now find the eigenspace by finding  
solutions to  $\begin{vmatrix} 3-4 & -1 \\ 1 & 5-x \end{vmatrix} \stackrel{\checkmark}{=} 0 \implies \begin{vmatrix} -1 & -1 \\ 1 & 1 \end{vmatrix} \stackrel{\circlearrowright}{=} 0 = 0$   
So The eigenspace is  $(\text{span}(\begin{bmatrix} 1 \\ -1 \end{bmatrix}))$ . Since there is only  
one eigenspace, and it is are dimensional, this matrix

**Exercise 4.** The eigenvalues of A are 2 and 8. Use this information to diagonalize A:

$$A = \begin{bmatrix} 4 & 2 & 2 \\ 2 & 4 & 2 \\ 2 & 2 & 4 \end{bmatrix}$$

In order to diagonalize A, we need to Rind eigenspaces  
corresponding to each eigenvector.  

$$X=2$$
: The eigenspace is soluhians to  $\begin{bmatrix} 4-2 & 2 & 2 \\ 2 & 4-2 & 2 \\ 2 & 2 & 4+2 \end{bmatrix} = 0$   
 $\begin{bmatrix} 2 & 2 & 2 \\ 2 & 2 & 4+2 \end{bmatrix} = 0$   
 $\begin{bmatrix} 2 & 2 & 2 \\ 2 & 2 & 4+2 \end{bmatrix} = 0$   
 $\begin{bmatrix} 2 & 2 & 2 \\ 2 & 2 & 4+2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$   
 $X=9$ : The eigenspace is colutions to  $\begin{bmatrix} 4-2 & 2 & 2 \\ 2 & 2 & 4+2 \end{bmatrix} = 0$   
 $\begin{bmatrix} -4 & 2 & 2 \\ 2 & 2 & 4+2 \end{bmatrix} = 0$   
 $\begin{bmatrix} -4 & 2 & 2 \\ 2 & 2 & 4+2 \end{bmatrix} = 0$   
 $\begin{bmatrix} -4 & 2 & 2 \\ 2 & 2 & 4+2 \end{bmatrix} = 0$   
 $\begin{bmatrix} -4 & 2 & 2 \\ 2 & 2 & 4+2 \end{bmatrix} = 0$   
 $\begin{bmatrix} -4 & 2 & 2 \\ 2 & 2 & 4+2 \end{bmatrix} = 0$   
 $\begin{bmatrix} -4 & 2 & 2 \\ 2 & 2 & 4+2 \end{bmatrix} = 0$   
So the solutions to  $\begin{bmatrix} 4-2 & 2 & 2 \\ 2 & 2 & 4+2 \end{bmatrix} = 0$   
So the solutions Are  $\begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix} = x_{1} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$   
So we have the following linearly independent set of 3 eigenvelocitors  
 $\begin{bmatrix} [1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \end{bmatrix}$  with 2 corresponding eigenvalue  $\{ 2, 2, 9 \}$   
So using the 5 on pg 2844, A=PD P<sup>-1</sup> where  $P = \begin{bmatrix} -1 & -1 \\ 0 & 1 & 1 \end{bmatrix}$ ,  $D = \begin{bmatrix} 2 & 0 \\ 0 & 0 & 8 \end{bmatrix}$ 

**Exercise 5.** Let  $\mathcal{B} = {\mathbf{b_1}, \mathbf{b_2}, \mathbf{b_3}}$  be a bisis for a vector space V and  $T : V \to \mathbb{R}^2$  be a linear transformation such that:

$$T(x_1\mathbf{b_1} + x_2\mathbf{b_2} + x_3\mathbf{b_3}) = \begin{bmatrix} 2x_1 - 4x_2 + 5x_3 \\ -x_2 + 3x_3 \end{bmatrix}$$

Find the matrix for T relative to  $\mathcal{B}$  and the standard basis for  $\mathbb{R}^2$ .

*Proof.* Let  $\mathcal{E}$  denote the standard basis for  $\mathbb{R}^2$ . The formula for the matrix  $_{\mathcal{E}}[T]_{\mathcal{B}}$  is

 $\begin{bmatrix} [T(\mathbf{b_1})]_{\mathcal{E}} & [T(\mathbf{b_2})]_{\mathcal{E}} & [T(\mathbf{b_3})]_{\mathcal{E}} \end{bmatrix}$ 

. We compute each column individually:

$$T(\mathbf{b_1}) = \begin{bmatrix} 2\\0 \end{bmatrix}$$
, which is already in standard basis coordinates.  
 $T(\mathbf{b_2}) = \begin{bmatrix} -4\\-1 \end{bmatrix}$ , which is already in standard basis coordinates.  
 $T(\mathbf{b_3}) = \begin{bmatrix} 5\\3 \end{bmatrix}$ , which is already in standard basis coordinates.

So our final matrix is  $\begin{bmatrix} 2 & -4 & 5 \\ 0 & -1 & 3 \end{bmatrix}$