## Math 110, Summer 2012 Short Homework 7

Due Monday 7/12, 10.10am, in Etcheverry 3109. Late homework will not be accepted.

## Calculations

1. Consider the  $\mathbb{C}$ -vector space  $\mathbb{C}_3[t]$  consisting of polynomials with  $\mathbb{C}$ -coefficients that have degree at most 3. We have dim<sub> $\mathbb{C}$ </sub>  $\mathbb{C}_3[t] = 4$ . Consider the  $\mathbb{C}$ -linear endomorphism

$$D: \mathbb{C}_3[t] \to \mathbb{C}_3[t] ; f \mapsto \frac{df}{dt}.$$

- a) Show that D is a nilpotent endomorphism and determine the exponent of D,  $\eta(D)$ .
- b) For each k,  $0 \le k \le \eta(D)$ , determine

$$H_k = \{f \in \mathbb{C}_3[t] \mid \mathsf{ht}(f) \le k\},\$$

and determine dim  $H_k = m_k$ .

c) Recall the algorithm from Section 2.3 used to determine a basis of V, given a nilpotent endomorphism g ∈ End<sub>ℂ</sub>(V). Using this algorithm find an ordered basis B of ℂ<sub>3</sub>[t] such that [D]<sub>B</sub> is block diagonal matrix, each block being a 0-Jordan block.

(Hint: there is only one 0-Jordan block.)

## Solution:

- a) You can easily check that  $D^4$  is the zero morphism: for any  $f \in \mathbb{C}_3[t]$  we have  $D^4(f) = 0_{\mathbb{C}_3[t]}$ . Hence,  $\eta(D) = 4$ .
- b) For each  $0 \le k \le 4$  we have

$$H_k = \{ f \in \mathbb{C}_3[t] \mid D^k(f) = 0 \} = \{ f \in \mathbb{C}_3[t] \mid \deg f \le k - 1 \}.$$

Then, dim  $H_k = \dim \mathbb{C}_{k-1}[t] = k$ .

c) We proceed through the algorithm described in the notes:<sup>1</sup>

We have

$$\mathbb{C}_3[t] = H_4 = H_3 \oplus G_4 = \operatorname{span}\{1, t, t^2\} \oplus \operatorname{span}\{t^3\}$$

where we have used that  $t^3 \notin H_3$  (so that  $G_4 = \operatorname{span}\{t^3\}$ ) and  $H_3 = \operatorname{span}\{1, t, t^2\}$ . Thus, we have  $z_1 = t^3$ . Then, since  $\operatorname{ht}(t^3) = 4$  we have that  $\{t^3, D(t^3), D^2(t^3), D^3(t^3)\}$  is linearly independent therefore must be a basis of  $\mathbb{C}_3[t]$ . If we let  $\mathcal{B} = (6, 6t, 3t^2, t^3)$  then

$$[D]_{\mathcal{B}} = egin{bmatrix} 0 & 1 & 0 & 0 \ 0 & 0 & 1 & 0 \ 0 & 0 & 0 & 1 \ 0 & 0 & 0 & 0 \end{bmatrix}$$

2. Let

$$A = egin{bmatrix} 0 & 1 \ 0 & 0 \end{bmatrix} \in \mathit{Mat}_2(\mathbb{C}),$$

and consider the endomorphism

$$R_A: Mat_2(\mathbb{C}) 
ightarrow Mat_2(\mathbb{C}) \; ; \; B \mapsto BA.$$

<sup>&</sup>lt;sup>1</sup>However, this is not required since the exponent of D is 4. This means the largest number appearing in  $\pi(D)$  is 4. The only partition of 4 for which 4 appears is the partition  $\pi(D)$ : 4. Thus, we necessarily must have that  $(D^3f, D^2f, Df, f)$  is a Jordan basis, where f is any vector of height 4.

- a) Show that  $R_A$  is a nilpotent endomorphism and determine the exponent of  $R_A$ ,  $\eta(R_A)$ .
- b) For each k,  $0 \le k \le \eta(R_A)$ , determine

$$H_k = \{B \in Mat_2(\mathbb{C}) \mid ht(B) \leq k\},\$$

and determine dim  $H_k = m_k$ .

c) As in 1*c*) above, determine an ordered basis  $\mathcal{B} \subset Mat_2(\mathbb{C})$  such that  $[R_A]_{\mathcal{B}}$  is a block diagonal matrix, each block being a 0-Jordan block.

(Hint: there is more than one 0-Jordan block in this case.)

Solution:

- a) You can check that  $R^2_A = 0 \in \operatorname{End}_{\mathbb{C}}(\operatorname{Mat}_2(\mathbb{C}))$  so that  $\eta(R_A) = 2$ .
- b) We have, for each  $0 \le k \le 2$  that

$$H_k = \operatorname{\mathsf{ker}} R^k_A = \{B \in \operatorname{\mathit{Mat}}_2(\mathbb{C}) \mid R^k_A(B) = 0\}$$

Thus, we have

$$\mathcal{H}_0=\{0\},\ \mathcal{H}_1=\{B\in \mathit{Mat}_2(\mathbb{C})\mid \mathit{BA}=0\}=\left\{egin{bmatrix}0&a\\0&b\end{bmatrix}\mid a,b\in\mathbb{C}
ight\}, \mathcal{H}_2=\mathit{Mat}_2(\mathbb{C}).$$

Hence,

$$m_0 = 0, m_1 = 2, m_2 = 4.$$

c) We have

$$\mathit{Mat}_2(\mathbb{C}) = \mathit{H}_2 = \mathit{H}_1 \oplus \mathit{G}_2 = \mathit{H}_1 \oplus \mathsf{span}\{\mathit{e}_{11}, \mathit{e}_{21}\}$$

so take  $z_1 = e_{11}$ ,  $z_2 = e_{21}$ . Then, we know that  $\{R_A(e_{11}), e_{11}, R_A(e_{21}), e_{21}\}$  is linearly independent and hence must be a basis. Thus, if we define

$$\mathcal{B} = \left( \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \right)$$

we must have

$$[R_A]_{\mathcal{B}} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

## Proofs

3. Let  $f \in \text{End}_{\mathbb{C}}(V)$ , where V is a finite dimensional  $\mathbb{C}$ -vector space. Denote the eigenvalues of f by  $\lambda_1, \ldots, \lambda_k$ . Prove: f is diagonalisable if and only if, for every i, the algebraic multiplicity of  $\lambda_i$  is equal to the geometric multiplicity of  $\lambda_i$ .

(Looking at Proposition 2.1.14 and its proof may help here.)

4. Let  $f \in \text{End}_{\mathbb{C}}(V)$ , where dim V = n, and suppose that there is an ordered basis  $\mathcal{B} = (b_1, ..., b_n)$  of V such that

$$[f]_{\mathcal{B}} = \begin{bmatrix} A & B \\ 0_{n-k,k} & C \end{bmatrix}$$

Prove that  $U = \operatorname{span}_{\mathbb{C}} \{ b_1, \dots, b_k \}$  is *f*-invariant.

Solution: Let  $u \in \text{span}_{\mathbb{C}}\{b_1, \dots, b_k\}$ . Then,

$$u = c_1 b_1 + ... + c_k b_k, \ c_1, ..., c_k \in \mathbb{C}$$

Thus, we have

$$[f]_{\mathcal{B}}[u]_{\mathcal{B}} = \begin{bmatrix} A & B \\ 0_{n-k,k} & C \end{bmatrix} \begin{bmatrix} c_1 \\ \vdots \\ c_k \\ 0 \\ \vdots \\ 0 \end{bmatrix} = \begin{bmatrix} A\underline{c} \\ 0 \\ \vdots \\ 0 \end{bmatrix},$$

where  $\underline{c} = \begin{bmatrix} c_1 \\ \vdots \\ c_k \end{bmatrix} \in \mathbb{C}^k$ . Then,  $A\underline{c} \in \mathbb{C}^k$  since  $A \in Mat_k(\mathbb{C})$ . Hence,

$$[f(u)]_{\mathcal{B}}=[f]_{\mathcal{B}}[u]_{\mathcal{B}}\in \mathsf{span}_{\mathbb{C}}\{[b_1]_{\mathcal{B}},\ldots,[b_k]_{\mathcal{B}}\},$$

so that  $f(u) \in \text{span}_{\mathbb{C}}\{b_1, \dots, b_k\}$ , since the  $\mathcal{B}$ -coordinate morphism is an isomorphism. (Short Homework 6) 2. Consider the matrix

$$B = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \in Mat_3(\mathbb{C}).$$

Show that the subspace

$$U = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \mathbb{C}^3 \mid x_1 + x_2 + x_3 = 0 \right\} \subset \mathbb{C}^3,$$

is *B*-invariant and that 1 is an eigenvalue of *B*. Show that  $E_1 \cap U = \{0_{\mathbb{C}^3}\}$ . Find a *B*-invariant subspace  $W \subset V$  such that

$$V = W \oplus U$$

Justify your answer.

Solution: Let  $\underline{x} \in U$  so that  $x_1 + x_2 + x_3 = 0$ . Then,

$$B\underline{x} = \begin{bmatrix} x_3 \\ x_1 \\ x_2 \end{bmatrix} \left( = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \right),$$

and  $y_1 + y_2 + y_3 = x_3 + x_1 + x_2 = 0$ , so that  $B\underline{x} \in U$ . Hence, U is B-invariant.

You can check that

$$B\begin{bmatrix}1\\1\\1\end{bmatrix}=\begin{bmatrix}1\\1\\1\end{bmatrix}$$
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so that 1 is an eigenvalue of B.

Let  $z \in E_1 \cap U$ . Then, Bz = z and  $z_1 + z_2 + z_3 = 0$ . As Bz = z we must have

$$\begin{bmatrix} z_3 \\ z_1 \\ z_2 \end{bmatrix} = Bz = \begin{bmatrix} z_1 \\ z_2 \\ z_3 \end{bmatrix},$$

so that  $z_3 = z_1 = z_2$ . Now, as  $z_1 + z_2 + z_3 = 0$  this can only occur if  $z_1 = z_2 = z_3 = 0$ . Hence, z = 0. As U is 2 dimensional (you can easily check this) and  $E_1 + U = E_1 \oplus U \subset \mathbb{C}^3$  we must have

$$3 = \dim \mathbb{C}^3 \ge \dim E_1 \oplus U = \dim E_1 + \dim U = \dim E_1 + 2 \ge 3$$
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since dim  $E_1 \ge 1$ . Hence, we have that dim  $E_1 \oplus U = 3$  so that  $E_1 \oplus U = \mathbb{C}^3$ . Also, since eigenspaces are always *B*-invariant we have found a *B*-invariant complement to *U*.